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NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

(FOR ALL LAUNCH DATES)

APOLLO 17

FINAL LUNAR SURFACE PROCEDURES

VOL. 1: NOMINAL PLANS

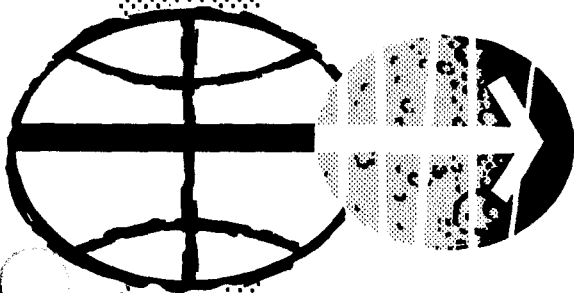
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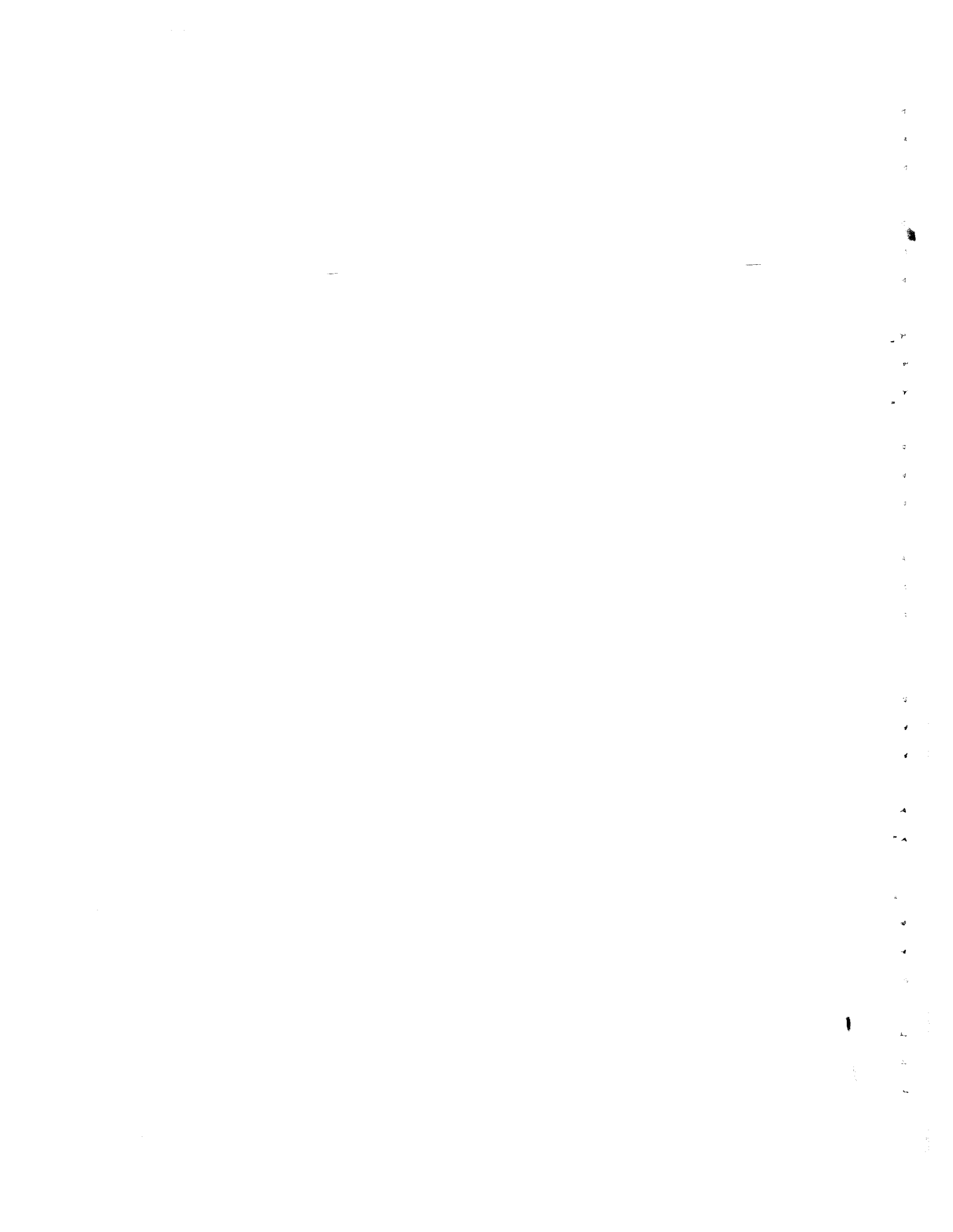
Lunar Science Institute

**EVA AND EXPERIMENTS BRANCH
CREW PROCEDURES DIVISION**



MANNED SPACECRAFT CENTER
HOUSTON, TEXAS

NOVEMBER 6, 1972



FINAL
APOLLO 17
LUNAR SURFACE PROCEDURES
VOL. 1: NOMINAL PLANS

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APOLLO 17
LUNAR SURFACE PROCEDURES

VOL. I: Nominal Plans

FINAL

PREFACE

This document has been prepared by the Crew Procedures Division, Flight Crew Operations Directorate, Manned Spacecraft Center, Houston, Texas and by General Electric, Apollo and Ground Systems, Houston Programs. The information contained herein represents Lunar Surface Procedures for Apollo 17 Mission J-3, the seventh manned lunar landing mission. The final document consists of two parts: Vol. 1 - Nominal Plans; Vol. 2 - Contingency Plans.

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ACKNOWLEDGEMENT

Much of the geological data and traverse planning material in this document was prepared by the Operation Analysis Branch of the Systems Engineering Division, Apollo Spacecraft Program Office, and was distributed under separate cover as "Apollo 17 Traverse Planning Data." All procedures and planning data for lunar surface operations are superceded by this document.

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1.0 INTRODUCTIO

2.0 MISSION DESCRIPTIC

3.0 PROCEDURE

3.1 EVA

3.2 EVA

3.3 EVA

3.4 SAMPLIN

3.5 PHOTOGRAPH

3.6 EXPERIMENT

3.7 EQUIPMENT

3.8 LRV

4.0 APPENDI



1.0 INTRODUCTION

This Final Apollo 17 Lunar Surface Procedures Document is used to document the planning for lunar surface EVA operations on Mission J-3, to describe the crew equipment interface, and to document the manner in which the lunar surface mission requirements are to be implemented.

The nominal plan includes three two-man EVA periods during the 75 hour stay of the LM vehicle on the lunar surface. The first, second and third EVA's are each planned for seven hours of activity from depressurization to repressurization of the LM.

EMU operations and procedures (including contingency) are covered in the EMU AOH, Reference 6.

Photographic and TV camera operations are integrated herein in a summary manner.

This document contains summary and detailed timeline and procedures data. The voice data plan and copies of the crew's cuff checklist are included. The summary timelines are essentially a task flow analysis along a time base showing coincident activities and points of interaction between crewmen. The detailed timeline procedures simply list in the sequence of performance, the steps required to carry out each of the tasks identified in the summary timeline. It is in the detailed timeline procedures that the crew/equipment interfaces are revealed. Both the summary and detailed timeline procedures present the CDR's and the LMP's task side-by-side to minimize the confusion as to which crewman is doing what and to show how they cooperate in the lunar surface operations. The voice data plan is provided coincident with the detailed timeline procedures as a device by which cap-com (capsule communicator) is able to keep abreast of the crew's activities and to provide cap-com with cues, data and data recording points with which to provide realtime assistance to the lunar surface crew during the EVA activities. The crew's cuff checklists are included for information only, showing the procedural cues the crew have at their fingertips.

The procedures herein are responsive to the Mission Requirements for SA-512/CSM-114/LM-12 J-3 Type Mission currently in effect as of the date of this document.

2.0 MISSION DESCRIPTION

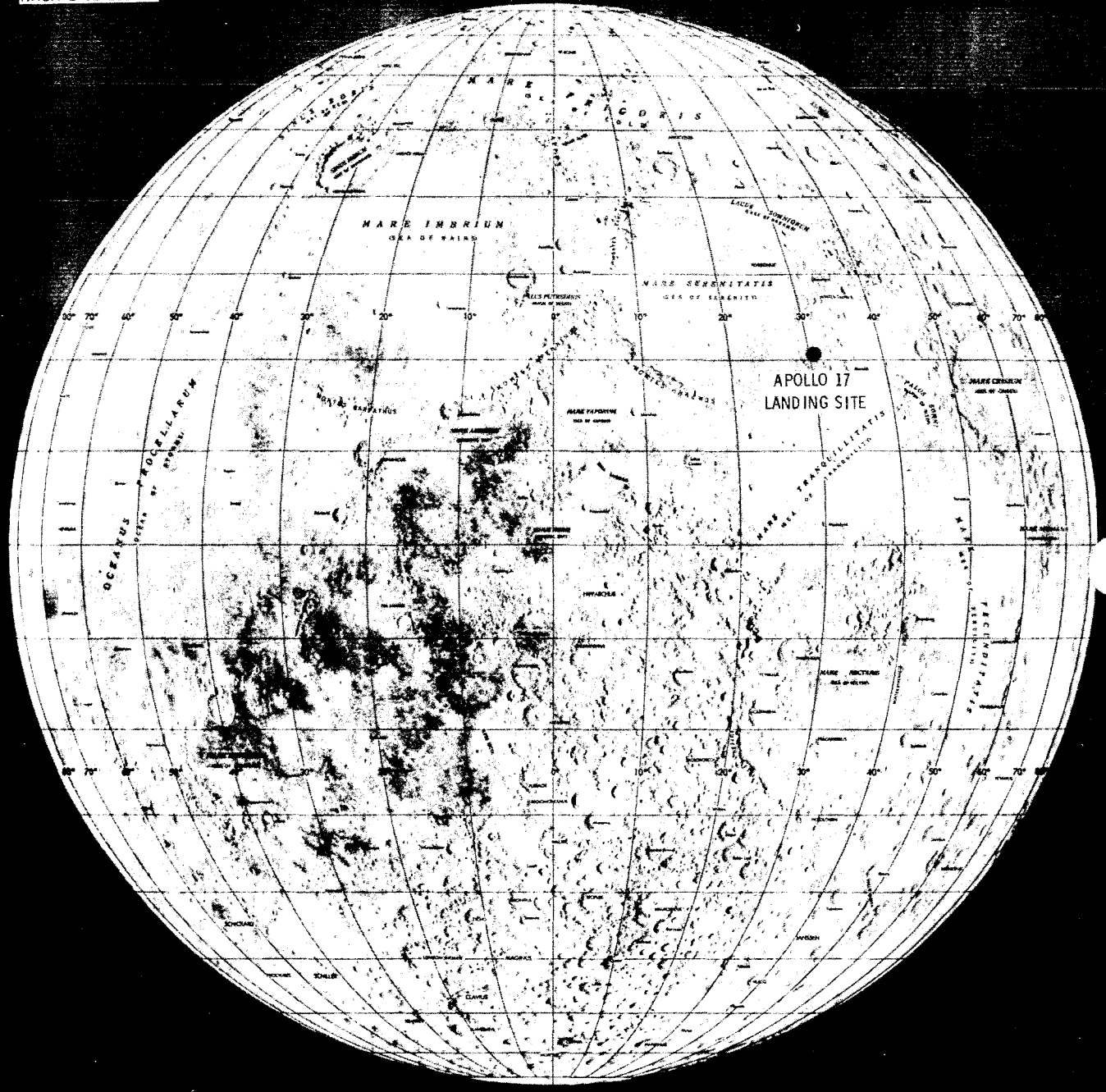


Figure 2.1-1 Whole moon view showing Apollo 17 landing site: 20° 09' 50" N, 30° 44' 58" E.

2.0 MISSION DESCRIPTION

2.1 LANDING SITE

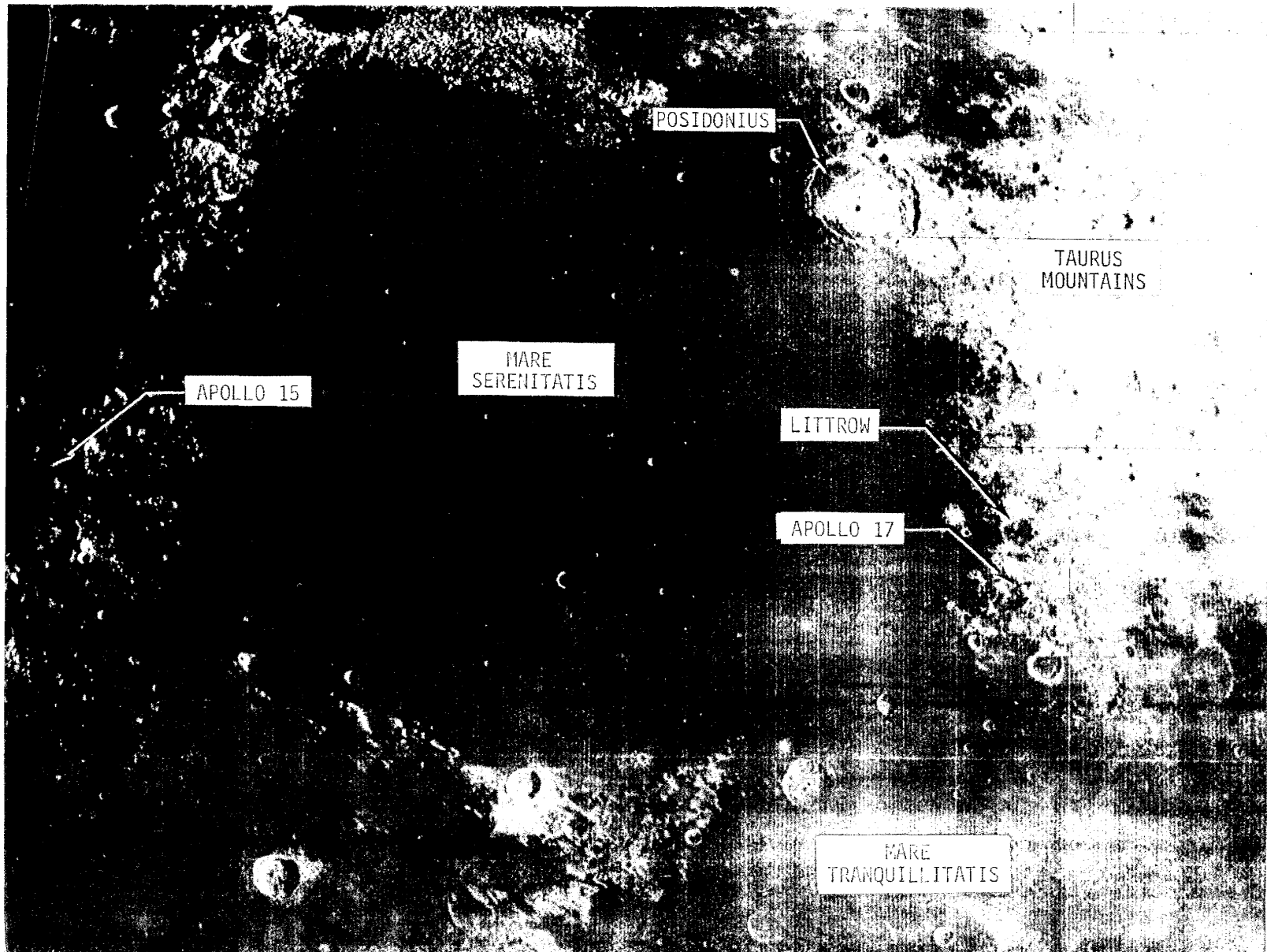
The description of the Taurus Littrow site has been developed by a number of sources: notably, the Field Geology Experiment Team, various individuals in the Science and Applications Directorate, the Operations Analysis Branch of ASPQ, and the Experiments Branch of Flight Control Division. Special acknowledgement is made to Drs. V. L. Freeman, J. W. Head, W. R. Muehlberger, and E. W. Wolfe who prepared the material on the geologic objectives of the mission, and the discussion of the Taurus-Littrow geologic setting.

2.1.1 Geographic Setting - The Taurus-Littrow region is located in the northeast quadrant of the moon (Figure 2.1-1), in the mountainous region of the southeastern rim of the Serenitatis basin, approximately 750 km east of the Apollo 15 site (Figure 2.1-2). The site name is derived from the Taurus Mountains, which lie to the north and northeast of the site forming a mountainous plateau at the eastern edge of Serenitatis between Posidonius and Macrobius, and from Littrow, an old 30 km highland crater which lies approximately 35 km north of the landing site. This area is well illustrated in Figure 2.1-3, an Apollo 15 metric camera oblique, a view of the Taurus-Littrow area from south of the landing site. Posidonius is the large crater in the upper left near the horizon, Mare Serenitatis is the dark region along the left margin, and the crater Littrow lies in the left-center, just north of the landing site. Macrobius is off the picture to the west and the relatively fresh large crater in the upper right is Romer. Figure 2.1-4 shows the map location of this region.

Approach and Landing - The approach to the landing point is from due east over a set of the sculptured hills which rise about 1-1/2 km above the plains. At the point where the descent trajectory passes over the hills, the terrain is about 750 meters above the landing site, the spacecraft clears the local terrain by about 3000 meters.

Figures 2.1-5 and 1-6 show two oblique views of the landing area and approach path. In Figure 2.1-6, South Massif is just out of view on the left margin but the light mantled material of the debris slide can be seen just downrange from the landing point.

Figure 2.1-7 shows a closer view of the landing area with the landing dispersion ellipse superimposed. Coordinates of the target point are as follows: longitude 30° 44' 58.3" E, latitude 20° 09' 50.5" N, radius 1,734,484 meters based on analytical triangulation of Apollo 15 photography.



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Figure 2.1-2 Lunar surface view of Apollo 17 landing region.

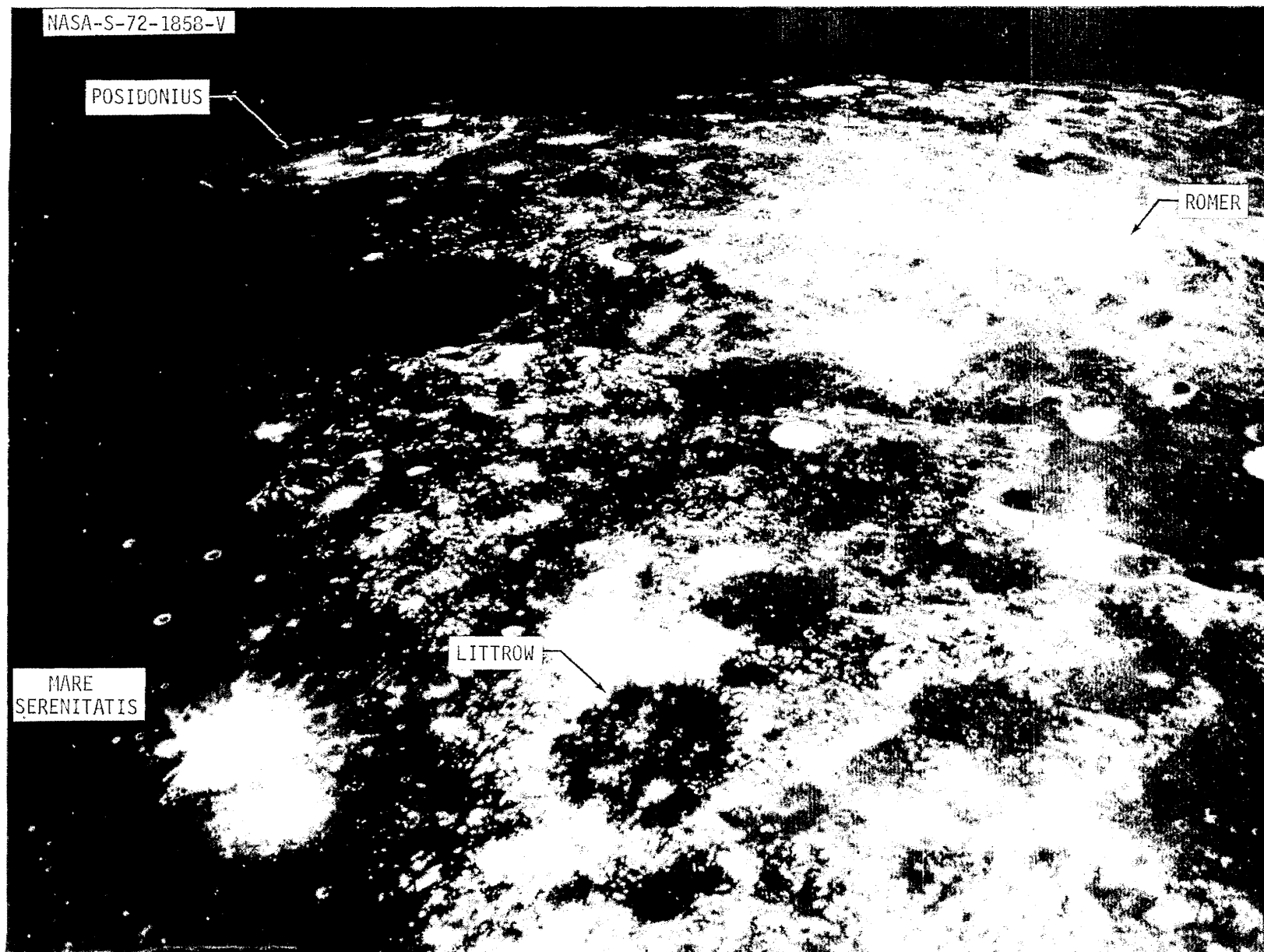


Figure 2.1-3 Oblique view of Apollo 17 landing region as seen by Apollo 15 mapping camera.
The landing site itself is off the picture just below the center margin.

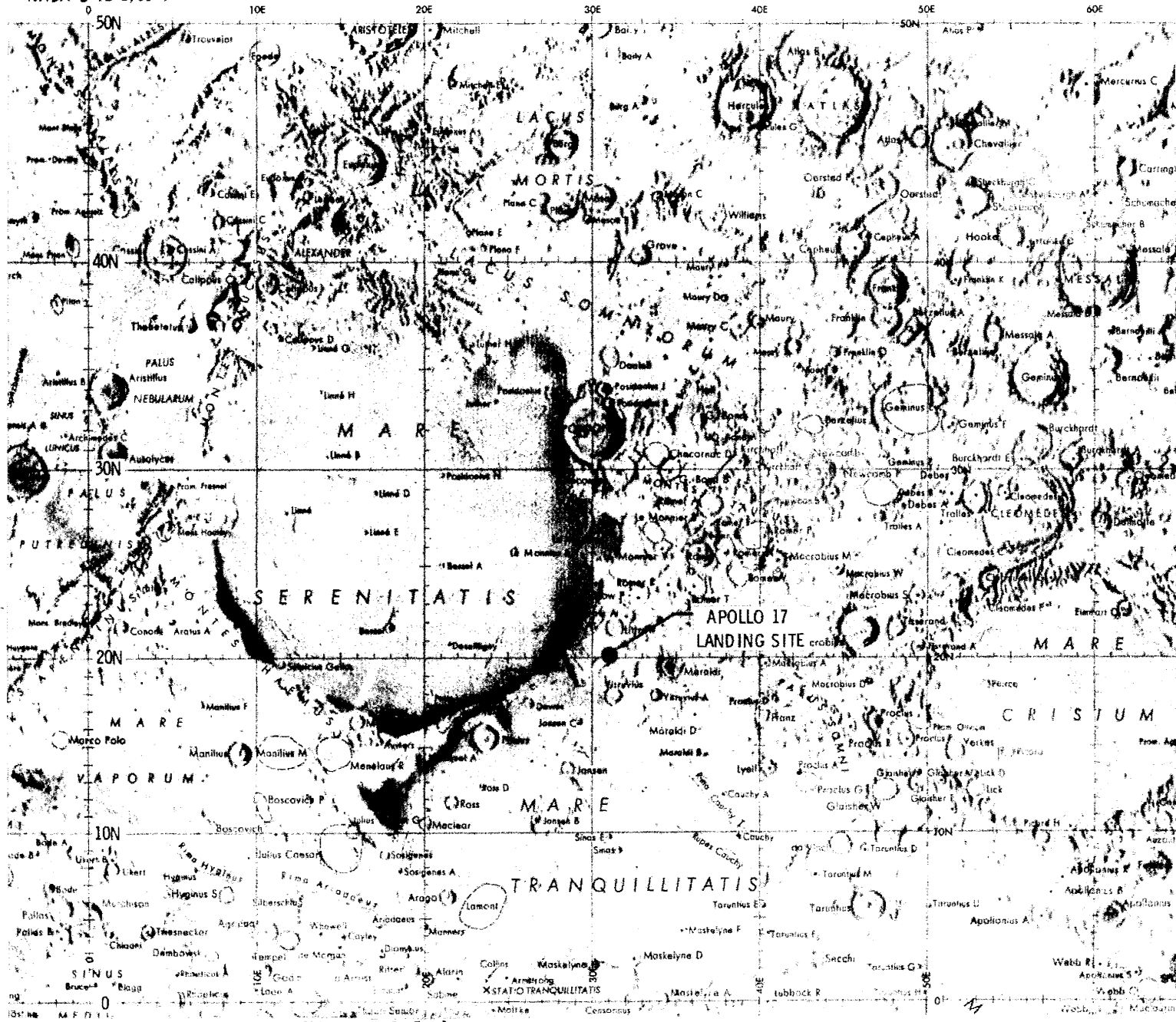


Figure 2.1-4 Map view of Apollo 17 landing region.

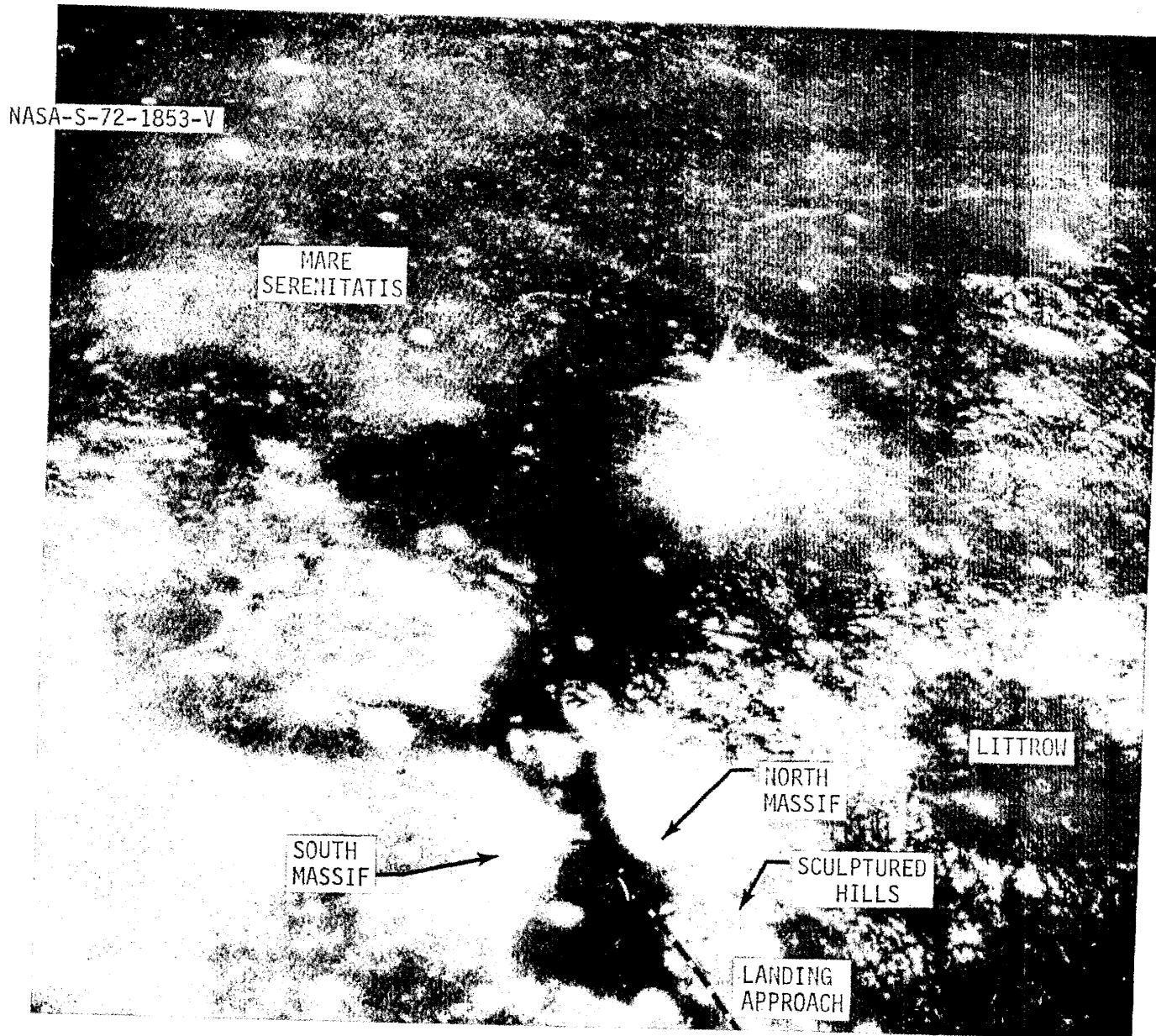


FIGURE 2.1-5 Apollo 15 oblique view of Taurus-Littrow area.

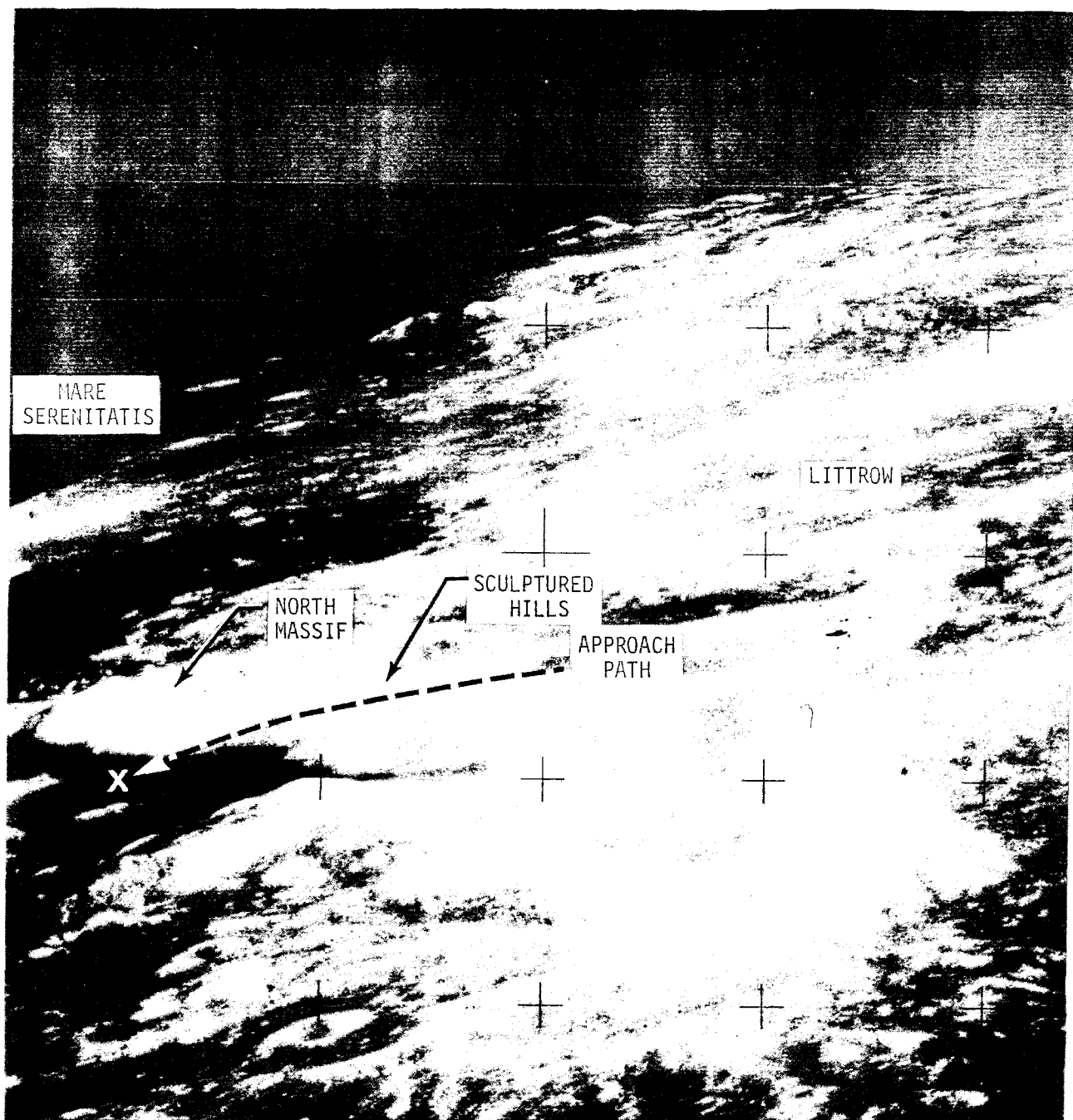


Figure 2.1-6 Apollo 15 oblique view looking northwest at the Taurus-Littrow area.

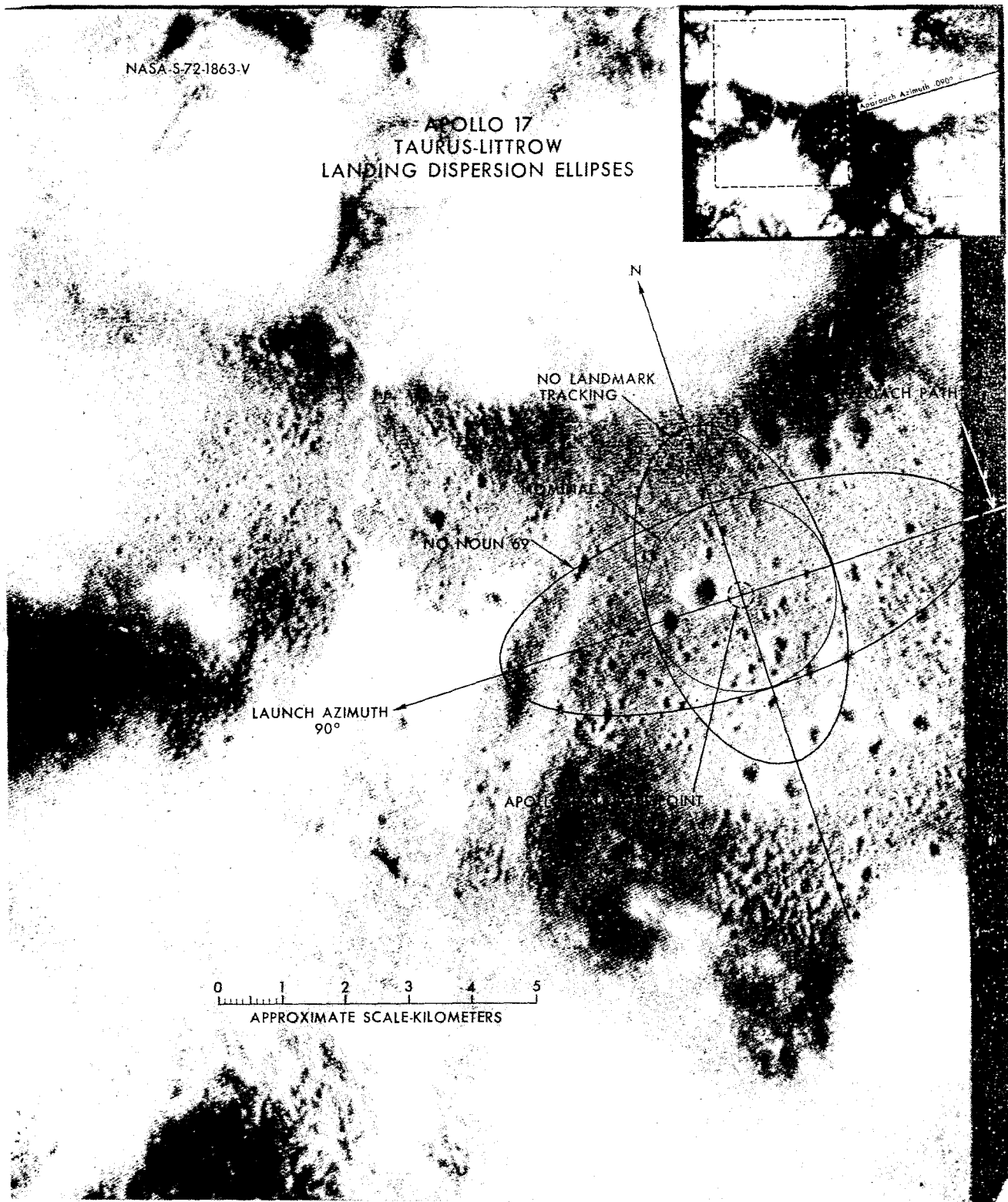
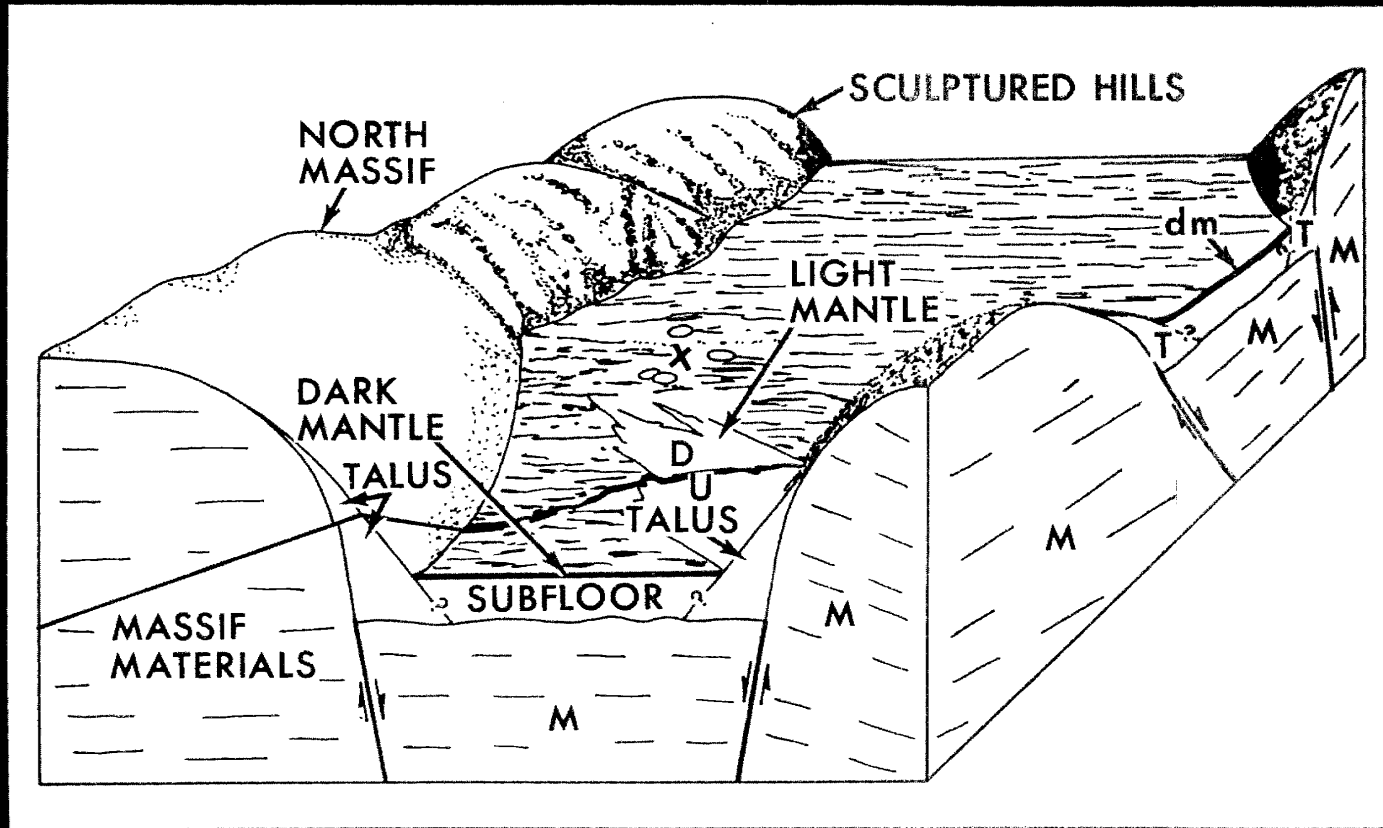


Figure 2.1-7 Landing approach and landing dispersion ellipse.

SCHEMATIC VIEW OF TAURUS-LITTROW LANDING REGION



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X NORMAL LANDING SITE
VERTICAL EXAGGERATION ABOUT 2.5

Figure 2.1-8 Schematic view of Taurus-Littrow landing and traverse region looking east-southeast.
X is nominal landing site.

2.1.2 Geologic Setting

General - The Taurus Mountains and associated highlands form the eastern uplifted edge of the Serenitatis basin, one of the moon's large multiringed basins. The bulk of this region probably consists of highland material uplifted to its present position at the time of formation of the Serenitatis basin. The landing point itself is on the floor of a flat-floored trough (Figure 2.1-8) whose subsurface is thought to consist of highlands material down-dropped by graben formation and partially buried by younger basin-filling plains materials. The valley floor, as well as portions of the upland area, is covered by a fine dark mantle that may be composed of volcanic fragments. The regional distribution of the dark mantle material is well illustrated in Figure 2.1-9, an earth-based telescopic view of the Serenitatis and Taurus-Littrow region.

Figure 2.1-10 is an Apollo 15 photograph looking south toward the Apollo 17 landing site at the edge of Mare Serenitatis (on the right). Several of the linear rilles so characteristic of basin margins are seen in the center. The large crater in the center is Littrow B. The South Massif appears just at the upper tip of the RCS engine nozzle and the top of the North Massif just below that. The dark mantle is readily visible south of Littrow and around the massifs. Plains units and low highlands are seen in the foreground.

Geology of the landing area - The local setting of the landing site is shown in Figure 2.1-11 and 2.1-12 and the distribution of major geologic units is shown on Figure 2.1-13, a geologic map which covers approximately the same area as Figure 2.1-12.

Massif Material - Massif material forms the high, steep, relatively blocky mountain face immediately north and southwest of the landing point. The distinctive nature of the massifs is illustrated in Figure 14 which shows them grouped on the horizon in a view looking south. South Massif is indicated by the arrow. The materials of the massifs probably consist of breccia formed during impacts that created some of the major mare basins. Significant contributions of ejecta may have come from Tranquillitatis, Serenitatis, Nectaris, Crisium, and Imbrium (listed in order of decreasing age). These ejecta deposits probably overlie still older ejecta from earlier impact basins. Accordingly, the age of the massif material is regarded as Imbrian and pre-Imbrian. Faults bounding the massifs may have originated in the Serenitatis event. However, the sharp definition of the massif boundaries suggests that subsequent structural adjustments have occurred.

A possible alternative interpretation is that the North and South Massifs are volcanic in origin. Their very steep faces and arcuate convex-outward shapes (Figure 2.1-12) are similar to shapes common in terrestrial volcanic domes on earth and thus they could be extrusive volcanic constructs.

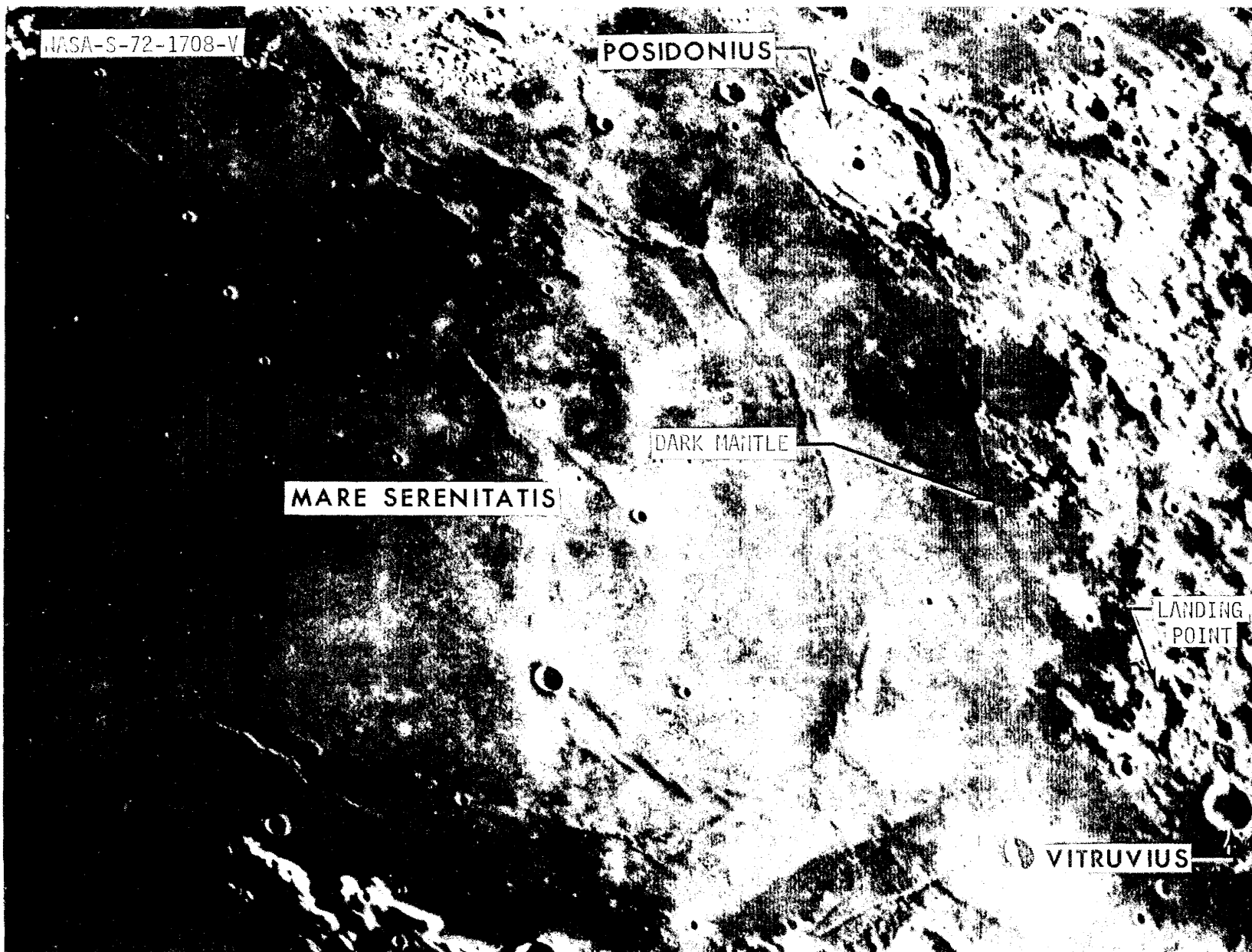
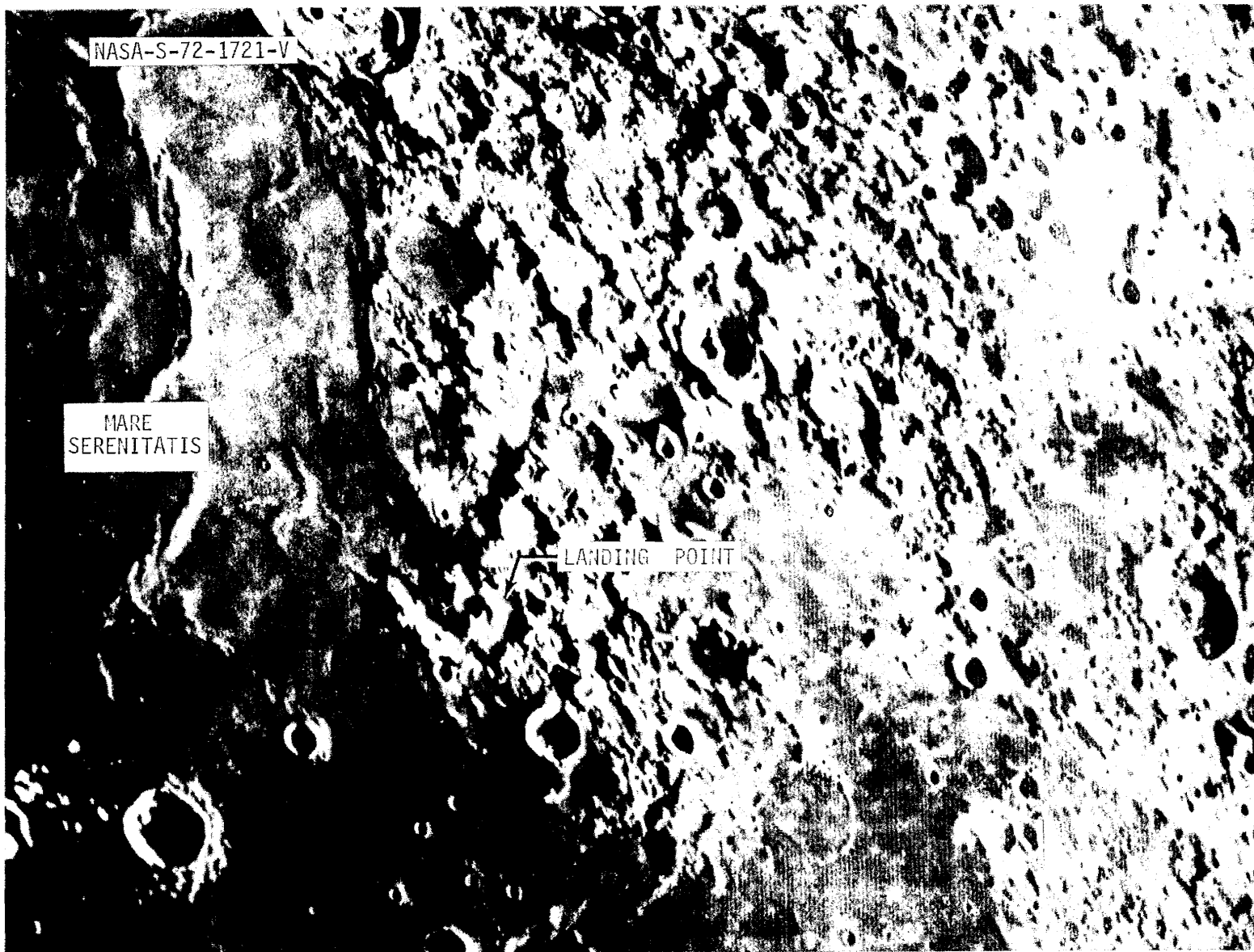


Figure 2.1-9A- Earth-based telescopic view of Apollo 17 landing region.



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Figure 2.1-9B- Earth-based telescopic view of Apollo 17 landing region.

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SOUTH MASSIF

LITTROW B

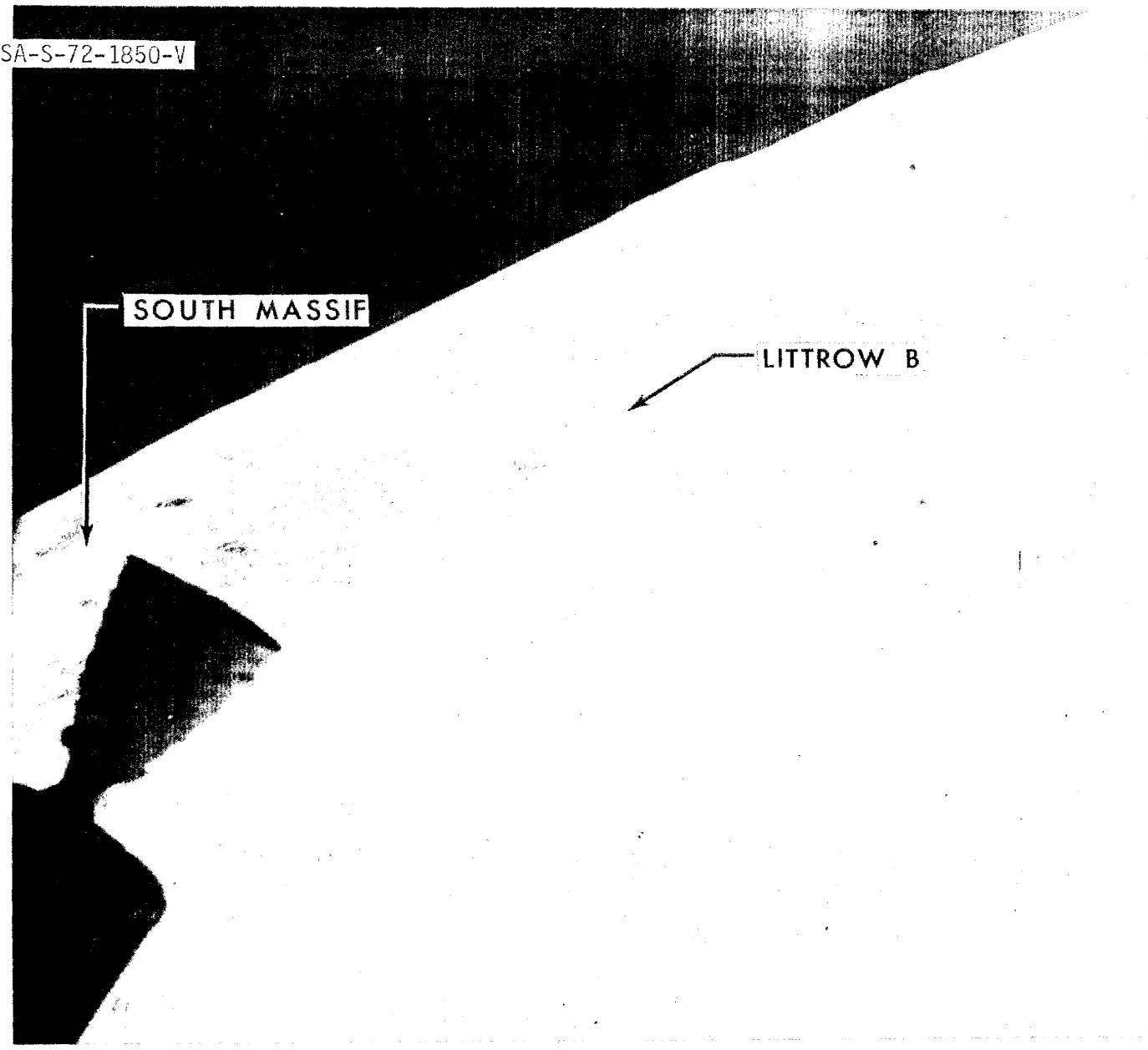


Figure 2.1-10 Southerly-looking oblique view of Apollo 17 landing region taken from Apollo 15.

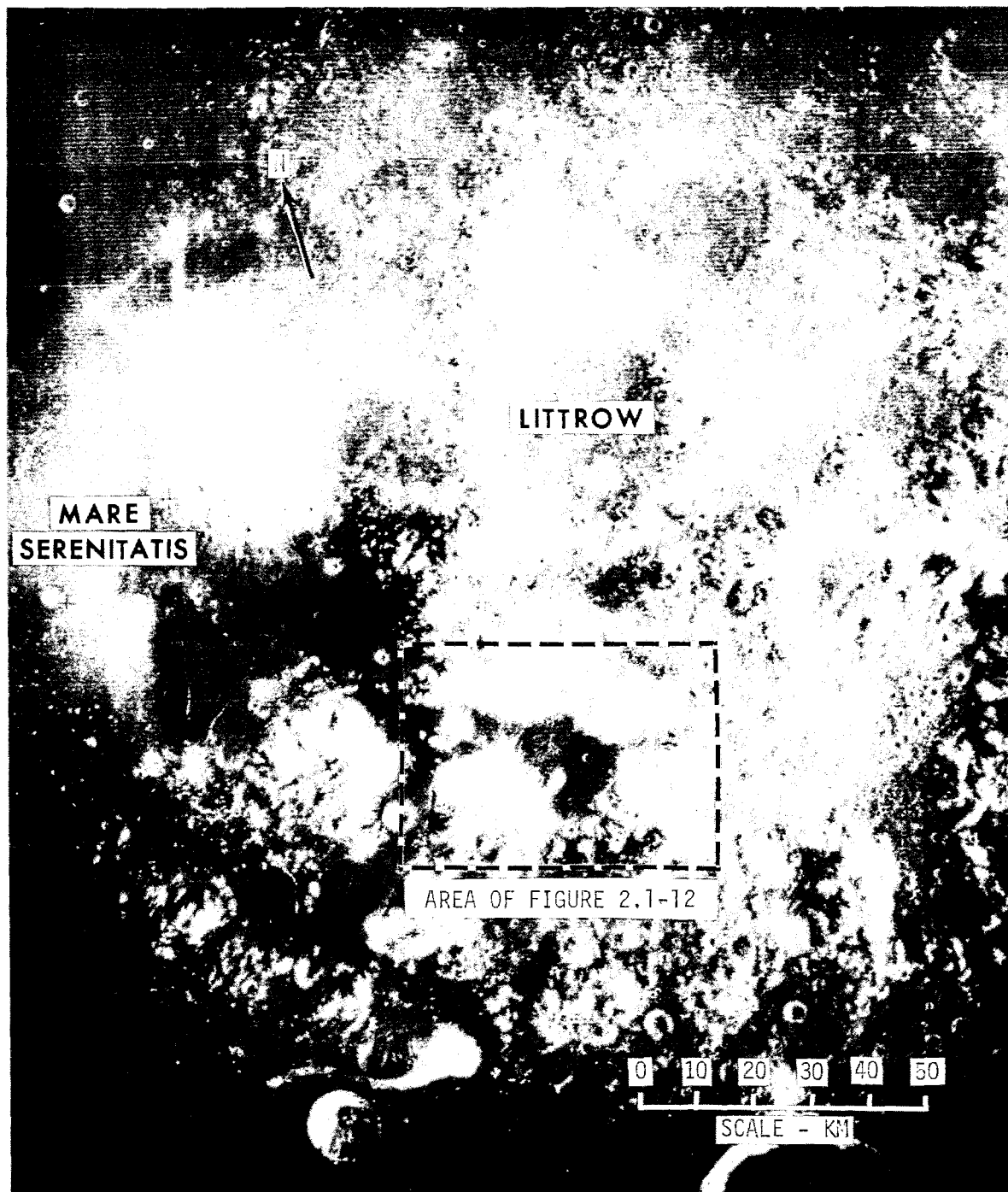
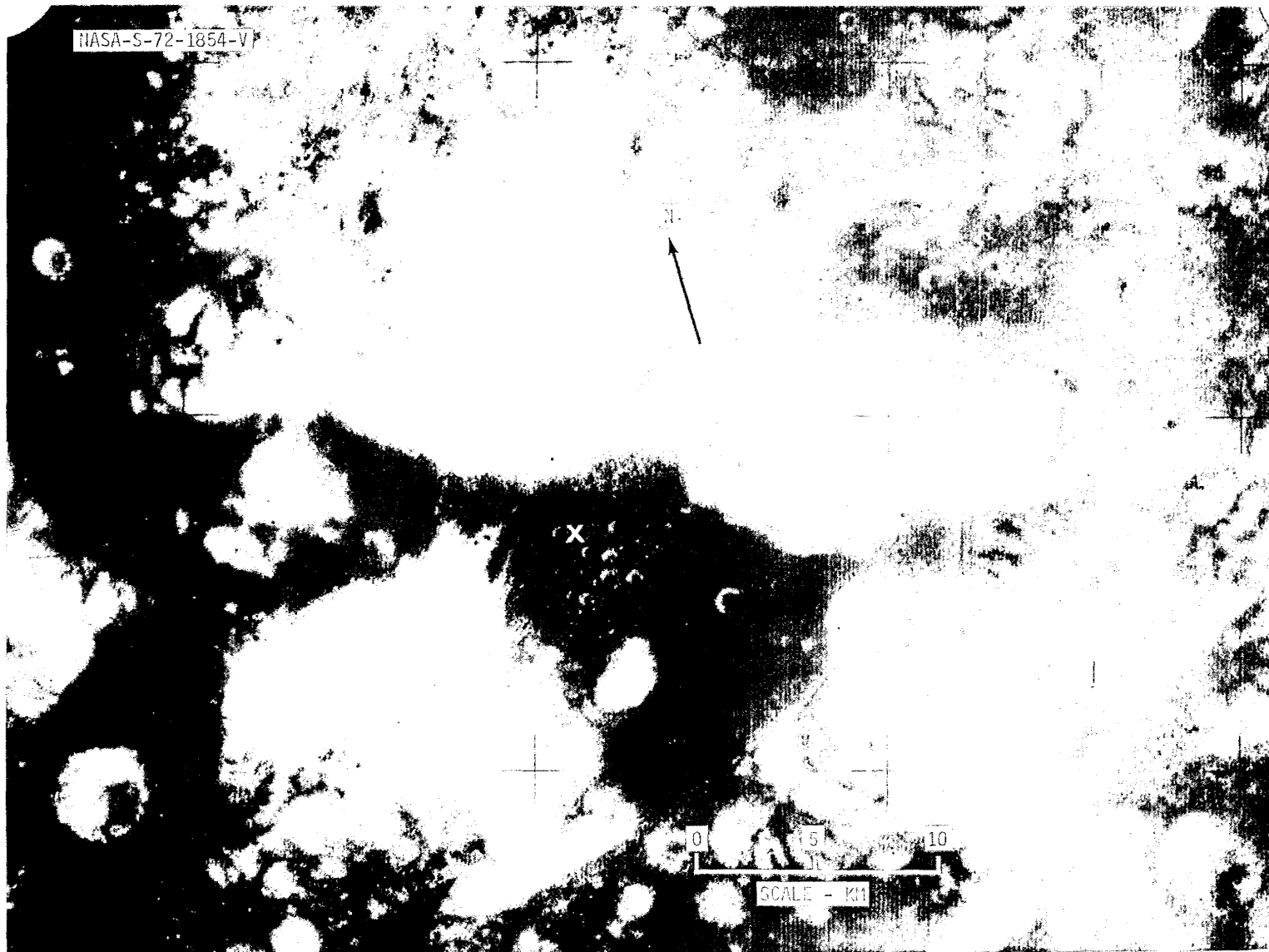


Figure 2.1-11 Apollo 15 mapping camera view of Apollo 17 landing area.



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Figure 2.1-12 Enlargement of mapping camera view of Apollo 17 landing area and traverse area

Sculptured Hills Material - The sculptured hills unit, characterized by the occurrence of closely spaced domical hills (Figure 2.1-11) is widespread in the highlands between Serenitatis and Crisium. It is within traverse range northeast of the landing point (Figure 2.1-12, -13). Because of its occurrence in the walls and rims of old craters (e.g., Littrow), (Figure 2.1-11) the sculpturing may be interpreted as an erosional of highlands material degradation controlled by pre-existing sets of fractures. Accordingly, the sculptured hills unit may be similar in composition and different only in structural history from the massifs or it may differ in composition so as to have responded differently to deformational stress. The lack of resolvable blocks at the bases of slopes in the sculptured hills compared with their relative abundance at the bases of massif slopes supports the hypothesis of compositional difference. The sculptured hills probably consist of ejecta of Imbrian and pre-Imbrian ages, but, again, they have some characteristics suggestive of volcanic origin.

Low Hills Material - Low hills material occurs in discontinuous patches adjacent to massif and sculptured hills materials where they border the plains (Figure 2.1-11). The low hills are most likely the tops of downfaulted blocks of massif or sculptured hills material that protrude slightly above the general plains surface (Figures 2.1-8, -11). In addition, they may include materials derived from the adjacent uplands by mass wasting.

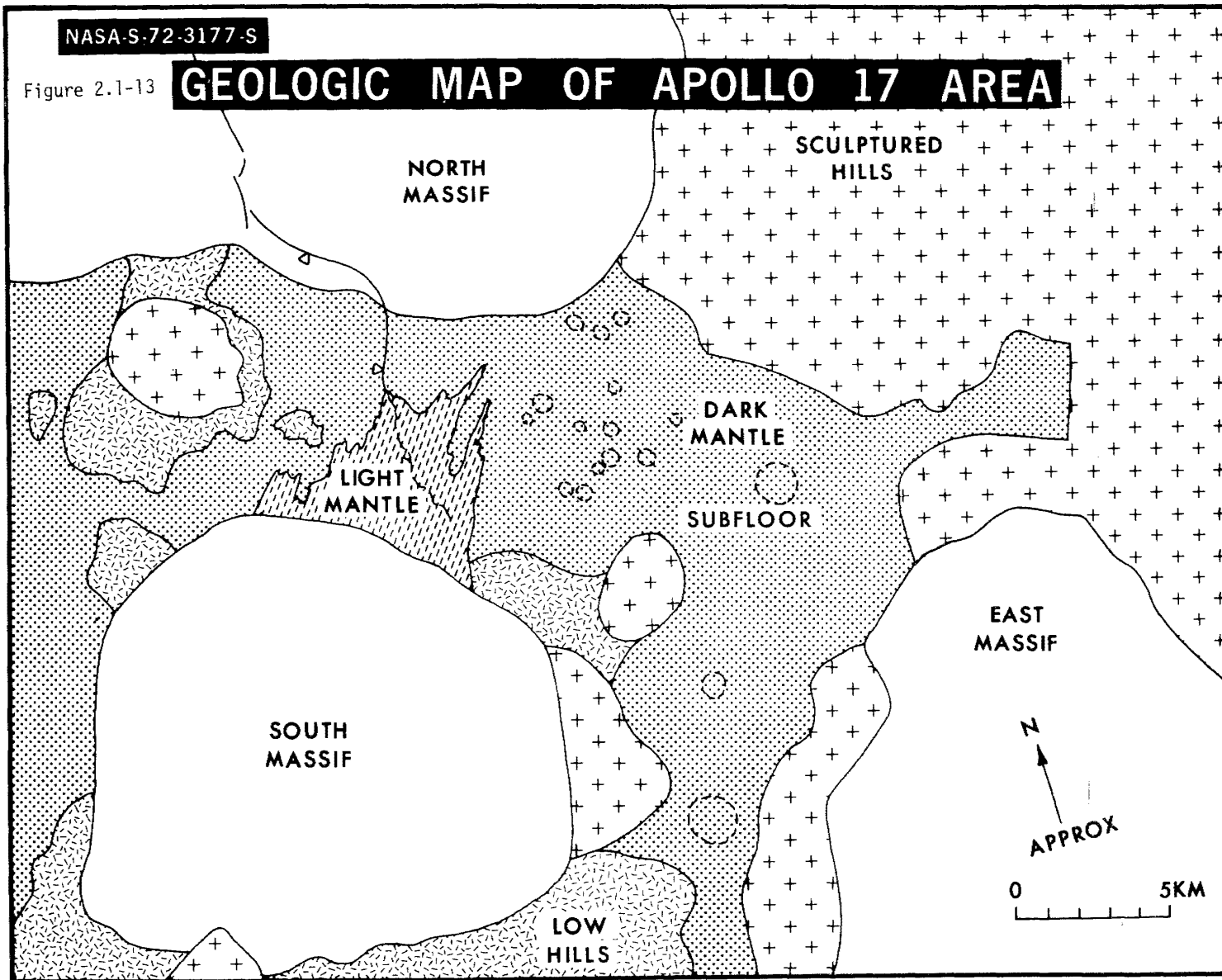
Plains Material ^{*} - The relative evenness of the valley floor at the landing site suggests that a basin-filling unit (plains material) that apparently submerged all but the highest projections of hill-forming material was emplaced after formation of the trough (Figure 2.1-8). Such fill might consist of volcanic flows, colluvium derived from the adjacent uplands, or sheets of breccia. Similar materials may fill nearby upland basins (e.g., Littrow) or may underlie the topographic bench around the east edge of the Serenitatis basin. Plains material is presumably exposed in the bright walls of the craters on the plains. The abundance of blocks in the crater walls and on their rims indicates that the plains material is either indurated or contains large indurated blocks. The large craters may penetrate through the plains material into the underlying massif or hills units, which may be represented in their ejecta. Plains material appears to be younger than the bulk of the massif and the hill materials and is probably older than youngest mare fill of the Serenitatis basin. Hence an age of Imbrian or pre-Imbrian is inferred for the plains material.

Dark Mantle Material - Dark, presumably unconsolidated material with no resolvable blocks (i.e., no blocks larger than 2 meters in diameter) occurs as a blanket a few meters to tens of meters thick on the plains surface and on the floors of nearby upland basins (Figure 2.1-9). It is discontinuous on sloping upland surfaces and on the steep walls of pre-existing craters (Figure 2.1-16). Low reflectivity

* Or, better, "sub-floor material" to avoid confusion with the more familiar usage of "plain" meaning the valley floor independent of any stratigraphic connotation.

Figure 2.1-13

GEOLOGIC MAP OF APOLLO 17 AREA











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GENERALIZED GEOLOGIC MAP OF THE TAURUS-LITTROW AREA

E. W. Wolfe, J. W. Head, V. L. Freeman, and H. H. Schmitt

EXPLANATION

COPERNICAN		Light mantle material		
COPERNICAN AND ERATOSTHENIAN		Dark mantle material		
IMBRIAN AND PRE-IMBRIAN	(Plains) *			
	Plains material (mantled except in crater walls)			
		Massif material	Sculptured Hills material	Low Hills material
		Contact (includes fault contacts)		
		Rim of larger pre-mantle crater on plains (plains material exposed in walls and rims)		
		Scarp; barbs point downhill		

Adapted in part from Lucchitta, B. K., 1972, Preliminary Geologic Map of the Littrow Region of the Moon: U.S. Geological Survey, unpublished map.

* Plains = Subfloor

Source and Explanation of Symbols in Figure 2.1-13 Geologic Map

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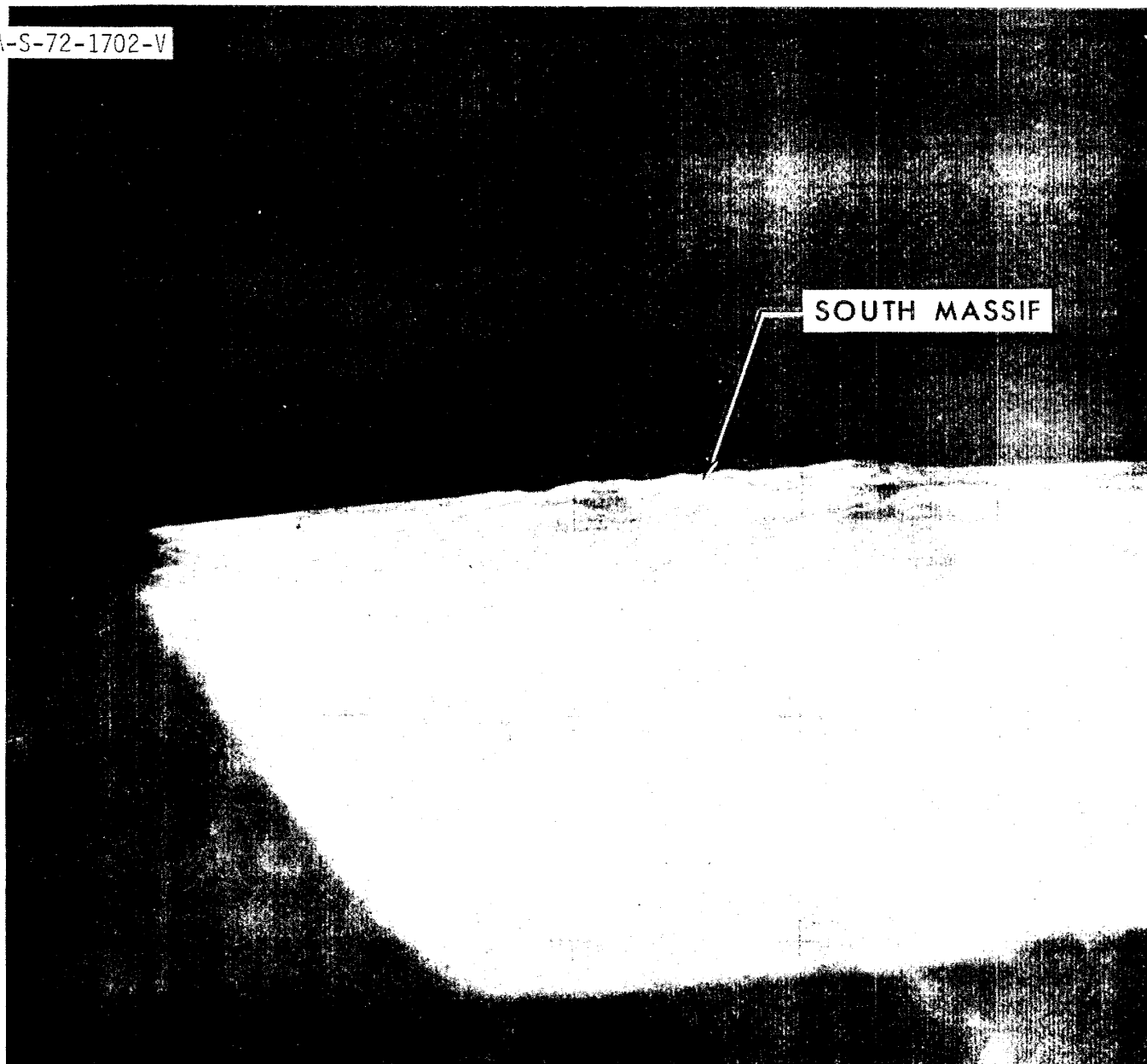


Figure 2.1-14- Southerly-looking oblique from Apollo 15.



NASA-S-72-1869-V

SCARP

K1

LIGHT
MANTLE

SOUTH
MASSIF

I0

I1

K1

Figure 2.1-15- Detailed view of south massif / light mantle / scarp area.



Figure 2.1-16 Detailed view of plains/dark mantle area.

in 3.8 and 70 cm radar images implies relative scarcity of cobbles and boulders in near-surface materials. The dark mantle is most readily interpreted as a pyroclastic deposit and is probably unconsolidated. A few small dark halo craters that could be vents for volcanic ash can be recognized in areas of massif and hills materials. No undoubted vents have been identified on the plains in the landing area. If vents are present in the Landing area, they may be too small to resolve in the orbital photographs, or we may misinterpret them as impact craters.

The dark mantle is interpreted to be younger than all of the large craters on the plains. Its relatively smooth uncratered surface and the sharpness of some of the underlying craters suggest a fairly young, perhaps Copernican, age.

Light Mantle Material - A bright ray-like feature with linear ridges and finger-like projections onto the dark mantle extends north from the South Massif (Figures 2.1-12,-15). No source crater for such a ray of ejecta can be identified. Hence this light mantle material may have been deposited by an avalanche of unconsolidated debris from the slopes of the South Massif. It seemingly overlies the dark mantle because craters with dark ejecta dot the surface of the deposit. Large craters and a prominent scarp are visible although mantled and attest to the thinness of the deposit. Resolvable blocks (>2 m) are absent except near the south end of the slide and on the adjacent south massif slope. The light mantle shows greater reflectivity than the dark mantle in 3.8 cm radar imagery, which indicates a greater frequency of cobble on the surface of the light mantle. The absence of all but fresh small impact craters, apparent position of the light mantle over the dark mantle, and the relative absence of mixing near the thin edges of the light mantle imply a young, probably Copernican, age.

Surface Features - Major surface features of special geologic interest include craters, shallow troughs at the bases of the massifs and sculptured hills, and the prominent east-facing fault scarp.

The larger craters (generally >100 m) on the plains surface (Figure 2.1-16) are of three types:

- (1) large (.5-1 km) steep-sided craters that occur in a cluster near the landing point
- (2) large subdued craters with barely perceptible rims,
- (3) scattered clusters of smaller (<.5 km) craters.

All three types are inferred to be older than the dark mantle although some could be contemporary volcanic sources. Exposures of wall and rim material are discontinuous and generally occur only on the inner wall

below the rim crest. Elsewhere the ejecta are mantled except for scattered blocks large enough to project through the thin mantle. Although the larger craters are probably of impact origin, a volcanic origin for some may be considered.

The dark mantle is excavated only by relatively small craters that are generally much less than 100 m in diameter. The most likely vents for dark mantle material in the nearby uplands are small craters with related dark deposits of local extent. Vents in the plains area may be represented by similar small craters closely enough spaced so that the ejecta blankets overlap.

An apparently young, east-facing scarp, with local height of as much as 80 m, crosses the floor of the trough about 5 km west of the landing point and continues into the North Massif (Figure 2.1-15). The scarp, which probably represents the surface trace of a complex fault, consists of alternating north and northwest-striking segments, each on the order of 5 km long. Some segments occur as single, continuous, approximately straight scarps, others as zones of discontinuous en echelon scarps. Between the light mantle unit and the North Massif the scarp is covered by the dark mantle unit, which it therefore appears to antedate. However, distinctness of some segments of the scarp in the area of the light mantle and absence of dark mantle on some segments of the scarp on the North Massif suggest that younger movement may have occurred.

Regolith - An unusually small thickness of regolith is expected on the surfaces of the dark and light mantle units. In Apollo 15 orbital photographs with resolution of a few meters, these surfaces are not saturated by resolvable craters. An albedo boundary that may represent the edge of a local dark mantle unit crossing a .5 km crater about 2 km south of the landing point (Figure 2.1-16) shows no evidence of mixing at the same high resolution. Extrapolation from crater counts in the dark mantle suggests that crater diameters at the upper limit of the steady state distribution are most probably .3 m but may be as large as 3 m. Hence the mean thickness of completely mixed regolith may lie within the range of 3 to 30 cm.

2.2 LUNAR SURFACE OBJECTIVES

The following information is taken from the "Mission Requirements, SA-512/CSM-114/LM-12 J3 Type Mission, Lunar Landing," and its approved revisions.

2.2.1 Mission Objectives

The following primary mission objectives have been assigned to this mission by the Office of Manned Space Flight (OMSF) in the Mission Implementation Plan (Reference 1):

- 1) Perform selenological inspection, survey, and sampling of materials and surface features in a pre-selected area of the Descartes region.
- 2) Emplace and activate surface experiments.
- 3) Conduct in-flight experiments and photographic tasks from lunar orbit.

Detailed objectives have been derived from the OMSF-assigned primary objectives, placed in order of priority, and detailed to the extent necessary for mission planning.

2.2.2 Lunar Surface Priorities

The detailed objectives and experiments are listed below in their order of priority. Accomplishment of the detailed objectives and detailed experiments planned for the lunar surface will not be jeopardized for the sake of those planned for lunar orbit or coasting flight. The planning will, however, permit the surface Electrical Properties experiment to be turned OFF at certain times as defined in the Test Conditions for the Lunar Sounder Experiment.

<u>Priority</u>	<u>Detailed Objectives and Experiments</u>
	<u>Lunar Surface</u>
1	Documented Sample Collection at highest priority traverse station (Part of Lunar Geology Investigation)
2	Heat Flow (S-037) (Part of Apollo 17 ALSEP)
3	Lunar Surface Gravimeter (S-207) (Part of Apollo 17 ALSEP)
4	Lunar Seismic Profiling (S-203) (Part of Apollo 17 ALSEP)
5	Lunar Atmospheric Composition (S-205) (Part of Apollo 17 ALSEP)
6	Lunar Ejecta and Meteorites (S-202) (Part of Apollo 17 ALSEP)
7	Lunar Geology Investigation (S-059) (Portions other than priority items 1 and 8)
8	Drill Core Sample Collection (Part of Lunar Geology Investigation)

- 9 Surface Electrical Properties (S-204)
- 10 Lunar Neutron Probe (S-299)
- 11 Traverse Gravimeter (S-199)
- 12 Cosmic Ray Experiment

2.3 EVA REQUIREMENTS

2.3.1 General Requirements

The stay time on the lunar surface is open-ended and the planned maximum will not exceed approximately 75 hours. After checkout of the LM to assess its launch capability, the LM will be depressurized to allow egress of astronauts to the surface. The nominal plan will provide for three periods of simultaneous EVA by both astronauts. The first EVA period will be up to approximately 7 hours in duration, as will the second and third EVA periods.

Traverse planning will provide for returning the crew to the LM under each of the following single-failure conditions.

Use of the buddy-secondary life support system due to an inoperative PLSS anytime during a riding traverse (based on the assumption that the LRV will operate properly during the return to the LM).

Use of two PLSS's for a walking return to the LM for an inoperative LRV anytime during a riding traverse (based on the assumption that both PLSS's will operate properly during the return to the LM).

Traverse planning will not be provided for dual failure conditions such as two PLSS failures or an LRV failure combined with a PLSS failure. ALSEP deployment operations will be accomplished during the first EVA within the limitations and constraints defined in the CSM/LM Spacecraft Data Book, SNA-8-D-027, Vol. V, ALSEP Data Book for Apollo 17.

Television transmission will be provided as soon as the LRV mounted TV system (GCTA) is activated during the EVA period. Television coverage will include an external view of the landed LM, a panorama of distant terrain features and an astronaut conducting lunar surface activities. Television coverage will be provided by the GCTA during each science stop when using the LRV.

Photography will be employed throughout the EVA to document the activities and observations.

Figure 2.3-1 gives sun elevation and azimuth at the Littrow site as a function of date, GMT and GET. Table 2.3-1 gives earth and sun elevations and azimuths at the nominal EVA start times for this mission.

20 July 1972

SUN ELEVATION AND AZIMUTH AT TAURUS-LITTROW

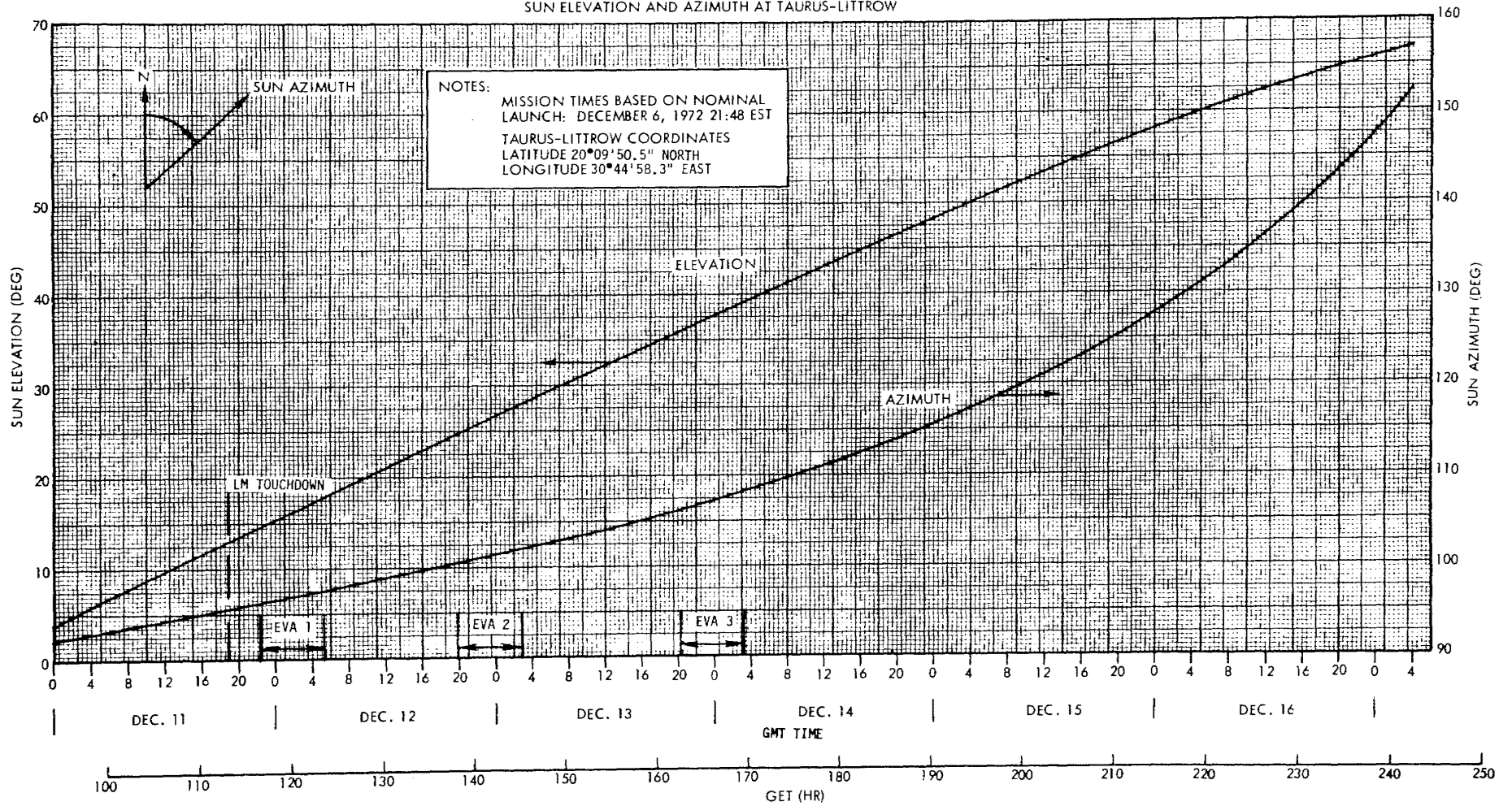


FIGURE 2.3 - 1: SUN ELEVATION AND AZIMUTH AT TAURUS-LITTROW

START EVA	AZIMUTH		ELEVATION		APPROX. EARTH CRESCENT SIZE
	EARTH	SUN	EARTH	SUN	
1	240.5°	96.5°	44.5°	14.5°	53%
2	239.5°	102.0°	45.5°	25.0°	50%
3	238.0°	107.0°	46.0°	36.5°	47%

Note: All data based on a nominal launch date and time

TABLE 2.3-1: EARTH/SUN AZIMUTH AND ELEVATIONS AT
NOMINAL EVA START TIMES FOR TAURUS-LITTROW

FIGURE 2.3-2: APOLLO 17 LUNAR STAY TIMELINE

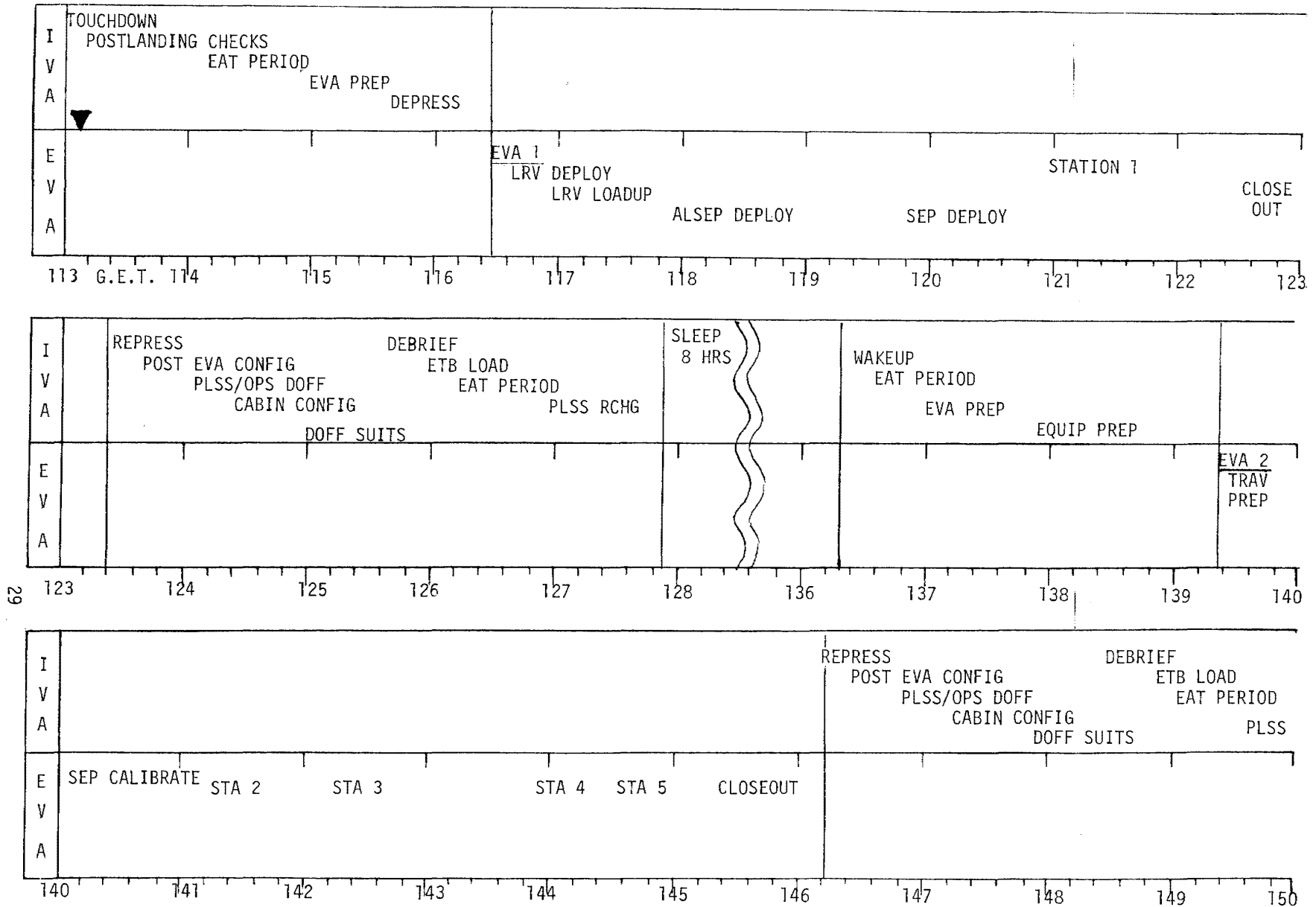
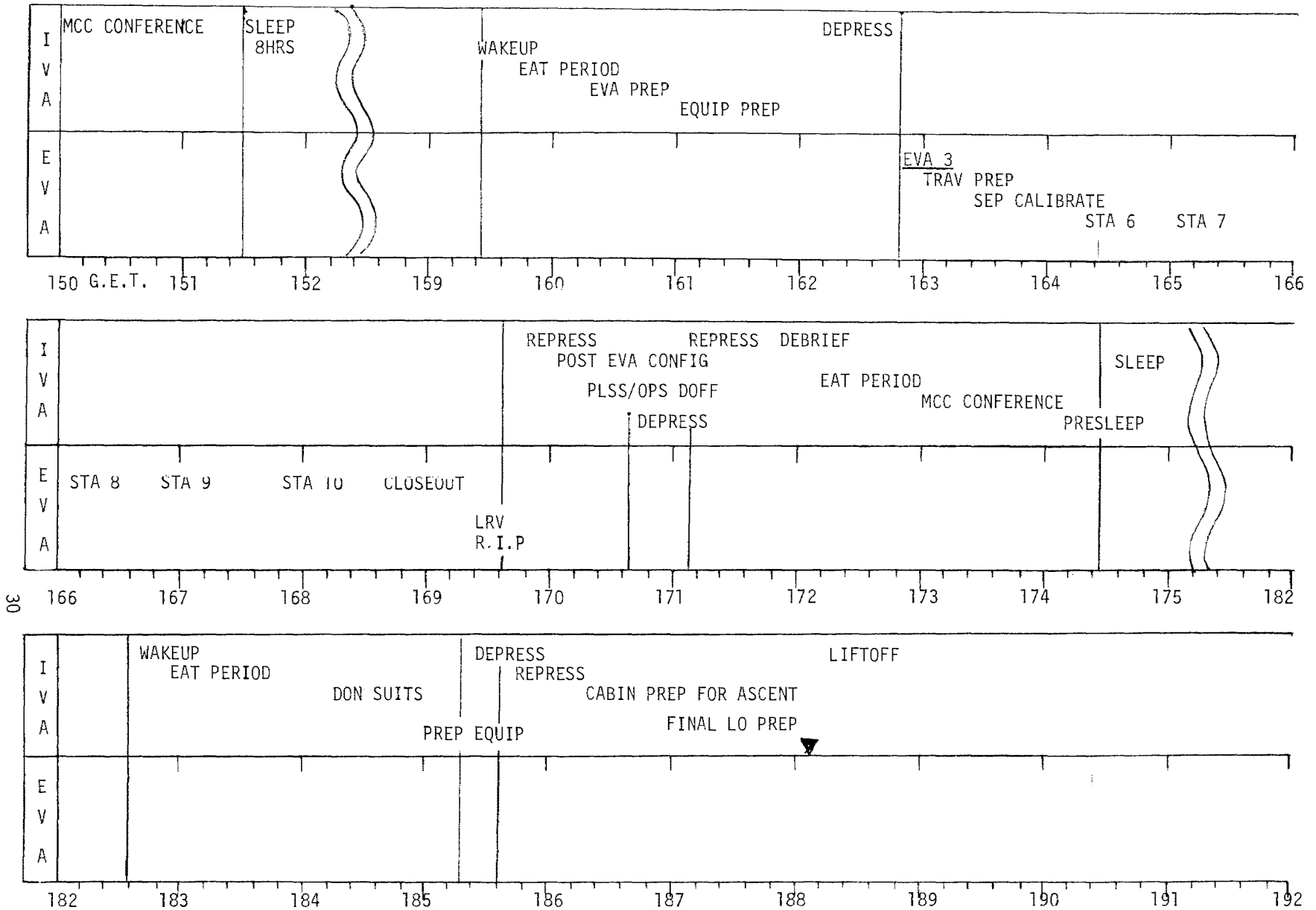


FIGURE 2.3-2: APOLLO 17 LUNAR STAY TIMELINE (Cont'd)



2.3.2 Traverse Objectives and Exploration Rationale

The crew's first objective on egress to the surface of the moon is to deploy and activate their principal geological exploratory tool, the Lunar Roving Vehicle (LRV). Following this operation, the crew puts the ground controlled television assembly (GCTA) into operation, and loads the LRV for lunar operations.

Their principal tasks on EVA 1 are to deploy the ALSEP and Surface Electrical Properties transmitter. Following these operations, the crew is ready for the exploration of Taurus Littrow. During the exploratory traverses, the Apollo 17 astronauts will deploy eight explosive packages, and take up to ten readings on the Traverse Gravimeter. The ALSEP, SEP, and other tasks mentioned above will be detailed in Section 3 of this document. The overall stay time timeline for Apollo 17 Lunar Surface Activities is given in Figure 2.3-2.

Geologic Objectives

Refer to Figure 2.3-3 for an overall schematic traverse map while reading this section.

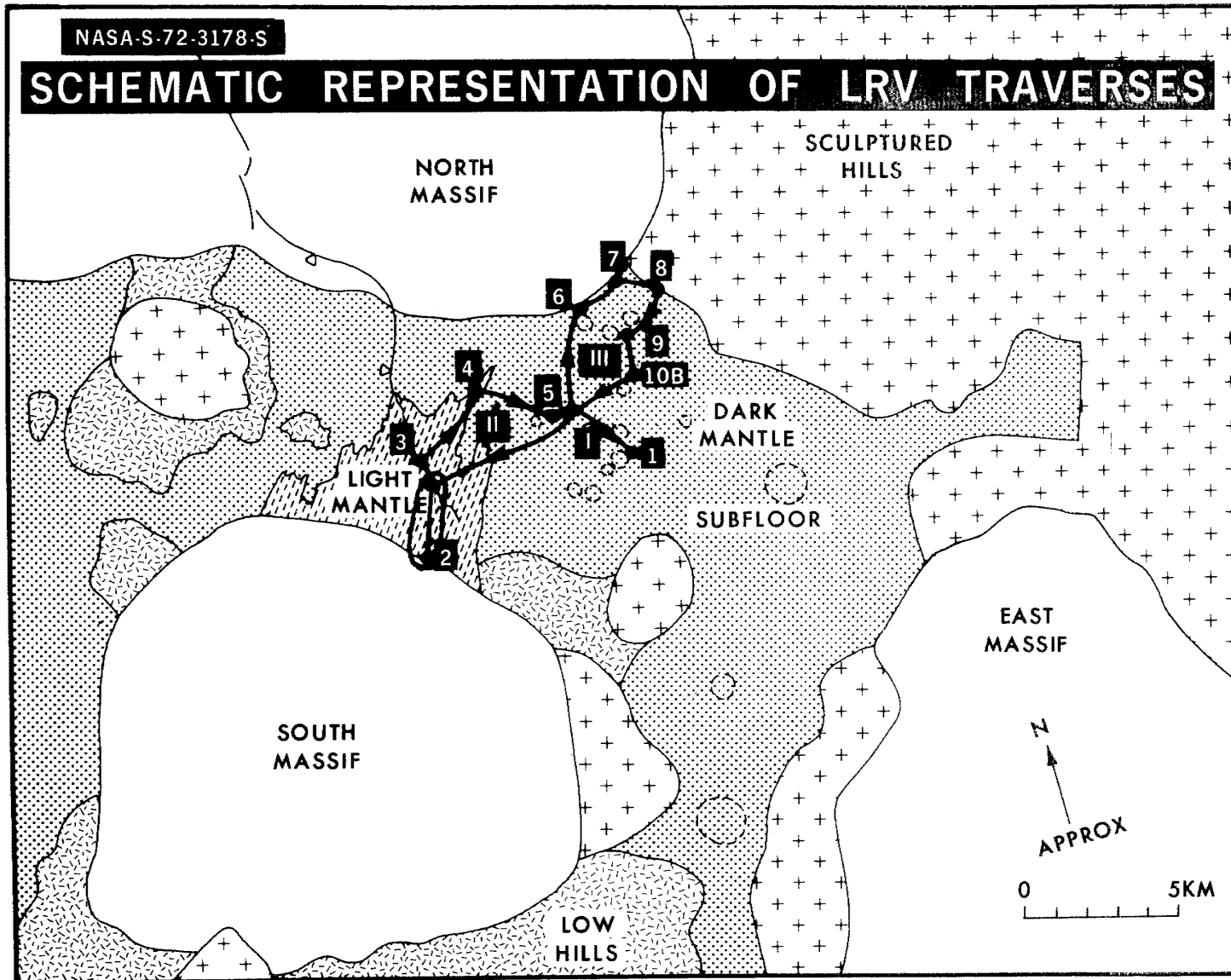
1. Massif and related units - observations, characterizations, and sampling.

a. Mode of origin and emplacement - the massif and related units are probably composed of breccia from various ejecta blankets, most likely arranged in subhorizontal layers with the youngest deposits lying at higher elevations. Observational and photographic data bearing on this problem will be gathered.

b. Stratigraphy - The light mantle unit appears to be some type of debris flow or avalanche which may contain massif material derived from the entire stratigraphic sequence comprising the South Massif. Sampling stations (2, 3, and 4) are scheduled in the light mantle in a direction normal to the mountain front in the hope that a maximum variety of South Massif rock types will be collected. Sampling at the base of the massifs is also designed to collect the widest possible variety of samples of massif material through sampling of boulders derived from the mountain slopes and collection of rake, soil, and other documented samples (stations 2, 6, and 7). Investigation of boulders should provide the opportunity to examine and document internal structures indicative of the mode of origin of the massif materials.

c. Areal variation - sampling at and within the North and South Massifs and comparison with the sculptured hill is designed to provide data on areal variation of highlands material.

Figure 2.3-3



The distinct morphology of the sculptured hills suggests that they may be of different composition from the massifs. Station 8 is designed to investigate this possibility.

Relationships of the massif and massif-related units to the dark mantle unit are being investigated at stations 6-7, and 8; with the light mantle at station 2.

2. Dark mantle material - observations, characterization and sampling.

a. Mode of origin and emplacement - the dark mantle may be a volcanic pyroclastic deposit. Sources of the widespread dark mantle on the plains have not been specifically identified, but a variety of crater types (stations 1, 4, 5, 9, 10), among which sources might be included, will be investigated. In addition, investigation of a possible exposure of the edge of a local young dark mantle unit (station 1) may provide important data on the mechanism of emplacement.

b. Internal stratigraphy - both the vertical compositional variation in the dark mantle and the time span during which is accumulated are of scientific interest. Radial sampling of craters at stations 4 and 9 as well as numerous core tubes are designed to provide data on these questions.

c. External stratigraphy - observations and photographs of the relationships of the dark mantle to other units will also help to establish its historical significance. Relationships to the plains unit will be studied at stations 1, 5, and 10 and with the massifs at stations 6, 7, and 8. Observations of the relations of the dark and light mantle will be made as the crew drives across the contact and at station 4 where they will investigate a dark halo crater in the light mantle.

d. Areal variation - possible areal variations will be investigated at widespread sampling points in the dark mantle (stations 1, 4, 5, 8, 9, 10); these stations will provide samples over an area of 30 square km. If sources are local, a variety of sources will be sampled.

3. Plains material - observations, characterization, and sampling.

a. Mode of origin and emplacement - the plains materials may be volcanic in origin or they may be impact breccias. Early characterization of rock types at station 1 should bear on this question.

b. Areal variation - separation of stations 1, 5, and 10 by several kilometers provides the opportunity to investigate areal variation. The relationship of the plains to the dark mantle and possibly to other units underlying the plains will also be investigated.

3.0 PROCEDURE

3.0 NOMINAL LUNAR SURFACE PROCEDURES

On Apollo 17, the CDR and LMP will spend 75 hours on the lunar surface at the Taurus Littrow site, of which as many as 21 hours will be spent in actual lunar surface activities. There will be three 7-hour EVA's scheduled as shown in Figure 2.3-2, the Summary Timeline. The EVA periods are separated by LM cabin activities, which include housekeeping, nutrition, and sleep.

Section 3.1 details the first EVA. The first subsection, 3.1.1 gives a general narrative description of the lunar surface activities. This narrative is followed by 3.1.2, which summarizes the EVA traverse in tabular form, and gives times on station, traverse velocities and times, plus parametric planning data. Section 3.1.3 provides the detailed, minute-by-minute procedural timeline for the EVA. Each page of the timeline is faced by the Voice Data Plan. These data are used by Mission Control during the actual EVA to conduct operations, record data as required, and follow the lunar surface operations as they transpire. The Voice Data Plan includes copies of the Cuff Check List that the crew has with them as a job aid in carrying out their tasks.

In like fashion, Section 3.2 documents EVA 2 nominal procedures, and Section 3.3 EVA 3.

Figure 3.0-1 depicts the nominal LRV traverses for all three EVA's on Apollo 17.

APOLLO 17 LRV TRAVERSES

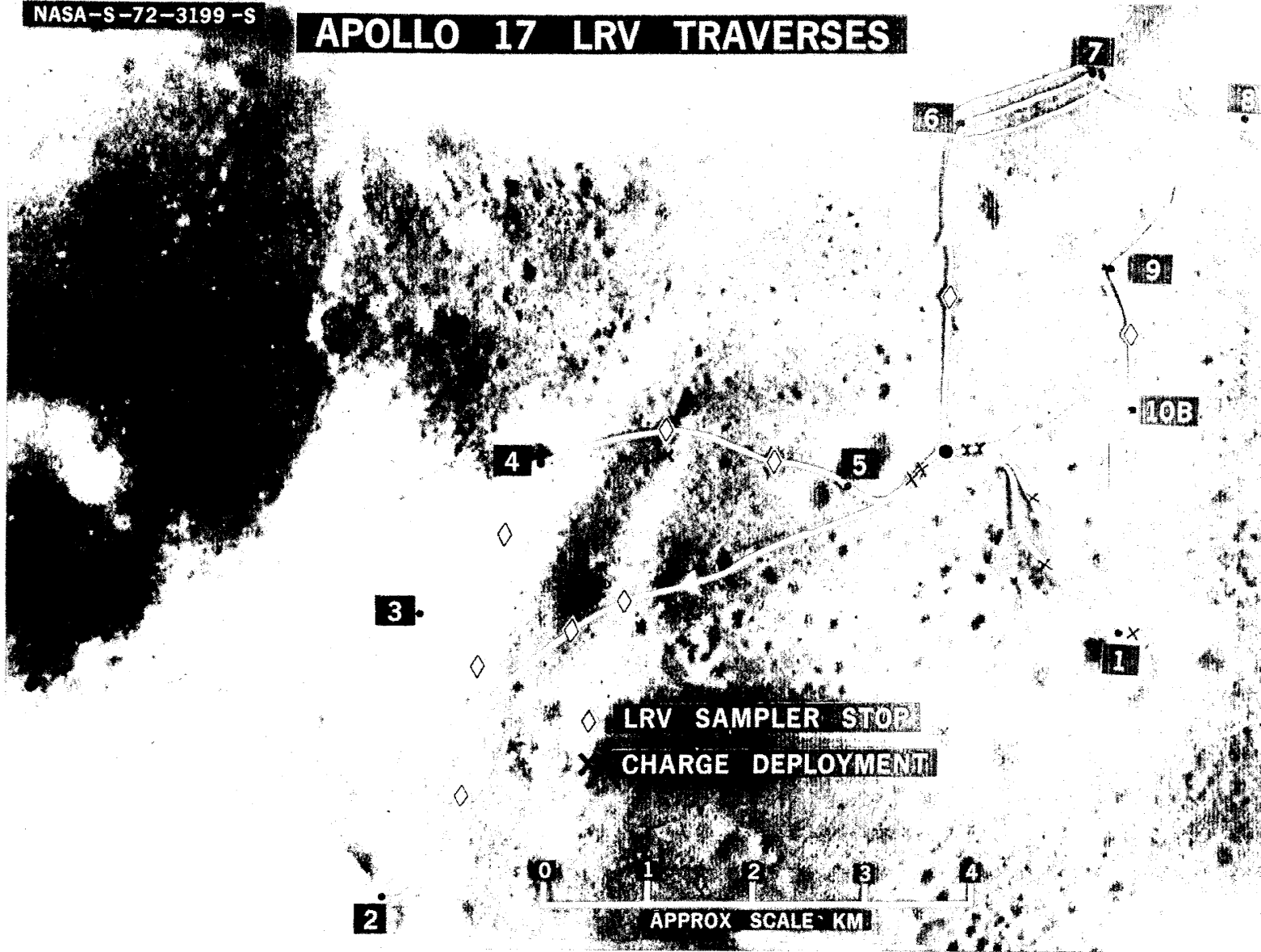
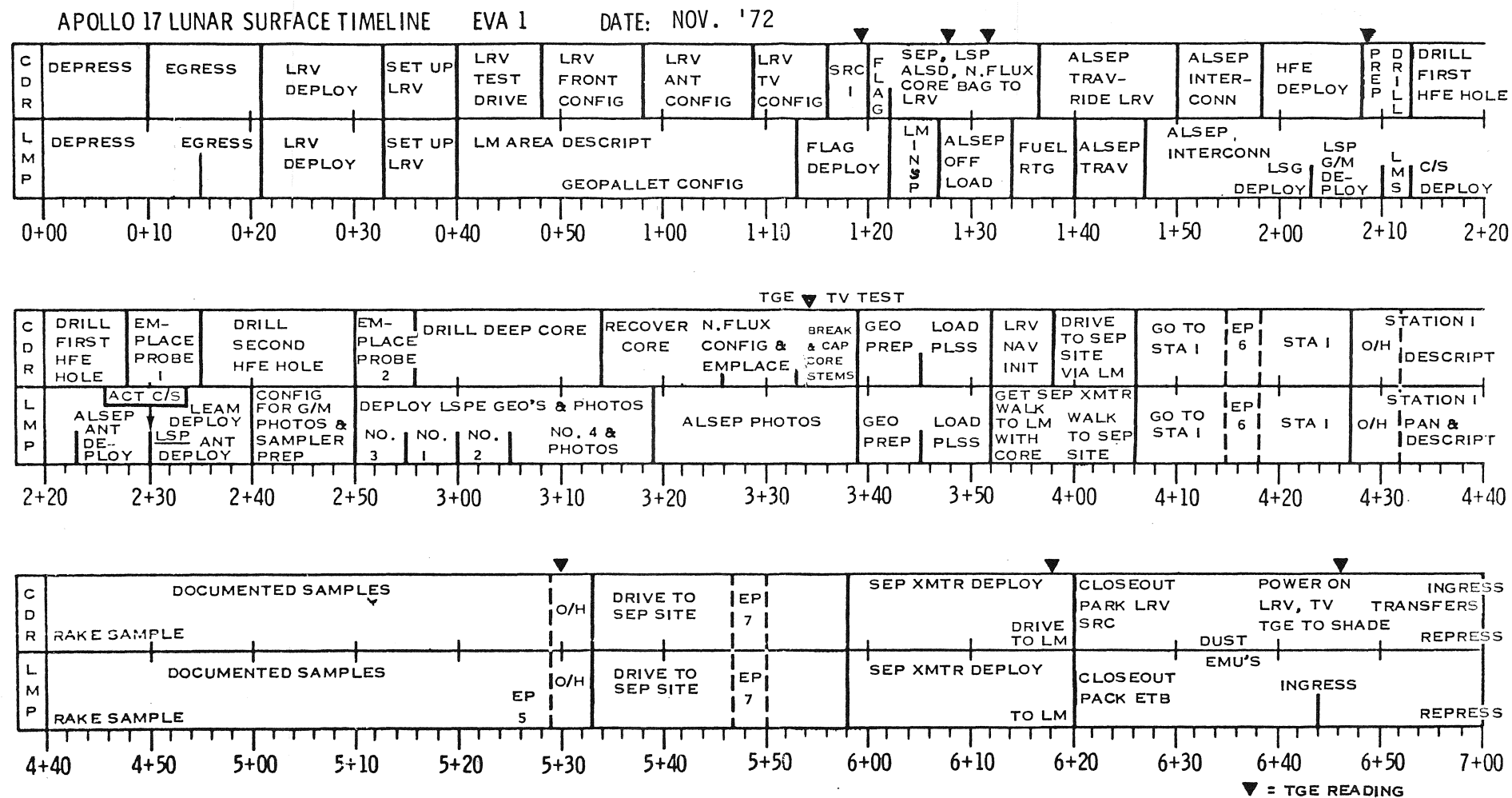


FIGURE 10-1: PI TORIAL VIEW OF THE LRV TRAVERSES

3.1 EVA 1



FIGURE 3.1-1



3.1 EVA 1

3.1.1 EVA 1 - GENERAL DESCRIPTION

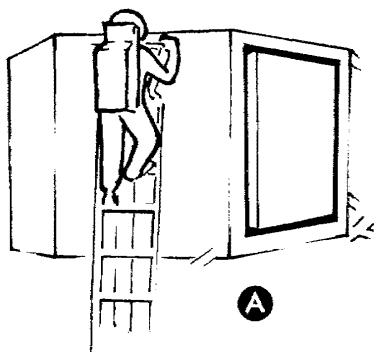
EVA 1 begins about four hours after touchdown on the lunar surface at Taurus-Littrow. The crew spends this pre-EVA time in site description from the LM windows, eating a light snack, and donning their extravehicular mobility equipment. The crew also readies a jettison bag of discarded items (see Table 3.7-4) and an Equipment Transfer Bag (ETB). The ETB contains an Electric Data Camera (70 mm), several magazines of film, maps, and the BSLSS, the contingency-use water umbilical. A block timeline is furnished to assist in understanding this EVA (Figure 3.1-1).

After depressurization of the LM cabin, the CDR exits the hatch first. The LMP hands out the jettison bag and the ETB. The ETB is attached to a line which can be hooked to the railings of the "porch" affixed before the forward hatch. The jettison bag is tossed clear of the LM, the ETB is gently lowered to the surface, and the CDR descends. CDR egress is followed shortly afterwards by LMP egress. After a preliminary period of familiarization, the two crewmen are ready for their first task--unloading the Lunar Roving Vehicle (LRV). It should be noted that the television system on Apollo 17 will not be operational until after it is loaded on the LRV. All operations on the lunar surface up to that point (about an hour and ten minutes into the EVA) will be covered by voice only.

The CDR and LMP lower the LRV from the side of the spacecraft by manipulation of lanyards and pulleys. They unfold the electric vehicle, set up the seats and the central console. This process is illustrated in Fig. 3.1-2. The CDR performs a short checkout of the LRV systems, then takes the vehicle around the LM to the vicinity of the MESA (Modular Equipment Stowage Assembly) and Quad III for loadup. During this time, the LMP busies himself with a walk-around and site description. The LMP takes some photos as he walks.

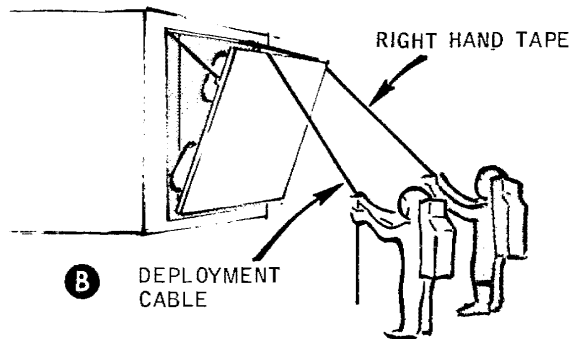
The next block of activities is concerned with loadup of the LRV. In general, the LMP concentrates on the aft end of the LRV, and items from Quad III. The CDR does the front end of the LRV, the deployment of the television and communications system. This system is comprised of the Ground Controlled Television Assembly (GCTA), the Lunar Communications Relay Unit (LCRU, pronounced "Lacru"), and the two antenna arrays. Fig. 3.1-3 illustrates the stowage of these items outbound on the MESA, plus other gear. Fig. 3.1-4 gives the general layout of the landing site when all the preliminaries of EVA 1 are complete. The LMP's tasks consist of loading a tool and bag stowed pallet (termed the "geopallet") onto the aft end of the LRV. This pallet is arranged to swing open like a gate to provide access to the mounting position of the Surface Electrical Properties receiver and antenna array. The pallet also holds the Traverse Gravimeter experiment. The LMP also brings the equipment transfer bag with the cameras and supplies over the LRV, and stows this gear.

FIGURE 3.1 - 2 LRV DEPLOYMENT SEQUENCE



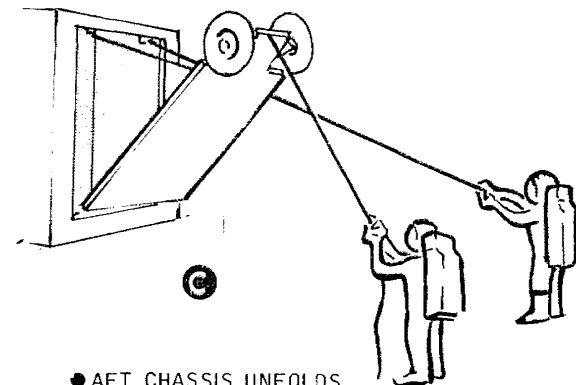
A

- LRV STOWED IN QUADRANT
- ASTRONAUT REMOVES INSULATION BLANKET, OPERATING TAPES
- ASTRONAUT REMOTELY INITIATES DEPLOYMENT



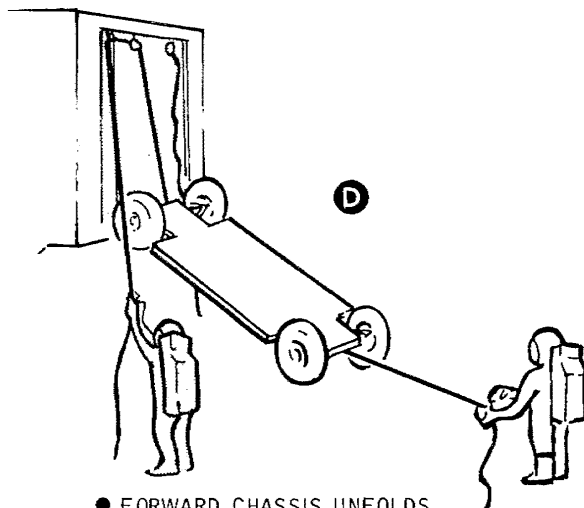
B

- ASTRONAUT LOWERS LRV FROM STORAGE BAY WITH RIGHT HAND TAPE



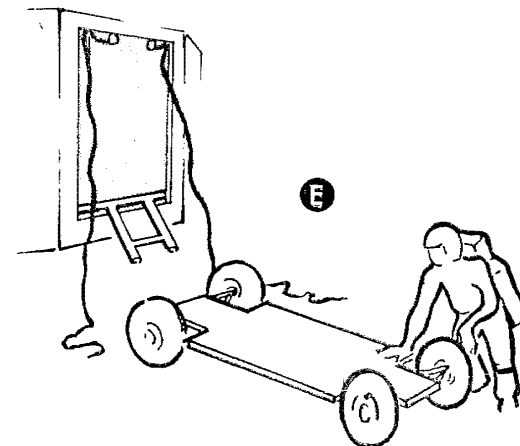
C

- AFT CHASSIS UNFOLDS
- REAR WHEELS UNFOLD
- AFT CHASSIS LOCKS IN POSITION



D

- FORWARD CHASSIS UNFOLDS AND LOCKS
- FRONT WHEELS UNFOLD
- ASTRONAUT LOWERS LRV TO SURFACE WITH LEFT HAND TAPE



E

- ASTRONAUT DISCONNECTS SPACE SUPPORT EQUIPMENT(SSE)

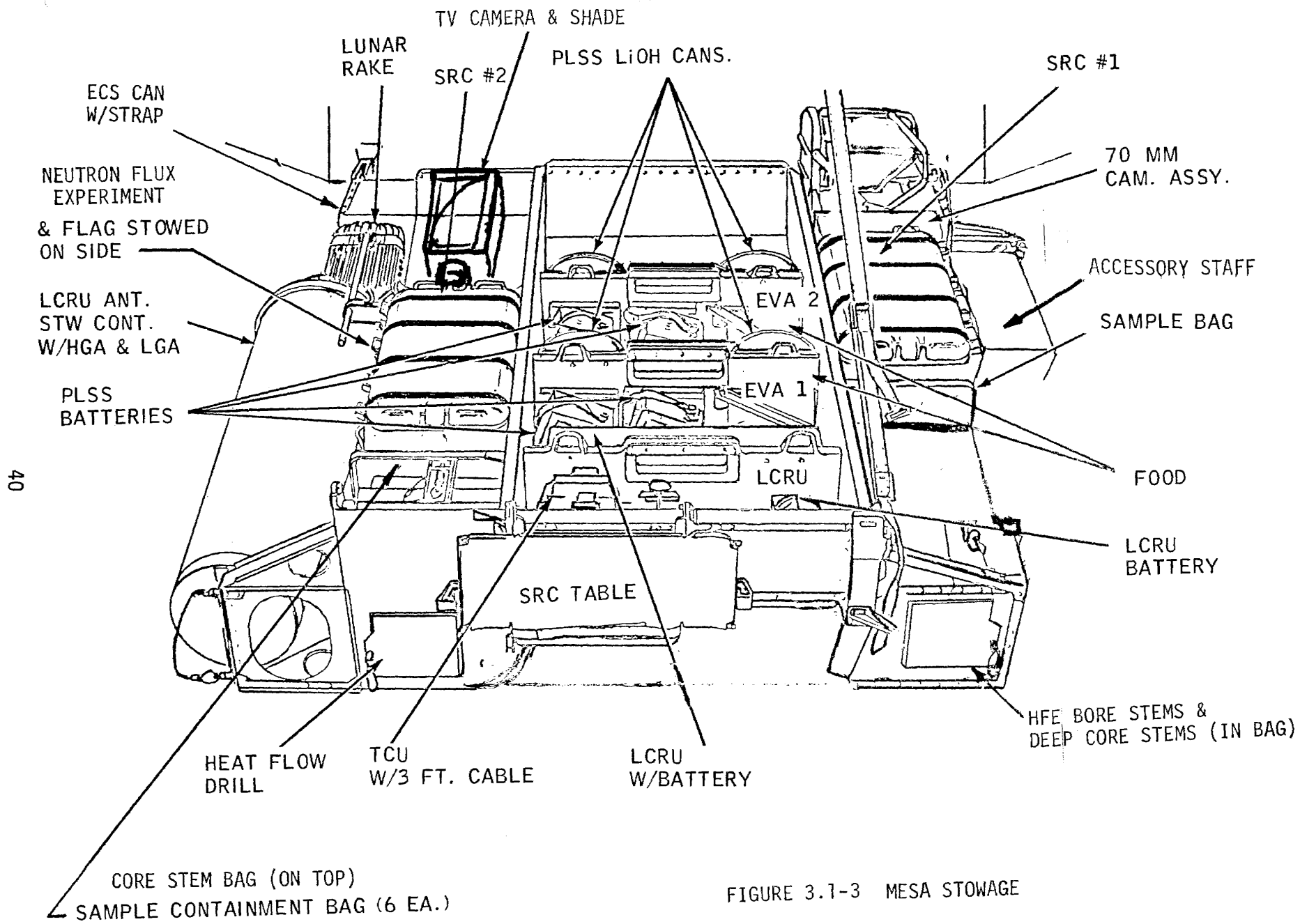


FIGURE 3.1-3 MESA STOWAGE

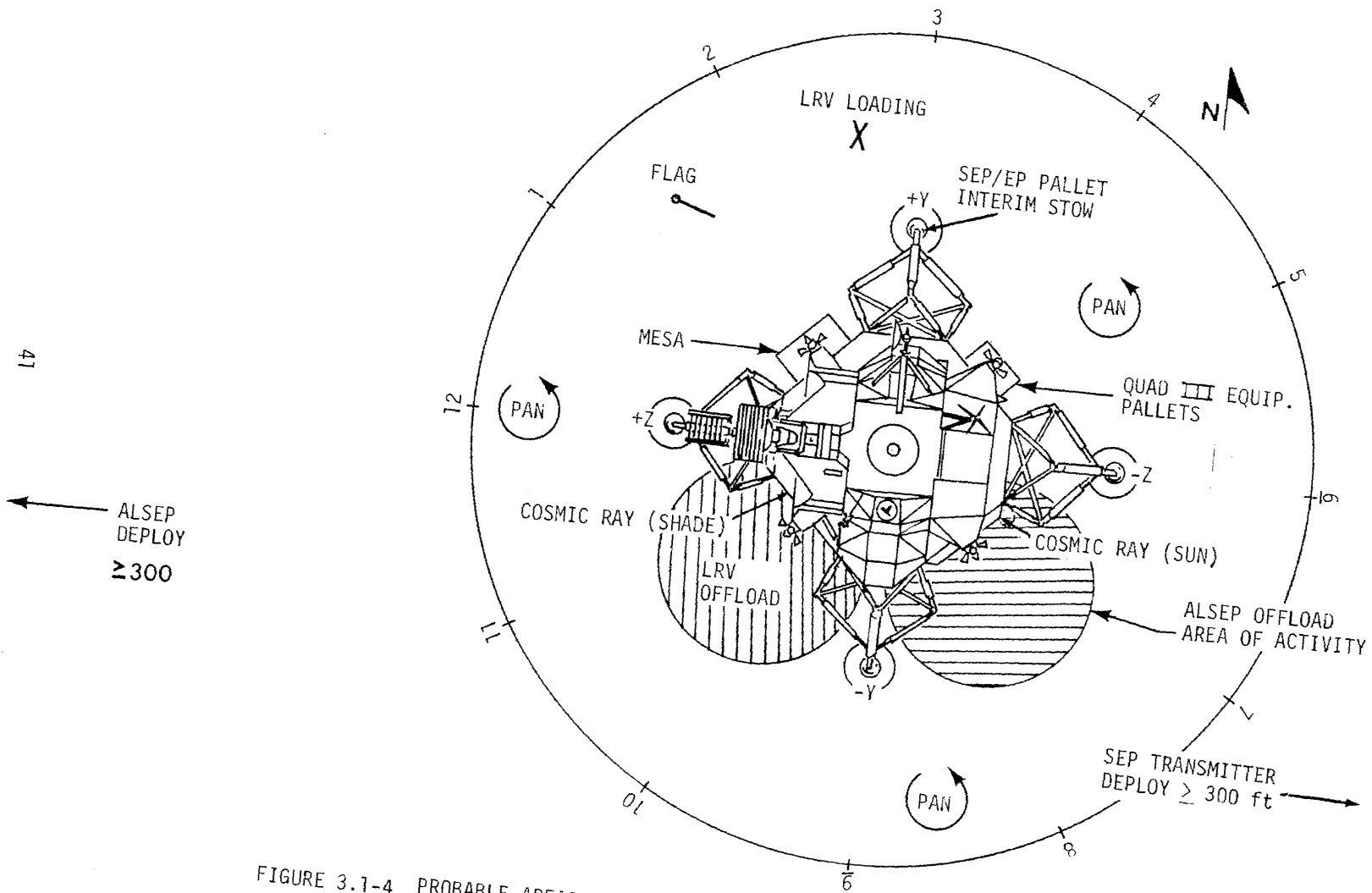


FIGURE 3.1-4 PROBABLE AREAS FOR NEAR LM LUNAR SURFACE ACTIVITY

During this operation the CDR finishes his setup of the television and LRV mounted communications system, and the TV is brought up. From this point on during the EVA, whenever the LRV is at a stop, the TV system is configured by the crew to be under ground control. When the LRV is under way, the communications system provides voice and telemetry only, via the low gain antenna.

The CDR's next task is to unload the bag of sampling supplies from Sample Return Container No. 1, and place the bag on the LRV aft geopallet. Immediately following this job, the two crewmen pause for a brief flag-planting ceremony. The LMP follows the flag ceremony by an inspection of the spacecraft, with photo documentation as required. The CDR busies himself during this period with offloading the equipment pallet from Quad III. This pallet contains the two brackets of Seismic Profiling explosive packages (four on each bracket), plus the Surface Electrical Properties Experiment transmitter and receiver. The CDR proceeds to mount the SEP receiver on the LRV, off the forward surface of the geopallet, between it and the LMP seat. The experiment is not activated until EVA 2, but the components are set up on EVA 1 for thermal control and for operational convenience. The CDR mounts one of the explosive package brackets on top of the geopallet, takes a gravimetric reading both on and off the LRV, replaces the gravimeter on the geopallet, and prepares to leave for the ALSEP site.

When the LMP finishes his LM inspection, he proceeds to unload the ALSEP packages (there are two) from the SEQ Bay or Quad II. He extracts a hot radioactive capsule from a graphite cask on the side of the LM, and places the capsule inside the radioisotope thermoelectric generator (RTG) to activate it. This is a SNAP-27 power source for the ALSEP array. The LMP then joins the two ALSEP packages with a handlebar for carryout to the ALSEP site.

The CDR and LMP rendezvous at the ALSEP site some 100 meters west of the spacecraft. The CDR parks the LRV about 20 meters NE of the prospective central station location. The heading is 180° for good TV coverage.

During ALSEP deployment, the CDR concentrates on the heat flow experiment (HFE) - drill core. The LMP lays out the rest of the experiment packages, after they interconnect the power package, the HFE, and the Lunar Ejecta and Meteorites Experiment (LEAM) to the central station.

The HFE consists of two sensor-and-heater probes connected by 6.5 meter cables to an electronics box, which in turn is connected by a 10 meter cable to the central station. The sensor probes are inserted down bore holes implanted by means of a special drill, the Apollo Lunar Surface Drill (ALSD). This system is almost identical to that carried on Apollo 16. The bore holes are made up of a string of one long (212 cm), and two short (71 cm) stems made of fibreglas-boron (the joints are metal and screw together). The string for each hole is implanted a section at a time by the rotary-percussive action of the ALSD. The ALSD is decoupled from the string for adding new sections by using a type of Stillson wrench.

When the CDR finishes placing a string of bore stems in the lunar surface, he drops the probe assembly down the hole. A fishing-rod like tool, the "rammer" is used to ensure the probe's location at the bottom of the hole. The rammer has an alphanumeric scale on the side, and the CDR reports depth of the probe to MCC. A small thermal plug is inserted to a depth of 10 cm, and a cover is placed over the hole.

The LMP's first task after interconnect is to deploy the Lunar Surface Gravimeter (LSG), an ultra-sensitive seismometer which can measure the lunar gravitational vector to an accuracy of 1 part in 10^5 , detect tidal forces and oscillations which may provide data in support of the theory of gravitational radiation. The deployment consists of removal of the package from the central station, implacement 8 meters west, and erection of a sunshade. The gravimeter is then uncaged and is ready to go to work.

Next, the LMP interim deploys the Lunar Seismic Profiling Experiment (LSPE) geophone module to the south of the Central Station to get the module out of the way. The Lunar Atmospheric Composition Experiment, the Lunar Mass Spectrometer (LMS), is then placed 14 meters NE of the central station. The LMP aligns, levels the package, then inserts his Universal Handling Tool (UHT), an elongated Allen wrench, to crack a ceramic seal to expose the orifice of this experiment to the lunar environment. The LMS will measure particles in the mass range 1 to 110 amu.

The LMP then erects the central station sunshade assembly, puts up the antenna, aligns the antenna to point at earth, and requests establishment of MCC - ALSEP communication. He removes a dummy load from the RTG package to supply power to ALSEP.

The LEAM is carried on a separate subpallet that was on the RTG package. This experiment is a sensor for primary dust particle impacts, as well as ejecta particle impacts (from meteoroid events). It has an earth-commanded jettison-able-detector plate cover. The LMP deploys its legs, aligns the box with respect to a shadow cast by an integral gnomon, and bubble levels it.

The LMP continues his ALSEP task by retrieving the subpallet the HFE experiment was attached to. The subpallet forms a base for the whip antenna of the Lunar Seismic Profiling Experiment. This antenna sends the signals to the deployable explosive charges the crew will scatter about the site which detonates them.

The LMP picks up some supplies to enable him to take samples, dons a camera, and prepares to deploy the geophone array, the sensors which transduce the shocks of the detonating explosive packages. The array is kite or T-shaped, with the geophone module (it now becomes a terminal box) at the cross of the T. A geophone is placed at each end of the cross-bar, 100 meters apart, a 3rd phone is deployed due south at 29 meters, and the last at 85 meters distant south of the geophone module.

The finished ALSEP array is depicted schematically in Fig. 3.1-5.

The LMP proceeds to photographically document the array, as the CDR finishes his HFE deployment.

The CDR moves from HFE deployment to drilling the deep (4 meter) core. He uses sections of titanium core stems, in four sets of two 41 cm stems each. The site is about 18 meters north of the HFE area. The ALSD is used for this operation, too.

After all 8 stems are in the ground, the CDR utilizes a jack to pull the string out of the ground. In its place he deposits the Neutron Flux Experiment (NFE), a two-part rod with material to capture neutron tracks. The experiment is recovered at the end of EVA 3. The NFE is emplaced either by hand, by hammering, or by using the versatile ALSD. See Fig. 3.6-4 for details of this experiment.

The CDR winds up his ALSEP site tasks by disassembling 3 of the 7 joints of the core string. He uses the wrench and a special vise on the aft pallet of the LRV. Each section is capped and put aside, ready to be returned to the spacecraft.

Although the CDR and LMP are nominally independent in all their ALSEP operations, they may very well assist one another, particularly in core drilling, recovery, and neutron flux deployment.

Following this operation, the two crewmen prepare for their traverse to Station 1. The PLSS's are loaded with bags and equipment, and the LMP offloads one of the explosive packages. This package will be carried on his lap and deployed directly off the LRV on the way to Station 1.

Then the LMP carries the core stems back to the LM, while the CDR mounts the LRV, initializes the navigational system, and drives to the Surface Electrical Properties Experiment area (SEP).

The LMP drops off the core stems at the LM, unstows the SEP transmitter, and carries this unit out to the SEP site, 100 meters east of the LM.

It should also be mentioned that throughout this EVA, at the LM, at ALSEP, and at SEP, the Traverse Gravimeter is actuated to make measurements of the local gravity force. Each station visited also involves a gravimeter measurement as well.

Objectives for the EVA 1 traverse are to investigate and sample the dark mantle and the plains material, emplace seismic profiling charges, and obtain traverse gravimeter measurements. Figure 3.1-6 shows the route of the traverse across the dark mantle material southeastward to station 1. Enroute to station 1, a short stop is made (noted by the X) to emplace the 1 pound explosive charge for the Seismic Profiling experiment. Station 1 duration is 66 minutes and details of the station objectives and activities are shown in Figure 3.1-7. A 3 pound charge is deployed at Station 1. Leaving station 1, the traverse returns along the same

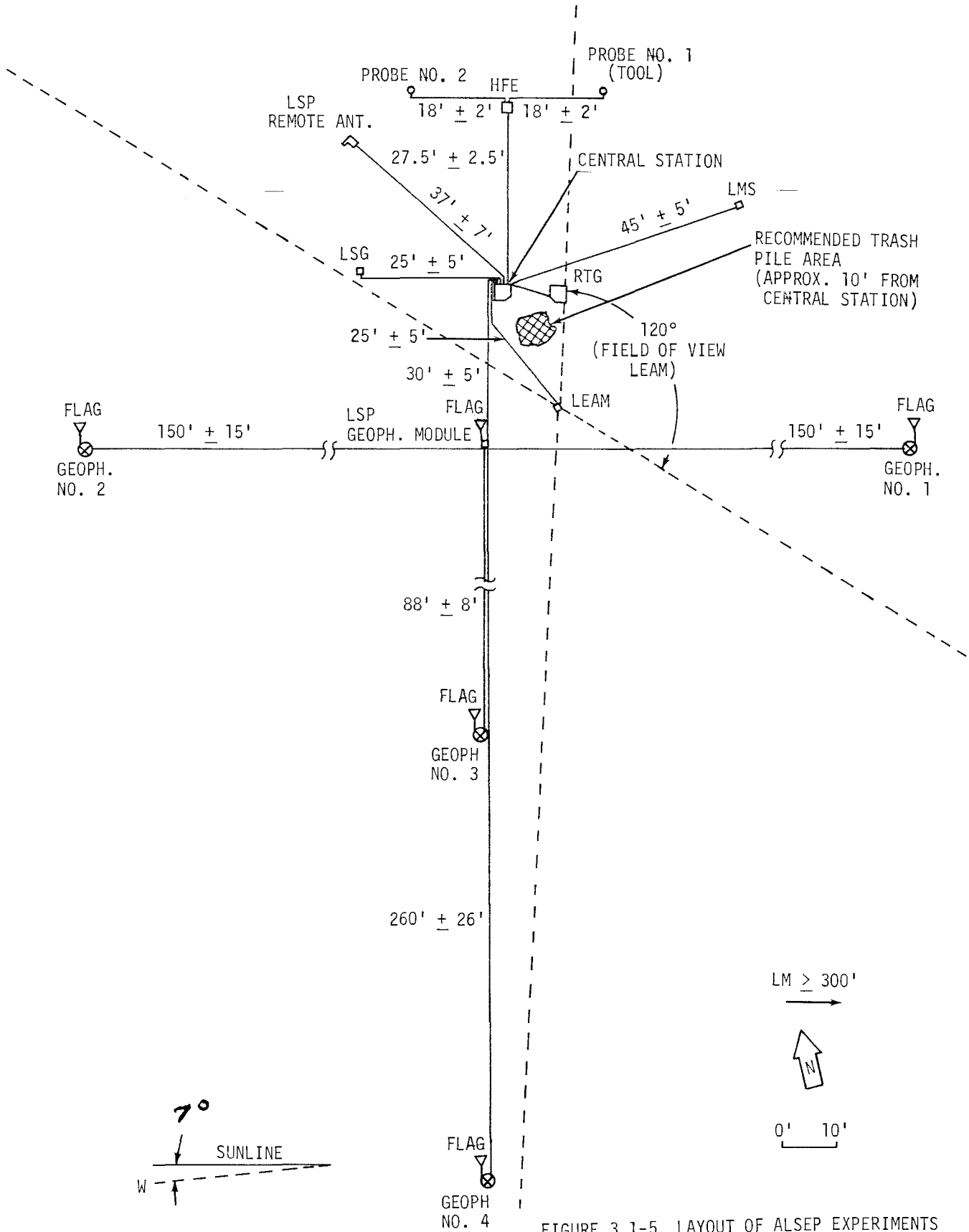


FIGURE 3.1-5 LAYOUT OF ALSEP EXPERIMENTS

path. The crew returns to the LM with a short stop enroute to emplace the 1/2 pound explosive charge.

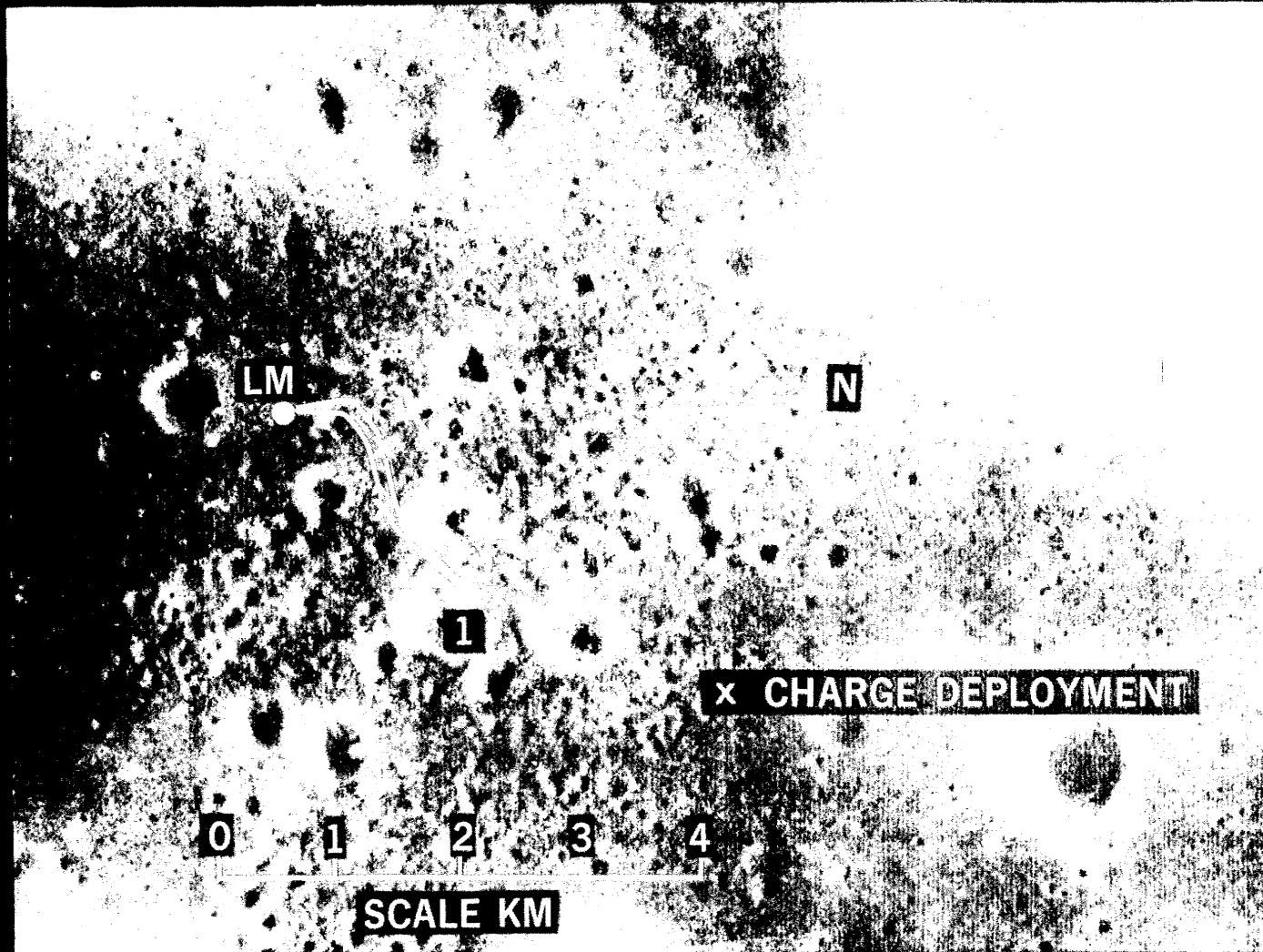
The crew returns to the SEP deployment site to deploy the SEP Transmitter. The CDR drops off the LMP, and proceeds to lay out the SEP transmitter antenna array with LRV tracks. He maneuvers the LRV in an X-shaped pattern aligned to the cardinal points of the compass.

The SEP uses rf radiation from 1-32MHz and an alternately rotated energy plane to derive data on subsurface layering and structure. The transmitter uses two orthogonal dipole antennas (the X-array) deployed along the ground. The receiver is mounted on the LRV. A recorder accepts both receiver data and LRV navigational data. Hence, the finished SEP recording will reflect a three-dimensional rf reflection profile of the Taurus-Littrow area.

The LMP places the transmitter in the center of the "X" traced by the LRV. The CDR parks the LRV, joins the LMP, and helps deploy the antenna. The LMP is photographed by the CDR as they reach opposite ends of each dipole, hence provided complete documentation of the array. The LMP completes the SEP transmitter deployment by unfolding the solar panels and turning the transmitter to STANDBY. The unit will be operational on EVA 2.

Closeout activities include unloading the PLSS tool carriers, packing up the cameras and magazines, and loading the sample return container. The SRC, extra sample bags, the core stems, the bag of cameras, and a pallet of PLSS expendables and food are transferred to the ascent stage. The LMP precedes the CDR into the ascent stage to implement these transfers. The CDR dusts, then shuts down the television/communications system, takes a final traverse gravimeter measurement, and ingresses the spacecraft. Repressurization is then initiated to end EVA 1.

EVA 1 LRV TRAVERSE



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FIGURE 3.1-6 EVA 1 LRV traverse.

FIGURE 3.1-7: STATION 1 TASKS

EVA-1

Station 1

Station time 1+06

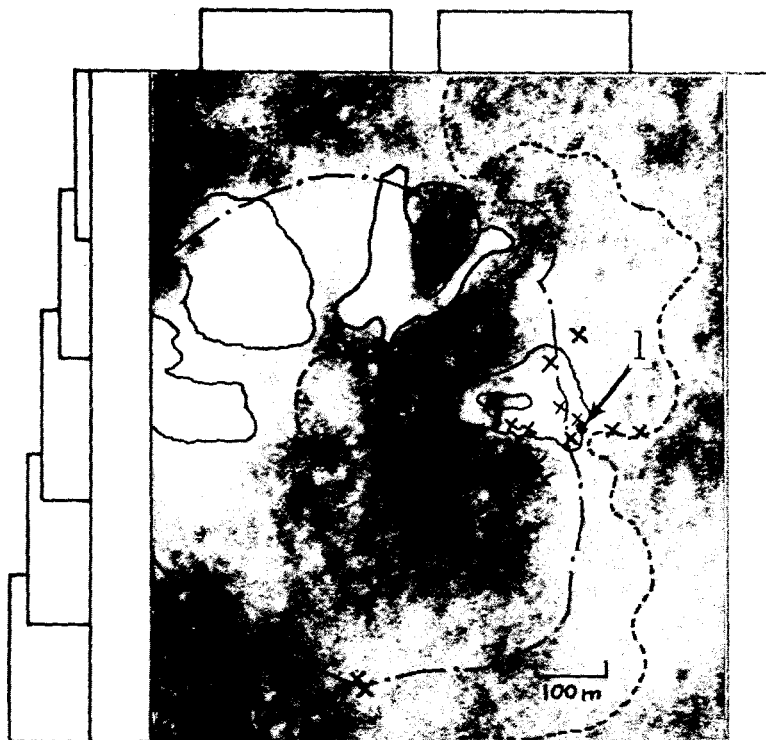
Location: East rim of 650 m crater at boundary between dark mantle and blocky subfloor material.

Geologic setting: Subfloor material is exposed in parts of the crater wall and rim as ejecta, talus, and perhaps outcrop. The subfloor unit is interpreted as basin-filling material such as lava flows, impact breccias, impact melts, or colluvial deposits emplaced after formation of the landing site valley. The original valley floor upon which the subfloor unit was deposited may have consisted of the upper part of the massif or sculptured hills units, and these materials may have been included in the ejecta at station 1.

Dark mantle covers the floor and parts of the crater wall and rim. Unusually dark mantle that could represent a younger or thicker (and hence less mixed) mantle deposit covers the southern half of the crater. Its northern boundary crosses the crater floor and wall as a distinct nearly straight line. An additional small patch of very dark mantle occurs on the north wall and rim of the crater. The dark mantle may be young, fine grained pyroclastic material derived from abundant, small vents that are generally unidentifiable in the orbital photographs.

Objectives:

- Characterize subfloor material
- Investigate historical sequence and mode of origin of dark mantle



<u>Tasks *</u>	<u>Rationale</u>
• <u>Observe/photograph</u> crater walls, rims, ejecta	•Origin of crater
<u>Subfloor:</u>	
• <u>Blocks</u> • <u>Observe/photograph</u> structures and textures in several blocks in both bright and dark portions of crater rim • <u>Documented samples</u>	•Block structure and lithology as recorded in photographs and samples provide data on variety and inter-relations of rock types and on origin and history of subfloor unit; lithologic distinction across albedo boundary would suggest high angle contact between distinct subfloor units.
• <u>Rocks and soils</u> • <u>Documented samples</u> • <u>Rake</u>	•Supplemental to block sampling; increases probability of comprehensively sampling subfloor materials.
• <u>Pan</u>	•Location; setting; crater wall structures; plains--dark mantle relationships
<u>Dark mantle:</u>	
• <u>Observe/photograph</u> dark mantle--very dark mantle-subfloor contacts • <u>Documented samples</u> - dark mantle and very dark mantle • <u>Rake</u> -very dark mantle	•Geometry and origin of mantle •Composition; age; mixing •Texture of mantle permitting, rake might optimize collection of scattered lithic fragments
• <u>Trench</u> - dark mantle--very dark mantle contact; very dark mantle--subfloor contact	•Geometry and origin of mantle units; relative amounts of regolith development
• <u>Double core</u> in very dark mantle near contact with dark mantle	•Stratigraphy; contact attitude; regolith history; sampling undisturbed mantle material
• <u>Observe/photograph</u> mantle--block relationships	•Chronology of blocks and mantle; origin of mantle
• <u>Observe/photograph</u> contrasting light and dark areas elsewhere on crater rim (especially dark patch on north rim)	•Possible clues to origin of mantle
• <u>Pan</u>	•Stereoscopic view (with earlier pan) of crater wall, very dark mantle contact crossing crater

* Considered to include all inclusive stopping list of tasks if time were available. The station timeline which follows presents the particular tasks (and time allocations) which were selected as the nominal station activities.

Station 1 Timeline

EVA-1	1+06	
	CDR	LMP
<u>Initial overhead</u>	5	5
<u>Observation</u>	10	10
•Crater, rim, ejecta, wall (500 mm)		
•Blocks, characterize and compare		
•relate to subfloor		
•Subfloor and mantle contacts		
•Block-mantle relationships		
•Regolith development		
<u>Subfloor</u>	21	21
•Documented sampling-emphasis on blocks		
•Rake/soil (kg)		
•Pan		
<u>Subfloor and mantle contacts</u>	14	14
•Exploratory trench and photographs		
•Double core in youngest unit		
<u>Very dark mantle</u>	7	7
•Documented sample		
•Rake/soil (kg)		
•Pan		
<u>Dark mantle</u>	3	5
•Documented sample		
<u>Seismic charge deploy</u>	2	
<u>Final overhead</u>	4	4
	66	66

3.1.2 EVA-1 TRAVERSES

This section is comprised of a tabular summary of the EVA 1 activities. Table 3.1-1 provides calculated data on distances, velocities, and times as the crew progresses through ALSEP deployment, SEP deployment, and station stops. The tabular data also show the time and location of the three explosive charges deployed on EVA 1.

The table also provides traverse contingency information, LRV - or PLSS - malfunctioned walkbacks or ridebacks. Table 3.1-2 lists input data for the program that generated Table 3.1-1.

Finally, Table 3.1-3 provides the basic assumptions inherent in the layout of the EVA traverses. These assumptions hold for all 3 EVA's, and this table will be repeated in Sections 3.2 and 3.3 for the reader's convenience.

TABLE 3.1-1 APOLLO 17 TAURUS LITTRON TRAVERSES

EVA 1

CALCULATED DATA

OCT 25 1972

EVA START 116:40 HR:MIN GET

STATION	SEGMENT DISTANCE (KM)	LRV MOBILITY RATE (KM/HR)	RIDE TIME (MIN)	TOTAL TRAVEL DISTANCE (KM)	ARRIVE STATION EVA TIME (HR+MIN)	STOP TIME (HR+MIN)	DEPART STATION EVA TIME (HR+MIN)
LM				0.00	0+ 0	1+45	1+45
ALSEP				0.00	1+45	2+21	4+ 6
SEP							
RIDE	1.43	7.30	12				
1@CH5				1.43	4+18	0+ 3	4+21
P=1.3							
RIDE	0.98	7.30	8				
1				2.41	4+29	1+ 6	5+35
3@CH							
P=2.3							
RIDE	1.65	7.30	14				
1/2@CH				4.06	5+48	0+ 3	5+51
P=0.8							
RIDE	0.76	7.30	6				
SEP				4.82	5+58	0+22	6+20
LM				4.82	6+20	0+40	7+ 0
TOTALS			40			6+20	7+ 0

----- TRAVERSE CONTINGENCIES -----

STAT NO	RETURN DISTANCE TO LM (KM)	-----LRV FAILURE-----			-----PLSS FAILURE-----		AVG EVA MET RATE (BTU/HR)	
		WALKBACK TIME TO LM (HR+MIN)	STATION WALKBACK FM (HR+MIN)	MARGIN ABOVE REQUIREMENTS 02 (HR+MIN)	AMP HRS (HR+MIN)	MIN LRV RIDEBACK SPEED REQUIRED 0 MIN (KM/HR)		10 MIN (KM/HR)
LM	0.00	0+ 0	****	****	****	0.00	0.00	1050.00
ALSEP	0.10	0+ 2	3+26	3+ 8	3+14	0.10	0.12	1050.00
SEP	0.10	0+ 2	3+26	3+ 9	3+14	0.10	0.12	1050.00
1@CH5	1.51	0+25	2+39	2+21	2+36	1.47	1.75	1026.31
P=1.3								
1	2.49	0+41	1+ 3	0+44	1+ 6	2.42	2.88	999.81
3@CH								
P=2.3								
1/2@CH	0.84	0+14	1+34	1+16	1+17	0.82	0.97	982.02
P=0.8								
SEP	0.10	0+ 2	1+26	1+ 7	1+ 1	0.10	0.12	978.85
LM	0.00	0+ 0	1+ 7	0+49	0+45	0.00	0.00	985.64

TABLE 3.1-2 APOLLO 17 TAURUS LITTON TRAVERSES

EVA 1

INPUT DATA

OCT 25 1972

EVA START 116:40 HR:MIN GET

STATION NO	STOP TIME (HR+MIN)	SEGMENT DISTANCE (KM)	RETURN DISTANCE (KM)	HEAT LEAK (BTU/HR)	-MOBILITY RATES-		MET RATE WALK (BTU/HR)
					WALK (KM/HR)	RIDE (KM/HR)	
LM	1+45	0.00	0.00	0.00	♦♦♦♦	♦♦♦♦	♦♦♦♦♦♦
ALSEP SEP	2+21	0.00	0.10	0.00	3.60	7.30	1560.0
1#CHG R=1.3	0+ 3	1.43	1.51	0.00	3.60	7.30	1560.0
1 3#CH R=2.3	1+ 6	0.98	2.48	0.00	3.60	7.30	1560.0
1/2#CH R=0.8	0+ 3	1.85	0.84	0.00	3.60	7.30	1560.0
SEP	0+22	0.76	0.10	0.00	3.60	7.30	1560.0
LM	0+40	0.00	0.00	0.00	3.60	7.30	1560.0

MET RATE ALSEP (BTU/HR)	MET RATE RIDING (BTU/HR)	MET RATE STATION (BTU/HR)	MET RATE LM O/H (BTU/HR)	LEAK RATE 02 (LB/HR)	EVA START (F/W-LB)	EVA START (02-LB)	OPS TIME (MIN)
1050.00	550.00	950.00	1050.00	0.020	10.86	1.403	61.8

TABLE 3.1-3

LRV TRAVERSE ASSUMPTIONS

1. 30 MINUTES RESERVES MAINTAINED ON ALL PLSS CONSUMABLES AT STATION METABOLIC RATE
2. ALL DISTANCES AND SPEEDS ARE MAP DISTANCES AND MAP SPEEDS (MOBILITY RATES)
3. REQUIRED RATE = RETURN DISTANCE/AVAILABLE OPS RIDING TIME
AVAILABLE OPS RIDING TIME = TOTAL OPS TIME LESS ALLOWANCES
ALLOWANCES $\left\{ \begin{array}{l} 5 \text{ MIN BSLSS HOOKUP} \\ 13 \text{ MIN LM INGRESS} \end{array} \right.$
4. TIME MARGIN AT STATION METABOLIC RATE
TIME REMAINING AFTER ALLOWANCE
STATION MARGIN = FOR 10 MINUTES AT LRV, WALKBACK, AND 13 MINUTES INGRESS
5. FINAL LM O/H MARGIN = TIME REMAINING WITH NO ALLOWANCES
6. RESPIRATORY EXCHANGE QUOTIENT = 0.9
7. FEEDWATER HEAT OF VAPORIZATION 1038 $\frac{\text{BTU}}{\text{LB}}$

3.1.3 DETAILED EVA 1 TIMELINE PROCEDURES

The detailed procedures for EVA 1 are shown on the following vertical format pages. The crew cuff check list pages which correspond approximately to the timeline are shown on the far left-hand side of the facing Voice Data Plan pages that accompany each page of the vertical timeline. Each page corresponds to 20 minutes of lunar surface time.

These data assure that the required information is given by the crew to MCC and assists Capcom in essential communications with the crew. The crew's cuff check list does not necessarily correspond to the vertical timeline in content or in terminology. The checklist is a crew preference item, and thus contains those cues and information that the crew feels it needs to accomplish the required tasks.

CREW EVA CHECKLIST

VOICE DATA

EVA 1

CDR-3	<p><u>PLSS TO LM H2O TRANSFER</u></p> <p>PLSS Pump - OFF - Disconnect PLSS H2O Connect LM H2O CB(16) ECS: LCG Pump-Close</p>	SSTd
EVA1	<p><u>LM TO PLSS H2O TRANSFER</u></p> <p>CB(16) ECS: LCG Pump-Open Disconnect LM H2O Connect PLSS H2O PLSS Pump -ON-</p>	
11-1-72		

LMP-3	<p><u>PLSS TO LM H2O TRANSFER</u></p> <p>PLSS Pump - OFF - Disconnect PLSS H2O Connect LM H2O CB(16) ECS: LCG Pump - Close</p>	PLSS
EVA1	<p><u>LM TO PLSS H2O TRANSFER</u></p> <p>CB(16) ECS: LCG Pump - Open Disconnect LM H2O Connect PLSS H2O PLSS Pump - ON -</p>	
11-1-72		

EVA 1		CDR-6
DEPRESS LRV DE	<p>0+00 CABIN DEPRESS Start watch (call mark)</p> <p>0+10 EGRESS/PORCH Jett bag - discard Receive ETB/LEC MESA deploy</p> <p>FAM Comment on surroundings Jett bag under LM Deploy PLSS ants (CDR/LMP)</p>	EVA1
		11-1-72

EVA 1		LMP-6
DEPRESS LRV DE	<p>0+00 CABIN DEPRESS Open hatch</p> <p>0+10 CDR EGRESS Assist CDR Jett bag to CDR ETB/LEC to CDR Tape Recorder - OFF - VERIFY: *Vox Sens (2) - max - *Cb Config (white dots out + EVA decals) Utility Floodlights - OFF - 16 mm cam</p> <p>EGRESS Close hatch Deploy PLSS ants (CDR/LMP)</p>	EVA1
		11-1-72

CODE:

- (1) Mandatory requirement for data at time or event designated
- (2) Data may be deferred until later in EVA or debriefing

AT START OF EVA:

SUN ANGLE ~ 14.5°

LM SHADOW ~ 26.2 m (86.5 ft)

ASTRONAUT SHADOW ~ 5.2 m (17.1 ft)

0+00

- (1) CDR/LMP EVA watch start - MARK _____

(2)

- ETB CONTENTS
- 500MM CAM with MAG _____ R
- LMP HEDC with MAG _____ (A)
- 2-70 MM MAGS _____ (B) _____ (C) HCEX
- 2-70 MM MAGS _____ (G) _____ (H) HBW
- MAPS, LRV Ck List, sun compass
- Map holder
- BSLSS/OPS Ant Cosmic Ray Exp.
- 2 Lens brushes
- 20 - DSBD Camera shoe
- Tape & Scissors

(2)

- LMP - Verify CB config OK

0+10

CREW EVA CHECKLIST

EVA 1

VOICE DATA

EVA 1

0+00 CABIN DEPRESS
Start watch (Call mark)

0+10 EGRESS/PORCH
Jett bag - discard
Receive ETB/LEC
MESA deploy

FAM
Comment on surroundings
Jett bag under LM (LMP)
Deploy PLSS ants (EGRESS (CDR/LMP))

CDR-6
EVA1
11-1-72

0+21 OFFLOAD LRV
Open Quad thermal blanket
•Drape tape over strut
•Conting. tool to LM strut
•Unstow aft deployment
cable - drape over strut

VERIFY:
•Walking hinge latches
engaged
•Fwd & aft chassis parallel
to center chassis
•LH & RH outrigger cables
taut
Deploy rec OPS tape, RH side
& back away from deploy
area
VERIFY LRV rotates
outboard PULL
D-HANDLE

CDR-7
EVA1
11-1-72

EVA 1

0+00 CABIN DEPRESS
Open hatch

0+10 CDR EGRESS
Assist CDR
Jett bag to CDR
ETB/LEC to CDR
Tape Recorder - OFF -
VERIFY:
•Vox Sens (2) - max -
•Cb Config (White dots out
+ EVA decals)
Utility Floodlights - OFF -
16 mm cam

EGRESS
Close hatch
Deploy PLSS ants (CDR/LMP)

LMP-6
EVA1
11-1-72

FAM & MESA CONFIG
Comment on surroundings
Unhook conting. strap
Adjust height - open links
Big bag to ladder LRV
hook DEPLOY
ETB to table

0+23 LRV DEPLOY
Pull D-ring on request
Pull deploy cable 20 lbs
•Release pull at aft
chassis unlock
•Pull cable after aft
wheels on gnd
Pull LH pin, outrigger cable
Pull LH reel tape until 45°
cable slack
Pull saddle release cable,
VERIFY release
Move LRV from LM

LMP-7
EVA1
11-1-72

0+10 (1) LMP - Deploy CDR PLSS Antenna

- (1) LMP - LM Switches
- Power Amp Sw - OFF
 - Bit Rate Sw - LOW
 - Modulation Sw - PM

(1) CDR - Deploy LMP PLSS Antenna

0+20 (1) CDR/LMP - EMU Check

	CDR	LMP
02		
FLAGS		
PRESS		
COOL		

- (1) LRV: Verify during offload & setup
- Walking hinges engaged
 - Fwd, aft, & center chassis parallel
 - Outrigger cables taut
 - LRV rotates o/b when D-handle pulled
 - Front & rear hinge pins & steering seal
 - Battery covers closed OK

0+30

MISSION: APOLLO 17

EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION			
			LMP	CDR		
OPEN HATCH	0+10	<u>EGRESS OPERATIONS</u> EGRESS CABIN TO LM PORCH RECEIVE & JETTISON BAG RECEIVE ETB/LEC DESCEND LADDER TO TOP RUNG UNLOCK & DEPLOY MESA LOWER ETB ON LEC DESCEND LADDER TO SURFACE HANG ETB ON LADDER HOOK CHECK FOOTING, STABILITY & MOBILITY KICK JETT BAG UNDER LM				
ASSIST CDR EGRESS						
DEPLOY CDR PLSS ANTENNA						
HAND JETTISON BAG TO CDR						
HAND ETB/LEC TO CDR						
TAPE RECORDER-OFF-						
VERIFY:						
VOX SENS (2) - 'MAX'						
CB CONFIG						
UTILITY FLOODLIGHTS						
- 'OFF'						
TURN ON 16 MM CAMERA						
<u>LMP EGRESS OPERATIONS</u> EGRESS LM TO PORCH						
PARTIALLY CLOSE LM HATCH						
DESCEND LADDER TO SURFACE						
CHECK FOOTING, STABILITY, MOBILITY	0+20	DEPLOY LMP PLSS ANT <u>LRV DEPLOY</u> RELEASE LRV INSULATION BLANKET REMOVE CONTINGENCY DEPLOY RELEASE LH DEPLOY TAPE - HANG ON +Z STRUT CHECK: OUTRIGGER CABLE TAUT CHASSIS PARALLEL RELEASE DEPLOY CABLE-DEPLOY FULL LENGTH AT 45 DEG RELEASE RH DEPLOY TAPE-MOVE AWAY FROM LRV-HOLD TAPE AS LMP UNLOCKS LRV PULL RH TAPE TO ROTATE LRV VERIFY AFT CHASSIS UNFOLDS & LOCKS, REAR WHEELS UNFOLD, REAR WHEEL STRUTS FREE & CONTINUE PULLING TAPE UNTIL FWD CHASSIS LOCKS INTO POSITION & WHEELS UNFOLD & SLACK IN OUTRIGGER CABLES PULL PIN RR TO RELEASE CABLE - DISCARD PIN & CABLE				
DEPLOY CDR ANT						
OPEN MESA BLNKTS						
UNSTOW SAMPLE RETURN BAG						
HANG ON LADDER HOOK						
HANG ETB ON MESA TABLE						
<u>LRV DEPLOY</u> ASCEND LADDER MONITOR LRV DEPLOY PREP						
PULL D-HNDL TO UNLOCK LRV (OBSERVE 4 DEG ROT) DESCEND LADDER						
GRASP DEPLOY CABLE, MONITOR DEPLOYMENT, MAINTAIN CAUTION: SLACKEN TENSION AS AFT CHASSIS DEPLOYS UNTIL WHEELS TOUCH SURFACE						
			0+30			

0+30

LRV SET UP TEST BATTLE	Pull down on RH reel tape until outrigger cables slack	PULL ON DEPLOY CABLE	CDR-8
	Pull RH pin, outrigger cable When fwd wheels on surface	PULL LH PIN, LOWER	
	*Pull pins on deploy cable & fittings	RELEASE SADDLE	EVA1
	Move LRV from LM		
	0+32 SET UP LRV		
	Do RH side-aft 1st Erect geo post	LMP DOES LH SIDE	
	Extend rear fender		
	VERIFY rear hinge pins & seal		
	Erect seat & unstow seatbelt		11-1-72

0+40

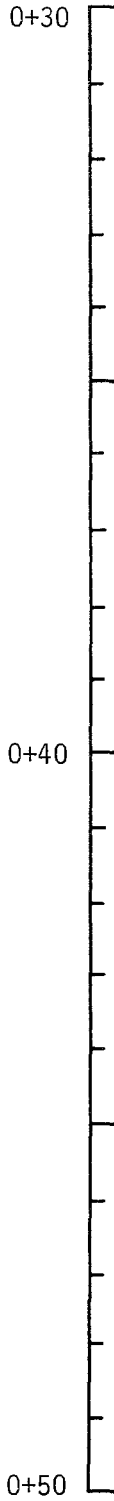
CDR-9 EVA1	Lower armrest		BOTH
	Pull T-handle		
	Lower console, raise handhold, lock & T-handle	CDR & LMP	
	Remove tripod apex		
	Tool behind footrest		
	VERIFY front hinge pins		
	Erect footrest		
	Extend front fender		
	VERIFY bat covers CLOSED		
	0+40 LRV CHECKOUT		
	POWER UP	LM AREA DESCRIP	
	Drive to MESA		
	+15 VDC sw - OFF -		TEST BATTLE

0+32

LRV SET UP LRV AFT	SET UP LRV	CDR DOES	LMP-8
	Do LH side - aft 1st	RH SIDE	
	Extend rear fender		
	VERIFY rear hinge pins		
	Release inboard handhold strap		
	Erect seat & unstow seatbelt		
	Pull T-handle	BOTH	
	Lower console, raise handhold, lock & T-handle	CDR & LMP	
	Pull attitude indicator & CAM flags		
	Remove tripod apex		
	Tool behind footrest		
	VERIFY front hinge pins & seat		
	Erect footrest		
	Extend front fender		11-1-72

0+40

LMP-9 EVA1	AREA DESCRIPTION	LRV TEST DRIVE	LMP-8
	Get LRV cam (ETB)		
	Take L1 photo pan at 4:00/30'		
	Describe LM area		
	Stow cam - ETB		
	0+47 LRV AFT CONFIG		
	Geo pallet (LR) to LRV, VERIFY latches engaged	FRONT CONFIG	
	Remove handrails		
	Config geo pallet:		
	*Pull TGE launch pins (3)		
	*Discard TGE velcro		
	*TGE - ON -		
	*TGE - READ -		TEST BATTLE



(2) LMP - Area description

(1) CDR - Checkout LRV

Verify - PWM SEL Sw - BOTH

Read out displays:

Temp Bat 1	
Temp Bat 2	
Temp LF mtr	
Temp RF mtr	
Temp LR mtr	
Temp RR mtr	

Amp-Hr Bat 1	
Amp-Hr Bat 2	

Volts:(1) _____ (2) _____

MISSION: APOLLO 17

EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
	0+30	RETRIEVE DEPLOY CABLE FROM LMP & MAINTAIN TENSION TO SLIDE WHEELS AS REQD		
HAND DEPLOY CABLE TO CDR				
PULL PIN LR TO RELEASE CABLE - DISCARD PIN & CABLE		PULL PIN TO RELEASE DEPLOY CABLE-DISCARD		
PULL LH DEPLOY TAPE TO LOWER FRONT END				
PULL SADDLE RELEASE CABLE & VERIFY RODS FREE**				
<u>SET UP LRV</u>		<u>SET UP LRV</u>		
PICK UP & TURN LRV		PICK UP & TURN LRV		
DEPLOY LR FENDER EXT		ERECT GEO PALLET POST		
CHECK LR HINGE PIN ENGAGED				
ERECT CDR SEAT & UNSTOW SEAT BELT		DEPLOY RR FENDER EXT		
RELEASE INBRD HNDHLD TIEDOWN		CHECK RR HINGE PIN ENGAGED		
		CHECK REAR STEERING RING		
		ERECT LMP SEAT & UNSTOW BELT		
		LOWER ARMREST		
PULL T-HNDL, ROTATE 90 DEG, LOWER CONSOLE, RAISE HANDHOLD		PULL T-HNDL, ROTATE 90 DEG LOWER CONSOLE RAISE HANDHOLD		
ROTATE T-HNDL 90 DEG TO LOCK		ROTATE T-HNDL 90 DEG TO LOCK		
PULL & DISCARD ATTITUDE & C/W FLAGS		REMOVE TRIPOD & STOW RIGHT TOEHOLD		
REMOVE TRIPOD & STOW LEFT TOEHOLD		CHECK RF HINGE PIN ENGAGED		
CHECK FRONT STEER DECOUPLE		ERECT FOOTREST		
CHECK LF HINGE PIN ENGAGED		DEPLOY LF FENDER EXT		
ERECT FOOTREST		0+40		
DEPLOY LF FENDER EXT		VERIFY BATT COVERS CLOSED		
<u>LM AREA DESC & PHOTO</u>		<u>LRV TEST DRIVE</u>		
GET LMP CAM		MOUNT LRV		
		FASTEN SEATBELT		
		POWER UP LRV PER DECAL		
		TEST DRIVE LRV AROUND LM		
DO LM AREA INSPECTION				
TAKE PHOTO PAN 30 FT FROM LM AT 4:00		POSITION LRV NEAR MESA		
STOW CAM IN ETB		+15 VDC SW-OFF-		
<u>LRV AFT CONFIG</u>		DISMOUNT LRV		
REMOVE QUAD III THERM BLNKTS FROM PALLET		<u>LRV FRONT CONFIG</u>		
OFFLOAD GEO PALLET		LIFT LCRU MTG POST LOCKS		
		RELEASE Y-CABLE VELCRO TABS		
		UNSTOW TCU CONN - DISCARD ADAPTER		
MOUNT GEO PALLET ONTO LRV		UNSTOW LCRU		
	0+50			

**PUSH DOWN W/CONT DEPLOY TOOL IF REQD

CREW EVA CHECKLIST

EVA-1

VOICE DATA

LRV FRONT CONFIG	0+46	LRV FRONT CONFIGURE Life LCRU post locks Release Y-cable Install LCRU, lock posts & conn. pwr conn. [GEO PALLET SET-UP] Install TCU(conn. inboard) Conn. pwr cable to TCU Unstow Rake Install LGA, CDR side, tilt to 45°, align Conn LGA to LCRU [CDR CAM, ETB] Install, raise HGA mast Conn HGA to LCRU Velcro cable to staff	CDR-10
			EVA1
			11-1-72

CDR-11	0+08	Unstow TV cam (MESA LH) TV to TCU TV sunshade to TV cam TV cable (TCU) to TV cam Deploy HGA/Align Check LCRU: •Deploy LCRU whip ant •LCRU Bikts - 100% open •Cb - Closed •Pwr sw - INT - •Report - AGC, TEMP, PWR •Pwr sw - EXT - •Mode sw - 2 - (FM/TV) •TCU pwr sw - ON -(mom.) •VERIFY - AGC & PWR ~2	LRV FRONT CONFIG
			11-1-72

LRV AF ETB	0+56	•Tongs to LMP floor pan •Ext hndls to gate clips •Hammer to pallet top •Gnomon to bag (unfold) •Dust brush to LCRU •Rake to LH ext hndl •Scoop to RH ext hndl •Conn pallet stop strap •Discard rammer brkt •Vise to pallet top •SCB 2 to gate •SCB 3, Acces. Staff, & LCRU Strap to LMP handhold	LMP-10
			EVA1
			11-1-72

LMP-11	1+04	LRV EQUIP STOWAGE Config CDR cam (MESA) [TV •Remove cam •Mount cam on RCU ETB to CDR seat •Reseau cover to ETB •Darkslide (Mag B) to ETB •Install Mag B (ETB) •Fire 2 frames •Install bag adapter (ETB) •CDR cam to CDR footpan Maps & holder to LMP seat Stow under CDR seat: • 3 mags (rpt C,G,H) [SRC •Sun compass •Tape • Scissors •Lens brushes (2) •500 mm cam • LMP cam BSLS to CDR seatback ETB to MESA table Check for TGE - GRAV -	LMP-11
			11-1-72

0+50

(1) LMP - TGE ON -

RDG: _____

1+00

(1) LMP - CDR Cam Mag _____ (B)

(1) LMP - Mags stowed

_____ (C) _____ (G) _____ (H)

Lens brushes

Maps & holder

BSLS

Bag shoe

Sun Compass

Tape

Scissors

1+10

500 mm Camera (Mag R)

MISSION: APOLLO 17

EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
	0+50			
		MOUNT LCRU ON LRV		
		UNSTOW & CONNECT LCRU PWR CABLE-DISCARD ADAPTER		
REMOVE & DISCARD PALLET HANDRAILS		UNSTOW TCU		
REMOVE & DISCARD LAUNCH PINS & VELCRO ON TGE				
SET TGE ON / STBY SW TO -ON- RWD DISPLAY TO MCG		MOUNT TCU ON LRV		
CONFIG TOOLS ON GEO PALLET *TONGS TO FLOOR *EXT HNDLS TO GATE *HAMMER *GNOMON *BAG STAFF TO HANDHOLD *DUST BRUSH TO LCRU		CONNECT TCU PWR CABLE		
UNSTOW RAKE-MOUNT ON EXT HANDLE		UNSTOW RAKE TO CDR SEAT		
CONNECT PALLET STOP STRAP PUT SCB 2 ON GATE		OPEN LRV ANT CANISTER		
INSTALL SCOOP ON RH EXT HANDLE				
DISCARD DRIVE TOOL BRKT INSTALL VISE IN PALLET	1+00	UNSTOW LGA FROM CANISTER		
		MOUNT LGA IN CDR HANDHOLD		
		POINT LGA TO EARTH DEPLOY & CONNECT LGA CABLE		
PUT SCB 3 ON BAG STAFF - SECURE OPEN W/LCRU STRAP LRV MISC EQUIP STOWAGE		UNSTOW HGA FROM CANISTER		
UNSTOW CDR CAM FROM MESA				
MOUNT CDR CAM ON RCU		MOUNT HGA ON LRV		
RETRIEVE ETB - TO CDR FOOTPAN				
REMOVE & STOW RESEAU COVER IN ETB		ROTATE ANTENNA & EXTEND MAST		
PULL SLIDE, MAG B		UNSTOW CABLE, DISCARD FOAM		
INSTALL MAG B ON CDR CAM FIRE 2 FRAMES		CONNECT HGA CABLE TO LCRU		
INSTALL SAMPLE BAG ADAPTER PUT CDR CAM ON FOOTPAN PUT MAPS & HOLDER ON LMP SEAT		VELCRO CABLE TO STAFF LRV TV CONFIG		
STOW 3 70 MM MAGS UNDER CDR SEAT (C,G,H)		UNSTOW TV FROM MESA, CARRY TO LRV		
STOW 500 CAM UNDER CDR SEAT	1+10	MOUNT TV ON TCU-HORIZONTAL UNSTOW SUNSHADE - INSTALL ON TV CW TO AFT		

CREW EVA CHECKLIST

VOICE DATA

EVA 1

SRC CONFIG EXPTS OFF	SRC 7 (RH) to MESA table SCB 1 to MESA top Seal organic cont sample Close SRC	CDR-12
SRC CONFIG EXPTS OFF	SCB 1 to tool gate Hammer to leg pocket TGE - GRAV -	EVA1
SRC CONFIG EXPTS OFF	1+18 FLAG DEPLOY •Unstow kit •Select site 2:00/30' •Photos (COR cam) •Cam to LMP •Hammer to geo pallet	EVA1

CDR-13 EVA1	1+22 EXPT PALLET OFFLOAD Remove QTTI thermal blanket Offload pallet to +y pad TGE - READ - TGE to surface TGE - GRAV - Swivel geo pallet open BSLSS over seatback	LM IN-SPECT, ALSEP OFFLOAD
CDR-13 EVA1	Mount SEP Rcvr on post Read Temp Meter - close cover Deploy ant (decals 1-5) Mount ant on post Remove SEP Nav cable Conn SEP Nav to LRV (decal 6)	EVA1

ALSEP TRAV EVA1	Remove EP Xptr brkt from LRV pallet (backside), lock on pallet top EP Xptr to LRV topside (4,5,6,7) Close geo pallet TGE - READ - TGE - BIAS - Orient Expt. pallet to sun	CDR-14
ALSEP TRAV EVA1	1+30 ALSEP TRAV PREP Core/Bore bag to LMP seat [FUEL RTG N. Flux Expt to LMP seat Drill to LMP seat, secure with seatbelt TGE - READ - TGE to LRV	EVA1

FLAG DEPLOY ALSEP OFF	1+12 FLAG DEPLOY •Unstow kit •Get hammer •Select site 2:00/30' •Photos (COR cam) •Get cam from CDR	LMP-12
FLAG DEPLOY ALSEP OFF	1+22 LM INSPECTION Inspect 4 struts & engine bell status [EXPT PALLET OFFLOAD Note TGE status Stow cam under CDR seat Deploy Cosmic Ray (if desired) •Shade first •Bag to LRV bay	EVA1

LMP-13 EVA1	1+26 ALSEP OFFLOAD Open SEQ doors Descent ECA Temp Mon. SW-ON - RTG to surface Discard Hockey Stick C/S to surface, 90° to RTG Remove Hockey Stick Remove tool brkt, RTG: •Config UHT/blocks •UHT's to PKG sockets •Carry bar to C/S •ORT, FIT to SEQ bay	ALSEP OFFLOAD
LMP-13 EVA1	1+33 FUEL RTG Rotate RTG up [OFFLOAD DRILL Remove RTG dust cover Deploy fuel cask Remove dome, discard Fuel RTG Close SEQ bay doors Conn RTG to C/S bar	EVA1

1+10

(1) CDR/LMP - EMU CHECK

	CDR	LMP
02		
FLAGS		
PRESS		
COOL		

(1) CDR - LCRU covers open 100%

Report LCRU:

AGC _____

POWER _____

TEMPS _____

AGC(Verify 2)

1+20

(1) CDR-TGE-GRAV _____

(1) LMP - Comment on soil effects, LM condition, LM strut stroking

(1) CDR - TGE Rdg _____

(1) CDR - TGE - GRAV _____

(1) CDR - SEP RCVR Temp _____

(1) LMP - Report EP Pallet _____

(1) LMP - DES ECA Temp Monitor Sw - ON

(1) CDR - TGE Rdg _____

1+30

(1) CDR - TGE BIAS _____

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
STOW TAPE & SCISSORS IN CDR SEAT	1+10	CONNECT TV PWR CABLE FROM TCU		
PUT BOTH CAMERAS UNDER CDR SEAT		TIP HGA AFT, DEPLOY DISH & LOCK		
ALSO 2 LENS BRUSHES, COMPASS		POINT HGA AT EARTH, REALIGN AS REQUIRED		
STOW BSLSS ON CDR SEAT		CONFIGURE LCRU:		
STOW ETB ON SRC TABLE		*DEPLOY WHIP	*REPORT-AGC,	
FLAG DEPLOY		*LCRU BLKTS-	TEMP, PWR	
UNSTOW FLAG KIT, OPEN,		100% OPEN	*PWR SW-'EXT'	
PLACE ON MESA		*CB-'CLOSED'	*MODE SW-2	
REMOVE STAFF & GET HAMMER		*POWER SW-'INT'	*TCU PWR SW-ON	
SELECT SITE 2:00/30'		*VERIFY AGC	(MOM.)	
DRIVE STAFF INTO SURFACE		SRC 1 CONFIG		
DEPLOY FLAG-EXTEND MAST & SPAR		UNSTOW SRC 1		
MOUNT FLAG IN BASE STAFF		PLACE SRC ON MESA TABLE		
GET CDR 70MM CAM		OPEN SRC 1		
PHOTO CDR/FLAG		REMOVE SCB 1-PLACE ON MESA		
GIVE CAM TO CDR	1+20	SEAL ORGANIC CONTROL SAMPLE		
POSE WITH FLAG		& LEAVE IN SRC		
RECEIVE CAM FROM CDR		TAKE SCB 1 TO TOOL GATE		
LM INSPECTION		PUT HAMMER IN LEG POCKET		
DO LM INSPECTION, PHOTO		PRESS 'GRAV' ON TGE		
UNUSUAL CONDITIONS		FLAG DEPLOY		
INSPECT 4 STRUTS & ENGINE		POSE WITH FLAG		
NOTE TGE STATUS		RECEIVE CAM FROM LMP		
STOW CAM UNDER CDR SEAT		PHOTO LMP/FLAG & HAND CAM TO LMP		
ALSEP OFFLOAD		LRV MISC OPR		
OPEN SEQ BAY DOORS		OPEN QUAD III THERMAL BLNKT		
POSITION DES ECA TEMP MON SW-ON		UNSTOW PALLET-PLACE ON +Y		
UNLOCK PKG 2		FOOTPAD		
PULL LANYARD RELEASE RING		PRESS READ-READ TGE DISPLAY		
REMOVE PKG 2 - PLACE ON SURFACE		PLACE TGE ON SURFACE, LEVEL		
PULL PIN & DISCARD HOCKY STICK	1+30	PRESS GRAV PB-NOTE FLASH		
UNLOCK PKG 1		OPEN PALLET-BSLSS OVER SEATBACK		
PULL LANYARD RELEASE RING		MOUNT SEP RCVR ON LRV POST		
		READ TEMP		
		DEPLOY & ERECT SEP ANT		
		MOUNT SEP ANT ON LRV POST		
		REMOVE DUST CAP FROM LRV/SEP		
		CONNECT SEP NAV CABLE TO LRV		
		REPOSITION BSLSS		
		UNSTOW LSPE ADAPTER BRKT & MOUNT ON PALLET		
		REMOVE LSPE CHARGE PALLET (4,5,6,7)		
		MOUNT PALLET ON ADAPTER & CLOSE LRV PALLET		
		PRESS READ-READ TGE DISPLAY		
		PRESS BIAS PB-NOTE FLASH		
		ORIENT EXPT PALLET TO SUN		

CREW EVA CHECKLIST

VOICE DATA

EVA 1

CDR-15	Remove MESA brkts, L. side LiOH Cann. to middle of MESA Tidy MESA Blankets	ALSEP TRAV
	1+35 LRV Equip Ck • LCRU - Brkts 100% open • TV/Sunshade • SEP RCVR/ant - nav cable • EP Xptr (4,5,6,7) on LRV • TGE (3 meas. complete) • Drill, bag, N. Flux	
EVA1	1+37 ALSEP TRAV TV cam; Mode sw -1-(PM1/ND) Drive to ALSEP site, 300 ft W Park 60 ft NE of C/S, H = 180 +15 vdc sw - OFF - Mode sw - 3 - (TV RMT) Dust TV, TCU & LCRU HGA TGE - GRAV -	11-1-72

1+30

- (1) CDR - TGE Rdg _____
& TGE back on LRV
- (1) LMP - RTG Fueled _____

- (1) CDR/LMP - EMU CHECK

	CDR	LMP
O2		
FLAGS		
PRESS		
COOL		

- (1) LMP - SEQ Bay Doors - CLOSED

- (1) CDR - Mark LM Depart time _____

1+40

LMP-13	1+26 ALSEP OFFLOAD Open SEQ doors Descent ECA Temp Mon. SW-ON- RTG to surface Discard Hockey Stick C/S to surface, 90° to RTG Remove Hockey Stick Remove tool brkt, RTG: •Config UHT/blocks •UHT's to PKG sockets •Carry bar to C/S •DRT, FTT to SEQ bay	ALSEP OFF FLAG
	1+33 FUEL RTG OFFLOAD Rotate RTG up DRILL Remove RTG dust cover Deploy fuel cask Remove dome, discard Fuel RTG Close SEQ bay doors Conn RTG to C/S bar	
EVA1		11-1-72

- (1) CDR - At ALSEP site, LRV displays

Temp Bat 1	
Temp Bat 2	
Temp LF mtr	
Temp RF mtr	
Amp-Hr Bat 1	Temp LR mtr
Amp-Hr Bat 2	Temp RR mtr

- (1) CDR - TGE - GRAV _____

1+50

- (1) LMP - RTG cable temp Label
reading _____ (or report)

ALSEP TRAV	1+40 TRAVERSE TO ALSEP SITE Select ALSEP site ~ 300' W of LM ~ 80' S of deep core Place ALSEP on surface, C/S-South	LMP-14
	1+47 ALSEP INTERCONNECT Disc carry bar - discard Attach blocks to C/S Pos RTG 10'E of C/S Remove 2 HFE pull pins Remove 1 LEAM pull pin Rotate RTG to gnd IF CDR DELAYED •Offload HFE 10'N C/S •Conn HFE to C/S, Lock	
EVA1		11-1-72

MISSION: APOLLO 17

EVA: 1

DATE: NOV. '72

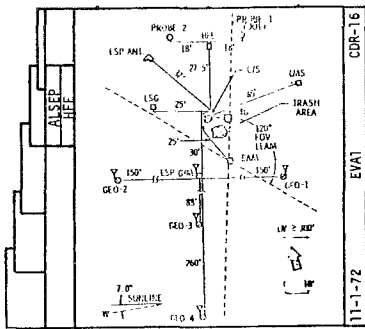
LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
REMOVE PKG 1 - PLACE ON SURFACE, ROT 90 DEG	1+30	UNSTOW CORE/BORE STEM BAG & UNSTOW NEUTRON FLUX MONITOR		
PULL PIN & REMOVE HOCKY STICK		CARRY TO LRV & STOW OFFLOAD DRILL FROM MESA		
REMOVE & DISCARD TOOL BRKT ASSY CONFIG C/S BLOCKS		PLACE DRILL ON LMP SEAT		
STOW UHT'S ON PKG'S		PRESS READ-READ TGE DISPLAY		
REMOVE & EXTEND CARRY BAR & INSTALL IN PKG 1		STOW TGE ON LRV-ROTATE HNDL		
PLACE DRT & FIT IN SEQ BAY		REMOVE MESA BRACKETS		
FUEL RTG		LiOH CANN TO MIDDLE OF MESA		
POSITION PKG 2 FOR FUELING		TIDY MESA BLNKTS		
REMOVE RTG DUST COVER-DISCARD		LRV EQUIP CHECK		
GET CASK LANYARD		*LCRU BLANKETS 100% OPEN		
ROTATE FUEL CASK, DISCARD LANYARD		LGA, HGA ALIGNED		
GET DRT, REMOVE DOME		*TV SUNSHADE INSTALLED		
READ TEMPILABEL-DISCARD DOME		*SEP RCVR/ANT-NAV CABLE		
GET FIT-ENGAGE IN FUEL ELEMENT		*LSP PALLET ON LRV		
		*TGE (3 MEAS)		
		*DRILL, BAG, NFE ON LRV		
REMOVE ELEMENT, FUEL RTG		ALSEP TRAV		
		SWITCH LCRU - 'POS 1' (PM1/WB)		
REMOVE FIT-READ TEMP-DISCARD TIP PKG 2 UP		POS TV HORIZ CW & AFT		
CLOSE SEQ BAY DOORS		MOUNT LRV-FASTEN SEATBELT		
ATTACH PKG 2 TO CARRY BAR		POWER UP LRV		
ALSEP TRAV				
CRADLE BARBELL IN CROOK OF ELBOW	1+40	DRIVE TO ALSEP SITE AREA		
CARRY ALSEP TO DEPLOY SITE & SURVEY SITE				
SELECT DEPLOY SITE FOR ALSEP**				
		POSITION LRV 60 FT NE C/S		
		HEADING 180		
		+15 VDC SW - OFF -		
		READ OUT DISPLAYS		
		DISMOUNT LRV		
POSITION ALSEP PKG 1 SOUTH OF PKG 2 WITH PKG 1 IN DESIRED LOCATION		SWITCH LCRU - 'POS 3' (TV RMT)		
ALSEP INTERCONNECT (L)		ORIENT HGA		
REMOVE PKG 1&2 FROM CARRY BAR & DISCARD CARRY BAR		DUST BATT COVERS & MIRRORS -		
POSITION PKG 2 10 FT EAST C/S		TCU, CTV, LCRU		
PULL 2 HFE PULL PINS & LEAM		DEPRESS GRAV PB ON TGE		
ROTATE PKG 2 TO SURFACE		OBSERVE TGE INDICATOR CYCLING		
RELEASE RTG CABLE REEL-3 BB'S				
ENGAGE UHT IN CABLE REEL				
READ TEMPILABEL (DO NOT TOUCH				
IF >250° = REPORT TO MCC)	1+50			
**300 FT W OF LM, 80 FT S OF LIKELY DRILL CORE SITE				

CREW EVA CHECKLIST

VOICE DATA

EVA 1

11-1-72	EVA1	1+50	<p>HFE DEPLOY Unload HFE 10'N of C/S Conn HFE to C/S, lock Carry HFE 30'N of C/S, place on gnd, expt. up Remove probe box (4BB's) Stow box 2 on pallet [LSG Carry box 1 16'E of HFE, place on gnd Carry box 2 16' W of HFE, place on gnd Remove elec pkg (4BB's) Lift with UHT - remove cover Emplace & align elec [G/M</p> <p>TGE - READ - Assemble Drill</p>	<p>CDR-17</p> <p>LSG</p> <p>W/S</p> <p>W/S</p>



11-1-72	EVA1	1+49	<p>Unstow RTG cable (3 BB's) *Read Temp label if > 250° *Pull pin - discard brkt *Get conn. - read mtr *Attach & lock to C/S</p> <p>Reposition RTG wrt C/S if reqd Release LEAM pallet (2BB's) Carry 10'W of C/S Get LEAM conn Remove dust covers on conn and C/S Conn LEAM to C/S, lock Tip C/S down, coarse align</p>	<p>CDR-16</p> <p>LSG</p> <p>W/S</p>

11-1-72	EVA1	1+58	<p>LSG DEPLOY Remove BB's IN ORDER [HFE * Knock BB's off LSG Carry LSG 25'W of C/S Extend & tilt sunshield to 20° Level & align Uncage Gimbal</p>	<p>LSG</p> <p>W/S</p>
		2+04	<p>LSG GEOPHONE MOD DEPLOY Remove flag pin Remove 4 BB's Carry Geophone Module 30'S of C/S Align G/M to sun Deploy flags Anchor module - use a flag, point face to S</p>	<p>W/S</p> <p>W/S</p>

1+50	<p>(1) LMP - Shorting SW - <u>SHORT</u> Reading _____ AMPS</p> <p>(2) LMP - RTG cable connected to C/S _____ (time)</p>
2+00	<p>(1) CDR - Report if HFE Cables crossed</p> <p>(1) LMP - LSG aligned and uncaged</p>
2+10	<p>(1) CDR - TGE Rdg _____</p> <p>(1) LMP - Verify vent ring pulled</p>

MISSION: APOLLO 17

EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION		
			L	M	P
WALK TO PKG 1 DEPLOYING CABLE REMOVE SHORT PLUG FROM REEL, READ SHORTING PLUG METER TO MCC DISCARD SHORT PLUG DUST COVER DISCARD RTG C/S DUST COVER CONNECT SHORT PLUG TO C/S - ROTATE T-HANDLE REPOSITION RTG IT REQD	1+50	ALSEP INTERCONNECT (C) GET PKG 1 UHT ERECT HFE PALLET CARRY HNDL RELEASE TWO STRUT BOYD BOLTS ON HFE LIFT HFE FROM PKG 2 CARRY HFE 10 FT NORTH OF PKG 1 UNSTOW HFE CONNECTOR LOWER HFE TO SURFACE DISCARD C/S CONN DUST COVER DISCARD HFE CONN DUST COVER MATE & LOCK HFE CONN			
RELEASE 2 LEAM PALLET BB'S ENGAGE UHT-REMOVE PALLET PLACE PALLET ON SURFACE 10 FT W C/S REMOVE LEAM CONN PULL PIN REMOVE LEAM CONN FROM PALLET REMOVE DUST COVERS FROM LEAM MATE & LOCK LEAM CONN PARTIALLY OPEN C/S DUST COVER TIP PKG 1 DOWN REMOVE & DISCARD C/S DUST COVER USE UHT, COARSE ALIGN C/S		HFE DEPLOY CARRY HFE 30 FT N C/S LAY HFE PALLET ON SURFACE RELEASE 4 BB'S ON PROBE BOX			
LSG DEPLOY RELEASE 4 BB'S SECURING LSG ENGAGE UHT IN LSG CARRY SOCKET CARRY LSG 25 FT W OF C/S					
DEPLOY/LOCK SUNSHADE	2+00	LIFT PROBE BOX SEPARATE PROBE BOX HALVES STOW BOX 2 ON HFE ROTATE RAMMER FROM STOWED POSITION CARRY BOX 1 16 FT E PLACE BOX 1 ON SURFACE RETRIEVE BOX 2 FROM HFE CARRY BOX 2 16 FT WEST PLACE BOX 2 ON SURFACE REMOVE 4 BB'S ON HFE ELEC LIFT HFE FROM PALLET PUSH PALLET ASIDE & EMLACE HFE ELEC DRILL PREP & TGE CHECK TGE LIGHT - OFF - DEPRESS READ PG ON TGE READ TGE DISPLAYS TO MCC CLOSE COVER ASSEMBLE DRILL PER DECAL			
TILT SUNSHADE TO PRESET ANGLE					
EMPLACE LSG ON LUNAR SURFACE					
ALIGN & LEVEL LSG					
UNCAGE LSG GIMBAL-CHECK LEVEL RETURN TO C/S					
LSPE G/M DEPLOY RELEASE 4 BB'S SECURING MODULE ENGAGE UHT IN CARRY SOCKET CARRY G/M 30 FT S C/S					
REMOVE FLAG RETAINING PINS DEPLOY & INTERIM STOW 5 FLAGS IN SURFACE					
EMPLACE G/M					
USE 1 FLAG TO ANCHOR MODULE RETURN TO C/S					
LMS DEPLOY USE UHT, PULL VENT RING RELEASE 3 LMS BB'S	2+10				

CREW EVA CHECKLIST

VOICE DATA

EVA 1

HFE	2+11	Carry to HFE site: • Drill • Rack • Bore/core bag 1st PROBE HOLE DPTH: • 1 long stem • 2 short stems	CDR-18 EVA1
	2+26	EMPLACE PROBE 1 Ram 1st thermal shield/probe (Pi) Ram 2nd shield (F1) Measure height of stem Position top (3rd) shield Exit cable S	LMS, C/S DEPLOY LEAM 11-1-72

LMS C/S	2+08	LMS DEPLOY Use UHT to pull vent ring Remove 3 BB's Lift LMS, rotate to carry pos Carry 45° NE of C/S Align E/W & level Snap breakseal • VERIFY dust cover action Level & align C/S Housekeep C/S	LMP-18 EVA1 11-1-72
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LMP-19	EVA1	2+12	C/S DEPLOY Remove rear curtain cover, 2BB's Remove 3 ant BB's Remove ant mast pull pins Remove ant bracket Remove ant cable bracket Free ant cable Remove 16 perimeter BB's Extend mast Check C/S corners free Release 3 interior BB's, guide C/S up Discard curtain covers Secure thermal curtains	SMT S/O 11-1-72
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C/S ANT LEAM, LSP	EVA1	2+23	ALSEP ANTENNA DEPLOY Remove ant gimbal from LEAM pallet (2BB's) Remove dust cover ONLY Place gimbal container on ant mast Pull retaining pin, remove & discard cover & foam Mount ALSEP ant on gimbal, seat firmly Check LAT/LONG setting • (LAT=2.02, LONG=3.08) Level gimbal Align gnomon shadow Turn RTG shorting SW - ON - Read mtr	LMP-20 11-1-72
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- 2+10 (1) LMP - LMS level/aligned Breakseal open
- (1) CDR - Start HFE Bore hole 1 drilling
- 2+20 (1) CDR - 54" stem in surface
- (2) CDR - 28" stem in surface
- (2) CDR - 28" stem in surface
- 2+30 (1) LMP - _____ AMPS
(Short Sw actuated)

MISSION: APOLLO 17

EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION		
			C	LMP	CDR
ENGAGE UHT, LIFT LMS & ROTATE 90 DEG ON SWIVEL - LOCK DEPLOY LMS 45 FT NE C/S, EMPLACE & LEVEL**	2+10	CARRY TO HFE SITE: *DRILL *RACK *STEM BAG			
INSERT UHT & SNAP BREAKSEAL, ADJUST DUST COVER IF REQ		PLACE DRILL ON SURFACE LOCATE RACK/STEMS FOR DRILLING OPEN STEM BAG			
WALK TO C/S		DRILL 1ST PROBE HOLE			
C/S DEPLOY USE UHT-LEVEL & ALIGN C/S RELEASE REAR THERMAL CURTAIN		ATTACH LONG BORE TUBE TO DRILL FIND HOLE INDEX ON PROBE CABLE DRILL BORE TUBE INTO SURFACE			
RELEASE 3 ANTENNA BB'S PULL ANT MAST RELEASE PINS					
REMOVE ANT BRACKET RELEASE & FREE RF ANT CABLE		ROTATE DRILL CCW TO REMOVE FROM BORE STEM			
RELEASE 16 PERIMETER BB'S		PLACE DRILL ON SURFACE ATTACH SHORT BORE TUBE SECTION TO STEM			
EXTEND & LOCK MAST SECTIONS		PICK UP DRILL, ENGAGE ROTATE DRILL CW TO SEAT THREADS			
CHECK 4 CORNERS LOOSE		DRILL BORE TUBE INTO SURFACE			
RELEASE 2 INTERIOR BB'S		2+20			
RELEASE CENTER BB-GUIDE C/S UP	ROTATE DRILL CCW TO REMOVE FROM BORE STEM				
CHECK SUNSHIELD COMPLETELY UP	PLACE DRILL ON SURFACE ATTACH 2ND SHORT BORE TUBE SECTION TO STEM				
CLOSE SIDE CURTAINS-DISCARD COVERS	PICK UP DRILL, ENGAGE .. ROTATE DRILL CW TO SEAT THREADS				
ALSEP ANTENNA DEPLOY WALK TO LEAM SUBPALLET	DRILL BORE TUBE INTO SURFACE				
RELEASE 2 BB'S ON GIMBAL CASE LIFT GIMBAL FROM PALLET					
CARRY TO C/S REMOVE GIMBAL BASE DUST COVER					
MOUNT GIMBAL ON ANTENNA MAST PULL PIN, REMOVE & DISCARD HOUSING & FOAM	ROTATE DRILL CCW TO REMOVE FROM BORE STEM				
MOUNT ANTENNA ON GIMBAL VERIFY LAT/LONG & LEVEL GIMBAL*	PLACE DRILL ON SURFACE				
ALIGN SUN COMPASS-CHECK LEVEL	EMPLACE HFE PROBE 1 PICK UP BOX 1, GRASP HANDLE RULL REMAINING CABLE FROM BOX REMOVE PROBE LEAN BOX AGAINST RACK				
ACTUATE SHORT SW-READ METER **DO NOT EMBED LMS TO LEVEL-REPOSITION *LAT = 2.02; LONG = 3.08	2+30				

CREW EVA CHECKLIST

EVA 1

VOICE DATA

HFE	2+11	1st PROBE HOLE DRILL: • 1 long stem • 2 short stems	LMS, C/S DEPLOY	CDR-18 EVA1 11-1-72
	2+26	EMPLACE PROBE 1 Ram 1st thermal shield/probe (P1) Ram 2nd shield (F1) Measure height of stem Position top (3rd) shield Exit cable S		

CDR-19 EVA1 11-1-72	2+35	2nd PROBE HOLE DRILL: • 1 long stem • 2 short stems	LSPE ANT, GEO DEPLOY	HFE
	2+49	EMPLACE PROBE 2 Ram 1st thermal shield/probe (P1) Ram 2nd shield (F1) Measure height of stem Position top (3rd) shield Exit cable S Verify HFE Elec level/align UHT to LRV, LMP seat		

LMP-21 EVA1 11-1-72	2+30	LEAM DEPLOY Remove 4 BB's Carry 25' SE of C/S, line on RTG Remove dust cover Remove UHT socket pin, rotate to lock Deploy legs/gnomon Emplace, level & align	LMP-22 EVA1 11-1-72
	2+35	LSPE ANTENNA DEPLOY Retrieve HFE pallet Remove LSPE ant from C/S Carry ant & pallet 40' NW of C/S Place pallet on surface Deploy ant full length Use UHT to insert ant	

GEOPHONES GEO PHOTO	2+40	CONFIG FOR PHOTOS/SAMPLING Return to LRV Config LRV Sampler (opt) Get LMP cam Get gnomon	LMP-22 EVA1 11-1-72
	2+49	LSPE GEOPHONE DEPLOY Return to Geo Module Remove & discard cover Insert UHT in reel #3 Get flag Get gnomon Deploy Geo 3 88'S (Xsun) Embed Geo & anchor w/flag Emplace gnomon 2' NW of Geo 3 • Photo doc remaining Geo's as read if no LOS to Geo 3 Insert UHT in reel #1 Get flag Deploy Geo 150'E (Upsun) Embed Geo & anchor w/flag	

2+30 Capcom - advise crew on ALSEP down link
 (1) CDR - Probe depth _____ (P1)
 - 2nd Shield depth _____ (F1)
 - Bore stem height _____ (B6)

(1) LMP - LEAM Level _____
 Alignment _____

(2) CDR - Start HFE Bore hole 2 drilling - MARK

(1) CDR - 54" stem in surface

2+40 (2) CDR - 28" stem in surface

(2) CDR - 28" stem in surface

(2) CDR - 28" stem in surface

2+50 (1) CDR/LMP - EMU CHECK

	CDR	LMP
O2		
FLAGS		
PRESS		
COOL		

MISSION: APOLLO 17

EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
REQUEST XMTR TURN ON & VERIFY DOWN LINK	2+30	GRASP PROBE & REMOVE END CAPS UNFOLD PROBE ASSY		
LEAM DEPLOY		INSERT PROBE INTO BORE TUBE		
RELEASE 4 BB'S ON LEAM		REMOVE RAMMER FROM BOX 1, USE RAMMER, INSERT PROBE 1 & READ INDEX NUMBER ON RAMMER		
ENGAGE UHT, CARRY 25 FT SE C/S		USE RAMMER-INSERT 2ND THERMAL SHIELD, POSITION TO MARK F1		
PULL SOCKET PIN, ROTATE PKG REMOVE DUST COVER		REMOVE RAMMER, PLACE NEXT TO BORE TUBE, READ TUBE HEIGHT		
DEPLOY LEGS/GNOMON		POSITION 3RD THERMAL SHIELD EXIT CABLE S IN HOLE		
EMPLACE LEAM ON LUNAR SURFACE		CARRY DRILL, TUBES, RACK & RAMMER TO WEST HOLE DRILL 2ND PROBE HOLE		
LEVEL & ALIGN		PLACE RACK, RAMMER, DRILL ON SURFACE		
WALK TO HFE SITE		ATTACH LONG BORE TUBE TO DRILL		
LSPE ANT DEPLOY		FIND HOLE INDEX ON PROBE CABLE		
CARRY HFE PALLET TO C/S, PLACE ON SURFACE		DRILL BORE TUBE INTO SURFACE		
RETRIEVE LSPE ANT & REEL (C/S) LOWER CABLE REEL TO SURFACE				
CARRY HFE PALLET & ANT 40 FT NW C/S		ROTATE DRILL CCW TO REMOVE FROM BORE STEM		
PLACE HFE PALLET ON SURFACE EXTEND LSPE ANT TO FULL LENGTH		PLACE DRILL ON SURFACE ATTACH SHORT BORE TUBE SECTION TO STEM		
USE UHT-INSERT ANT INTO SOCKET LEVEL PALLET SO ANT IS VERTICAL	2+40	PICK UP DRILL, ENGAGE ROTATE DRILL CW TO SEAT THREADS		
CONFIG FOR SAMPLING		DRILL BORE TUBE INTO SURFACE		
RETURN TO LRV				
GET DIXIE CUPS OUT OF SCB 1				
GET LRV SAMPLER FROM AFT PALLET				
PUT CUPS IN LRV SAMPLER STOW REMAINING CUPS IN PORCH		ROTATE DRILL CCW TO REMOVE FROM BORE STEM		
INSTALL SAMPLER ON CDR UHT (CDR SEAT) AND TETHER UNIT		PLACE DRILL ON SURFACE ATTACH SHORT BORE TUBE SECTION TO STEM PICK UP DRILL, ENGAGE ROTATE DRILL CW TO SEAT THREADS DRILL BORE TUBE INTO SURFACE		
		ROTATE DRILL CCW TO REMOVE FROM BORE STEM		
PUT CAM ON RCU		PLACE DRILL ON SURFACE		
PICK UP GNOMON DROP AT GEOPH MODULE	2+50			

LMP OPTION

CREW EVA CHECKLIST

VOICE DATA

EVA 1

CDR-19	2+35	2nd PROBE HOLE Drill: • 1 long stem • 2 short stems	[LSPE ANT, GEO LDEPLOY
	2+49	EMPLACE PROBE 2 Ram 1st thermal shield/probe (P1) Ram 2nd shield (F1) Measure height of stem Position top (3rd) shield Exit cable S Verify HFE Elec level/align UHT to LRV, LMP seat	3/H
11-1-72			
DEEP CORE N. FLUX	2+56	DEEP CORE PREP Carry to Site. (55 ft. N of HFE): • Drill • Rack • Core bag DRILL DEEP CORE (1 IPS) Drill: • Bit stem first • 3 stems Clear Flutes • 5 sec each stem • 20 sec final Plug top end	CDR-20 EVA1 11-1-72
GEOPHONES GEO PHOTO	2+40	CONFIG FOR PHOTOS/SAMPLING Return to LRV Config LRV Sampler (opt) Get LMP cam Get gnomon	LMP-22
	2+49	LSPE GEOPHONE DEPLOY Return to Geo Module Remove & discard cover Insert UHT in reel #3 Get flag Get gnomon Deploy Geo 3 88'S (Xsun) Embed Geo & anchor w/flag Emplace gnomon 2'NW of Geo 3 • Photo doc remaining Geo's as reqd if no LOS to Geo 3 Insert UHT in reel #1 Get flag Deploy Geo 150'E (Upsun) Embed Geo & anchor w/flag	EVA1 11-1-72
LMP-23	3+00	Insert UHT in reel #2 Get flag Deploy Geo 2 150'W (Dnsun) Embed Geo & anchor w/flag Insert UHT in reel #4 [DEEP Get Flag [CORE Deploy Geo 4 260'S Embed Geo & anchor w/flag Return to Geo 3: • Move 25'SW, photo Geo's 1/3, 2, 4 • Move 25'SE, photo Geo's 2/3, 1, 4 • Take pan 10' S of Geo 3 GNOMON TO C/S	SENSOR CORE-20
EVA1	11-1-72		

2+50

- (1) CDR - Probe depth _____ (P1)
- 2nd Shield depth _____ (F1)
- Bore stem height _____ (B6)

(1) CDR - Core drill location

(1) CDR - Core Drill _____
Start - MARK _____

3+00 (1) CDR - 1st Section in _____
surface _____

(1) CDR - 2nd Section start - MARK

(1) CDR - 2nd Section in surface _____

(1) CDR - 3rd Section start - MARK

(1) CDR - 3rd Section in surface _____

3+10

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION		
			L	M	P
<p>GEOPHONE DEPLOY DEPLOY GEOPHONE 3: DISCARD G/M COVER *ENGAGE UHT IN REEL 3 & GET FLAG *RETRIEVE GNOMON *CARRY 88 FT SOUTH C/S *EMBED FLAG IN LUNAR SURFACE *REMOVE GEOPHONE FROM REEL *EMBED GEOPHONE IN SURFACE *DISCARD REEL *ANCHOR GEOPHONE WITH FLAG *PLACE GNOMON 2' NW OF GEO 3 *RETURN TO GEOPHONE MODULE</p> <p>DEPLOY GEOPHONE 1: *ENGAGE UHT IN REEL 1 & GET FLAG *CARRY 150 FT EAST C/S *EMBED FLAG IN LUNAR SURFACE *REMOVE GEOPHONE FROM REEL *EMBED GEOPHONE IN SURFACE *DISCARD REEL *ANCHOR GEOPHONE WITH FLAG *RETURN TO GEOPHONE MODULE</p> <p>DEPLOY GEOPHONE 2: *ENGAGE UHT IN REEL 2 & GET FLAG *CARRY 150 FT WEST C/S *EMBED FLAG IN LUNAR SURFACE *REMOVE GEOPHONE FROM REEL *EMBED GEOPHONE IN SURFACE *DISCARD REEL *ANCHOR GEOPHONE WITH FLAG *RETURN TO GEOPHONE MODULE</p> <p>DEPLOY GEOPHONE 4: *ENGAGE UHT IN REEL 4 & GET FLAG *CARRY 260 FT SOUTH C/S *EMBED FLAG IN LUNAR SURFACE *REMOVE GEOPHONE FROM REEL *EMBED GEOPHONE IN SURFACE *DISCARD REEL *ANCHOR GEOPHONE WITH FLAG *RETURN TO GEOPHONE 3**</p> <p>AT 3RD GEOPHONE SITE-PHOTO</p>	<p>2+50</p> <p>3+00</p> <p>3+10</p>	<p>EMPLACE HFE PROBE 2 PICK UP BOX 2, GRASP HANDLE PULL REMAINING CABLE FROM BOX REMOVE PROBE-DISCARD BOX GRASP PROBE & REMOVE END CAPS UNFOLD PROBE ASSY INSERT PROBE INTO BORE TUBE RETRIEVE RAMMER, MATE TO PROBE SEAT PROBE 2 & 1ST THERMAL SHIELD INTO BORE TUBE READ INDEX NUMBER ON RAMMER USE RAMMER - INSERT 2ND THERMAL SHIELD, POSITION TO MARK F1 REMOVE RAMMER, PLACE NEXT TO TUBE - READ INDEX DRESS CABLES, PROBE 1&2 TO LIE ALONG SURFACE, BLACK TO SOUTH RECHECK HFE ELEC LEVEL & ALIGN CARRY UHT TO LRV DRILL DEEP CORE CARRY TO CORE SITE 55 FT N HFE DRILL, RACK & CORE RETRIEVE CORE BIT SECTION ATTACH CORE SECTION TO DRILL DRILL CORE STEM INTO SURFACE ATTACH WRENCH TO STEM ROTATE DRILL CCW TO REMOVE FROM CORE STEM PLACE DRILL ON SURFACE REMOVE WRENCH ATTACH 2ND CORE SECT TO STEM PICK UP DRILL - MATE TO EMPLACED STEM ROTATE DRILL CW TO SEAT DRILL STEM INTO SURFACE ATTACH WRENCH TO STEM ROTATE DRILL CCW TO REMOVE FROM CORE STEM PLACE DRILL ON SURFACE REMOVE WRENCH ATTACH 3RD CORE SECT TO DRILL PICK UP DRILL - MATE TO EMPLACED STEM ROTATE DRILL CW TO SEAT THREADS DRILL STEM INTO SURFACE ATTACH WRENCH TO STEM ROTATE DRILL CCW TO REMOVE FROM CORE STEM PLACE DRILL ON SURFACE REMOVE WRENCH ATTACH 4TH CORE SECTION TO DRILL PICK UP DRILL-MATE TO EMPLACED STEM</p>			

**TAKE 360 DEG PANS & ANY OTHER PANS REQD TO FULLY DOCUMENT LSPE GEOPHONES

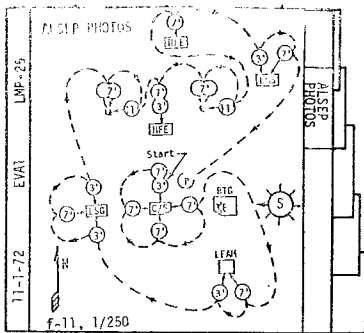
CREW EVA CHECKLIST

VOICE DATA

EVA 1

CDR-23	3+13	DEEP CORE RECOVER Get from LRV: •Treadle •N. Flux •Rammer TGE - GRAV - Jack to treadle Ram top plug Extract stem Plug & ram bit end Lay Core against rack	CDR-22
	EVA1	3+28	

CORE CAP PHOTOS	3+34	Carry core stem/caps/wrench to LRV Ram plugs Disjoint core in 3, 2, 3 Cap ends-rpt caps Stow on LRV TGE - READ - If LMP delayed: •Assist in Geo Deploy •Assist in photos	CDR-22
	EVA1	PHOTOS	



- 3+10 (1) CDR - 4th Section Start - MARK
- (1) CDR - 4th Section in Surface _____
- (1) CDR - Plug in top (depth) _____
- (1) LMP - Enable LSPE Sw
- 3+20
- (1) CDR - Cap on bit _____
(or plug _____ depth)
- (1) CDR - NFE lower section
activation - MARK _____
- 3+30 (1) CDR - NFE upper Section
activation - MARK _____

MISSION: APOLLO 17

EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
DOCUMENT GEOPHONE LAYOUT**	3+10	ROTATE DRILL CW TO SEAT DRILL STEM INTO SURFACE		
MOVE 25 FT SW, PHOTO GEOPHONES 1 & 3		ATTACH WRENCH TO STEM		
TURN AND PHOTO GEOPHONE 2		ROTATE DRILL CCW TO REMOVE FROM CORE STEM		
TURN & PHOTO GEOPHONE 4				
MOVE 25 FT SE, PHOTO GEOPHONES 2 & 3		REMOVE WRENCH		
TURN AND PHOTO GEOPHONE 1		SET DRILL ASIDE		
TURN AND PHOTO GEOPHONE 4		DEEP CORE RECOVER		
TAKE PAN 3' BEHIND GEOPHONE 3		GET CAPS FROM RACK, PLUG TOP		
RETRIEVE GNOMON, RETURN TO C/S TAKING OTHER PHOTOS REQD TO DOCUMENT GEOPHONES		GET TREADLE & NEUTRON FLUX PROBE FROM LRV, ALSO RAMMER TGE-PRESS 'GRAV'		
ACTIVATE LSPE ENABLE SW - STOW GNOMON ON LRV		INSTALL JACK ON TREADLE, EXTEND HNDL & PLACE TREADLE OVER CORE STEM		
		RAM TOP PLUG		
		JACK CORE STEM OUT OF SURFACE		
<u>ALSEP PHOTOS</u>				
PHOTO C/S 3', 7' XSUN TO SOUTH	3+20			
PHOTO C/S 7', UPSUN				
PHOTO C/S 7', XSUN TO NORTH				
PHOTO C/S 7', DNSUN				
PHOTO LEAM, 7' TOWARD C/S				
PHOTO LEAM, 3' TOWARD RTG				
PHOTO LSG, 3' XSUN TO NORTH				
PHOTO LSG, 7' UPSUN TOWARD C/S				
PHOTO LSG, 3' XSUN TO SOUTH				
PHOTO HFE W.HOLE, 7' XSUN STEREO TO SOUTH		PLUG BIT END OF CORE STEM - RAM LAY STRING AGAINST RACK		
PHOTO HFE 11' DNSUN		CONFIG NEUTRON FLUX		
PHOTO HFE ELECT, 7' XSUN		ACTIVATE LOWER SECTION		
PHOTO HFE ELECT, 3' XSUN SOUTH		HANG CAP ON RACK		
PHOTO HFE E.HOLE, 7' XSUN STEREO TO SOUTH		MATE LOWER TO UPPER SECTION		
	3+30	ACTIVATE UPPER SECTION		

CREW EVA CUFF CHECKLIST

VOICE DATA

EVA 1

CORE CAP PHOTOS	3+34	Carry core stem/caps/wrench to LRV Ram plugs Disjoint core in 3, 2, 3 Cap ends-rpt caps Stow on LRV TGE - READ -	CDR-22
		If LMP delayed: •Assist in Geo Deploy •Assist in photos	EVA1 11-1-72

3+30

- (1) CDR - CORE STEM CAPS (unless nominal)
 - SECTION 1 LOWER _____
 - SECTION 2 UPPER _____
 - SECTION 2 LOWER _____
 - SECTION 3 UPPER _____

(1) CDR - TGE RDG: _____

3+40

- (1) CDR/LMP - EMU CHECK

	CDR	LMP
02		
FLAGS		
PRESS		
COOL		

- (1) CDR/LMP - MAG/FRAME COUNT

CDR: /
LMP: /

Verify - Gnomon back to LRV

SCB 1 CONTENTS:

- 2 - 20 DSBD (ON CAMERAS)
- 2 - CAP DISPENSERS
- 3 - CORE TUBES: 2 L 44,46
 1 U 31
- 4 - SETS LRV SAMPLER BAGS

- (1) CDR - SCB _____ 2 on LMP PLSS

3+50

GEO PREP SEP FILE	3+39	GEO PREP Configure EVA maps Config LRV Sampler if not done Hold still [LOAD PLSS]	LMP-26
		SCB 1 to CDR PLSS Change cam mag (G) Stow LMP cam under LMP seat	EVA1 11-1-72

GEO PREP SEP FILE	3+41	GEO PREP Mount 20 Bag Disp (SCB 1) to each cam •LMP cam to LMP seat •CDR cam to CDR floorpan Cap Disp (SCB 1) to gate Stow LMP PLSS [HOLD STILL] •Cap Disp (SCB 1) •Hammer •Hammer •SCB 2 LMP to secure SCB 1 Mount CDR cam Tether tongs	CDR-24
			EVA1 11-1-72

MISSION: APOLLO 17
 EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
	3+30	PUSH UNIT DOWN CORE HOLE		
PHOTO NFE IN SITU, 7' TO S				
PHOTO LMS, 3' XSUN TO S				
INCLUDE ORIFICE				
PHOTO LMS, 7' TOWARD C/S				
		<u>BREAK CORE STEMS</u>		
		CARRY TO LRV:		
		CORE CAPS WRENCH		
TAKE PHOTO PAN AT C/S		USE WRENCH & VISE TO LOOSEN 3RD STEM JOINT		
		LOOSEN SIXTH JOINT		
		UNSCREW & CAP EACH SECTION		
PUT CAM ON CDR SEAT				
<u>CONFIG FOR TRAVERSE</u>		READ TGE TO MCC		
LOAD LRV SAMPLER WITH DIXIE CUPS IF RQD				
ASSIST CDR IF RQD	3+40	STOW ON LRV <u>CONFIG FOR TRAVERSE</u>		
		MOUNT 20 DSBD (SCB 1) TO EACH CAM		
MOUNT MAP HOLDER - CONFIG MAPS		PUT CDR CAM ON PAN, LMP CAM ON LMP SEAT		
		PUT CAP DISPENSER ON TOOL GATE		
<u>LOAD PLSS'S</u>		<u>LOAD PLSS'S</u>		
HOLD STILL		STOW RAMMER ON LMP PLSS		
		STOW HAMMER ON LMP PLSS		
		STOW CAP DISPENSER ON LMP PLSS		
	3+50	STOW SCB 2 ON LMP PLSS		

CREW EVA CUFF CHECKLIST

VOICE DATA

EVA 1

3+50

CDR-29	3+52	LRV NAV INIT Mode sw - T - (PM1/WB) LM TV cam +15 vdc sw - PRIM - NAV INITIALIZE	WALK LM	SEP PREP GEO PREP
	3+57	ALSEP TO SEP SITE VIA LM Drive to LM - Rpt: • Bearing, Dist., Range Drive to SEP site • (>100m E) +15 vdc sw - OFF - Rpt: Bearing, Dist., Range, Amp Hrs & Temps NAV: RESET then OFF LGA = 150	WALK TO DEPLOY SITE GET EP 6	

(1) LMP - SCB 1 ON CDR PLSS
- CAMERA UNDER SEAT

- (1) CDR - NAV INITIALIZE
- NAV CB - CLOSE (1.5 MIN SPINUP)
 - NAV RESET - THEN OFF (RESET SW)
 - HEADING _____
 - SSD _____
 - PITCH _____
 - ROLL _____

BEARING/RANGE = 0
TORQUE GYRO _____
LRV UNDERWAY

(1) CDR - LRV at LM →

HEADING	
BEARING	
DISTANCE	
RANGE	

(1) CDR - AT SEP SITE

LRV DATA:

NAV RESET -
THEN OFF
(RESET SW)

HEADING		Temp Bat 1	
BEARING		Temp Bat 2	
DISTANCE		Temp LF mtr	
RANGE		Temp RF mtr	
Amp-Hr Bat 1		Temp LR mtr	
Amp-HR Bat 2		Temp RR mtr	

4+00

CDR-29	3+53	SEP XMTR DEPLOY PREP Get core stems Walk to LM Lay core stems on #2 struts • Shade Unstow SEP Xmtr Walk to SEP site, ~100m E Deploy and lock Xmtr legs Place Xmtr on surface Upon CDR arrival: • Get EP 5 • Mount LMP cam (LMP seat)	NAV INIT	SEP PREP GEO PREP
	11-1-72			

(1) LMP - EP #6 OFF PALLET
VERIFY SAFE

(1) CDR - LGA AZIMUTH 150°
(1) CDR - LRV UNDERWAY MARK _____

4+10

MISSION: APOLLO 17
EVA: 1

DATE: NOV. '72

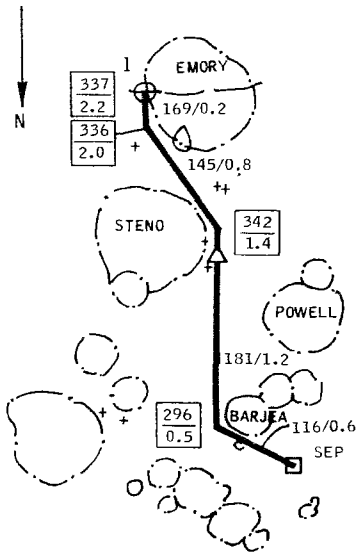
LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
	3+50			
PLACE SCB 1 ON CDR PLSS		HOLD STILL		
STOW LMP CAM UNDER SEAT (LMP)		<u>LRV NAV INITIALIZATION</u>		
PICK UP CORE STEMS (IN BAG)		LCRU MODE SW 'POS 1' (PM1/WB)		
WALK TO LM		POS TV HORIZ CW & AFT		
		MOUNT LRV - FASTEN SEATBELT		
		POWER UP LRV		
		ORIENT LRV FOR NAV INIT.		
		LRV NAV CB - 'CLOSE'		
		NAV RESET - 'RESET' - 'OFF'		
<u>SEP XMTR DEPLOY PREP</u>		READ HEADING, SSD, PITCH, ROLL		
PLACE CORE STEMS ON +Z STRUTS		VERIFY BEARING, RANGE = 0		
		TORQUE GYRO TO HOU		
UNSTOW SEP TRANSMITTER		UPDATE		
		<u>SEP XMTR DEPLOY SITE</u>		
CARRY SEP XMTR TO DEPLOY SITE >100 M E OF LM		DRIVE TO SEP DEPLOY AREA >100 M EAST OF LM		
	4+00			
DEPLOY & LOCK XMTR LEGS IN POSITION		POWER DOWN LRV		
PLACE XMTR ON SURFACE		REPOSITION LGA TO H		
GET EP 6 FROM GEOPALLET		REPORT NAV DATA SYSTEM		
VERIFY 'SAFE'		RESET NAV SYSTEM		
PUT ON LMP CAMERA		POSITION LGA 150°		
MOUNT LRV WITH EP 6		POWER UP LRV		
RIDE TO STATION 1		DRIVE TO STATION 1		
	4+10			

CREW EVA CUFF CHECKLIST

VOICE DATA

EVA 1

11-1-72	COP-27	4+06 TRAV TO STA 1-23 min(116/2.8) • NO LRV Photos • MEI - variatn, pat gnd • Blk - types, distributn 296/0.2 View BARJEA ▲ 340/1.2 EP 6 • Partial pan 342/1.3 STENO rim, blocks 340/1.6 hi pt - sta 1 view 339/1.8 poss view N wall cone 338/2.0 gully - EMORY interior 337/2.0 20 m Cra to left	TRAV STN TO ANVL
	EVA1	4+29 337/2.2 STA 1 (66 min) Park - E rim hi pt, H = 180 [STOP] Mode sw - 2 - (FM/TV) Dust; HGA Gnomon/Rake TGE - GRAV - Scoop	



HISTORICAL SEQUENCE OF DARK MANTLE & CHARACT OF PLAINS MAT'L

11-1-72	LMP-29	4+06 TRAV TO STA 1-23 min(116/2.8) • NO LRV Photos • MEI - variatn, pat gnd • Blk - types, distributn 296/0.2 View BARJEA ▲ 340/1.2 EP 6 • Partial pan 342/1.3 STENO rim, blocks 340/1.6 hi pt - sta 1 view 339/1.8 poss view N wall cone 338/2.0 gully - EMORY interior 337/2.0 20 m Cra to left	TRAV STN TO ANVL
	EVA1	4+29 337/2.2 STA 1 (66 min) Park - E rim hi pt, H = 180 [STOP] Mode sw - 2 - (FM/TV) Dust; HGA Gnomon/Rake TGE - GRAV - Scoop	

4+10

(1) LMP - EP #6 - SAFE

(1) LMP - EP #6 PINS PULLED _____

(1) CDR - NAV DATA:

HEADING	
BEARING	
DISTANCE	
RANGE	

(1) LMP - Rpt 70mm mag/frame _____

4+20

(1) CDR - STATION 1 ARRIVAL _____

4+30

MISSION: APOLLO 17
EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	L C R U I V	TASK FUNCTION	
				L M P	C D R
	4+10				
PHOTO APPROACH CHECK EP DISPLAY 'SAFE' PULL 3 PINS (DISCARD PINS) EXTEND EP ANTENNA PLACE EP ON SURFACE OUTSIDE TRACKS SHOOT PART PAN		PHOTO APPROACH STOP LRV POWER DOWN LRV REPORT NAV DATA SHOOT PART PAN POWER UP LRV			
	4+20				
GO TO STA 1		GO TO STA 1			
STATION 1		STATION 1 POWER DOWN LRV			
	4+30				

EVA 1

4+30

(1) CDR - LRV DATA:

HEADING	Temp Bat 1
BEARING	Temp Bat 2
DISTANCE	Temp LF mtr
RANGE	Temp RF mtr
Amp-Hr Bat 1	Temp LR mtr
Amp-HR Bat 2	Temp RR mtr

(1) CDR/LMP - TGE - GRAV

(1) CDR - Verify Dusting

(1) CDR/LMP - MAG/FRAME

CDR - /
 LMP - /

(1) CDR/LMP - Pan locations

(1) CDR/LMP - EMU CHECK

	CDR	LMP
02		
FLAGS		
PRESS		
COOL		

4+40

(1) CDR/LMP - RAKE SAMPLE:

ROCKS BAG# _____

SOIL BAG# _____

11-1-72	EVA1	CDR-29	STA 1 (66 MIN) 337/2.2	STA 1
			OBSERVATION • Contacts - mtl, mtl/subflr • Blks - otc, variety • Mtl Sources - EMORY wall • Mtl vs Blks - dynamics • Misc - xenos, alter, gls SUBFLR • Doc spl - blk types, tex, old reg • Rake - btw blk, relate blks • (Soil spl on blk top) CONTACTS • Trench - sequence • Dbt core - in youngest VERY DARK DARK • Rake • Doc spl • Doc spl PANS	

4+50

MISSION: APOLLO 17
 EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
DISMOUNT FROM LRV	4+30	REPORT NAV & SYSTEM DATA		
		DISMOUNT FROM LRV		
TAKE PHOTO PAN		LCRU MODE SW '2'		
		ALIGN HGA		
GET GNOMON & SCOOP FROM AFT PALLET		DUST TV, TCU, LCRU		
		PRESS GRAV ON TGE		
		VERIFY LIGHT FLASHING		
		GIVE MCC 'MARK'		
OBSERVATIONS		OBSERVATIONS		
PHOTOS		PHOTOS		
RAKE SAMPLE		RAKE SAMPLE		
	4+40			
DOCUMENTED SAMPLING		DOCUMENTED SAMPLING		
	4+50			

EVA 1

4+50

5+00

(1) CDR/LMP - CORE TUBE NO'S

5+10

MISSION: APOLLO 17
 EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
	4+50			
DOCUMENTED SAMPLES		DOCUMENTED SAMPLES		
	5+00			
DOUBLE CORE		DOUBLE CORE		
(SOME PLACE DURING STATION - IN A YOUNG CONTACT)				
	5+10			

EVA 1

5+10

EVA 1	CDR-31	STA 1 CLOSEOUT ▲ Deploy EP 5 • Locator photo to LRV • Include in a pan Get EP 7 TGE - READ - TV cam; Mode sw - 1 -(PM1/WB) LGA = 330 (frame, tools)	TRAV TO SEP
		5+35 TRAV TO SEP-21 min (349/2.8) • LRV photos Mtl • Blks - variatn • Mtl - variatn, dynamics 336/2.0 N wall cone 347/1.6 STENO Crater ▲ 320/0.7 EP 7 • Partial pan • TRIOENT - source, xenos 296/0.3 View BARJEA	

5+20

(1) CDR/LMP - EMU CHECK

	CDR	LMP
02		
FLAGS		
PRESS		
COOL		

(1) LMP - EP #5 - SAFE

(1) LMP - EP #5 PINS PULLED _____

(1) LMP - EP #7 OFF PALLET

VERIFY SAFE

(1) CDR/LMP - MAG/FRAME

CDR _____/_____

LMP _____/_____

5+30

(1) CDR/LMP - TGE RDG _____

MISSION: APOLLO 17
EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	L C R U T V			TASK FUNCTION	
			L	M	P	C	D
DOCUMENTED SAMPLES	5+10	DOCUMENTED SAMPLES					
	5+20						
TAKE EP #5 OFF PALLET CHECK EP DISPLAY - 'SAFE'							
PULL PINS(3) DISCARD PINS							
DEPLOY ANTENNA							
PLACE EP ON SURFACE PHOTO LOCATOR TO LRV GET EP #7 OFF PALLET CHECK EP DISPLAY - 'SAFE'							
PLACE EP #7 ON LMP FOOTPAN							
PHOTO PAN							
REPORT FILM COUNTER		REPORT FILM COUNTER					
STOW SAMPLES, SCOOP, RAKE, GNOMON	5+30	PRESS 'READ' ON TGE					

EVA 1

5+30

(1) CDR - LGA AZIMUTH 330°

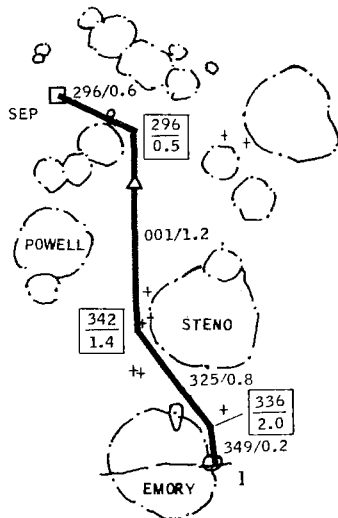
(1) CDR - LRV UNDERWAY
MARK _____

CAPCOM: REMIND CREW DEPLOYED EXPLOSIVE
PACKAGE ON RETURN PATH

5+40

(1) CDR/LMP - LRV: SPEED _____
AMPS _____

11-1-72	EVA 1	STA 1 CLOSEOUT ▲ Deploy EP 5 • Locator photo to LRV • Include in a pan Get EP 7 TGE - READ - TV cam; Mode sw - 1 - (PM1/WB) LGA = 330 (frame, tools)	DEF. OF TABLE
		CDR-31 5+35 TRAV TO SEP-21 min (349/2.8) • LRV photos M1 • Bks - variatn • Mt1 - variatn, dynamics 336/2.0 N wall cone 341/1.6 STENO Crater ▲ 320/0.7 EP 7 • Partial pan • TRIDENT - source, xenos 296/0.3 View BARJEA	



(1) LMP - EP #7 SAFE

(1) LMP - EP #7 PINS PULLED _____

(1) CDR - NAV DATA:

HEADING	
BEARING	
DISTANCE	
RANGE	

5+50

MISSION: APOLLO 17
EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
	5+30	REPORT READING TO MCC		
		CLOSE LID		
		LCRU MODE SW - '1'		
		POSITION TV AFT, HORIZ		
MOUNT LRV - PUT EP 7 ON LAP		MOUNT LRV		
FASTEN SEATBELT		FASTEN SEATBELT		
		POSITION LGA 330°		
		POWER UP LRV		
RETURN TO LM AREA (SEP SITE)		RETURN TO LM AREA (SEP SITE)		
	5+40			
PHOTO APPROACH		PHOTO APPROACH		
CHECK EP DISPLAY 'SAFE'		STOP LRV		
PULL 3 PINS (DISCARD PINS)		POWER DOWN LRV		
EXTEND EP ANTENNA				
		REPORT NAV DATA		
PLACE EP ON SURFACE OUTSIDE TRACKS				
	5+50	SHOOT PART PAN		

CREW EVA CUFF CHECKLIST

VOICE DATA

EVA 1

SEP XMTB	5+58	Arrive SEP site (Xmtr)	CDR-32 EVA 1 11-1-72
		+15 vdc sw - OFF -	
		LMP dismount	
		Hou: Nav, Amp Hrs & Temps	
		Position LRV, H = 090	
		NAV: RESET then OFF	
		Drive LRV:	
		H Dist	
		090 0.1	
		210 0.1	
	360 0.2		
	Park H = 180		
	+15 vdc sw - OFF -		
	Mode sw - 3 - (TV Rmt)		
	Dust: HGA		
	TGE - GRAV -		
	WaTk to SEP Xmtr		

5+50

(1) LMP - Rpt 70mm mag/frame

(1) CDR - REPORT ARRIVAL SEP SITE

(1) LMP - CAMERA UNDER SEAT

(1) CDR - NAV RESET, THEN RESET SW OFF

(2) LMP - SEP SITE DESCRIPTION

6+00

SEP XMTB CLOSEOUT	6+58	SEP XMTB DEPLOY	LMP-34 EVA1 11-1-72
		Dismount at SEP Xmtr	
		LMP can under LMP seat	
		Describe location, TRACK LAYOUT	
		prominent features	
		Walk to track crossing w/Xmtr	
		Release ant reel retainers	
		Align diagonals, shadow- graph in sun quadrant	
		Deploy reel #2 W	
		*Pose for CDR	
	Deploy reel #4 N		
	*Pose for CDR		
	Level & align Xmtr		
	+200 on shadowgraph		
	Deploy Carry Handle		
	Remove thermal cover		
	Deploy Solar Panels		
	Verify level & align		
	Place Xmtr sw -STBY-		

(1) CDR - TGE GRAV

6+10

MISSION: APOLLO 17
EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
SHOOT PART PAN	5+50	POWER UP LRV		
CONTINUE TO SEP SITE		CONTINUE TO SEP SITE		
		GO NEAR SEP XMTR		
<u>SEP SITE</u>		<u>SEP SITE</u>		
DISMOUNT LRV PLACE CAM UNDER SEAT		STOP LRV POWER DOWN LRV, VERIFY LMP CLEAR POWER UP LRV, DRIVE 0.1 W OF LMP		
DESCRIBE AREA PROMINENT FEATURES TO MCC AS CDR DRIVES LAYOUT	6+0	H = 090° NAV RESET CONTINUE ON CONSTANT HEADING 0.1 KM COME RIGHT TO HEADING 210° CONTINUE ON 210° FOR 0.1 KM COME RIGHT TO HEADING 360° CONTINUE ON 360° FOR 0.2 KM*		
MOVE XMTR TO TRACK CROSSING		PARK LRV ON H = 180° POWER DOWN LRV		
RELEASE ANT REEL RETAINERS & DISCARD		DISMOUNT LRV LCRU MODE SW - '3'		
PLACE XMTR ON CROSSING WITH SHADOWGRAPH IN SUN QUAD		ALIGN HGA		
REMOVE REEL 2 & DEPLOY ANTENNA WEST ALONG LRV TRACK		DUST TV, TCU, LCRU PRESS TGE 'GRAV' WALK TO SEP XMTR		
		REMOVE REEL 1 & DEPLOY ANTENNA EAST ALONG LRV TRACK		
	6+10			

*THESE MANEUVERS PROVIDE
ORTHOGONAL LAYOUT FOR SEP
ANTENNA

CREW EVA CUFF CHECKLIST

VOICE DATA

6+05 SEP XMTR DEPLOY
 Deploy reel #1 E
 Photograph ant, Xmtr & LMP
 *F11, 74', 1/250
 Deploy reel #3 S
 Photograph ant, Xmtr & LMP
 *F8, 74', 1/250
 Take locator photo to LM
 TGE - READ -
 TRAV TO LM

6+20 EVA 1 CLOSEOUT
 Park LRV 30' NW of MESA,
 H = 012
 STOP + Volts
 LMP to remove SCB 1 [SCB 1
 Cam to CDR seat [TO GATE
 HGA
 Offload LMP PLSS [HOLD
 *Core cap disp to [STILL
 LMP underseat
 *Tools
 SCB 2 to +2 pad

6+58 SEP XMTR DEPLOY
 DTsmount at SEP Xmtr
 LMP cam under LMP seat
 Describe location, TRACK
 prominent features LAYOUT
 Walk to track crossing w/Xmtr
 Release ant reel retainers
 Align diagonals, shadow-
 graph in sun quadrant
 Deploy reel #2 W
 *Pose for CDR
 Deploy reel #4 N
 *Pose for CDR
 Level & align Xmtr
 *Zero on shadowgraph
 Deploy Carry Handle
 Remove thermal cover
 Deploy Solar Panels
 Verify level & align
 Place Xmtr sw -STBY-

6+20 EVA 1 CLOSEOUT
 Cam to Footpan
 Get CDR SCB 1
 Read SEP Rcvr temp
 To LMP underseat:
 *Unused SCB 1 equip
 LRV samples to SCB 1
 LMP cam, maps to CDR seat
 SCB 1 to gate
 Hold Still REMOVE &
 STOW
 TOOLS,
 SCB 2
 Underseat samples to Big Bag
 Core stem bag to
 Ladder & pack
 Stow Containment
 bag pkg in ETB

ETB Contents:

Mag (A) (B) (C) (G)

2 CAMS (R)

Maps

Sample Containment Bags

(1) CDR/LMP - LRV Samples Location
 FSR's

EVA 1

6+10

(1) LMP - SEP XMTR
 LEVEL _____
 ALIGNMENT _____
 PANELS DEPLOYED _____
 SW - STDBY _____

(1) CDR/LMP - TGE RDG -----

6+20

(1) CDR - ARRIVAL AT LM _____

(1) CDR - LRV Data

HEADING		Temp Bat 1	
BEARING		Temp Bat 2	
DISTANCE		Temp LF mtr	
RANGE		Temp RF mtr	
Amp-Hr Bat 1		Temp LR mtr	
Amp-Hr Bat 2		Temp RR mtr	

Volts: (1) _____ (2) _____

(1) CDR/LMP - EMU CHECK

(1) LMP - SEP Temp _____

(1) CDR/LMP - MAG/FRA

CDR: ____/____

LMP: ____/____

	CDR	LMP
O2		
FLAGS		
PRESS		
COOL		

SRC 1 CONTENTS:

SCB 1

ORGANIC CONTROL SAMPLE

(1) LMP - Mag/frames ____/____
 ____/____
 ____/____

MISSION: APOLLO 17

EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
STAND BEHIND REEL FOR CDR PHOTO	6+10	STAND BEHIND REEL - PHOTO REEL, XMTR, LMP f11, 1/250, 74'		
RETURN TO XMTR		RETURN TO XMTR		
REMOVE REEL 4 & DEPLOY ANTENNA NORTH ALONG LRV TRACK		REMOVE REEL 3 & DEPLOY ANTENNA SOUTH ALONG LRV TRACK		
STAND BEHIND REEL - FOR CDR PHOTO		STAND BEHIND REEL - PHOTO REEL, XMTR, LMP f8, 1/250, 74'		
RETURN TO XMTR		RETURN TO LRV		
ALIGN & LEVEL XMTR (ZERO ON SHADOW GRAPH)				
DEPLOY CARRY HANDLE REMOVE & DISCARD THERMAL COVER - DEPLOY SOLAR PANELS		GO TO LRV, READ TGE		
VERIFY ALIGNMENT		MOUNT LRV		
PLACE XMTR SW - 'STNDBY'		POWER UP LRV		
RETURN TO LM		DRIVE TO LM		
<u>TRAV TERMINATION</u>	6+20	<u>TRAV TERMINATION</u>		
		PARK LRV 30 FT NW OF MESA H = 012 + 15 VDC SW - OFF -		
		ADJUST LGA		
		READ OUT ALL LRV DISPLAYS ON CONSOLE		
READ SEP RCVR TEMPERATURE		DISMOUNT LRV		
REMOVE SCB 1 - PLACE ON GATE		PLACE 70MM CAM ON CDR SEAT		
XNSFER UNUSED EQUIP TO LMP UNDERSEAT		POINT HGA TO EARTH		
XNSFER LRV SAMPLES TO SCB 1		REMOVE TOOLS FROM LMP PLSS TOOL HARNESS		
ASSIST CDR TO REMOVE & STOW TOOLS FROM PLSS		STOW TOOLS ON GEO GATE		
<u>EVA-1 CLOSEOUT (LMP)</u>		<u>CLOSEOUT PREP</u>		
PUT UNDERSEAT SAMPLES IN SRB	SCB 2 TO +Z PAD			
TAKE CORE BAG TO LADDER	SCB 1 TO MESA TABLE			
PACK CORE STEMS IN BAG CARRY TO PORCH & STOW AGAINST LM	OPEN SRC 1			
STOW SAMPLE CONTAINMENT PKG	PLACE SCB 1 IN SRC (POCKETS UP)			
TRANSFER ETB TO LRV-CDR FOOTPAN	REMOVE SRC SKIRT & DISCARD			
STOW 70MM CAM IN ETB(2)	REMOVE SEAL PROTECTOR & CLOSE & SEAL SRC (SEAL CLEAR OF BAG MAT'L)			
STOW MAPS IN ETB (CDR SEAT)	<u>EVA-1 CLOSEOUT (CDR)</u>			
TRANS 70MM MAGS FROM UNDER CDR SEAT TO ETB (READ FRAME COUNT EACH MAG)				
TAKE MAG OFF 500 MM CAM				
RESTOW CAM UNDER SEAT				
ATTACH ETB TO LEC	6+30			

CREW EVA CHECKLIST

VOICE DATA

EVA 1

CDR-35	SCB 1 to SRC 1, [ETB] pockets up Remove skirt & seal protector Close & seal SRC 1 •Verify good seal •Place SRC in +Z pad LRV cb's Bus A,B,C,D -Open LCRU pwr sw - OFF - Dust TV, TCU, Batt covers Open Batt covers Dust Batts if dirty Dust LCRU LCRU bkts open - 65% Final LRV Check • Batt covers open • LCRU blinks open 65% • Samples off • Equip stowed	L1015070
EVA 1		
11-1-72		

EVA PERM	Dust SEP Rcvr • Blankets A & B - Open VERIFY: • Pwr sw - OFF - • Rcdr - OFF - Offload TGE to R. side of MESA, IN SHADE • Take dust brush TGE - GRAV - 6+37 Dust EMU's • Stow PLSS ants (CDR/LMP) Brush to ladder hook EVA-1 pallet to LMP [INGRESS] TGE - READ - then - STBY - Open TGE thermal lid & dust Brush to ladder hook	CDR-36
EVA 1		
11-1-72		

- 6+30 (1) LMP - PALLET 1 LIOH PINS GREEN
- (1) CDR - TGE in shade (verify)
- (1) CDR - TGE GRAV
- (1) CDR - Verify CB's A-B-C-D pulled
Batt Covers - OPEN
LCRU - 65% OPEN
- (1) CDR - Verify Dusting

EVA PERM	ETB to CDR footpan [PACK SRC] Stow ETB: • 2 cams, lenses inboard • 3 mags (rpt mag/frame) • 500 mm mag R (fire 2 frames) • Maps ETB to LEC hook EVA-1 pallet to table • LIOH pins green tidy MESA blankets SCB 2, Core stem bag to porch binhead 6+37 Dust EMU's • Stow PLSS ants (CDR/LMP)	LMP-36
EVA 1		
11-1-72		

- 6+40 (1) CDR/LMP - PLSS Antennas stowed
- TRANSFER ITEMS:
 ETB
 CORE STEMS (in Bag)
 SCB # _____
 SRC 1 (1) LMP - In Cabin
 PALLET 1

LMP-37	Get EVA-1 pallet from CDR INGRESS w/pallet Stow pallet equip. • Food first Hand pallet to CDR Receive & stow • SCB 2 • Core stem bag • SRC 1 • ETB Assist CDR Close hatch 6+57 6+58 Repress	PALLET TO LMP
EVA 1		
11-1-72		

- (1) CDR - TGE Rdg _____
 TBE - STNDBY

6+50

MISSION: APOLLO 17

EVA: 1

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
UNSTOW PALLET 1 FROM MESA - VERIFY PINS GREEN HANG PALLET 1 FROM SEC TABLE TIDY BLANKETS ON MESA	6+30	UNSTOW DUST BRUSH		
CARRY SCB 2 & CORE BAG TO LM PORCH		PULL LRV CB A-B-C-D DUST TV, TCU, BATT COVERS		
RETURN TO SURFACE		OPEN BATT COVERS DUST BATTS IF DIRTY		
		DUST LCRU & SW OFF LCRU BLANKETS - 65%		
		DUST TGE & SEP RECEIVER		
		OPEN BLANKET A AND B		
		OFFLOAD TGE TO R. SIDE OF MESA IN SHADE		
		PRESS GRAV PB - NOTE FLASH IND FOR LEVEL CYCLE		
DUST CDR'S EMU		HAND LMP DUST BRUSH		
HAND DUST BRUSH TO CDR				
		DUST LMP'S EMU		
	6+40			
STOW PLSS ANTENNAS <u>EVA TERM LMP</u>		STOW PLSS ANTENNAS STOW DUST BRUSH <u>EVA TERM LMP</u>		
RECEIVE EVA-1 PALLET FROM CDR		HAND EVA 1 PALLET TO LMP		
INGRESS CABIN WITH EVA-1 PALLET				
SHUT OFF 16 MM CAM - REPOSITION ON BRACKET		GET DUST BRUSH TGE READ, THEN - STBY - OPEN LID (RADIATOR)		
INTERIM STOW EQUIP AS REQD		DUST TGE HANG BRUSH ON HOOK <u>EVA TERM CDR</u>		
HAND EVA-1 PALLET TO CDR		CARRY SRC 1 UP LADDER & STASH ON PORCH		
		RECEIVE & DISCARD EVA - 1 PALLET		
	6+50			

CREW EVA CHECKLIST

VOICE DATA

EVA 1

11-1-72	EVA 1	CDR-37	Final Transfer Check	EVA 1	TERM
		6+57	Close hatch		
		6+58	Repress		

6+50 (1) CDR -
Verify brush stowed

(1) LMP - Hatch Closed _____

7+00 (1) CDR - Cabin Repress _____

11-1-72	EVA 1	LMP-35	6+20 EVA 1 CLOSE OUT	EVA 1	CLOSE OUT
			Underseat samples to Big Bag		

MISSION: APOLLO 17

EVA: 1

DATE: NOV. '72

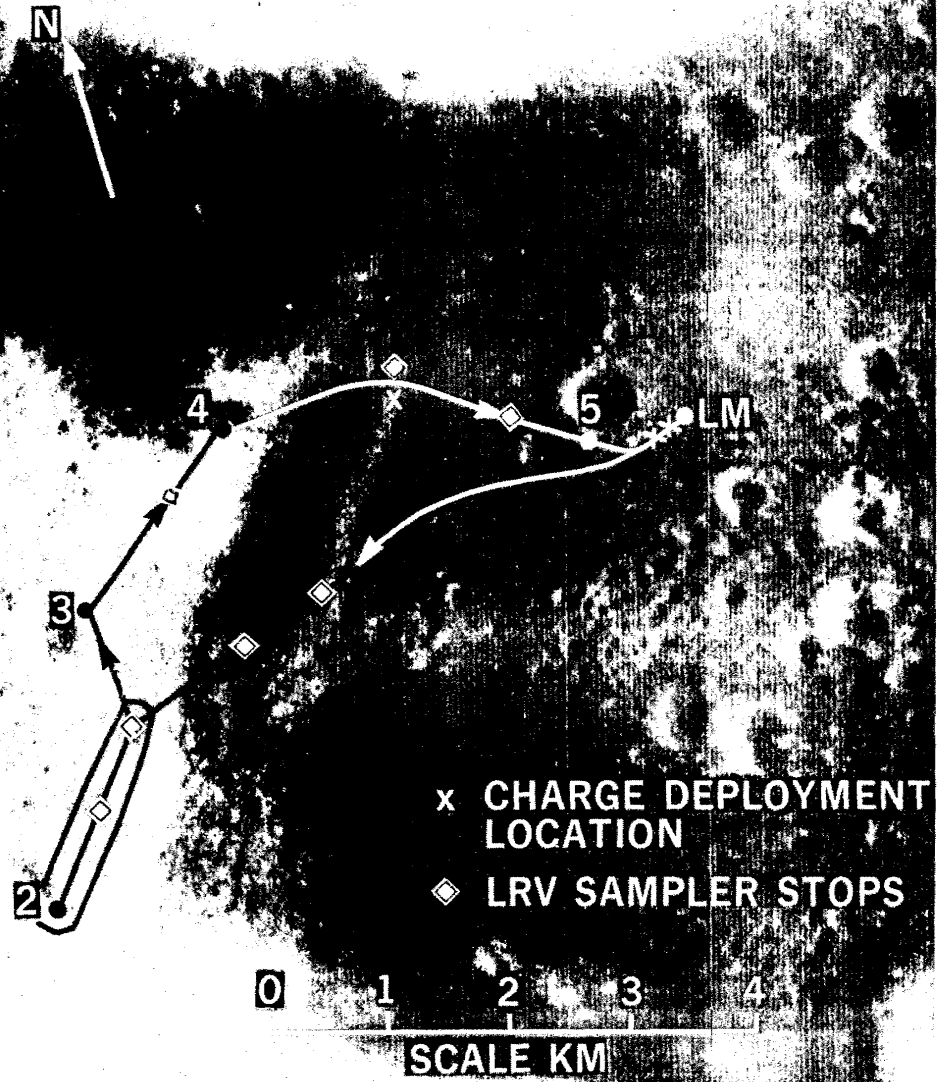
LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	C D R	TASK FUNCTION	
				L M P	C D R
	6+50				
RECEIVE & STOW CORE BAG, SCB 2		HAND IN CORE BAG & SCB 2			
		HAND SRC 1 IN TO LMP			
RECEIVE SRC 1, INTERIM STOW					
		PULL ETB UP WITH LEC HAND IN TO LMP			
RECEIVE ETB FROM CDR					
ASSIST CDR DURING INGRESS		INGRESS LM			
CLOSE HATCH		CLOSE HATCH			
REPRESS OPERATIONS		REPRESS OPERATIONS			
	7+00				

3.2 EVA 2

FIGURE 3.2-1

NASA-S-72-3196-5

EVA 2 LRV TRAVERSE



3.2 EVA 2

3.2.1 EVA 2 - GENERAL DESCRIPTION

EVA 2 begins with depressurization of the spacecraft cabin, followed by CDR egress. The CDR jettisons a bag of equipment no longer needed, then lowers the Equipment Transfer Bag (ETB) to the surface. The LMP follows the CDR soon afterwards. The operations around the LM are mainly devoted to preparing for the second geology traverse. SRC 2 is opened, and its contents made fast to the CDR's PLSS. In like fashion a sample bag is fastened to the LMP. The crew makes a base camp Traverse Gravimeter reading, also places this instrument back on the LRV.

The LCRU is switched to its own power for this EVA, and the spare battery is taken out of the MESA for placement under the CDR seat on the LRV. As before, photographic supplies are located under the CDR seat.

The CDR drives out to the Surface Electrical Properties site, while the LMP walks. The CDR first brings up the LRV navigation system, and then heads for the SEP. He parks near the west leg of the antenna array, heading down sun for a navigational system initialization. All ranges and distances are, as they were on EVA 1, referenced to the SEP transmitter site.

While the CDR is initializing and correcting the navigational system, the LMP takes some photos to document the initial relationship between the LRV (where the SEP receiver-recorder is located) and the SEP transmitter. He then turns on the receiver and takes his place beside the CDR to begin the EVA 2 traverse.

Objectives of the EVA 2 traverse are to investigate and sample the base of the South Massif and the light mantle material of the debris slide, further investigation and sampling of the dark mantle and plains material, emplacement of seismic profiling charges, obtaining traverse gravimeter measurements, and obtaining data for the Surface Electrical Properties Experiment. A short stop is made about 500 feet west of the ALSEP area where a 1/8 pound seismic profiling charge is deployed. En route to station 2 (Figure 3.2-1), two short stops are scheduled (2 minutes each) where samples are taken from the LRV using the LRV sampling device. Approximately 2-1/2 hours of station time are spent on the light mantle material at three major stations (2, 3, and 4) and three short LRV sampling stops.

Proceeding eastward from station 4, there is a short stop at the depression about 1 km east of station 4 where the 6 pound seismic profiling charge is deployed, an LRV sample is collected, and observations

and photographs of the depression are made. Depending upon the crews' assessment, additional time could be invested here at the expense of station 5. An additional LRV sample is collected en route to station 5. Station 5, where approximately 1/2 hour is available, provides a further opportunity for investigating the plains material and dark mantle. The traverse then returns to the LM with an intermediate stop about 250 m west of the ALSEP where a 1/4 pound seismic profiling charge is deployed. The final 44 minutes of EVA 2 are spent in closeout activities in the LM area.

On arrival at the LM, the LRV is parked to maximize battery cooldown between EVA's, and powered down. The CDR, as he has done at each station stop, dusts the communications gear on the front of the LRV and brings up the TV. The LMP shuts off the SEP receiver. Then the two men unload each other's PLSS harnesses of the tools and sample bags they carry. The sample collection bag that came out of the SRC goes back into it, and this box is sealed. The LMP loads the cameras and magazines, maps, and the polarizing filter into the ETB, ready for transfer to the ascent stage. The Traverse Gravimeter is taken off the LRV and placed in the shade of the spacecraft. A final EVA 2 measurement is made. The crewmen dust each other off, and the LMP scales the ladder with an expendables supply pallet. The CDR shuts down the TV, configures the LRV for its between EVA stay. He carries the SRC and the two sample collection bags to the ascent stage and hands them in. Finally, he pulls up the ETB, hands it in to the LMP. He makes a final check that all transfer items are accounted for, and ingresses the cabin, thus closing EVA 2.

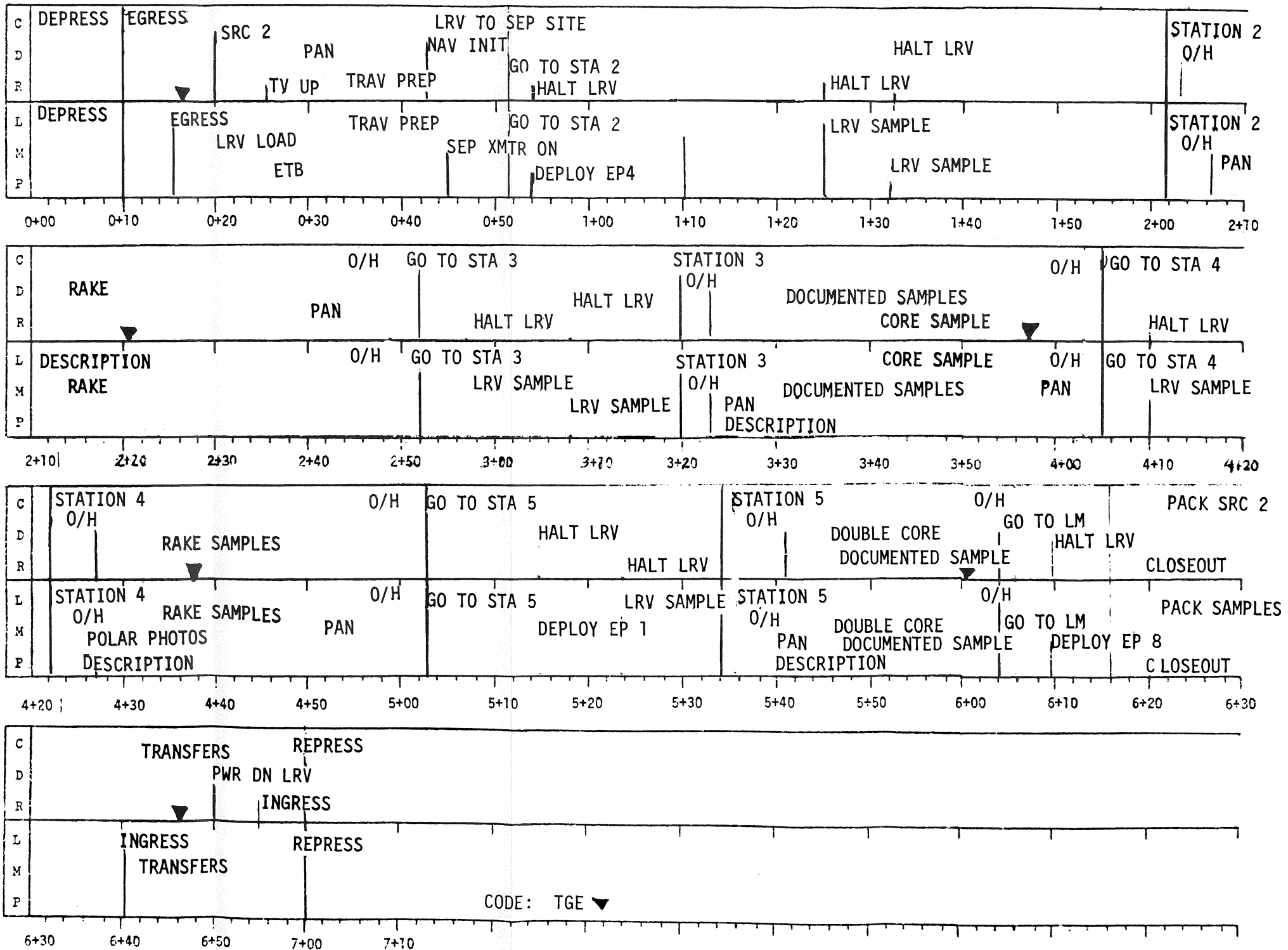
Figure 3.2-2 summarizes this EVA in a block timeline. Figures 3.2-3 through 3.2-6 provide task information for each of the stations planned for this EVA.

FIGURE 3.2-2

APOLLO 17 LUNAR SURFACE TIMELINE

EVA 2

DATE NOV. '72



CODE: TGE ▼

FIGURE 3.2-3 STATION 2 TASKS

EVA 2

Station 2

Station time 0 + 50

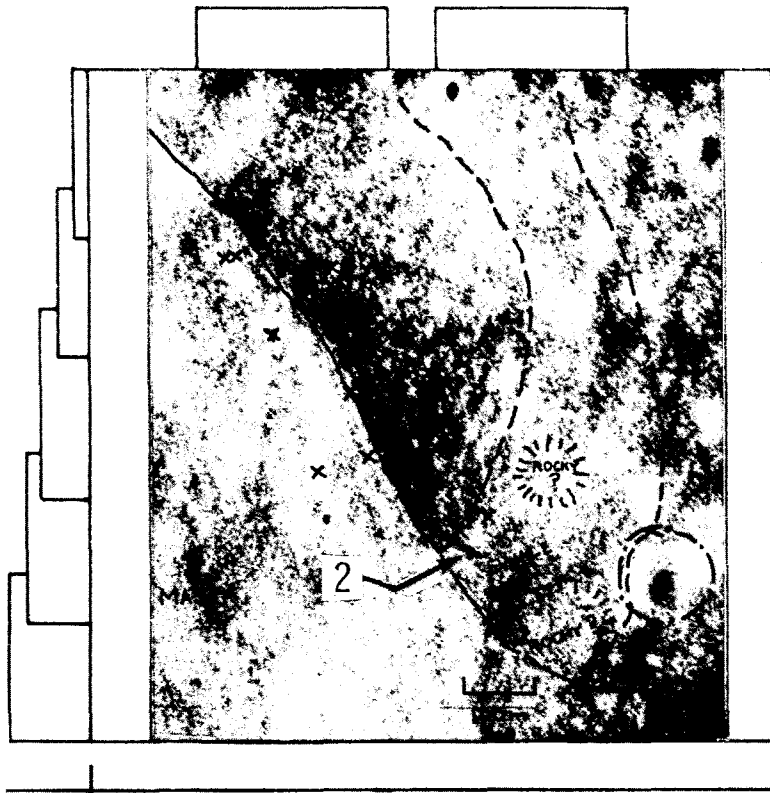
Location: Base of South Massif at contact between South Massif and light mantle

Geologic setting: Massif material underlies the steep mountain face at station 2. Most probably it consists of sheets of breccia ejected from the moon's large basins as they were formed. Faulting related to the Serenitatis event is thought to have uplifted the massif relative to the valley floor. Subsequent movement may also have occurred. However, the lower part of the mountain face is probably covered by talus that buries the bounding fault zone.

Light mantle occurs as a relatively thin ray-like sheet that extends onto the valley floor from the base of the massif. Absence of a likely source crater suggests that the light mantle is not a ray of ejecta. It may be debris from the mountain face deposited by an avalanche fairly late in the history of the landing area.

Objectives:

- Characterize South Massif bedrock as represented by materials at base of slope.
- Characterize light mantle and investigate features indicative of its origin.



TASKS *	RATIONALE
<u>Massif:</u>	
• <u>Documented samples</u> of rocks and soil with special emphasis on blocks with tracks.	• Collect representative sample of massif rock types as represented in talus at base; blocks with tracks most probably derived from massif
• <u>Observe/photograph</u> tracks and block sources	• Documentation of block sources may permit stratigraphic analysis of massif
• <u>Observe/photograph</u> block structures--textures	• Block structures and textures record history of emplacement and deformation of massif materials
• <u>Rake sample</u>	• Statistical sample of lithologic variety in pebble-size fragments in massif talus
• <u>Observe/photograph</u> proximal edge of light mantle	• Documents discrimination between talus and light mantle materials; may show light mantle features indicative of mantle origin
• Relate sample locations to proximal edge of light mantle; collect from above light mantle if possible	• Light mantle, if derived from massif, may represent source distinct from major sources of talus; hence discriminate sampling may permit stratigraphic interpretation of massif materials
• <u>Pan-southeast crest</u> of rim of Nansen crater near base of massif	• Massif-light mantle structures, contact; trough at massif base; blocks near massif base
<u>Light mantle:</u>	
• <u>Documented samples</u> of rocks and soil	• Characterize lithology of light mantle materials (which presumably were derived from south massif); exposure age of light mantle surface; possible sample of Nansen ejecta (could include subfloor or massif materials)
• <u>Rake sample</u> (intercrater area)	• Statistical sample of lithologic varieties in pebble-size fragments for comparison with rake samples from massif and from stations 3 and 4
• <u>Observe/photograph</u> surface structures such as ridges and troughs	• Surface structures may be indicative of emplacement mechanism
• <u>Trench</u>	• Internal structures may provide evidence of mode of emplacement of light mantle
• <u>Observe/photograph</u> layering or other structure in trench walls	
• <u>Pan</u> from rim of Nansen crater 50(?) m away from intersection of rim with massif	• Stereoscopic view (with pan 1) of lower massif, trough and boulders near massif base; surface structures on light mantle.

* Considered to be an all inclusive chopping list of tasks if time were available. The station timeline which follows presents the particular tasks (and time allocation) which were selected as the nominal station activities.

EVA 2

Station 2 timeline

0 + 50

	CDR	LMP
Initial overhead	5	5
Observation	10	10
•Blocks, tracks and sources		
•Blocks, structures and textures		
•Massif/light mantle contact		
•Light mantle, surficial and internal structure		
•Regolith		
Massif	21	21
•Documented sampling-emphasis on blocks with tracks		
•Rake/soil (kg)		
•Pan		
Light mantle	10	10
•Documented sampling-rocks		
•Rake/soil (intercrater area)		
•Pan		
Final overhead	<u>4</u>	<u>4</u>
	50	50

FIGURE 3.2-4 STATION 3 TASKS

EVA 2

Station 3

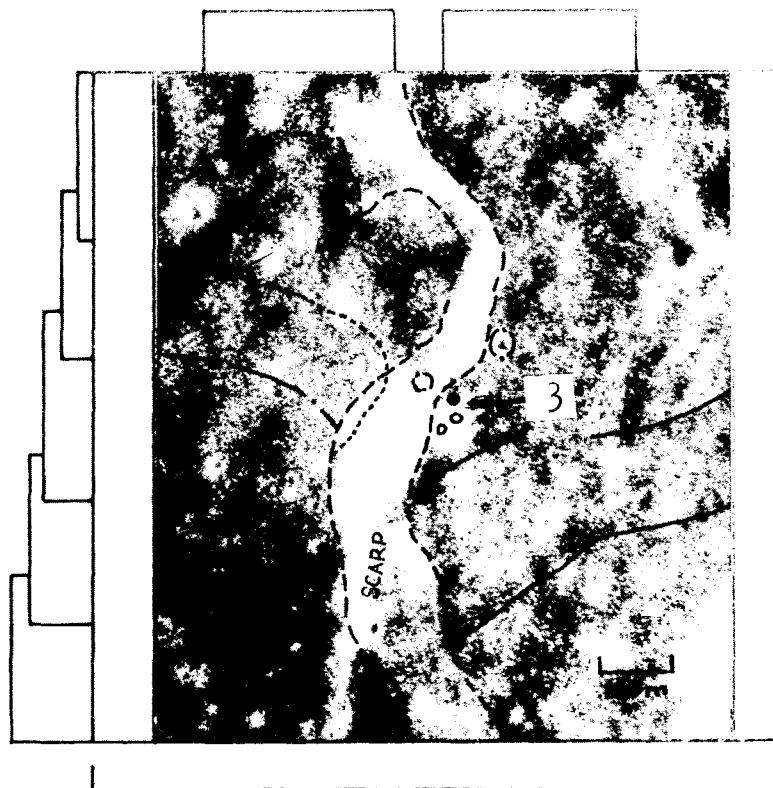
Station time 0 + 45

Location: Base of scarp approximately halfway from station 2 to station 4.

Geologic setting: Light mantle apparently veneers the scarp, which may be the topographic expression of a fault, upthrown on the west. Presence of the scarp when the light mantle was emplaced may have produced depositional structures in the light mantle that can be used to interpret its origin. Ledges or blocks representing the bedrock underlying the scarp face may be accessible although none are recognized in pre-mission photographs. Two fresh craters, 15 and 20 m in diameter penetrate the surface of the light mantle near the base of the scarp.

Objectives:

- Sample central part of light mantle near base of scarp.
- Examine and sample scarp to determine interrelations and chronology of scarp and mantle materials.



TASKS *

RATIONALE

Light mantle:

- | | |
|---|---|
| • <u>Documented samples</u> of rocks and soil | • Characterize lithology of light mantle materials (presumably these were derived from South Massif); exposure age of light mantle surface. |
| • <u>Rake sample</u> (inter-crater area) | • Statistical sample of lithologic varieties in pebble-size fragments for comparison with samples from stations 2 and 4. |
| • <u>Double core</u> in undisturbed surface near base of scarp (lower section goes in CSVG) | • Regolith development; detailed stratigraphy of upper meter of light mantle; possible volatiles in fault zone. |
| • <u>Radial sample</u> 15-20 m fresh crater | • Stratigraphy of upper 3 to 4 m of light mantle. |
| • <u>Pan</u> near 15-20 m fresh crater | • Location; character of scarp, light mantle surface, and sampled crater. |
| • <u>Observe/photograph</u> surface structures, textures, and fragment distribution; note apparent relations to scarp | • May indicate mode of emplacement of light mantle. |
| • <u>Trench</u> in undisturbed surface of light mantle | • Internal structures may indicate emplacement mechanism for light mantle; regolith thickness--relative age by comparison with regolith on dark mantle. |
| • <u>Observe/photograph</u> layering or other structure in trench walls | |

Scarp:

- Observe/photograph (flight-line surveys) surface structures, textures, and fragment distribution.
- Documented samples of scarp materials--may be desirable to observe and sample at small fresh crater.
- Trench - Observe/photograph layering or other structures in trench walls
- Pan near scarp base
- Characterize scarp and forming its surface; chronology of scarp and mantle units; origin of mantle units.
- Scarp (or small fresh crater in scarp face) may expose (or excavate) materials older than the light mantle (e.g. dark mantle or sub-floor). Occurrence of such materials at or near scarp face bears on chronology of scarp and mantle units and on mechanisms of scarp and mantle origins.
- Stratigraphy; origin of scarp face; origin of light mantle.
- Scarp and light mantle features; stereoscopic view with previous pan.

* Considered to be an all inclusive shopping list of tasks if time were available. The station timeline which follows presents the particular tasks (and time allocations) which were selected as the nominal station activities.

EVA 2

Station 3 timeline

0 + 45

	CDR	LMP
<u>Initial overhead</u>	5	5
<u>Observation</u>	5	5
•Distinguish light mantle and scarp materials		
•Chronology of scarp and light mantle (light mantle draping?, faulted?)		
•Depositional features of mantle on surface and in exploratory trenches; regolith development		
<u>Light mantle</u>	29	14
•Documented sampling (possible radial sampling) - rim of 20 m bright crater		
•Rake/soil (inter-crater area)		
•Pan		
•Double core by CDR near scarp base; lower section goes in CSVC		
<u>Scarp</u>	2	17
•Exploratory trench; documented sampling (by LMP)		
•Flight-line survey		
•Pan		
<u>Final overhead</u>	4	4
	<u>45</u>	<u>45</u>

FIGURE 3.2-5 STATION 4 TASKS

EVA 2

Station 4

Station time 0 + 40

Location: Dark halo crater at distal end of light mantle.

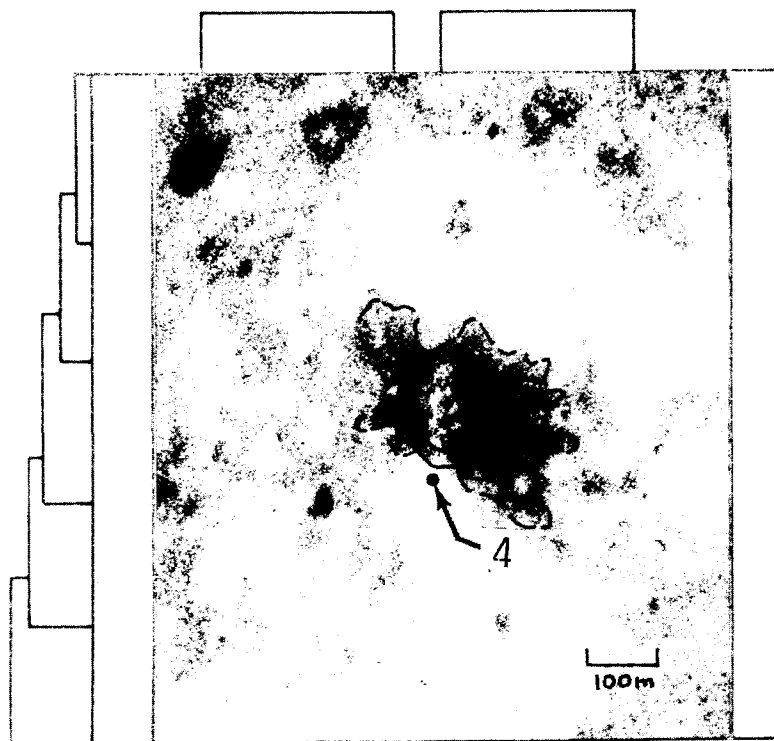
Geologic setting: A rayed, 110 m, dark halo crater is superimposed on the distal end of the light mantle. It seems likely that the crater was formed by impact and excavated thick dark mantle from below the light mantle. The crater floor is flat, benched, very rough, and is apparently covered by dark mantle material. This floor may represent a resistant layer, perhaps the top of the subfloor unit, about 10 m below the general level of the valley floor. No light colored materials or blocks are visible on the crater walls or rim, but subfloor fragments could be present.

Alternatively, the crater could be a vent that produced a small amount of dark mantle material after emplacement of the light mantle.

Several small bright craters occur in the light mantle south of the dark halo crater. They suggest that the light mantle may be as much as 4 m thick in this area. Two small craters nearest the dark halo crater could be in light colored ejecta (overturnd light mantle) of the dark crater.

Objectives:

- Examine dark halo crater to determine its origin and sample its ejecta.
- Examine distal end of light mantle and sample its variety of rock types.



TASKS *	RATIONALE
<u>Dark halo crater:</u>	
• <u>Observe/photograph</u> ejecta, rim, crater interior	• Crater origin; sampling rationale
• <u>Radial sample</u> (dixie cup) 5 sample minimum	• Stratigraphy of dark mantle
• <u>Documented samples</u> - rocks and soil at crater rim (possible rake sample)	• Characterize lithology of dark mantle; possible sample of subfloor material; exposure age of crater
• <u>Double core</u> near edge of dark halo (if impact, core just within dark ejecta; if volcanic, try for one drive tube full of dark ejecta)	• Stratigraphy of ejecta and underlying light mantle
• <u>Pan</u> - crater rim	• Crater structures; scarp
• <u>Polarimetry</u> - crater rim	• Polarimetry of north and south massifs and sculptured hills to provide data on their similarities and differences
• <u>Exploratory trench</u>	• Compare regolith development with regolith on light mantle
<u>Light mantle:</u>	
• <u>Observe/photograph</u> surface structures, textures, fragment distribution, internal structure, regolith	• Mode of emplacement; compare with stations 2 and 3; relative age based on regolith thickness
• <u>Rake sample</u> (intercrater area)	• Statistical sample of lithologic varieties in pebble-size fragments for comparison with samples from stations 2 and 3
• <u>Documented samples</u> of rocks and soil from rim and ejecta blanket of small (approx. 10 m) fresh crater	• Characterize lithology of light mantle materials
• <u>Pan</u>	• Location, sampling context
* Considered to be an all inclusive shopping list of tasks if time were available. The station timeline which follows presents the particular tasks (and time allocations) which were selected as the nominal station activities.	

EVA 2

Station 4 Timeline

0 + 40

	CDR	LMP
<u>Initial overhead</u>	5	5
<u>Observation</u>	5	5
•Dark halo crater interior, deposits (origin), regolith		
•Light mantle lithology, structures, regolith		
•Uplands and scarp (500 mm)		
<u>Dark halo crater</u>	12	15
•Documented sampling (rim) possible rake soil		
•Pan (rim)		
•Polarimetry (rim)		
•Radial sample (dixie cup) (at least 5 samples)		
<u>Light mantle</u>	14	11
•Documented sampling (bright crater)		
•Rake/soil (inter-crater)		
•Pan		
<u>Final overhead</u>	<u>4</u>	<u>4</u>
	40	40

FIGURE 3.2-6 STATION 5 TASKS

EVA 2

Station 5

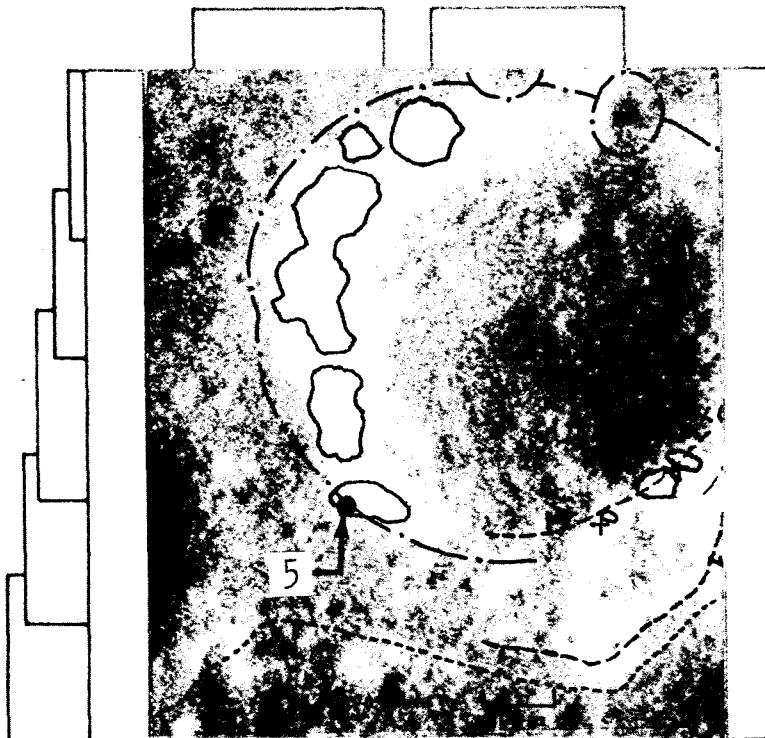
Time 0 + 30

Location: Southwest side of low-rimmed 700 m crater west of landing point.

Geologic setting: As at station 1, subfloor material is exposed in parts of the crater rim and wall. Accessible exposures, however, are few and small, and no blocks are resolvable in the station area. Dark mantle covers the floor and much of the rim and wall of the crater.

Objectives:

- Observe and sample subfloor and dark mantle materials for comparison with other stations.



TASKS*	RATIONALE
• <u>Observe/photograph</u> crater walls, rims	•Crater origin
<u>Dark mantle:</u>	
• <u>Double core</u> through dark mantle/subfloor interface	•Lateral variation in dark mantle (compare with deep drill core); character, age of pre-mantle surface
• <u>Trench; observe/photograph</u> regolith	•Comparison with light mantle for relative age; with other dark mantle areas for cause of thinning on crater rim
<u>Subfloor:</u>	
• <u>Documented samples</u> • <u>Rake/soil</u>	•Representative sampling of subfloor materials for comparison with samples from stations 1 and 10

* Considered to be an all inclusive shopping list of tasks if time were available. The station timeline which follows presents the particular tasks (and time allocations) which were selected as the nominal station activities.

EVA 2

Station 5 Timeline

0 + 30

	CDR	LMP
<u>Initial overhead</u>	5	5
<u>Observation</u>	3	3
•Crater wall/rim (origin)		
•Subfloor - compare with station 1		
•Subfloor/dark mantle contact		
•Regolith		
<u>Subfloor</u>	9	9
•Documented sampling		
•Rake/soil		
<u>Dark mantle</u>	9	9
•Double core (including top of subfloor unit)		
•Pans (stereo-camelot)		
<u>Final overhead</u>	4	4
	<hr/>	<hr/>
	30	30

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3.2.2 EVA-2 TRAVERSES

This section is comprised of a tabular summary of the EVA 2 activities. Table 3.2-1 provides calculated data on distance, velocities, and times as the crew progresses through their preparations and station stops, culminating in closeout back at the LM. The tabular data also shows the time and location of the three explosive packages deployed on EVA 2.

The table also provides traverse contingency information, LRV - or PLSS - malfunctioned walkbacks or ridebacks.

Table 3.2-2 lists input data for the program that generated Table 3.2-1.

Finally, Table 3.2-3 provides the basic assumptions inherent in the layout of the EVA traverses.

TABLE 3.2-1 APOLLO 17 TAURUS LITTON TRAVERSES

EVA 2

CALCULATED DATA

OCT 25 1972

EVA START 139:10 HR:MIN GET

STATION	SEGMENT DISTANCE (KM)	LRV MOBILITY RATE (KM/HR)	RISE TIME (MIN)	TOTAL TRAVEL DISTANCE (KM)	ARRIVE STATION EVA TIME (HR+MIN)	STOP TIME (HR+MIN)	DEPART STATION EVA TIME (HR+MIN)
LM				0.00	0+ 0	0+52	0+52
RISE	0.40	7.30	3				
1/8@CH				0.40	0+55	0+ 3	0+58
R=1.20							
RISE	3.43	7.30	28				
LRV-SA				3.83	1+26	0+ 2	1+28
RISE	0.39	7.30	3				
LRV-SA				4.22	1+32	0+ 2	1+34
RISE	3.48	7.30	29				
2				7.70	2+ 2	0+50	2+52
RISE	1.08	7.30	9				
LRV-SA				8.78	3+ 1	0+ 2	3+ 3
RISE	1.08	7.30	9				
LRV-SA				9.86	3+12	0+ 2	3+14
RISE	0.73	7.30	6				
3				10.59	3+20	0+45	4+ 5
RISE	1.09	7.30	9				
LRV-SA				11.68	4+14	0+ 2	4+16
RISE	0.79	7.30	6				
4				12.47	4+22	0+40	5+ 2
RISE	1.39	7.30	11				
PHOTO				13.86	5+14	0+ 4	5+18
LRV-SA							
6@CH							
R=2.4							
RISE	0.93	7.30	8				
LRV-SA				14.79	5+26	0+ 2	5+28
RISE	0.79	7.30	6				
5				15.58	5+34	0+30	6+ 4
RISE	0.72	7.30	6				
1/4@CH				16.30	6+10	0+ 3	6+13
R=1.25							
RISE	0.40	7.30	3				
LM				16.70	6+16	0+44	7+ 0
TOTALS			137			4+43	7+ 0

TABLE 3.2-1 (Continued)

EVA 2 CALCULATED DATA (CONTINUED)

STAT NO	RETURN DISTANCE TO LM (KM)	----- TRVERSE CONTINGENCIES -----				-----PLSS FAILURE-----		AVG EVA MET RATE (BTU/HR)
		WALKBACK TIME TO LM (HR+MIN)	LRV FAILURE WALKBACK FW (HR+MIN)	STATION MARGIN ABOVE O2 (HR+MIN)	REQUIREMENTS AMP HRS (HR+MIN)	MIN LRV SPEED (KM/HR)	10 MIN RIDEBACK (KM/HR)	
LM	0.00	0+ 0	♦♦♦♦	♦♦♦♦	♦♦♦♦	0.00	0.00	1050.00
1/8#CH	0.30	0+ 5	6+21	5+52	6+19	0.29	0.35	1016.65
R=.20								
LRV-SA	3.73	1+23	4+21	3+52	4+31	3.62	4.32	866.46
LRV-SA	4.12	1+32	4+ 6	3+37	4+17	4.00	4.77	857.41
2	7.58	2+48	1+18	0+48	1+41	7.36	8.78	833.25
LRV-SA	6.50	2+24	1+41	1+12	1+54	6.31	7.53	820.80
LRV-SA	5.41	2+ 0	2+ 5	1+35	2+ 8	5.25	6.27	809.74
3	5.50	2+ 2	1+13	0+44	1+15	5.34	6.37	829.14
LRV-SA	4.65	1+43	1+30	1+ 1	1+23	4.51	5.39	820.31
4	4.13	1+32	1+ 0	0+32	0+48	4.01	4.79	831.66
PHOTO	2.84	0+47	1+35	1+ 7	1+17	2.76	3.29	823.03
LRV-SA								
6#CH								
R=2.4								
LRV-SA	1.91	0+32	1+51	1+24	1+23	1.85	2.21	817.43
5	1.12	0+19	1+37	1+10	0+59	1.09	1.30	823.59
1/4#CH	0.40	0+ 7	1+48	1+22	1+ 2	0.39	0.46	820.26
R=.25								
LM	0.00	0+ 0	1+32	1+ 5	0+45	0.00	0.00	842.20

TABLE 3.2-2 APOLLO 17 TAURUS LITTRON TRAVERSES

EVA 2

INPUT DATA

OCT 25 1972

EVA START 139:10 HR:MIN GET

STATION NO	STOP TIME (HR+MIN)	SEGMENT DISTANCE (KM)	RETURN DISTANCE (KM)	HEAT LEAK (BTU/HR)	-MOBILITY RATES- WALK (KM/HR)	RIDE (KM/HR)	MET RATE WALK (BTU/HR)
LM	0+52	0.00	0.00	135.00	♦♦♦♦	♦♦♦♦	♦♦♦♦♦♦
1/8#CH	0+ 3	0.40	0.30	135.00	3.60	7.30	1560.0
R=.20							
LRV-SA	0+ 2	3.43	3.73	135.00	2.70	7.30	1290.0
LRV-SA	0+ 2	0.39	4.12	135.00	2.70	7.30	1290.0
2	0+50	3.48	7.58	135.00	2.70	7.30	1290.0
LRV-SA	0+ 2	1.08	6.50	135.00	2.70	7.30	1290.0
LRV-SA	0+ 2	1.08	5.41	135.00	2.70	7.30	1290.0
3	0+45	0.73	5.50	135.00	2.70	7.30	1290.0
LRV-SA	0+ 2	1.09	4.65	135.00	2.70	7.30	1290.0
4	0+40	0.79	4.13	135.00	2.70	7.30	1290.0
PHOTO	0+ 4	1.39	2.84	135.00	3.60	7.30	1560.0
LRV-SA							
6#CH							
R=2.4							
LRV-SA	0+ 2	0.93	1.91	135.00	3.60	7.30	1560.0
5	0+30	0.79	1.12	135.00	3.60	7.30	1560.0
1/4#CH	0+ 3	0.72	0.40	135.00	3.60	7.30	1560.0
R=.25							
LM	0+44	0.40	0.00	135.00	3.60	7.30	1560.0

MET RATE ALSEP (BTU/HR)	MET RATE RIDING (BTU/HR)	MET RATE STATION (BTU/HR)	MET RATE LM O/H (BTU/HR)	LEAK RATE O2 (LB/HR)	EVA START (F/M-LB)	EVA START (O2-LB)	O2S TIME (MIN)
1050.00	550.00	950.00	1050.00	0.028	11.29	1.353	61.8

TABLE 3.2-3

LRV TRAVERSE ASSUMPTIONS

1. 30 MINUTES RESERVES MAINTAINED ON ALL PLSS CONSUMABLES AT STATION METABOLIC RATE
2. ALL DISTANCES AND SPEEDS ARE MAP DISTANCES AND MAP SPEEDS (MOBILITY RATES)
3. REQUIRED RATE = RETURN DISTANCE/AVAILABLE OPS RIDING TIME
AVAILABLE OPS RIDING TIME = TOTAL OPS TIME LESS ALLOWANCES
ALLOWANCES { 5 MIN BSLSS HOOKUP
13 MIN LM INGRESS
4. TIME MARGIN AT STATION METABOLIC RATE
TIME REMAINING AFTER ALLOWANCE
STATION MARGIN = FOR 10 MINUTES AT LRV, WALKBACK, AND 13 MINUTES INGRESS
5. FINAL LM O/H MARGIN = TIME REMAINING WITH NO ALLOWANCES
6. RESPIRATORY EXCHANGE QUOTIENT = 0.9
7. FEEDWATER HEAT OF VAPORIZATION 1038 $\frac{\text{BTU}}{\text{LB}}$

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3.2.3 DETAILED EVA 2 TIMELINE PROCEDURES

The detailed procedures for EVA 2 are shown on the following vertical format pages. The crew cuff check list pages which correspond approximately to the timeline are shown on the far left-hand facing sheets together with the Voice Data Plan.

CREW EVA CHECKLIST

VOICE DATA

EVA 2

CDR-1	EVA-2	PLSS
	PLSS TO LM H2O TRANSFER	
EVA-2	PLSS Pump - OFF - Disconnect PLSS H2O Connect LM H2O CB(16) ECS: LCG Pump - Close	
	LM TO PLSS H2O TRANSFER	
11-B-72	CB(16) ECS: LCG Pump - Open Disconnect LM H2O Connect PLSS H2O PLSS PUMP - ON -	

EGRESS LMP-4	0+00 CABIN DEPRESS Start watch (call mark)	CDR-4
	0+10 EGRESS/PORCH Jett bag - discard ETB to LEC & lower TGE - ON - [EGRESS] TGE - READ - Deploy PLSS ants (CDR/LMP)	
EVA-2	0+20 LCRU Pwr sw - INT - VERIFY: •Mode sw - 3 - (TV RMT) •LCRU blankets - 100% open Batt covers closed & tight Orient HGA LRV cbs Bus A,B,C,D - close •VERIFY NAV cb - close	11-B-72

EGRESS LMP-4	0+00 CABIN DEPRESS Open hatch	LMP-4
	0+10 CDR EGRESS Assist CDR Jett bag to CDR ETB to CDR Tape Recorder - OFF - VERIFY: •VOX Sens (2) - max •CB Config (White dots out + EVA decals) Utility Floodlights - OFF 16mm cam EGRESS Close hatch [LCRU/TV] Deploy PLSS ants (CDR/LMP)	
EVA-2		11-B-72

CODE:

(1) MANDATORY REQUIREMENT FOR DATA AT TIME OR EVENT DESIGNATED

(2) DATA MAY BE DEFERRED UNTIL LATER IN EVA OR DEBRIEFING

AT START OF EVA:

SUN ANGLE ~ 25°

LM SHADOW ~ 15.2 m (50 ft)

ASTRONAUT SHADOW ~ 4.5 m (15 ft)

0+00

(1) CDR/LMP - EVA WATCH START MARK _____

(2) ETB CONTENTS

CDR HEDC WITH MAG _____ (C)

LMP HEDC WITH MAG _____ (H)

MAGS _____ (D) _____ (I) _____ (J) _____ (K)

_____ (B) _____ (R)

POLAR FILTER

MAPS

COSMIC RAY (IF NOT DEPLOYED EVA 1)

(2) LMP - VERIFY CB CONFIG OK

0+10

APOLLO 17

NOMINAL TIMELINE

LUNAR SURFACE EVA 2

NOV. 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	LCRUITV	TASK FUNCTION	
				LMP	CDR
<u>PRE-EGRESS OPERATIONS</u>	0+00	<u>PRE-EGRESS OPERATIONS</u> START EVA WATCH (CALL MARK)		PRE-EGRESS OPERATIONS	PRE-EGRESS OPERATIONS
		NOTE: DETAILED PROCEDURES ARE PRESENTED IN LUNAR SURFACE CHECKLIST EQUIPMENT PREP - EVA 2 SECTION			
	0+10				

CREW EVA CHECKLIST

VOICE DATA

0+00 CABIN DEPRESS
Start watch (call mark)

0+10 EGRESS/PORCH
Jett bag - discard
ETB to LEC & lower
TGE - ON - [EGRESS]
TGE - READ -
Deploy PLSS ants (CDR/LMP)

0+20 LCRU
Pwr sw - INT -
VERIFY:
• Mode sw - 3 - (TV RMT)
• LCRU blankets - 100% open
Batt covers closed & tight
Orient HGA
LRV cbs Bus A,B,C,D - close
• VERIFY NAV cb - close

CDR-4
EVA-2
11-8-72

0+25 SRC 2 CONFIG [LRV EQUIP]
SRC 2 (LH) to MESA table
SCB 5 to MESA top
Seal organic cont sample
Close SRC
Get LCRU batt (MESA)
Tidy MESA blankets
TGE - GRAV
To LRV:
• SCB 5 to tool gate (LH)
• LCRU Batt under CDR seat
• Dust brush to LCRU

0+30 SCB 7 to gate (RH) [PAN]
Xfer from SCB 5 to 7:
• 3 core tubes (loose)
• 2 - 20 bag disp
• 1 core cap disp
• Short can

CDR-5
EVA-2
11-8-72

0+00 CABIN DEPRESS
Open hatch

0+10 CDR EGRESS
Assist CDR
Jett bag to CDR
ETB to CDR
Tape Recorder - OFF -
VERIFY:
• VOX Sens (2) - max
• CB Config (White dots out + EVA decals)
Utility Floodlights - OFF
16mm cam
EGRESS
Close hatch [LCRU/TV]
Deploy PLSS ants (CDR/LMP)

CDR-4
EVA-2
11-8-72

0+20 LRV EQUIP [SRC 2]
ETB to CDR footpan
SEP RCVR:
• Pwr sw - STBY
• Read temp
• Close blink A

To LMP seat
• LMP cam
• Maps
Stow under CDR seat:
• 5 mags (rpt D,I,J,X,B)
• Mag R to 500mm
• Polar filter
CDR cam on seat

LMP-5
EVA-2
11-8-72

EP 4 btw LRV seats
Discard Xptr under LM
ETB to MESA table
Mount EP Xptr (1,2,3,8)

0+30 Get CDR cam
Photo pan 8:00/30' [SCB 7]
Doff cam CDR seat

GEO PREP [GEO PREP]
Configure EVA maps

Hold still [LOAD PLSS]
SCB 5 to CDR PLSS
Mount cam

LMP-6
EVA-2
11-8-72

EVA 2

0+10

- (1) LMP - LM SWITCHES
RECORDER - OFF
VOX SENS (2) - MAX
CB CONFIG
UTILITY FLOOD LIGHTS - OFF

(1) CDR - TGE - ON

(1) CDR - TGE RDG _____, _____, _____

0+20

- (1) LMP - DEPLOY CDR PLSS ANTENNA
- (1) CDR - DEPLOY LMP PLSS ANTENNA
- (1) LMP - SEP RCVR - STNDBY
- (1) LMP - SEP RCVR - TEMP _____
- (1) CDR - LCRU BLANKETS OPEN 100%
- BATT COVERS CLOSED

(1) CDR/LMP - EMU CHECK

	CDR	LMP
02		
FLAGS		
PRESS		
COOL		

(1) LMP - MAGS (5) UNDER SEAT

(1) LMP - Report EP pallet on LRV
& EP 4 between seats

(1) CDR - TGE GRAV

(1) CDR - DUST BRUSH ON LCRU

0+30

MISSION: APOLLO 17
 EVA: 2

DATE: NOV. '72

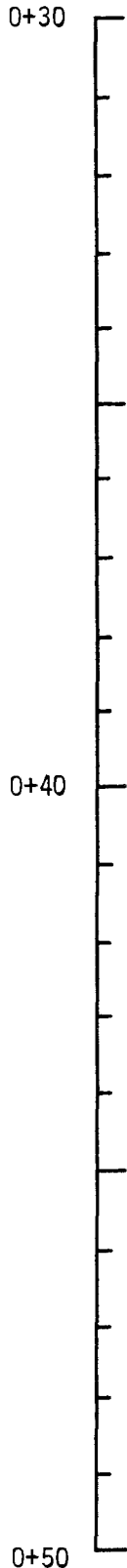
LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	LCRUV	TASK FUNCTION	
				LMP	CDR
OPEN HATCH	0+10	<u>EGRESS OPERATIONS</u>			
ASSIST CDR EGRESS		EGRESS CABIN TO LM PORCH			
HAND JETTISON BAG TO CDR HOOK ETB TO LEC		RECEIVE & JETTISON BAG PASS IN LEC HOOK			
HAND ETB/LEC TO CDR		RECEIVE ETB/LEC			
VERIFY: *RECORDER - OFF *VOX SENS(2) - MAX *CB CONFIG *UTILITY FLOODLIGHTS OFF		DESCEND LADDER TO TOP RUNG & LOWER ETB			
		DESCEND LADDER TO SURFACE			
<u>LMP EGRESS OPERATIONS</u>		HANG ETB ON LADDER HOOK			
EGRESS LM TO PORCH		TGE MODE SW - ON TGE READ			
PARTIALLY CLOSE LM HATCH DESCEND LADDER TO SURFACE DEPLOY CDR PLSS ANTENNA		DEPLOY LMP PLSS ANTENNA			
SEP RCVR - STNDBY READ SEP RCVR TEMP CLOSE BLANKET A <u>LRV EQUIP</u>	0+20	<u>LCRU</u>			
TAKE ETB TO CDR FOOTPAN		PLACE PWR SW - INT VERIFY: MODE SW - 3 OPEN BLANKETS; CLOSE LRV BATTS COVERS & PRESS TIGHT PUSH IN CB's A, B, C, D VERIFY NAV CB - IN			
PLACE ON LMP SEAT OR PAN: 2-70 MM CAMERAS MAPS		<u>SRC 2</u>			
STOW UNDER CDR SEAT: 4-MAGS (D, I, J, K, B)		UNSTOW SRC 2 (LH MESA) PLACE SRC 2 ON TABLE OPEN, FOLD BACK SKIRT			
TAKE OFF EP #4 - PLACE EP BETWEEN SEATS		TAKE OUT SCB 5, PLACE ON MESA (INTERIM STOW) SEAL ORGANIC CONTROL SAMPLE CLOSE SRC 2 (DON'T LATCH)			
DISCARD TRANSPORTER FRAME		TAKE OUT LCRU BATT; PLACE UNDER CDR SEAT TIDY UP MESA BLANKETS			
TAKE ETB BACK TO HOOK MOUNT EP TRANSPORTER(1,2,3,8) ON LRV <u>PHOTO PAN</u>		<u>TGE - PRESS 'GRAV'</u>			
GET CAMERA, PLACE ON RCU					
PROCEED TO 30' OFF SEQ BAY (8:00)					
TAKE COMPLETE PAN	0+30				

CREW EVA CHECKLIST

VOICE DATA

EVA 2

TRAV PREP SEP TRAV	Core cap disp to gate (SCB 5) Mount 20 bag disp on CDR cam (CDR seat) 20 bag disp to LMP Stow SCB 7 under LMP seat SCB 4 to LMP SCB 6 to gate GEO PREP [GEO PREP Stow LMP PLSS •Cap disp (SCB 5) •Hammer •Hammer •SCB 4 LMP to secure SCB 5 TGE - READ - TGE to LRV	CDR-6
	EVA-2	11-8-72
CDR-7	LRV EQUIP CHECK •LCRU Batt •EP Xptr (1,2,3,8) •LCRU blankets 100% open •LRV batt covers closed •Dust brush on LCRU •TGE •Mags & Polar filter 0+40 TRAV TO SEP [WALK TO SEP TV cam; Mode sw -1- (PM1/WB) Mount cam Tether tongs Drive to SEP: •West leg, H = 27D •10m from Xmtr •5m to side of ant [PHOTO •STOP + Volts	SEP TRAV TRAV PREP
EVA-2	11-8-72	



- (1) CDR - LRV EQUIP CHECK
 LCRU BATT _____
 EP XPTR (1,2,3,8) _____
 LCRU BLNKTS OPEN 100% _____
 LRV BATT COVERS CLOSED _____
 DUST BRUSH ON LCRU _____

 MAG & POLAR FILTER _____
- (1) CDR - TGE Rdg _____
 Verify TGE on LRV

LMP-7	0+40 TRAV TO SEP Walk to SEP Xmtr Sw SEP Xmtr -ON- Photo LRV/SEP: •Stereo part pan x-sun 50' •Rcvr dn-sun 7' SEP Rcvr: [NAV INIT •Pwr sw - ON - •Rcdr - ON - Get EP 4	SEP TRAV TRAV PREP
	EVA-2	11-8-72

- (1) LMP - SEP XMTR - ON
- (1) CDR - LRV DISPLAYS & NAV INIT

Temp Bat 1		
Temp Bat 2		
Temp LF mtr		
Temp RF mtr		
Amp-Hr Bat 1	Temp LR mtr	
Amp-Hr Bat 2	Temp RR mtr	
SSD	ROLL	PITCH
COMPUTED NAV HEADING		

- (1) CDR - Report SEP / LRV Distance
- (1) LMP - SEP RCVR - ON
- (1) LMP - SEP RCDB - ON
- (1) CDR - NAV RESET
- (1) LMP - EP 4 "SAFE"
- (1) CDR - POSITION LGA 240°

MISSION: APOLLO 17
 EVA: 2

DATE: NOV. '72

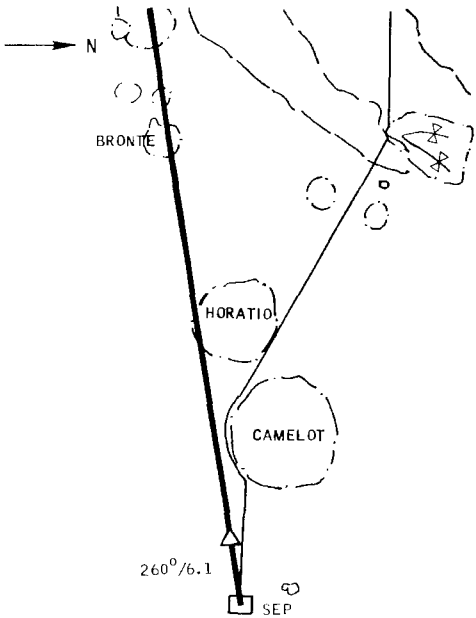
LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
	0+30	UNSTOW SCB 7, HANG ON GATE		
		TRANSFER FROM SCB 5 TO SCB 7:		
		1 - CORE CAP DISP		
		2 - 20 DSBD		
		3 - CORE TUBES (LOOSE)		
		STOW SCB 7 UNDER LMP SEAT		
		PUT 2 - 20 DSBD ON LMP PAN		
CONFIGURE MAPS ON LRV		PUT SCB 4 ON TOOL GATE		
		PUT SCB 6 ON PALLET BACK		
<u>GEOLOGICAL PREP</u>		<u>GEOLOGICAL PREP</u>		
HOLD STILL		LOADUP LMP PLSS		
		TOOL CARRIER:		
		HAMMER		
		CORE RAMMER		
		CORE CAP DISP. (SCB 5)		
		SCB 4		
PLACE SCB 5 ON CDR		HOLD STILL		
		READ TGE		
		PLACE TGE ON LRV		
<u>SEP SITE</u>	0+40	PUT ON 20 DSBD & TETHER TONGS		
WALK TO SEP SITE		POSITION LCRU MODE SW-1		
		TURN TV CW AFT & HORIZ		
TURN ON SEP XMTR		MOUNT LRV & FASTEN BELT		
		POWER UP LRV		
		DRIVE TO SEP SITE:		
		W LEG X-ARRAY		
		<10 M FROM XMTR		
PART PAN XSUN 50' TO LRV/SEP		5M FROM ANT WIRE		
		HEADING 270°		
PHOTO SEP RCVR DNSUN 7'		POWER DOWN LRV		
SW ON SEP RCVR		REPORT SSE, PITCH, ROLL, HEADING		
RCVR PWR - 'ON'		RESET NAV		
SEP RECORDER - 'ON'		TORQUE GYRO PER MCC		
MOUNT LRV (EP #4 ON LAP)		POSITION LGA 240°		
FASTEN SEATBELT		POWER UP LRV		
	0+50			

CREW EVA CHECKLIST

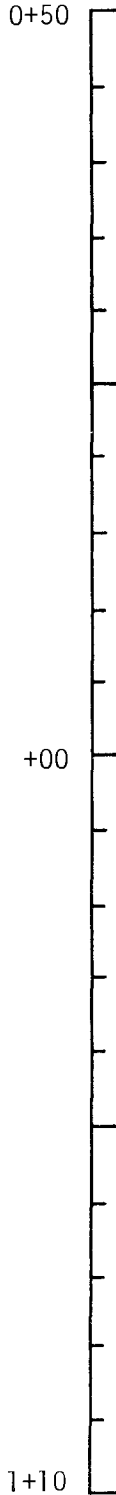
VOICE DATA

EVA 2

CDR-9	NAV INITIALIZE		TRAV STA 2
	LGA = 250		
EVA-2	0+52 TRAV TO STA 2-66min (260/8.4)		
	Δ 060/0.4 EP 4 - part pan (0.2 W ALSEP)		
11-B-72	•Mtl - variatn,dynam,pat gnd		
	•Cra - strat, sources		
	080/1.1 View Sta 5		
	080/1.5 HORATIO - subflr		
	060/3.9 LRV spl - 1st lt mt1		
	090/4.0 Contact - age		
	•Cra - strat, thick, req		
	•TORTILLA FLAT		
	090/4.2 LRV spl - dk mt1		



LMP-9	0+52 TRAV TO STA 2-66min (260/8.4)		TRAV STA 2
	LRV Photos		
EVA-2	Δ 060/0.4 EP 4 - part pan (0.2 W ALSEP)		
	•Mtl - variatn,dynam,pat gnd		
11-B-72	•Cra - strat, sources		
	080/1.1 View Sta 5		
	080/1.5 HORATIO - subflr		
	080/3.9 LRV spl - 1st lt mt1		
	080/4.0 Contact - age		
	•Cra - strat, thick, req		
	•TORTILLA FLAT		
	080/4.2 LRV spl - dk mt1		



(1) CDR - LRV underway MARK _____
 - Passing end of SEP antenna MARK _____

(1) LMP - EP 4 "SAFE"

(1) CDR - Nav Data

HEADING	
BEARING	
DISTANCE	
RANGE	

(1) CDR - LRV Underway MARK _____

(1) LMP - Rpt 70mm mag/frame _____

(2) CDR/LMP - LRV: Speed _____
 Amps _____

CREW EVA CHECKLIST

VOICE DATA

EVA 2

LMP-9	0+52 TRAV TO STA 2-60min (260/8.4)	TRAV STA 2
	LRV Photos	
EVA-2	Δ 060/0.4 EP 4 - part pan (0.2 W ALSEP)	Z VIS APOL
	•Mtl - variatn, dynam, pat gnd	
	•Cra - strat, sources	
	080/1.1 View Sta 5	
11-8-72	080/1.5 HORATIO - subflr	
	080/3.9 LRV sp1 - 1st lt mt1	
	080/4.0 Contact - age •Cra - strat, thick, reg •TORTILLA FLAT	
	080/4.2 LRV sp1 - dk mt1	

1+10

1+20

1+30

(1) CDR/LMP - EMU Check

	CDR	LMP
02		
FLAGS		
PRESS		
COOL		

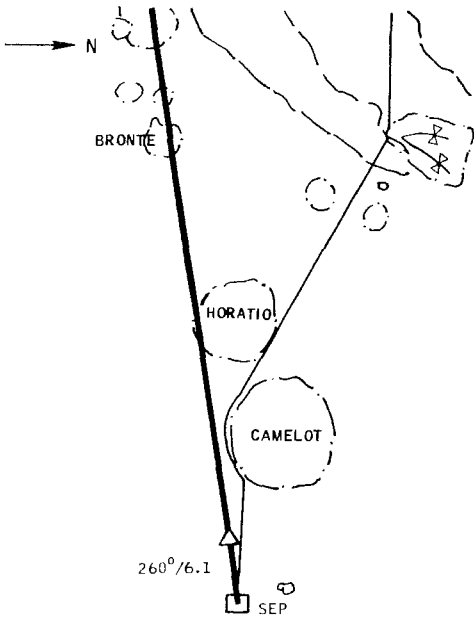
(1) CDR/LMP - LRV: Speed _____
Amps _____

(1) LMP - Samples Bag No. _____

(1) CDR - NAV Data

HEADING	
BEARING	
DISTANCE	
RANGE	

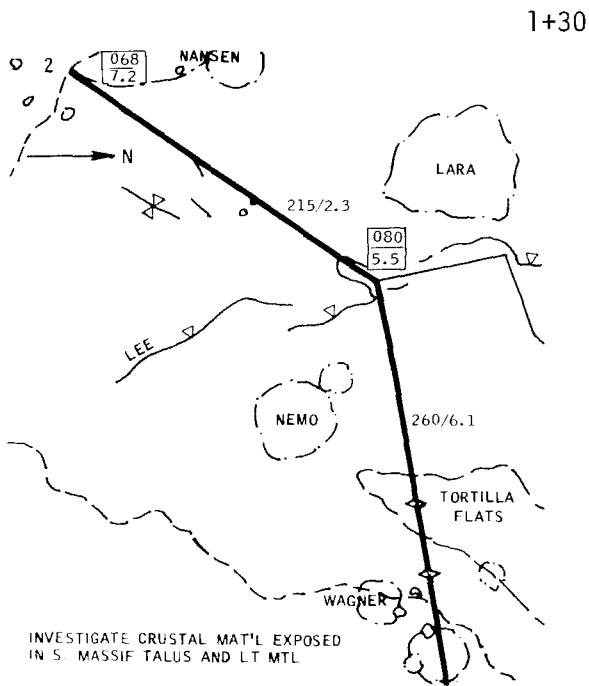
(1) CDR - LRV Underway
MARK _____



CREW EVA CHECKLIST

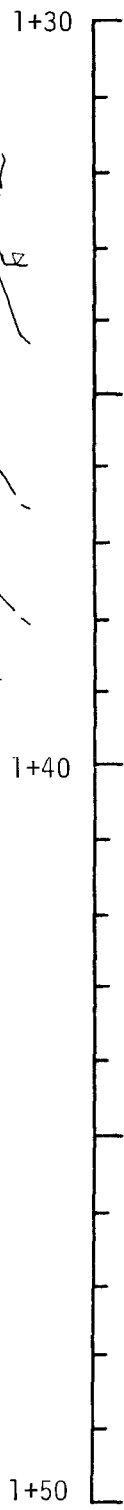
VOICE DATA

EVA 2



- (1) LMP - Samples Bag No. _____
- (1) CDR - NAV Data _____
- (1) CDR - LRV Underway MARK _____

HEADING	
BEARING	
DISTANCE	
RANGE	



- (2) CDR/LMP - LRV Speed _____
Amps _____

MISSION: APOLLO 17
 EVA: 2

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
GO	T+30	GO		
LRV SAMPLE		STOP LRV		
COLLECT SAMPLE		READ NAV DATA		
PHOTO PAN		PHOTO PAN		
CONTINUE TO STA 2		CONTINUE TO STA 2		
GO	T+40	GO		
GO	T+50	GO		

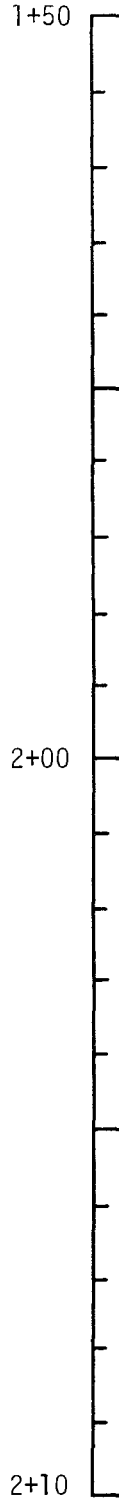
CREW EVA CHECKLIST

VOICE DATA

EVA 2

11-8-72	CDR-11	<ul style="list-style-type: none"> • Lt Mt1 - terminis, dynam • STONEWALL - otc, forms, struct 	TICAV STA 2
	EVA-2	<p>080/5.5 HOLE-IN-THE-WALL, etc, forms</p> <ul style="list-style-type: none"> • S. MASSIF - organ, blks, flt • Lt Mt1 - variatn • Surf forms - organ • Frags - populatns 	

11-8-72	CDR-13	<p>STA 2 (51 MIN) 068/7.2</p> <p><u>OBSERVATION</u></p> <ul style="list-style-type: none"> • Contact - Lt Mt1/Massif • Blks - tracks, variety • Lt Mt1 - forms, variety • Misc - xln rks <p>MASSIF</p> <ul style="list-style-type: none"> • Doc spl - blk types, tex • Rake(Kg) - talus, relate blks <p>Pan - E end NANSEN</p> <p>Lt Mt1</p> <ul style="list-style-type: none"> • Rake - btw cra • Doc spl - frag/soil variety <p>Pan - Rim 100m N 1st pan</p> <ul style="list-style-type: none"> • NANSEN - flr blks Sum - MASSIF 	STA 2
	EVA-2		



(1) CDR - Station 2 Arrival

(1) CDR - LRV Data

HEADING		Temp Bat 1	
BEARING		Temp Bat 2	
DISTANCE		Temp LF mtr	
RANGE		Temp RF mtr	
Amp-Hr Bat 1		Temp LR mtr	
Amp-Hr Bat 2		Temp RR mtr	

(1) CDR - Verify Dusting

(1) CDR/LMP - TGE - GRAV

(1) CDR/LMP - Pan locations

MISSION: APOLLO 17
 EVA: 2

DATE: NOV. '72

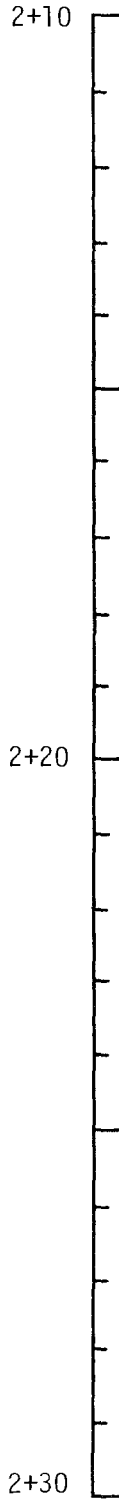
LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	LCRU TV	TASK FUNCTION	
				LMP	CDR
	1+50				
<u>STATION 2</u>		<u>STATION 2</u>			
DISMOUNT FROM LRV		POWER DOWN LRV			
TAKE PHOTO PAN		REPORT NAV & SYSTEM DATA			
GEOLOGICAL OBSERVATIONS		2+00 DISMOUNT LRV			
GET GNOMON & SCOOP FROM AFT PALLET		LCRU MODE SW - '2'			
		ALIGN HGA			
		DUST TV, TCU, LCRU			
		PRESS GRAV ON TGE			
		VERIFY LIGHT FLASHING			
		GIVE MCC MARK			
OBSERVATIONS		OBSERVATIONS			
PHOTOS		PHOTOS			
GET RAKE FROM LRV (CHECK TGE TO ENSURE CYCLE COMPLETE)		PLACE GNOMON			
	2+10				

CREW EVA CHECKLIST

VOICE DATA

EVA 2

11-B-72	EVA-2	CDR-13	<p>STA 2 (51 MIN) 068/7.2</p> <p><u>OBSERVATION</u></p> <ul style="list-style-type: none"> •Contact - Lt Mtl/Massif •Blks - tracks, variety •Lt Mtl - forms, variety •Misc - xln rks <p><u>MASSIF</u></p> <ul style="list-style-type: none"> •Doc spl - blk types, tex •Rake(Kg) - talus, relate blks <p><u>Pan</u> - E end NANSEN</p> <p><u>Lt Mtl</u></p> <ul style="list-style-type: none"> •Rake - btw cra •Doc spl - frag/soil variety <p><u>Pan</u> - Rim 100m N 1st pan</p> <p><u>NANSEN</u> - flr blks</p> <p><u>Sum</u> - MASSIF</p>	STA 2
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(1) CDR/LMP - RAKE Sample

- [A] Rocks BAG # _____
- Soil BAG # _____
- [B] Rocks BAG # _____
- Soil BAG # _____

CREW EVA CHECKLIST

VOICEL DATA

EVA 2

11-8-72	EVA-2	LMP-13	STA 2 (51 MIN) 058/7.2 OBSERVATION •Contact - Lt mt1/MASSIF •Blks - tracks, variety •Lt mt1 - forms, variety •Misc - xln rks . MASSIF •Doc spl - blk types, tex •Rake(kg) - talus, relate blks . Pan - E end NANSEN . Lt Mt1 •Rake - btw cra •Doc spl - frag/soil variety . Pan - Rim 100m N 1st pan •NANSEN - flr blks Sum - MASSIF	STA 2

2+30

2+40

(1) CDR/LMP EMU Check

	CDR	LMP
02		
FLAGS		
PRESS		
COOL		

(1) CDR - TGE Rdg _____

(1) CDR/LMP - Mag/frame

CDR - ___/___

LMP - ___/___

(1) CDR - LGA Azimuth 035°

2+50

(1) CDR - LRV Underway MARK _____

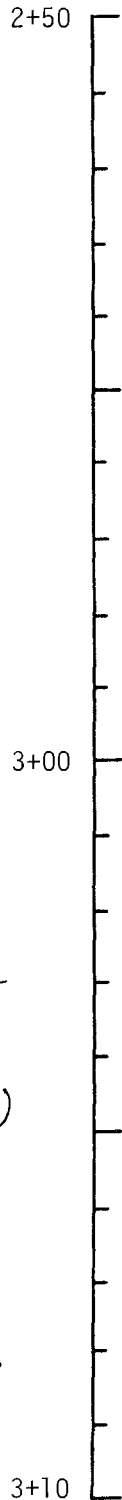
11-8-72	EVA-2	LMP-15	STA 2 CLOSEOUT TGE - READ - TV cam: Mode sw - 1 - (PH1/WB) LGA - 040 (frame, tools)	TRAV STA 3
			2+49 TRAV TO STA 3-29min (035/3.1) •LT Mt1 - variatn, dynam 073/6.3 LRV spl 080/5.5 LRV spl 080/5.5 HOLE-IN-THE-WALL •STONEWALL - forms, dynam •LARA - forms, struct •Lineaments	
			3+19 087/5.6 STA 3 (45 MIN) Park btw cra & scarp H=045 STOP Mode sw - 2 - (FM/TV) HGA: Dust gnomon/scoop TGE - GRAV - splr/rake	

CREW EVA CHLCKLIST

VOICE DATA

EVA 2

CDR-15	STA 2 CLOSEOUT	TRAV STA 3
	TGE - READ - TV cam; Mode sw - 1 - (PM1/WB) LGA = 040 (frame, tools)	
EVA-2	2+49 TRAV TO STA 3-29min (035/3.1)	TRAV STA 3
	•LT MEI - variatn, dynam 073/6.3 LRV spl 080/5.5 LRV spl LGA = 000 080/5.5 HOLE-IN-THE-WALL •STONEWALL - forms, dynam •LARA - forms, struct •Lineaments	
11-8-72	3+19 087/5.6 STA 3 (45 MIN)	
	Stop btw cra & scarp Park H=270 [NAV UPDATE] then: H=045 [STOP] Mode sw - 2 - (FM/TV) HGA; Dust gnomon/scoop TGE - GRAV - spir/rake	



(2) CDR/LMP - LRV Speed _____
Amps _____

(1) CDR - LRV start Mark _____

(1) LMP - Samples Bag No. _____

(1) CDR - NAV Data _____

(1) CDR - LRV Underway MARK _____

HEADING	
BEARING	
DISTANCE	
RANGE	

(2) CDR/LMP - LRV Speed _____
Amp Amps _____

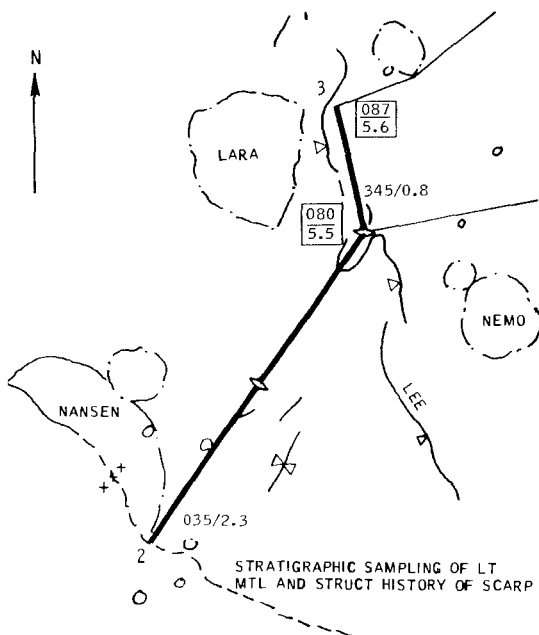
(1) CDR - Adjust LGA 345°

(1) LMP - Samples Bag No. _____

(1) CDR - NAV Data _____

(1) CDR - LRV Underway MARK _____

HEADING	
BEARING	
DISTANCE	
RANGE	



MISSION: APOLLO 17
 EVA: 2

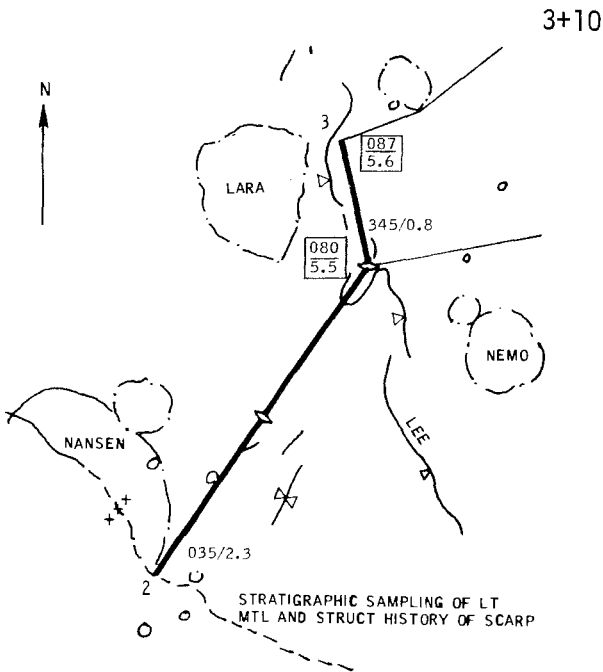
DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	L C R U V	TASK FUNCTION	
				L M P	C D R
	2+50				
<u>GO TO STA. 3</u>		<u>GO TO STA. 3</u> REPORT LRV UNDERWAY			
<u>LRV SAMPLE</u> COLLECT SAMPLE PHOTO PAN		<u>LRV SAMPLE</u> STOP LRV PHOTO PAN READ NAV DATA			
CONTINUE TO STA 3		CONTINUE TO STA 3			
	3+00				
<u>LRV SAMPLE</u> COLLECT SAMPLE PHOTO PAN		<u>LRV SAMPLE</u> STOP LRV READ NAV DATA -ADJUST LGA 345° PHOTO PAN			
	3+10				

CREW EVA CHECKLIST

VOICE DATA

EVA 2



Capcom - Heading 270 at Station 3 for nav update

(1) CDR NAV UPDATE

SSD	ROLL	PITCH
COMPUTED NAV HEADING		

3+20

(1) CDR - ARRIVAL STA 3

(1) CDR - LRV DATA

HEADING	Temp Bat 1
BEARING	Temp Bat 2
DISTANCE	Temp LF mtr
RANGE	Temp RF mtr
Amp-Hr Bat 1	Temp LR mtr
Amp-HR Bat 2	Temp RR mtr

(1) CDR - Verify Dusting

(1) CDR/LMP - TGE GRAV

(1) CDR/LMP - Pan locations

CDR-17	STA 3 (45 MIN) 087/5.6	STA 3
	<p>OBSERVATION</p> <ul style="list-style-type: none"> •Scarp - otc, struct •Lt Mtl - scarp, dynam •Misc - alter, lobes <p>Lt Mtl (20m brt cra)</p> <ul style="list-style-type: none"> •Doc spl - rim, variety •Rake - btw cra •CDR: Dbl core-long can near scarp <p>Scarp</p> <ul style="list-style-type: none"> •LMP: Trench - face, base •Doc spl - otc, sub mtl •Flt line stereo <p>Pans</p>	
EVA-2		
11-6-72		

3+30

MISSION: APOLLO 17
 EVA: 2

DATE: NOV. '72

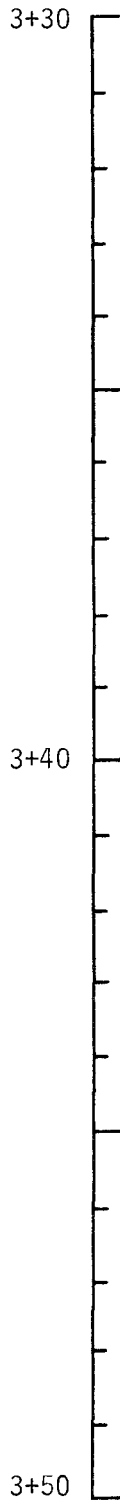
LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
<u>CONTINUE TO STA 3</u>	3+10	<u>CONTINUE TO STA 3</u>		
<u>DISMOUNT LRV</u>		PARK 270° NAV UPDATE REPORT NAV AND SYSTEM DATA		
		PARK 045°		
	3+20			
<u>STATION 3</u>		<u>STATION 3</u>		
PHOTO PAN		LCRU MODE - "2" ALIGN HGA		
GET GNOMON & SCOOP FROM AFT PALLET		DUST TV, TCU, LCRU		
		PRESS GRAV ON TGE VERIFY LIGHT FLASHING GIVE MCC MARK		
<u>OBSERVATIONS</u>		<u>OBSERVATIONS</u>		
<u>PHOTOS</u>		<u>PHOTOS</u>		
<u>DOCUMENTED SAMPLES</u>		<u>DOCUMENTED SAMPLES</u>		
	3+30			

CREW EVA CHLCKLIST

VOICE DATA

EVA 2

11-8-72	EVA-2	STA 3	STA 3 (45 MIN) 087/5.6 OBSERVATION •Scarp - otc, struct •Lt Mtl - scarp, dynam •Misc - alter, lobes Lt Mtl (20m brt cra) •Doc spl - rim, variety •Rake - btw cra •CDR: Dbl core-long can near scarp Scarp •LMP: Trench - face, base •Doc spl - otc, sub mtl •Flt line stereo Pans
	CDR-17		

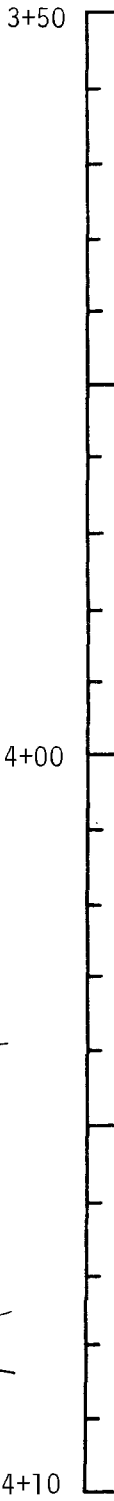


(1) CDR/LMP - EMU Check

	CDR	LMP
02		
FLAGS		
PRESS		
COOL		

EVA 2

CDR-19	STA 3 CLOSEOUT	TRAV STA 4
	TGE - READ - TV cam; Mode sw - 1 - (PMI/WB) LGA = 055 (frame, tools)	
EVA-2	4+04 TRAV TO STA 4-19min (069/2.1)	TRAV STA 4
	LT Mtl - variatn, dynam +N, MASSIF - organ 094/4.7 LRV spl 095/4.6 High point	
11-8-72	4+24 101/4.1 STA 4 (41 MIN)	
	Park S. edge SHORTY blanket H=045 STOP Mode sw - 2 - (FM/TV) HGA; Oust gnomon/spplr rake/scoop	
	Polar filter (1/125) TGE - GRAV -	



(1) CDR/LMP - MAG/FRAME

CDR - ___/___

LMP - ___/___

(1) CDR - TGE RDG _____

(1) CDR - LGA Azimuth 060°

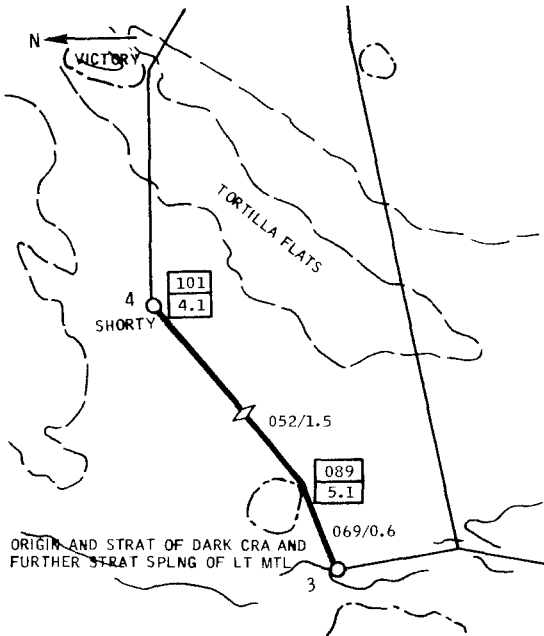
- LRV Heading _____

- Torque Gyro _____

(1) CDR - LRV Underway MARK _____

(2) CDR/LMP - LRV Speed _____

Amps _____



MISSION: APOLLO 17
 EVA: 2

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	LCRU TV	TASK FUNCTION	
				LMP	CDR
	3+50				
PHOTO PAN		REPORT FILM COUNTER			
REPORT FILM COUNTER		READ TGE DISPLAYS - CLOSE LID			
	4+00				
LOAD SAMPLES, TOOLS, & GNOMON ON LRV		LCRU MODE SW - 1 POSITION TV AFT, HORIZ.			
VERIFY GATE LATCHED		MOUNT LRV FASTEN SEAT BELT			
MOUNT LRV FASTEN SEAT BELT		UPDATE NAV POSITION LGA 060°			
		POWER UP LRV			
<u>GO TO STA 4</u>		<u>GO TO STA 4</u> REPORT LRV UNDER WAY			
<u>LRV SAMPLE</u>		<u>LRV SAMPLE</u>			
	4+10				

CREW EVA CHLCKLIST

VEHICLE DATA

EVA 2

HEADING	
BEARING	
DISTANCE	
RANGE	

CDR-19	STA 3 CLOSEOUT TGE - READ - TV cam; Mode sw - 1 - (PM1/WB) LGA = 055 (frame,tools)	
EVA-2	4+04 TRAV TO STA 4-19min (069/2.1) •Lt Mt1 - variatn, dynam •N. MASSIF - organ 094/4.7 LRV spl 095/4.6 High point	
11-8-72	4+24 101/4.1 STA 4 (41 MIN) Park S. edge SHORTY blanket H=045 [STOP] Mode sw - 2 - (FM/TV) HGA; Oust gnomon/splr raKe/scoop Polar filter (1/125) TGE - GRAV -	TRAV STA 4

4+10

- (1) CDR - NAV Data
- (1) LMP - Samples Bag No. _____
- (1) CDR - LRV Underway MARK _____

- (2) CDR/LMP - LRV Speed _____
Amps _____

4+20

- (1) CDR - Station 4 arrival _____
- (1) CDR - LRV Data

HEADING		Temp Bat 1	
BEARING		Temp Bat 2	
DISTANCE		Temp LF mtr	
RANGE		Temp RF mtr	
Amp-Hr Bat 1		Temp LR mtr	
Amp-Hr Bat 2		Temp RR mtr	

- (1) CDR - Verify Dusting

- (1) CDR/LMP - TGE GRAV

- (1) CDR/LMP - Pan locations

4+30

CDR-21	STA 4 (41 MIN) 101/4.1 OBSERVATION •Blnkt - radial variatn •SHORTY - wall, fir struct •LINCOLN Scarp - forms •Misc - xeno, alter Dk Cra •Doc spl - rim •LMP: Pan - cra rim, scarp Polar - WESSEX, S MASSIF (000-080; 130-210) Remove filter Rad spl - 5m intvl + chgs Avoid ray	STA 4
EVA-2	Lt Mt1 •Rake - btw cra •Doc spl - 10m cra, variety •CDR: 500mm - N & S MASSIF, scarp •Pan Sum - SHORTY	
11-8-72		

CREW EVA CHECKLIST

VOICE DATA

EVA 2

CDR-21	STA 4 (41 MIN) 101/4.1	STA 4
	OBSERVATION	
EVA-2	•Blnkt - radial variatn	
	•SHORTY - wall, flr struct	
	•LINCOLN Scarp - forms	
	•Misc - xeno, alter	
	DK Cra	
	•Doc spl - rim	
	•LMP: Pan - cra rim, scarp	
	Polar - WESSEX, S MASSIF	
	(000-080; 130-210)	
	Remove filter	
Rad spl - 5m intvl + chgs		
Avoid ray		
11-8-7Z	Lt Mt1	
	•Rake - btw cra	
	•Doc spl - 10m cra, variety	
	•CDR: 500mm - N & S MASSIF,	
	scarp	
	•Pan	
	Sum - SHORTY	

4+30

(1) LMP - Polar filter on cam
Reset Cam 1/125

Pos 1 - Pan L C R

 L C R

 L C R

Pos 2 - Pan L C R

 L C R

 L C R

Polar Filter off
Reset Cam 1/250

(1) CDR/LMP - Rake Sample

[A] Rocks BAG # _____

Soil BAG # _____

[B] Rocks BAG # _____

Soil BAG # _____

4+40

(1) CDR/LMP - EMU Check

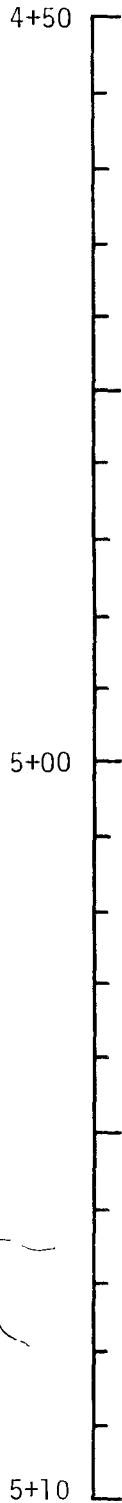
	CDR	LMP
O2		
FLAGS		
PRESS		
COOL		

4+50

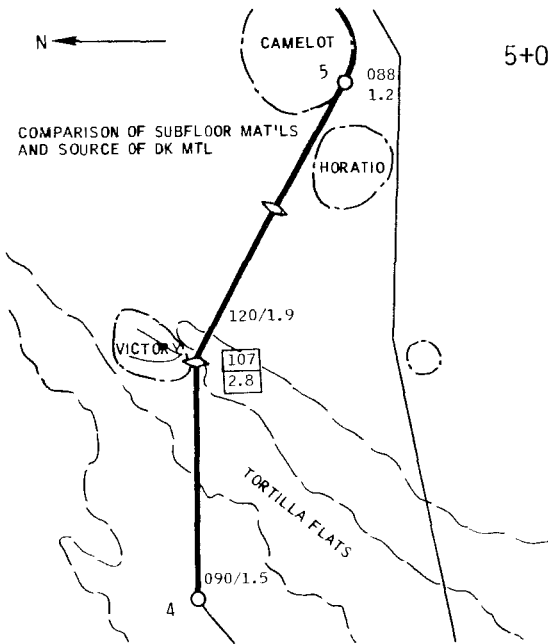
CREW EVA CHECKLIST

VOICE DATA

EVA 2



CDR-23	STA 4 CLOSEOUT	TRAV STA 5
	TGE - READ - Get EP 1 TV cam; Mode sw - 1 - (PM1/WB) LGA = 110 (frame, tools)	
EVA-2	5+05 TRAV TO STA 5-33min (090/3.4)	TRAV STA 5
	• Lt Mtl - variatn, gradtn • Mtl - compare, reg	
11-6-72	107/2.8 VICTORY - source	TRAV STA 5
	EP 1 - part pan LRV pan LRV spl Misc - xenos, altn Lt Mtl - compare	
	Sum - Lt Mtl	



(1) CDR/LMP - MAG/FRAME

CDR - ___/___

LMP - ___/___

(1) CDR - TGE Read _____

(1) LMP - EP-1 VERIFY "SAFE" _____

(1) CDR - LGA Azimuth 110° _____

(1) CDR - LRV Underway MARK _____

(2) CDR/LMP - LRV Speed _____
Amps _____

MISSION: APOLLO 17
 EVA: 2

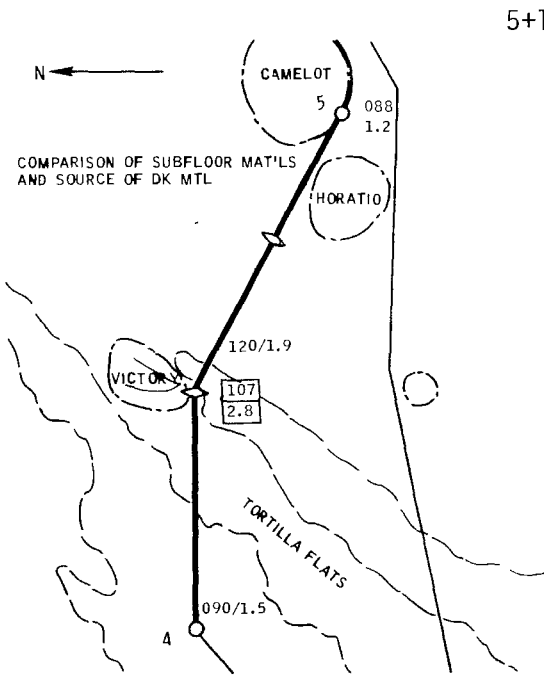
DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
	4+50			
PHOTO PAN				
REPORT FILM COUNTER		REPORT FILM COUNTER TGE READ		
LOAD SAMPLES, TOOLS, & GNOMON ON LRV GET EP - 1 (VERIFY 'SAFE') VERIFY GATE LATCHED		LCRU MODE SW - 1 POSITION TV AFT, HORIZ.		
MOUNT LRV WITH EP-1 FASTEN SEAT BELT	5+00	MOUNT LRV FASTEN SEAT BELT POSITION LGA <u>110°</u> POWER UP LRV		
<u>GO TO STA 5</u>		<u>GO TO STA 5</u> REPORT LRV UNDERWAY		
	5+10			

CREW EVA CHECKLIST

VOICE DATA

EVA 2



CDR-25	105/2.4 DRUID-mtl strat,source
	101/1.9 LRV spl
	097/1.5 HORATIO N. rim-subflr
	090/1.3 Cra chain
EVA-2	5+34 088/1.2 STA 5 (32 MIN)
	Park's S. rim CAMELOT
	H=045 STOP
	Mode sv - 2 - (FM/TV)
	HGA; Dust gnomon/rake
	TGE - GRAV - /scoop
11-B-72	TRAV STA 5
	VICTORY

5+10

5+20

5+30

HEADING	
BEARING	
DISTANCE	
RANGE	

- (1) CDR - NAV Data
- (1) LMP - EP 1 "SAFE"
- (1) LMP - Rpt 70mm mag/frame _____
- (1) LMP - Sampler Bag No. _____
- (2) CDR - Distance moved from EP - estimate
- (1) CDR - LRV Underway MARK _____

- (2) CDR/LMP - LRV Speed _____
- Amps _____

HEADING	
BEARING	
DISTANCE	
RANGE	

- (1) CDR - NAV Data
- (1) CDR - LRV Underway MARK _____
- (1) LMP - Sampler Bag No _____

MISSION: APOLLO 17
 EVA: 2

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION		
			L	M	P
	5+10				
PHOTO APPROACH		PHOTO APPROACH			
<u>"PHOTO SITE"</u>		<u>"PHOTO SITE"</u>			
CHECK EP-1 DISPLAY 'SAFE'		STOP LRV			
PULL 3 PINS (DISCARD PINS)		POWER DOWN LRV			
EXTEND EP ANTENNA		REPORT NAV DATA			
PLACE EP ON SURFACE OUTSIDE TRACKS		SHOOT PART PAN			
SHOOT PART PAN		POWER UP & MOVE AWAY STOP & POWER ON LRV			
TAKE SAMPLE		SHOOT PART PAN			
PART PAN		POWER UP LRV			
<u>CONTINUE TO STA 5</u>		<u>CONTINUE TO STA 5</u>			
	5+20				
<u>LRV SAMPLE</u>		<u>LRV SAMPLE</u>			
COLLECT SAMPLE		READ NAV DATA			
PHOTO PAN		PHOTO PAN			
<u>CONTINUE TO STA 5</u>		<u>CONTINUE TO STA 5</u>			
	5+30				

EVA 2

5+30

(2) CDR/LMP - LRV Speed _____
 Amps _____

(1) CDR - Arrival Sta. 5 _____

(1) CDR - LRV Data

HEADING		Temp Bat 1	
BEARING		Temp Bat 2	
DISTANCE		Temp LF mtr	
RANGE		Temp RF mtr	
Amp-Hr Bat 1		Temp LR mtr	
Amp-Hr Bat 2		Temp RR mtr	

(1) CDR - Verify Dusting

(1) CDR/LMP - EMU Check

	CDR	LMP
02		
FLAGS		
PRESS		
COOL		

5+40

(1) CDR/LMP - TGE GRAV

(1) CDR/LMP - Pan locations

(1) LMP - CORE TUBES L _____
 U _____

5+50

CDR-27	STA 5 (30 MIN) 088/1.2	STA 5
	OBSERVATION	
EVA-2	*Rim - beds, ejecta	STA 5
	*Wall - subflr, sources, old reg	
11-8-72	*Contacts - subflr/mtl	STA 5
	Subflr	
	*Doc spl - blk types, tex	
	*Rake - btw blk, relate blks	
	Mtl	
	*Obt core - mtl into subflr	
	Pans	
	*Stereo of CAMELOT	

MISSION: APOLLO 17
 EVA: 2

DATE: NOV. '72

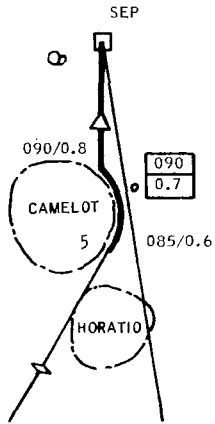
LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
	5+30			
<u>STATION 5</u>		<u>STATION 5</u>		
DISMOUNT LRV TAKE PHOTO PAN		POWER DOWN LRV REPORT NAV & SYSTEM DATA		
GEOLOGICAL OBSERVATIONS		DISMOUNT LRV LCRU MODE - 2 ALIGN HGA		
GET GNOMON & SCOOP FROM AFT PALLET (ALSO EXTRA XT HANDLE)	5+40	DUST TV, TCU, LCRU PRESS GRAV ON TGE VERIFY LIGHT FLASHING GIVE MCC MARK		
OBSERVATIONS		OBSERVATIONS		
PHOTOS		PHOTOS		
<u>DOUBLE CORE</u>		<u>DOUBLE CORE</u>		
	5+50			

CREW EVA CHECKLIST

VOICEL DATA

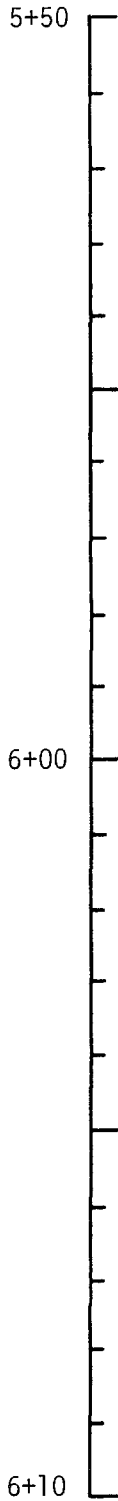


EVA 2



CDR-27	STA 5 (30 MIN) 088/1.2 OBSERVATION *Rim - beds, ejecta *Mtl - subflr, sources, old reg *Contacts - subflr/mtl Subflr *Doc spl - blk types, tex *Rake - btw blk, relate blks Mtl *Dbl core - mtl into subflr Pans *Stereo of CAMELOT	STA 5
EVA-2		
11-8-72		

CDR-29	STA 5 CLOSEOUT TGE - READ - Get EP 8 TV cam; Mode sw - 1 - (PM1/WB) LGA = 100 (frame, tools)	WT AVBL
EVA-2	6+06 TRAV TO LM-10min (085/1.4) *Mtl - distribtn *Rim - variatn Δ 090/0.4 EP 8 - part pan	
11-8-72		



(1) CDR/LMP - TGE RDG _____

(1) CDR/LMP - Mag/frame

CDR - ____/____

LMP - ____/____

(1) LMP - EP-8 Verify "SAFE"

(1) CDR - LGA Azimuth 100°

(1) CDR - LRV Underway MARK _____

MISSION: APOLLO 17
 EVA: 2

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
	5+50			
<u>DOC SAMPLE(S)</u>		<u>DOC SAMPLE(S)</u>		
PHOTO PAN	6+00			
REPORT FILM COUNTER		REPORT FILM COUNTER PRESS READ ON TGE READ DISPLAY TO MCC CLOSE LID		
LOAD SAMPLES, TOOLS, & GNOMON ON LRV GET EP-8 (VERIFY "SAFE") VERIFY GATE LATCHED		LCRU MODE SW-1 POSITION TV AFT, HORIZ		
MOUNT LRV WITH EP-8		MOUNT LRV		
FASTEN SEATBELT		FASTEN SEATBELT		
<u>GO TO LM</u>		POSITION LGA <u>100°</u> POWER UP LRV		
		<u>GO TO LM</u> REPORT LRV UNDERWAY		
PHOTO APPROACH	6+10	PHOTO APPROACH		

VOICE DATA

EVA 2

6+16 EVA 2 CLOSEOUT
Park LRV 30' NW of MESA
R-017
[STOP] + Volts
LMP to remove SCB 5
Cam to CDR seat
Mode sw - 3 - (TV RMT)

Offload LMP PLSS (HOLD)
•Core cap disp to LMP (STILL)
•Tools
•SCB 4&6 to +Z pad

Deploy Cosmic Ray
•Shade side first [ETB]

CDR-30
EVA-2
11-8-72

CDR-31
EVA-2
11-8-72

SCB 5 to SRC 2, pockets up
Remove skirt & seal protector
Close & seal SRC 2:
•Verify good seal
•Place on +Z pad

LRV Cb's Bus A,B,C,D - Open

6+30 LCRU Pwr sw - OFF -
Dust TV, TCU, batt covers
Open batt covers
Dust batts if dirty
Dust LCRU
LCRU blinkt open - 100%

6+35 FINAL LRV CHECK:
•Batt covers open
•LCRU blinkt open 100%
•Samples off
•Equip stowed

CDR-30
EVA-2
11-8-72

LMP-20
EVA-2
11-8-72

STA 5 CLOSEOUT
TGE - READ -
Get EP 8
TV cam; Mode sw - 1 - (PMI/WD)
LGA = 100 (frame,tools)

6+06 TRAV TO LH-10 (085/1.4)
•MEI - distribtn
•Rim - variatn
•090/0.4 EP 8 - part pan

6+16 EVA 2 CLOSEOUT
Cam to footpan
Get CDR SCB 5
SEP Rcvr:
•Read temp
•Pwr sw - OFF -
•Rcdr - OFF -

CDR-30
EVA-2
11-8-72

LMP-29
EVA-2
11-8-72

SCB 5 unused equip to
LMP underseat
TO SCB 5:
•Long can
•LRV spls
TO CDR seat:
•LMP cam
•Maps
SCB 5 to gate

Hold still [REMOVE & STON TOOLS, SCB 4]

CDR-30
EVA-2
11-8-72

ETB Contents:

Mag/Frames _____ / _____, _____ / _____,
_____ / _____, _____ / _____, _____ / _____

Maps
2-Cameras

SCB 5 CONTENTS: Samples
4 Core Tubes (1 in CSVC)
Other _____

6+10

(1) CDR - NAV Data

HEADING	
BEARING	
DISTANCE	
RANGE	

(1) LMP - EP-8 "SAFE"

(1) CDR - LRV Underway MARK _____

(2) CDR/LMP LRV Speed _____
Amps _____

6+20

(1) CDR - Arrival at LM _____

(1) CDR - LRV Data VOLTS _____

HEADING		Temp Bat 1
BEARING		Temp Bat 2
DISTANCE		Temp LF mtr
RANGE		Temp RF mtr
Amp-Hr Bat 1		Temp LR mtr
Amp-Hr Bat 2		Temp RR mtr

(1) CDR/LMP - SEP RCDR - OFF Blanket A open

(1) LMP - SEP RCVR - OFF SEP TEMP _____

(1) CDR/LMP - Mag/Frame

CDR - _____ / _____

LMP - _____ / _____

(1) LMP - Cosmic Ray Deployed _____

SRC 2 Contents:

SCB 5

ORGANIC CONTROL SAMPLE

6+30

MISSION: APOLLO 17
 EVA: 2

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
CHECK EP-8- "SAFE" PULL 3 PINS (DISCARD)	6+10	STOP LRV READ NAV DATA		
EXTEND EP ANTENNA PLACE EP ON SURFACE OUTSIDE TRACKS		SHOOT PART PAN		
SHOOT PART PAN		POWER UP LRV		
<u>CONTINUE TO LM</u>		<u>CONTINUE TO LM</u>		
<u>ARRIVE AT LM</u>		<u>ARRIVE AT LM</u>		
DISMOUNT LRV DOFF CAMERA ONTO SEAT		PARK LRV NORTH H=017 ALIGN LGA		
OFFLOAD SCB 5 - CDR PLSS: PUT SCB 5 ON GATE		READ LRV DISPLAYS (INCL. VOLTS)		
REPORT SEP RCVR TEMP SEP RCVR - OFF SEP RECORDER - OFF STUFF UNUSED EQUIP UNDER LMP SEAT		DISMOUNT LRV DOFF CAMERA ONTO SEAT		
FILL SCB 5 WITH LRV SAMPLES		LCRU MODE SW - 3 ALIGN HGA		
<u>CLOSEOUT</u>	6+20	DUST TV, TCU, LCRU <u>CLOSEOUT</u>		
HOLD STILL		OFFLOAD LMP PLSS: HAMMER RAMMER CORE CAP DISPENSER (TO LMP) SCB 4 & 6 (TO +Z PAD)		
TAKE UNDERSEAT SAMPLES TO BIG BAG		PUT SCB 5 IN SRC 2 PULL SKIRT OFF, REMOVE SEAL COVER		
<u>COSMIC RAY</u>		CLOSE & SEAL SRC 2		
GET COSMIC RAY EXP FROM ETB - UNBAG		PLACE SRC 2 ON +Z PAD		
PULL EXPERIMENT APART, WALK TO L HINGE SSE				
HANG 'SHADE' PART, SURFACES OUT, ON HINGE (RESET HINGE)				
<u>CAUTION: SHADE PART MAX SUN EXPOSURE 60 SEC</u>		OPEN CB's A, B, C, D		
	6+30			

CREW EVA CHLCKLIST

VOICE DATA

EVA 2

6+30

EMU DUST EVA-2	DUST SEP Rcvr: •Blnkt A open VERIFY: •Pwr sw - OFF - •Rcdr - OFF -	CDR-32
	TGE to R. side MESA, IN SHADE TGE - GRAV - Tidy MESA blnkt	
6+45	DUST EMU'S - •Stow PLSS ants (CDR/LMP) Brush to ladder hook EVA 2 pallet to LMP •LiOH cans - pins green [INGRESS TGE - READ - then ***STBY*** Open TGE thermal lid & dust	EVA-2 11-8-72

- (1) CDR - TGE GRAV
- (1) CDR/LMP - PLSS Antennas
Stowed - Verify

	CDR	LMP
O2		
FLAGS		
PRESS		
COOL		

- (1) CDR/LMP - EMU Check
- (1) CDR - Verify LCRU Blankets
100%, Pwr Sw - OFF
- (1) CDR - Verify CB's A - B - C - D
pulled
Batt covers open
(Radiators clean/dirty)
Verify brush stowed

6+40

LMP-30 EVA-2	Underseat samples to Big Bag •Deploy Cosmic Ray* •Shade side first ETB to CDR footpan Stow ETB: •2 cams, lenses inboard •5 mags (rpt mag/frame) •500mm mag R •Maps ETB to LEC hook SCB 4 & 6 to porch bulkhead EVA-2 pallet on table •ECS LiOH can to pocket •LiOH cans - pins green	EVA-2 11-8-72
	6+45 DUST EMU'S •Stow PLSS ants (CDR/LMP)	

- (1) CDR - Verify Dusting

TRANSFER ITEMS:

SCB 4 & 6

Pallet 2 (with ECS LiOH can)

LMP-32 EVA-2	Get EVA-2 pallet from CDR [PALLET TO LMP] INGRESS w/pallet Stow pallet equip •Food first •LiOH cans 16mm cam - OFF - Hand pallet to CDR Receive & stow: •SCB 4 •SCB 6 •SRC 2 •ETB Assist CDR 6+57 Close Hatch 6+58 Repress	EVA-2 11-8-72

- (1) CDR - TGE RDG _____
TGE - STANDBY

- (1) LMP - Verify PLSS LiOH can pins green

6+50

MISSION: APOLLO 17
 EVA: 2

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
SECURE 'SUN' PART, SURFACES OUT, TO VELCRO ON	6+30	LCRU PWR SW - 'OFF'		
SECONDARY STRUT, -4 OR +4 LANDING GEAR		DUST TV, TCU		
GET ETB, PLACE ON CDR PAN		DUST LRV BATT COVERS, OPEN COVERS		
STOW: 4-MAGS		DUST LCRU		
MAPS		VERIFY LCRU BLANKETS OPEN 100%		
2-CAMERAS		FINAL LRV CHECK:		
500 CAM MAG		• BATTERY COVERS OPEN		
TAKE ETB TO LADDER, ATTACH LEC		• LCRU BLANKETS OPEN 100%		
TAKE SCB 4 & 6 TO PORCH		• SAMPLES OFF		
RETURN TO SURFACE		• EQUIPMENT STOWED		
REMOVE EVA 2 PALLET FROM MESA		DUST SEP RCVR		
PLACE PALLET ON SRC TABLE		• OPEN BLANKET A AND B		
PACK ECS LIOH CANNISTER IN POUCH		PLACE TGE ON SURFACE IN SHADE		
	GET DUST BRUSH			
	TGE - PRESS 'GRAV'			
	6+40			
EMU CLEAN		EMU CLEAN		
STOW ANTENNAS		STOW ANTENNAS		
HOLD STILL		DUST LMP		
DUST CDR		HAND DUST BRUSH TO LMP		
		HOLD STILL		
<u>EVA TERM</u>				
ASCEND LADDER		HAND EVA 2 PALLET TO LMP		
GET EVA 2 PALLET FROM CDR		PRESS TO 'READ', READ DATA TO MCC		
INGRESS ASCENT STAGE WITH PALLET		POSITION SW TO 'STNDBY'		
INTERIM STOW SUPPLIES FROM PALLET: FOOD & PLSS EXPEND; ECS, LIOH.		OPEN LID, DUST TGE		
VERIFY PINS GREEN ON PLSS CANS	6+50			

CREW EVA CHLCKLIST

VOICE DATA

EVA 2

CDR-33	Final Transfer Check: •EVA 2 pallet •ETB •SCB 4 •SCB 6 •SRC 2 •Big Bag if reqd	
EVA-2	SRC 2 to porch Hand in SCB 4 & 6 Hand in SRC 2 ETB up & in	EVA TERM
11-8-72	INGRESS 6+57 Close hatch 6+58 Repress	

6+50 Transfer Items: (CK)
 ETB
 SCB ____ (4) ____ (6)
 SRC 2
 Pallet 2

(1) LMP - Hatch closed _____

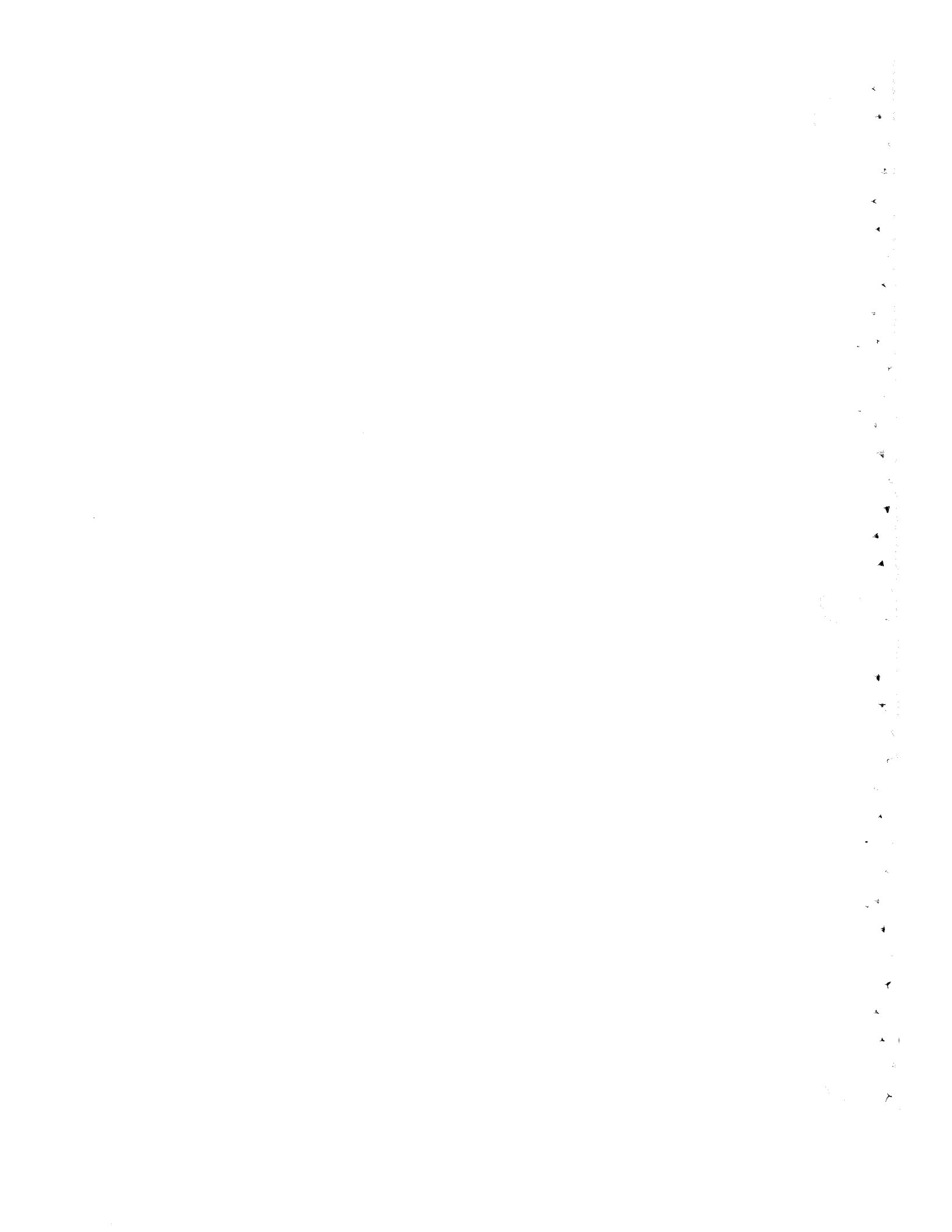
7+00 (1) CDR - Cabin Repress _____

LMP-32	Get EVA-2 pallet from CDR	PALLET TO LMP
EVA-2	INGRESS w/pallet Stow pallet equip •Food first •LiOH cans 16mm cam - Off - Hand pallet to CDR Receive & stow: •SCB 4 •SCB 6 •SRC 2 •ETB	
11-8-72	Assist CDR 6+57 Close Hatch 6+58 Repress	

MISSION: APOLLO 17
 EVA: 2

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
PASS OUT EVA 2 PALLET	6+50	GET SRC 2, CARRY UP TO PORCH		
RECEIVE & STOW SCB's		DISCARD EVA 2 PALLET HAND SCB 4 & 6 IN TO LMP		
RECEIVE & INTERIM STOW SRC 2		HAND SRC 2 TO LMP		
RECEIVE & STOW ETB		PULL ETB UP, HAND TO LMP		
ASSIST CDR		INGRESS CABIN		
CLOSE HATCH		CLOSE HATCH		
<u>REPRESS OPERATIONS</u>		<u>REPRESS OPERATIONS</u>		
	7+00			



3.3 EVA

FIGURE 3.3-1

NASA-S-72-3182-S

EVA 3 LRV TRAVERSE



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3.3 EVA 3

3.3.1 EVA 3 - GENERAL DESCRIPTION

EVA 3 begins with depressurization of the spacecraft cabin, followed by egress of the CDR, just as on the previous two EVA's. As before, he jettisons a bag of no longer needed gear, lowers the Equipment Transfer Bag to the ground, and descends to the surface. He is followed shortly thereafter by the LMP, who closes the ascent stage hatch after him. As before, the operations around the LM are concentrated on getting ready for the traverse this time to the North Massif area.

The CDR immediately upon gaining the lunar surface initiates a gravimetric measurement with the TGE, following which he changes the battery in the LCRU and brings up the television system. From this point on MCC and the general public have television coverage of the operations at Taurus Littrow.

The LMP unloads the ETB onto the LRV magazines and maps for use during the traverse. He powers up the LRV electrical system at this point to bring up the navigational system gyro (it requires nearly two minutes to reach operating speed).

The crew completes its around-LM activities by loading each other up with sample bags and tools. Then the CDR mounts the LRV for driveout to the SEP transmitter site, while the LMP walks out to that area. The CDR drives to the east leg of the crossed dipole on a parking heading of the 270 degrees to begin a navigational alignment procedure.

The LMP photos the relationship between this initialization location of the LRV and the SEP transmitter for establishing a baseline for SEP data obtained on EVA 3. He then turns on the SEP receiver-recorder and takes his place beside the CDR for driveout to the first station on EVA 3, Station Six.

Objectives of the EVA 3 traverse are to investigate and sample the North Massif and sculptured hills material to the north and northeast of the landing site, further investigation and sampling of the dark mantle and plains material, emplacement of seismic profiling charges, obtaining traverse gravimeter measurements, and obtaining data for the Surface Electrical Properties (SEP) experiment.

The traverse proceeds in a northerly direction (see Fig. 3.3-1) to Station 6 with a single LRV sampling stop en route. Approximately two and a quarter hours station time is spent in the North Massif sculptured hills area at three major stations (Stations 6, 7, and 8). Proceeding westerly from Station 8, the traverse continues to Station 9,

where a fresh 80 meter crater provides an opportunity to investigate the dark mantle and possibly learn something about its stratigraphy.

Leaving station 9, the traverse route goes in a southerly direction to Station 10. A single LRV sampling stop is made en route to this station. Sampling and observations of the dark mantle and plains material occupy the thirty-odd minutes available at Station 10.

The traverse then wends its way back to the spacecraft via an explosive Package deployment site 0.25 km from the ALSEP site. This charge is a 1/4 lb one.

The crew then stops at the LM. They immediately unload their PLSS tool harnesses and get the sample bags ready for transfer to the ascent stage. Several bags are, in fact, taken to the porch of the LM by the LMP at this time. The CDR makes a gravimetric measurement with the TGE.

The LMP loads up the ETB with camera magazines and the map package, while the CDR recovers the tape recorder from the SEP receiver, and takes down the two halves of the Cosmic Ray Experiment, which, it will be remembered, were hung up on the spacecraft at the beginning of EVA 1.

The CDR and LMP part company at this time. The CDR mounts the LRV to drive it to its final disposition site, jocularly called "V.I.P.", while the LMP trudges out to the ALSEP site to recover the Neutron Flux Experiment.

The CDR drives some 0.1 km East by SE not very far from the SEP transmitter. He parks the LRV to a prescribed heading, leaves the TV System in operation, and connected to LRV battery power. He thoroughly cleans the batteries and communications system, and removes the last Explosive Package from the aft end of the LRV. He deploys this charge some distance away from the LRV (later, long after the crew returns to the CM, the TV system will watch this charge detonate). He turns off the now-useless SEP transmitter, and returns to the LM.

The LMP uses the core-sample jacking mechanism to withdraw the two-part Neutron Flux Experiment from the lunar surface. He "turns off" each section of the experiment after disassembling them, and returns to the spacecraft with the experiment. He bags the two sections for transfer and stowage.

It is anticipated that the LMP will be back at the LM before the CDR completes his tasks at the "V.I.P." site. The LMP, accordingly,

polices the area, kicks as much loose gear as possible under the LM descent stage to preclude blowing it into the ALSEP area during LM ascent.

The two crewmen clean each other off, and effect a series of transfers of bags and gear to the ascent stage. The LMP enters the ascent stage first to receive and stow these items, and is followed shortly thereafter by the CDR to closeout the final EVA on Apollo 17 and the Lunar Landing Program.

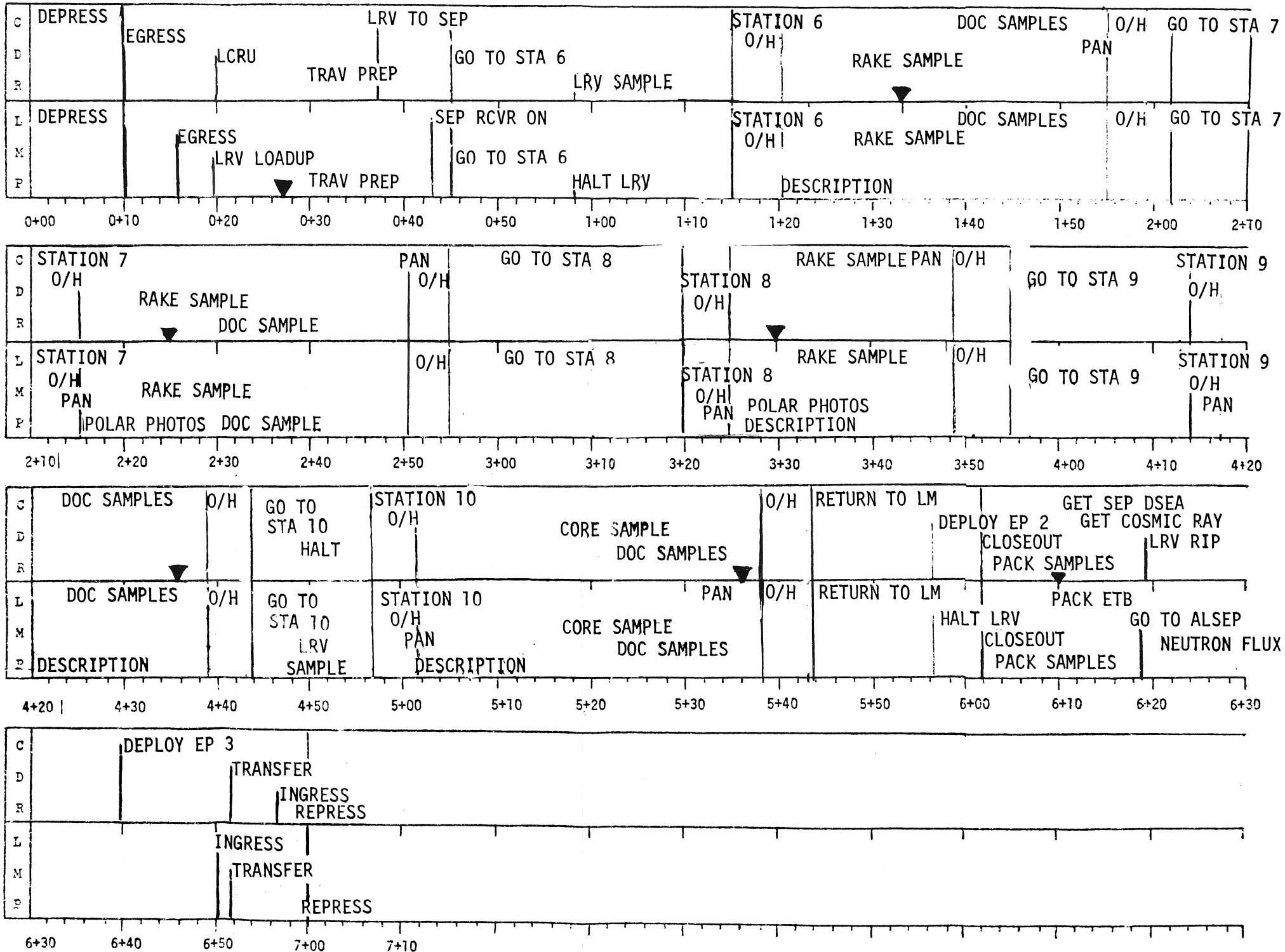
Figure 3.3-2 summarizes this EVA in a block timeline, figures 3.3-3 through 3.3-7 provide task information for each of the stations planned for EVA 3.

FIGURE 3.3-2

APOLLO 17 LUNAR SURFACE TIMELINE

EVA 3

DATE NOV. '72



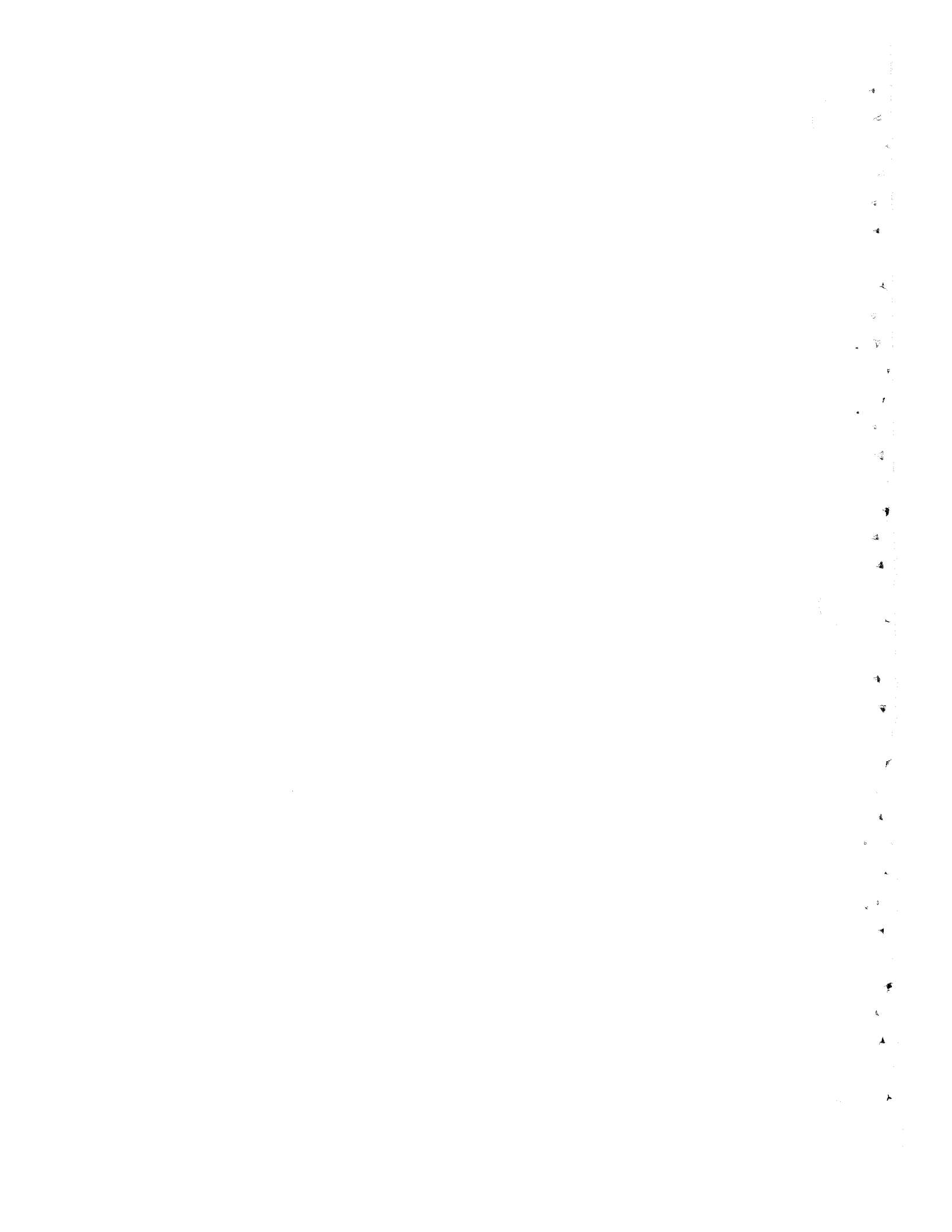


FIGURE 3.3-3

Stations' 6 and 7 TASKS

EVA-3

Stations 6 and 7

Station time 1+34

Location: Field of large blocks near base of north massif. West end (Station 6) defined as 8x16m block near 20m fresh crater.

Geologic setting: As at Station 2, the north massif materials, most probably ejecta from the moon's large basins, are thought to be buried by talus on the lower mountain slopes. In contrast to the sharp mountain foot at Station 2, the lower slope of the north massif grades through a gentle curve into the subhorizontal surface of the valley floor. Presumably the boundary has been subdued by accumulation of materials, including dark mantle, that have been transported down slope by mass wasting. The valley floor is covered by dark mantle, which extends upward locally onto the lower massif slopes.

Several large blocks, thought to be derived from the north massif are present near the mountain foot. Particularly notable is a large (8x16m) block lying at the end of a trail more than 1km long on the mountain face. A sharp crater near the block may contain reworked massif materials in its ejecta.

Objectives:

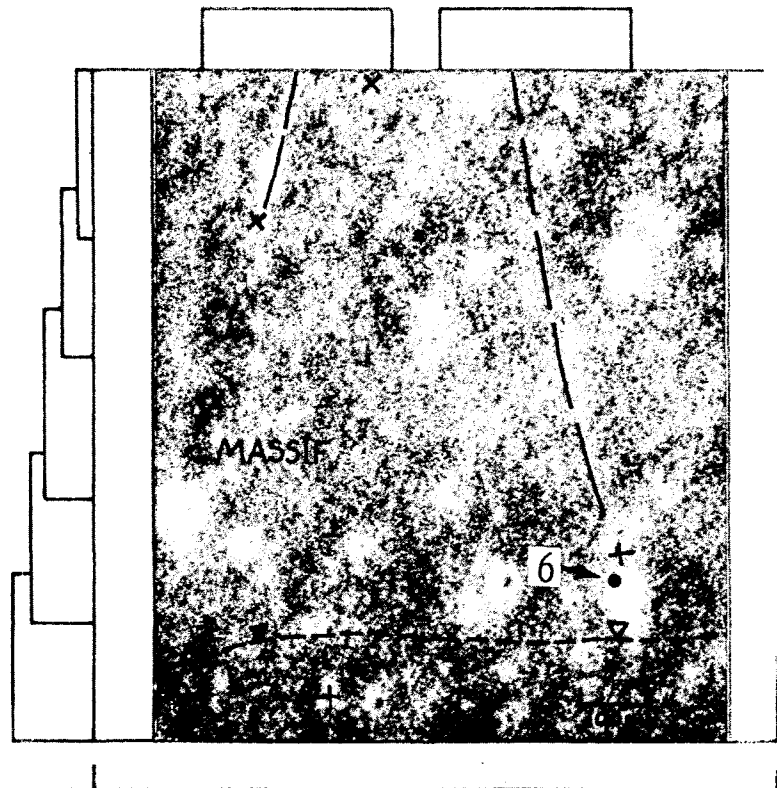
Characterize and sample materials representing the north massif.
Sample dark mantle.

EVA-3 - Station 6 and 7 continued

<u>Tasks *</u>	<u>Rationale</u>
<u>North Massif:</u>	
Documented samples from large blocks with special emphasis on blocks with tracks	Large blocks provide variety of clasts in their matrix - thus most detailed characterization of massif materials; blocks with tracks most probably derived from massif
<u>Observe/photograph tracks and block sources</u>	Identification of sources may permit stratigraphic analysis of massif
<u>Observe/photograph block structures and textures</u>	History of emplacement and subsequent modification of massif materials
<u>Rake/soil and documented samples of rocks on rim of bright 20 m crater</u>	Sample representative colluvium at massif base; may include both massif debris and dark mantle from massif surface.
<u>Rake/soil and documented samples of massif materials on top of or mixed with dark mantle (especially if bright 20 m crater does not excavate massif colluvium)</u>	Attempt to collect fragments of massif colluvium.
<u>Dark mantle:</u>	
<u>Documented sample from plains surface near massif base</u>	Lateral variation in dark mantle composition; compare with other stations
<u>Observe/photograph relations between blocks and dark mantle</u>	Timing, mechanism of emplacement of blocks or dark mantle.
<u>Single core</u>	Lateral and vertical variation in dark mantle

* Considered to be an all inclusive shopping list of tasks if time were available. The station timeline which follows presents the particular tasks (and time allocations) which were selected as the nominal station activities.

	CDR	LMP
<u>Initial overhead (includes TGE, TV pan)</u>	5	5
<u>Observation</u>	5	5
<ul style="list-style-type: none"> •Block tracks and sources (500 mm) •Block structures and textures •Block/mantle relationships •Slope/mantle relationships •Stations 7, 8 •Compare lithologies of blocks, crater rims, talus 		
<u>Blocks</u>		
•Documented sampling	15	15
<u>Talus</u>	8	8
<ul style="list-style-type: none"> •Documented sampling •Single core 		
<u>Crater (20 m, fresh)</u>	9	9
<ul style="list-style-type: none"> •Documented sampling •Rake/soil (Kg) 		
<u>Pans</u>	1	1
<u>Final overhead</u>	4	4
	47	47



Initial overhead (includes TGE, TV pan)

CDR LMP

5 5

Observation

5 5

- Block tracks and sources (500 mm)
- Block structures, textures
- Block/mantle relationships

Blocks

21 18

- Documented sampling

Dark Mantle

11 11

- Documented sampling
- SESC - permanently shadowed soil (east-west split)

Pans

1 1

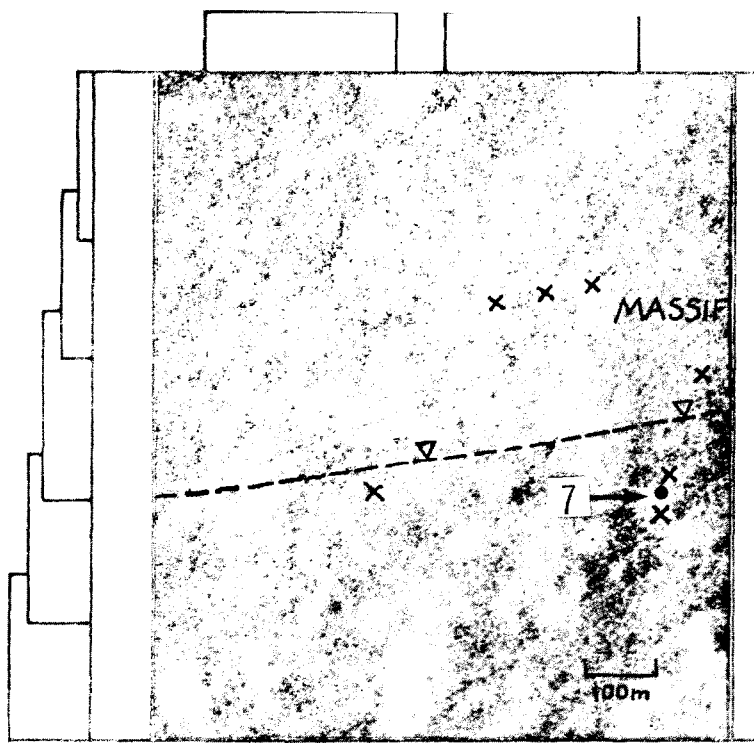
Polarimetry - Sculptured Hills

3

Final overhead

4 4

47 47



EVA-3

Station 8

Station time 0+47

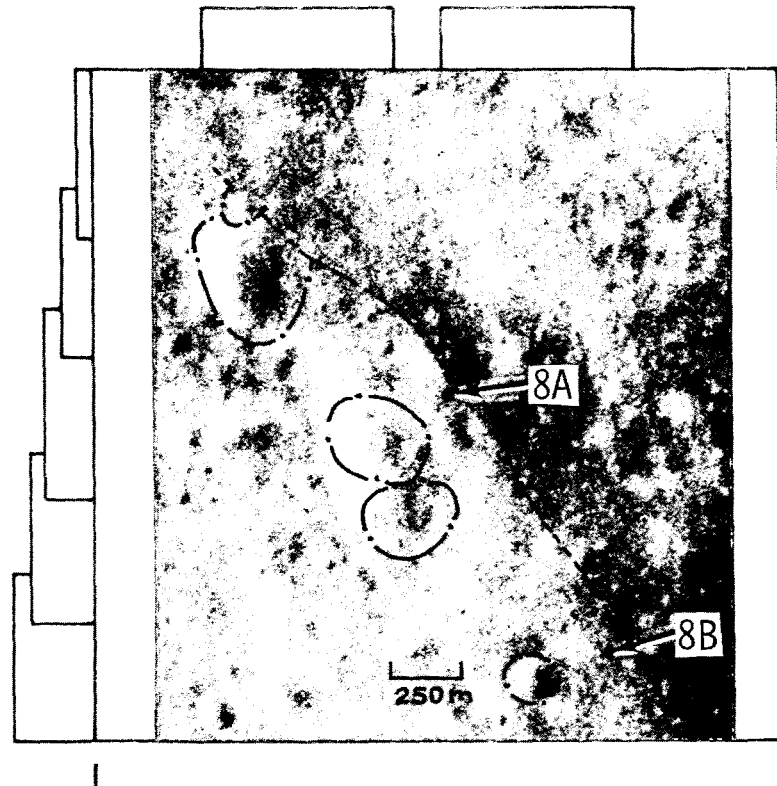
Location: Base of sculptured hills.

Geologic setting: Sculptured hills material underlies much of the highland area between the Serenitatis and Crisium basins. The base of the hills grades gently into the subhorizontal valley floor; apparently a thick accumulation of mass wasted materials has subdued the topographic break at the base of the slope.

Dark mantle covers the valley floor and extends well up onto the slope at the station. Craters that excavate materials from beneath the dark mantle have not been positively identified on the accessible part of the slope.

Objectives:

Characterize sculptured hills unit
Compare with massif and subfloor materials
Sample dark mantle



Sampling criteria:

- 1) area in which debris from hillside (other than dark mantle) is visible on surface of lower slope, or
- 2) crater on lower slope that excavates materials distinct from dark mantle, or
- 3) largest, freshest crater as high on lower slope as possible

<u>Tasks*</u>	<u>Rationale</u>
<u>Sculptured hills:</u>	
<u>Observe/photograph</u> lithology of blocks, rocks from sculptured hills	Characterization, comparison with massif and plains materials; sampling rationale; history of emplacement and deformation
<u>Trench</u> , observe soil	Colluvium from sculptured hills may be mixed with dark mantle - hence, may be sampled in soil
<u>Block area</u>	
<u>Documented samples</u> - blocks, rocks	Characterization of sculptured hills materials
<u>Rake/soil</u> (interblock area)	Attempt to concentrate fragments of sculptured hills material from soil
<u>Crater area</u>	
<u>Documented samples</u> - rocks from crater rim	Crater may excavate colluvium including sculptured hills material from beneath dark mantle
<u>Rake/soil</u> at crater rim	Attempt to concentrate fragments of sculptured hills material from soil excavated in small cratering event
<u>Dark mantle:</u>	
<u>Documented samples</u>	Comparison with other stations (i.e. lateral variation)
<u>Pans</u>	Location, sampling context

* Considered to be an all inclusive shopping list of tasks if time were available. The station timeline which follows presents the particular tasks (and time allocations) which were selected as the nominal station activities.

EVA 3

Station 8 Timeline

0 + 47*

	CDR	LMP
<u>Initial overhead</u>	5	5
<u>Observation</u>	10	10
•Rock tracks and sources		
•Rock lithology - compare with massifs		
•Hills debris in soil (trench)		
•Dark mantle occurrence		
<hr/>		
<u>Sculptured Hills material</u>		
<u>Rock debris</u> (on surface)	24	24
•Documented sampling		
•Rake/soil (interblock area) (Kg)		
	OR	
<u>Crater</u>	24	24
•Documented sampling (ejecta)		
•Rake/soil (ejecta) (Kg.)		
•Rake/soil (inter-crater area)		
	---	---
<hr/>		
<u>Dark mantle</u>	- 3	3
•Documented sampling		
<u>Pans</u>	1	1
<u>Final overhead</u>	4	4
	<hr/>	<hr/>
	47	47

* 47 minutes is available for station 8 provided an appropriate sampling site is found at the first encounter with the sculptured hills region (station 8A). If it is necessary to range along the base for some distance (approximately 1 km is allowed), the increased driving time to station 8 (and subsequently back to station 9) is about 10-12 minutes and will be done at the expense of station 8 time; the observation time will be reduced to a minimum on the premise that observations from the LRV (while driving) will suffice; thereafter, reduction in sampling time will be necessary.

Location: Sharp-rimmed 80m crater on valley floor about 2km northeast of the landing point.

Geologic setting: The 80m crater has a lumpy floor and a sharp raised rim. It occurs on the valley floor in an area extensively covered by dark mantle. No blocks are visible in its ejecta, and its walls, floor, and rim are indistinguishable in albedo from the surrounding dark mantle.

Most probably the crater was formed by impact, but volcanic origin is a viable alternate hypothesis. The freshness of the crater suggests that fresh ejecta can be sampled at the surface. However, the uniformity of albedo across the ejecta and onto the surface of the surrounding valley floor causes worry that a young thin deposit of dark mantle material could coat the crater ejecta.

Objectives:

Determine historical sequence and lateral continuity of dark mantle at young 80m crater.



EVA-3 - Station 9 continued

<u>Tasks*</u>	<u>Rationale</u>
<u>Observe/photograph</u> ejecta, rim, crater interior	Crater origin; sampling rationale
<u>Radial sample</u> (dixie cup) 5 sample minimum	Stratigraphy of dark mantle
<u>Documented samples</u> -rocks and soils at crater rim (possible rake sample)	Characterize lithology of dark mantle; possible sample of subfloor material; exposure age of crater
<u>Stereo-pan</u> at crater rim	Vantage point for crater structure and regional setting

* Considered to be an all inclusive shopping list of tasks if time were available. The station timeline which follows presents the particular tasks (and time allocations) which were selected as the nominal station activities.

EVA 3

Station 9 Timeline

0 + 30

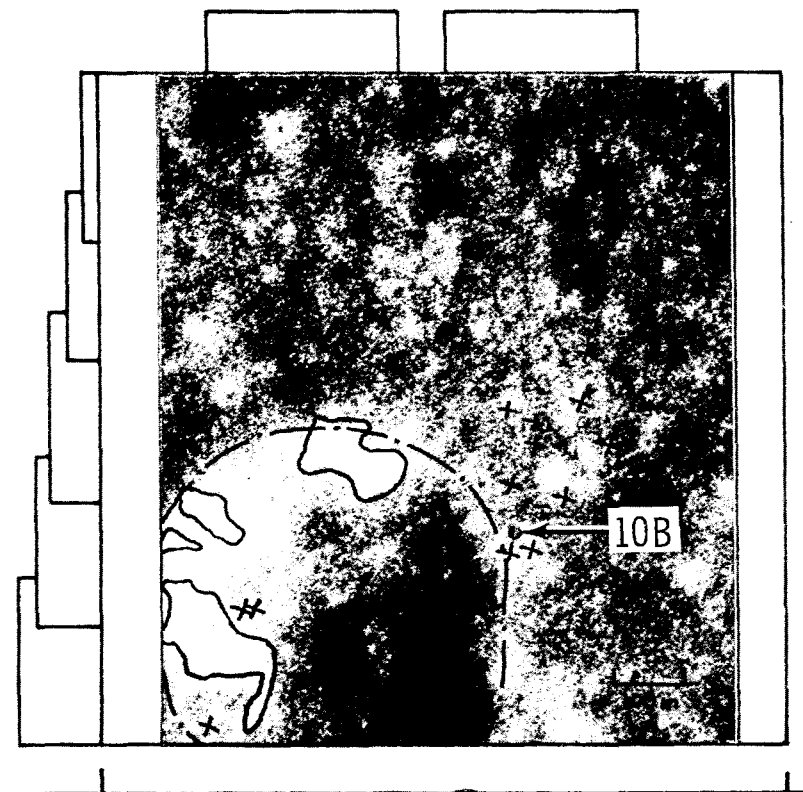
	CDR	LMP
<u>Initial overhead</u>	5	5
<u>Observation</u> •Relation of dark mantle to crater •Crater interior, deposits (origin)	5	5
<u>Crater</u> •Documented sampling (rim) possible rake/soil •Pan (rim) (stereo of crater interior) •Radial sampling (dixie cup) - by LMP (at least 5 samples)	11	16
<u>Dark mantle</u> •Documented sampling •Pan	5	0
<u>Final overhead</u>	4	4
	<u>30</u>	<u>30</u>

Location: Block field just northeast of Sherlock crater.

Geologic setting: Subfloor material is exposed in the west and north walls of Sherlock crater. The northeast part of the crater is extensively covered by dark mantle. However, a number of large blocks apparently protrude through the dark mantle on and beyond the northeast crater rim. Their occurrence near the crater rim suggests that they are ejecta from Sherlock. If so, they are most probably derived from the subfloor.

Objectives:

Compare, contrast numerous blocks with subfloor materials at Stations 1 and 5.
Sample dark mantle.



EVA-3 - Station 10B continued

<u>Tasks*</u>	<u>Rationale</u>
Blocks:	
<u>Observe/photograph</u> block textures and structures	Characterization, origin, history of subfloor materials
<u>Documented samples</u> of blocks	Extend subfloor sampling begun at Stations 1 and 5
Dark mantle:	
<u>Observe/photograph</u> relation of dark mantle to blocks	Mechanics of dark mantle emplacement
<u>Documented sample</u>	Comparison with dark mantle of other localities
<u>Double core</u>	Depositional and weathering history

* Considered to be an all inclusive shopping list of tasks if time were available. The station timeline which follows presents the particular tasks (and time allocations) which were selected as the nominal station activities.

EVA 3

Station 10B Timeline

0 + 47

	CDR	LMP
<u>Initial overhead</u>	5	5
<u>Observations</u>	5	5
•Block textures and structures compare with stations 1, 5		
•Relation between dark mantle and blocks		
<u>Blocks</u>	21	21
•Documented sampling		
<u>Dark mantle</u>	11	11
•Documented sampling		
•Double core		
<u>Pans</u>	1	1
<u>Final overhead</u>	4	4
	—	—
	47	47



3.3.2 EVA-3 TRAVERSES

This section is comprised of a tabular summary of the EVA 3 activities. Table 3.3-1 provides calculated data on distances, velocities, and times as the crew goes through their station stops, packs the LRV for the last time, and closes out the final EVA of the final Apollo moon mission. The tabular data also show the time of deployment and location of the two explosive packages deployed on EVA 3.

The table also provides traverse contingency information, LRV - or PLSS - malfunctioned walkbacks or ridebacks.

Table 3.3-2 lists input data for the program that generated Table 3.3-1.

Finally, Table 3.3-3 provides the basic assumptions inherent in the layout of the EVA traverses.

TABLE 3.3-1 APOLLO 17 TAURUS LITTON TRAVEL

EVA 3B

CALCULATED DATA

OCT 30 1972

EVA START 162:40 HR:MIN GET

STATION	SEGMENT DISTANCE (KM)	LRV MOBILITY RATE (KM/HR)	RIDE TIME (MIN)	TOTAL TRAVEL DISTANCE (KM)	ARRIVE STATION EVA TIME (HR+MIN)	STOP TIME (HR+MIN)	DEPART STATION EVA TIME (HR+MIN)
LM				0.00	0+ 0	0+45	0+45
RIDE	1.63	7.30	13				
LRV-3A				1.63	0+58	0+ 2	1+ 0
RIDE	1.75	7.30	14				
6				3.38	1+15	0+47	2+ 2
RIDE	0.75	7.30	6				
7				4.13	2+ 8	0+47	2+55
RIDE	3.03	7.30	25				
9B				7.16	3+20	0+35	3+55
RIDE	2.30	7.30	19				
9				9.46	4+14	0+30	4+44
RIDE	0.64	7.20	5				
LRV-3A				10.10	4+49	0+ 2	4+51
RIDE	0.73	7.30	6				
10B				10.83	4+57	0+47	5+44
RIDE	1.60	7.30	13				
1/4#CH R=.25				12.43	5+57	0+ 3	6+ 0
RIDE	0.65	7.30	0				
1/8#CH R=.20				12.48	6+ 1	0+ 3	6+ 4
RIDE	0.15	7.30	1				
LM				12.63	6+ 5	0+55	7+ 0
TOTALS			104			5+16	7+ 0

----- TRAVERSE CONTINGENCIES -----

STAT NO	RETURN DISTANCE TO LM (KM)	WALKBACK			STATION MARGIN ABOVE		MIN LRV RIDEBACK		AVG EVA NET RATE (BTU/HR)
		TIME TO LM (HR+MIN)	FM (HR+MIN)	REQD (HR+MIN)	ABOVE (HR+MIN)	0 MIN SPEED REQUIRED (KM/HR)	10 MIN (KM/HR)		
LM	0.00	0+ 0	****	****	****	0.00	0.00	1000.00	
LRV-3A	1.65	0+37	5+30	5+ 4	5+54	1.60	1.91	895.76	
6	3.40	0+57	3+49	3+23	4+24	3.30	3.94	895.70	
7	3.56	0+59	3+54	3+28	3+22	2.46	4.12	898.11	
9B	4.51	1+40	1+23	0+57	1+47	4.35	5.22	868.33	
9	2.39	0+40	1+49	1+24	1+58	2.32	2.77	856.25	
LRV-3A	1.98	0+33	1+54	1+29	1+52	1.92	2.29	871.36	
10B	1.30	0+30	1+ 7	0+42	1+ 8	1.75	2.05	858.53	
1/4#CH R=.25	0.20	0+ 3	1+35	1+11	1+19	0.19	0.23	849.03	
1/8#CH R=.20	0.15	0+ 2	1+33	1+ 9	1+16	0.15	0.17	849.53	

TABLE 3.3-2 APOLLO 17 TAURUS LITTRON TRAVERSES

EVA 3B

INPUT DATA

OCT 30 1972

EVA START 162:40 HR:MIN GET

STATION NO	STOP TIME (HR+MIN)	SEGMENT DISTANCE (KM)	RETURN DISTANCE (KM)	HEAT LEAK (BTU/HR)	-MOBILITY RATES- WALK (KM/HR)	RIDE (KM/HR)	MET RATE WALK (BTU/HR)
LM	0+45	0.00	0.00	200.00	****	****	*****
LRV-SA	0+ 2	1.63	1.65	200.00	3.60	7.30	1560.0
6	0+47	1.75	3.40	200.00	3.60	7.30	1560.0
7	0+47	0.75	3.56	200.00	3.60	7.30	1560.0
8B	0+35	3.03	4.51	200.00	2.70	7.30	1290.0
9	0+30	2.30	2.39	200.00	3.60	7.30	1560.0
LRV-SA	0+ 2	0.64	1.98	200.00	3.60	7.30	1560.0
10B	0+47	0.73	1.80	200.00	3.60	7.30	1560.0
1/4#CH	0+ 3	1.60	0.20	200.00	3.60	7.30	1560.0
R=.25							
1/8#CH	0+ 3	0.05	0.15	200.00	3.60	7.30	1560.0
R=.20							
LM	0+55	0.15	0.00	200.00	3.60	7.30	1560.0

MET RATE ALSEP (BTU/HR)	MET RATE RIDING (BTU/HR)	MET RATE STATION (BTU/HR)	MET RATE LM O/H (BTU/HR)	LEAK RATE (LB/HR)	EVA START (CF/0-LE)	EVA START (02-LE)	OPS TIME (MIN)
1050.00	550.00	950.00	1050.00	0.035	11.29	1.353	61.2

NOTE: OPS TIME IS TOTAL DRIVING TIME AVAILABLE!

TABLE 3.3-3

LRV TRAVERSE ASSUMPTIONS

1. 30 MINUTES RESERVES MAINTAINED ON ALL PLSS CONSUMABLES AT STATION METABOLIC RATE
2. ALL DISTANCES AND SPEEDS ARE MAP DISTANCES AND MAP SPEEDS (MOBILITY RATES)
3. REQUIRED RATE = RETURN DISTANCE/AVAILABLE OPS RIDING TIME
AVAILABLE OPS RIDING TIME = TOTAL OPS TIME LESS ALLOWANCES
ALLOWANCES $\left\{ \begin{array}{l} 5 \text{ MIN BSLSS HOOKUP} \\ 13 \text{ MIN LM INGRESS} \end{array} \right.$
4. TIME MARGIN AT STATION METABOLIC RATE
TIME REMAINING AFTER ALLOWANCE
STATION MARGIN = FOR 10 MINUTES AT LRV, WALKBACK, AND 13 MINUTES INGRESS
5. FINAL LM O/H MARGIN = TIME REMAINING WITH NO ALLOWANCES
6. RESPIRATORY EXCHANGE QUOTIENT = 0.9
7. FEEDWATER HEAT OF VAPORIZATION 1038 $\frac{\text{BTU}}{\text{LB}}$

3.3.3 DETAILED EVA 3 TIMELINE PROCEDURES

The detailed procedures for EVA 3 are shown on the following vertical format pages. The crew cuff check list pages which correspond approximately to the timeline are shown on the far left-hand facing sheets together with the Voice Data Plan.

CREW EVA CUFF CHECKLIST

VOICE DATA

EVA 3

EVA-3	
PLSS H2O LM H2O TRANSFER	SS72
PLSS Pump - OFF - Disconnect PLSS H2O Connect LM H2O CB(76) ECS: LCG Pump - Close	
LM - PLSS H2O TRANSFER	
CS(76) ECS: LCG Pump - Open Disconnect LM H2O Connect PLSS H2O PLSS HMP - ON	

CODE:

- (1) Mandatory requirement for data at time or event designated
- (2) Data may be deferred until later in EVA or debriefing

At start of EVA:

SUN ANGLE ~ 36.5°
LM SHADOW ~ 8.8 m (29 ft)
ASTRONAUT SHADOW ~ 2.4 m (8 ft)

EGRESS EQUIP PREP	0+00 CABIN DEPRESS Start watch (call mark)	CDR-4
	0+10 EGRESS/PORCH Jett bag - discard ETB to LEC & lower TGE - ON - TGE - READ - Deploy PLSS ants (CDR/LMP) EGRESS	EVA-3
	0+16 LCRU Change LCRU batt (CDR seat) Pwr sw - INT - VERIFY: • Mode sw - 3 - (IV RMT) • LCRU blinkts - 100. open Batt covers closed & tight Orient HGA LRV cbs Bus A,B,C,D close • VERIFY NAV cb - close	11-8-72

0+00

(1) CDR/LMP - EVA watch start MARK _____

(2) ETB Contents:

CDR HEDC with Mag _____(E)
LMP HEDC with Mag _____(L)
Mags _____(F) _____(K) _____(M) _____(N)
_____ (R) _____(D)

Maps

Polar filter

(2) LMP - verify CB Config OK

EGRESS EQUIP PREP	0+00 CABIN DEPRESS Open hatch	LMP-4
	0+10 CDR EGRESS Assist CDR Jett bag to CDR ETB to CDR Tape Recorder - OFF - VERIFY: • Vex Sens (2) - max - • CB Config (White dots out • EVA decals) Utility Floodlights - OFF - Illum cam EGRESS [LCRU/TV Close hatch Deploy PLSS ants (CDR/LMP)	11-8-72

0+10

APOLLO 17
NOMINAL TIMELINE
LUNAR SURFACE EVA 3

NOVEMBER 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			L	C
<u>PRE-EGRESS OPERATIONS</u>	0+00	<u>PRE-EGRESS OPERATIONS</u> Start EVA watch (Call "MARK")	PRE-EGRESS OPERATIONS	PRE-EGRESS OPERATIONS
NOTE: detailed procedures are presented in "Lunar Surface Checklist" Equipment Prep - EVA 3 Section				
<u>EGRESS OPERATIONS</u>	0+10	<u>EGRESS OPERATIONS</u>		

CREW EVA CUFF CHECKLIST

VOICE DATA

EVA 3

0+10

- (1) LMP - LM switches,
Tape Recorder - OFF
Vox Sens (2) - MAX

CB Config
Utility Floodlights - OFF

- (1) CDR/LMP - EMU check

	CDR	LMP
O2		
FLAGS		
PRESS		
COOL		

- (1) CDR - TGE ON _____
- TGE READ _____

0+20

- (1) CDR - Deploy PLSS antenna (LMP)
- (1) LMP - Deploy PLSS Antenna (CDR)
- (1) CDR - Power sw - INT Verify LCRU Batt Change
-LCRU Blankets open 100%
-LRV Bat covers closed
- (1) LMP - ETB items stowage:
Mags under CDR seat (F, M,N,K, R, D)
Maps to holder (via LMP seat)
Mag R to 500 mm Camera

- (1) CDR - LRV CB's A,B,C,D, NAV - IN
- (1) LMP - SEP RCVR - STNDBY
SEP RCVR Temp _____
- SEP RCVR Sw - OFF

- (1) CDR - Dust brush to LCRU

- (1) CDR - TGE GRAV

0+30

CDR-4
EVA-3
11-8-72

0+00 CABIN DEPRESS
Start watch (call mark)

0+10 EGRESS/PORCH
Jett bag - discard
ETB to LEC & lower
TGE - ON -
TGE - READ -
Deploy PLSS ants (CDR/LMP) [EGRESS]

0+16 LCRU
Change LCRU batt (CDR seat)
Pwr sw - INT -
VERIFY:
• Mode sw - 3 - (TV RMT)
• LCRU blinks - 100% open
Batt covers closed & tight
Orient HGA
LRV cbs Bus A,B,C,D close
• VERIFY NAV cb - close

CDR-5
EVA-3
11-8-72

TGE - GRAV -

TO LRV:
Big Bag to gate
Dust brush to LCRU

0+20 EQUIP PREP [LRV EQUIP]
SCB 7 to gate (LMP seat)
Mount 20 bag disp on CDR
cam
20 bag disp to LMP footpan
Core cap disp to gate PAN
Short can under LMP seat

CDR-4
EVA-3
11-8-72

0+00 CABIN DEPRESS
Open hatch

0+10 CDR EGRESS
Assist CDR
Jett bag to CDR
ETB to CDR
Tape Recorder - OFF -
VERIFY:
Vox Sens (2) - max -
CB Config (White dots out
- EVA decals)
Utility Floodlights - OFF -
16mm cam
EGRESS [LCRU/TV]
Close hatch
Deploy PLSS ants (CDR/LMP)

LMP-3
EVA-3
11-8-72

0+20 LRV EQUIP [EQUIP PREP]
ETB to CDR footpan
SEP Rcvr:
• Pwr sw - STRY
• Read temp
• Close blink A
To LMP seat:
• Maps
Stow under CDR seat
• 4 mags (rpt D,F,M,N)
• Mag R to 500mm
CDR cam on seat
Mount LMP cam
ETB to MESA table

Get CDR cam
Photo pan 12:00/30'
Doff cam to CDR seat

MISSION: APOLLO 17
 EVA: 3

DATE: NOV. 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION		
			L	M	P
ASSIST CDR	0+10	MOVE THRU HATCH			
PASS CDR JETTISON BAG		RECEIVE & TOSS JETTISON BAG TO -4 SIDE OF LM			
PASS ETB TO CDR		RECEIVE ETB			
VERIFY: TAPE RECORDER - OFF		HANG ETB ON LEC			
VOX SENS (2) - MAX		DESCEND LADDER TO TOP RUNG & LOWER ETB			
CB CONFIG					
UTILITY FLOODLIGHTS - OFF		DESCEND LADDER TO SURFACE			
<u>LMP EGRESS OPERATIONS</u>		KICK JETTISON BAG UNDER LM			
EGRESS LM TO PORCH		TGE - POWER SW - 'ON'			
PARTIALLY CLOSE LM HATCH		TGE - PRESS 'READ' - REPORT TO MCC			
DESCEND LADDER TO SURFACE					
DEPLOY PLSS ANTENNA - CDR		DEPLOY PLSS ANTENNA - LMP			
<u>LRV EQUIPMENT</u>		<u>LCRU & LRV</u>			
TAKE ETB TO CDR FOOTPAN	0+20	OPEN BATT ACCESS DOOR, PULL OUT OLD BATTERY - TOSS UNDER LM			
<u>SEP RECEIVER</u>		GET LCRU BATTERY UNDER CDR SEAT			
POWER SW (RCVR) - 'STANDBY'		INSTALL & CLOSE DOOR			
READ TEMP TO MCC		LCRU POWER SW - 'INT'			
VERIFY RECORDER SW - 'OFF'		MODE SW - 3(TV RMT)			
CLOSE BLANKET A		OPEN LCRU BLANKETS 100%			
<u>ETB</u>					
PUT BOTH CAMERAS ON LMP SEAT		CLOSE LRV BATT COVERS, PRESS TIGHT			
PUT MAPS ON LMP SEAT		ORIENT HGA			
STOW UNDER CDR SEAT		CLOSE LRV CB's - A, B, C, D			
4 MAGS - F, K, M, N, D		VERIFY NAV CB - CLOSED			
INSTALL MAG R ON 500		GET SAMPLE RET BAG (SRB)			
CAM & RESTOW		MOUNT ON AFT SIDE GEOPALLET			
MOUNT LMP CAM ON RCU					
RETURN ETB TO MESA TABLE		TAKE DUST BRUSH TO LCRU, STOW			
TAKE PHOTO PAN 12:00/30 FT		TGE - PRESS 'GRAV'			
PUT CAMERA ON LMP SEAT	0+30				

CREW EVA CHECKLIST

VOICE DATA

EVA 3

0+25 GEO PREP [GEO PREP] CDR-6
 Stow LMP PLSS
 • Cap disp (SCB 7)
 • Hammer
 • Hammer
 • SCB 8
 LMP to secure SCB 7
 TGE - READ -
 TGE to LRV
 LRV EQUIP CHECK:
 • EP Xptr (2,3)
 • LCRU blinks 100% open
 • LRV batt covers closed
 • Dust brush on LCRU
 • TGE
 • Mags & polar filter

SEP TRAV
 CDR-7
 11-8-72

0+30

(1) CDR/LMP - Report SCB's on PLSS's (Nos.)
 CDR _____ LMP _____

(1) CDR - TGE Read _____

(1) CDR - TGE to LRV

(1) CDR/LMP - leaving for SEP

SSDI	ROLL	PITCH
COMPUTED NAV HEADING		

0+40

(1) CDR - LRV displays + Volts _____ (1) _____ (2)

HEADING	Temp Bat 1
BEARING	Temp Bat 2
DISTANCE	Temp LF mtr
RANGE	Temp RF mtr
Amp-Hr Bat 1	Temp LR mtr
Amp-HR Bat 2	Temp RR mtr

(1) CDR - Report distance SEP/LRV

(1) LMP - SEP RCVR & RCDR - ON

(1) CDR - Position LGA 020°

(1) CDR - NAV Reset

(1) CDR - LRV underway

MARK _____

(1) CDR - Report passing end of SEP Antenna
 MARK _____

0+20 LRV EQUIP [EQUIP PREP] EVA-3
 ETB to CDR footpan
 SEP Rcvr:
 • Pwr sw - STRY
 • Read temp
 • Close blink A
 To LMP seat:
 • Maps
 Stow under CDR seat
 • 4 mags (rpt D,F,M,N)
 • Mag R to 500mm
 CDR cam on seat
 Mount LMP cam
 ETB to MESA table
 Get CDR cam
 Photo pan 12:00/30'
 Doff cam to CDR seat

EQUIP PREP
 EVA-3
 11-8-72

0+25 GEO PREP [GEO PREP] LMP-7
 Configure EVA maps
 Hold still [LOAD PLSS]
 SCB 7 to CDR PLSS
 Mount Cam

0+35 TRAV TO SEP EVA-3
 WALK to SEP Xptr [NAV INIT]
 Photo LRV/SEP: [SEP CALIB]
 • Stereo part pan dn-sun 50'
 SEP Rcvr:
 • Pwr sw - ON -
 • Rcdr - ON -

TRAV SEP
 11-8-72

0+50

MISSION: APOLLO 17
 EVA: 3

DATE: NOV. 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
			LCRU	TV
<u>GEOLOGY PREP</u>	0+30	<u>GEOLOGY PREP</u>		
LOAD LRV SAMPLER (BAGS UNDER LMP SEAT)		GET SCB 7 (LMP SEAT) PLACE ON TOOL GATE		
PLACE MAPS IN HOLDER		INSTALL 20 DSBD ON CDR CAM		
HOLD STILL		PUT 20 DSBD ON LMP FOOTPAN		
		PUT CORE CAP DISP ON TOOL GATE		
		LOAD LMP's PLSS:		
		RAMMER, HAMMER, CORE CAP DISPENSER, SCB 8		
PUT SCB 7 ON CDR PLSS		READ TGE AND LOAD TGE ON LRV		
		LRV EQUIP CHECK		
<u>TRAVERSE PREP</u>		<u>TRAVERSE TO SEP</u>		
MOUNT LMP CAMERA ON RCU		POSITION TV AFT & HORIZONTAL		
INSTALL 20 DSBD ON CAM		LCRU MODE SW - 1		
WALK TO SEP SITE		PUT ON CDR CAMERA		
(NE QUADRANT OF SEP TRANSMITTER ANTENNA ARRAY		MOUNT LRV & FASTEN SEAT BELT		
		POWER UP LRV		
	0+40	<u>NAV INITIATION</u>		
		READ SSD, ROLL, PITCH, LRV DISPLAYS		
		TORQUE GYRO AS REQUIRED		
		POWER UP LRV, DRIVE TO N LEG, H = 360°		
PHOTO LRV/SEP: STEREO PART PAN DN-SUN 50'		POWER DOWN LRV		
SEP RCVR & RCDR POWER - <u>ON</u>		NAV RESET SW - "RESET" - "OFF"		
MOUNT LRV & FASTEN SEAT BELT		POSITION LGA 020°		
GO TO STATION 6		POWER UP LRV		
		GO TO STATION 6		
	0+50			

CREW EVA CUFF CHECKLIST

VOICE DATA

CDR	0145 TRAV TO STA 6-27min (012/3.6)	TRAV STA 6
	<ul style="list-style-type: none"> *RT - variatn, dynam, pat gnd *Cra - strat, sources, reg *N. MASSIF - tal lim, flt, blks, trks, organ *Sculp Hills - ditto 	
EVA-3	192/0.7 N-S trough, JONES	TRAV STA 6
	192/1.6 LRV spl	
TAB-7C	192/1.8 AGRICULA-subflr, reg	TRAV STA 6
	192/2.2 HENRY-rim dome, subflr	
STA 6&7 area - blks, trks 196/3.1 tal contact 192 196/3.2 STA 6 (47 MIN) Park near blk & cra H=045 [STOP] SEP Rcdr -OFF- Mode sw - 2 - (FM/TV) HGA, Dust - gnomon/scoop TGE - GRAV - /rake		

EVA 3

0+50

(1) CDR/LMP - LRV: Speed _____
Amps _____

(1) LMP - samples bag no. _____

(1) CDR - NAV data

HEADING	
BEARING	
DISTANCE	
RANGE	

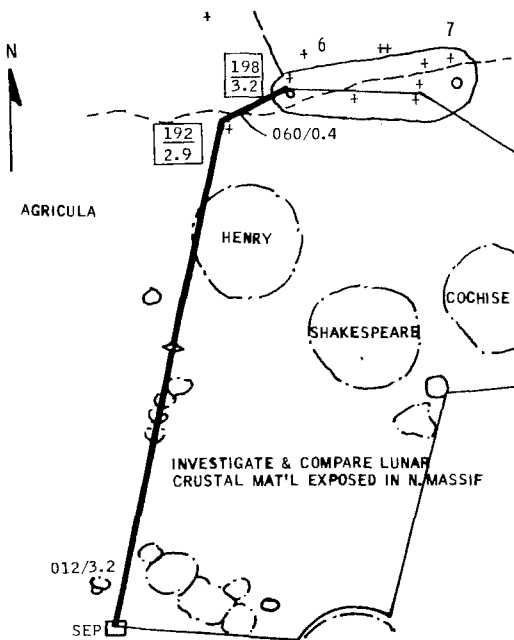
1+00

(1) CDR - LRV underway
MARK _____

(1) CDR/LMP - LRV: Speed _____
Amps _____

1+10

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MISSION: APOLLO 17
 EVA: 3

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	L C R I V	TASK FUNCTION	
				L M P	C D R
	0+50				
LRV SAMPLE		LRV SAMPLE			
Collect sample Photo PAN		Stop LRV Read NAV data Photo PAN			
	1+00				
CONTINUE TO STATION 6		CONTINUE TO STATION 6			
	1+10				

CREW EVA CUFF CHECKLIST

VOICE DATA

EVA 3

LMP-9	0+45 TRAV TO STA 6-2/min (012/3.6)	TRAV STA 6
	<ul style="list-style-type: none"> •Mel - variatn, dynam, pat gnd •Cra - strat, sources, reg •N. MASSIF - tal lim, flt, blks, trks, organ •Sculp Hills - ditto 192/0.7 N-S trough, JONES 192/1.6 LRV spl 192/1.8 AGRICOLA-subflr, reg 192/2.2 HENRY-rim dome, subflr 	
EVA-3	<p>STA 647 area - blks, trks</p> <p>196/3.1 tal contact</p>	
11-B-72	<p>1+12 198/3.2 STA 6 (47 MIN)</p> <p>Park near blk & cra</p> <p>H=045 [STOP] StP Rcdr -OFF-</p> <p>Mode sw - 2 - (FR/TV)</p> <p>HGA; Dust gnomon/scoop</p> <p>TGE - GRAV - /rake</p>	

1+10

(1) CDR - Station 6 arrival

(1) CDR - LRV data

HEADING		Temp Bat 1	
BEARING		Temp Bat 2	
DISTANCE		Temp LF mtr	
RANGE		Temp RF mtr	
Amp-Hr Bat 1		Temp LR mtr	
Amp-Hr Bat 2		Temp RR mtr	

(1) CDR - Verify Dusting

(1) CDR/LMP - SEP RCDR - OFF

(1) CDR/LMP - TGE - GRAV

1+20

(1) CDR/LMP - Pan locations

CDR-11	STA 6 (47 MIN) 198/3.2	STA 6
	OBSERVATION	
EVA-3	<ul style="list-style-type: none"> •Blks - trks, variety, struct •Talus - nature, cover, reg •Cra - rim pop, strat •Misc - xln rks 	
	<p>Blk</p> <ul style="list-style-type: none"> •Doc spl - variatn, tex 	
11-B-72	<p>Cra</p> <ul style="list-style-type: none"> •Rake - rim •Doc spl - variety, cover 	
	<p>Talus</p> <ul style="list-style-type: none"> •Doc spl - variety, dk mtl •Sgl core 	
	<p>Pans</p> <ul style="list-style-type: none"> •Stereo - base L contours 	

1+30

MISSION: APOLLO 17
 EVA: 3

DATE: NOV. '72

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	LCRU	TASK FUNCTION	
				LMP	CDR
	1+10				
STATION 6		STATION 6			
Dismount LRV TURN SEP RECORDER OFF Take photo PAN		Power down LRV Report nav & system data Dismount LRV			
Geological observations		LCRU mode sw - <u>2</u> Align HGA			
Get gnomon & scoop from aft pallet		Dust TV, TCU, LCRU Press GRAV on TGE Verify light flashing			
	1+20				
Observations		Observations			
		Photos			
		Get rake from tool gate (Verify TGE thru cycle)			
<u>RAKE SAMPLE</u>		<u>RAKE SAMPLE</u>			
Stow rake	1+30				

CREW EVA CUFF CHECKLIST

VOICE DATA

LMP-11	STA 6 (47 MIN) 198/3.2	STA 6
	OBSERVATION	
EVA-2	•Blks - trks, variety, struct	STA 6
	•Talus - nature, cover, reg	
11-B-72	•Gra - rim pop, strat	STA 6
	•Misc - xln rks	
	Blk	STA 6
	•Doc spl - variatn, tex	STA 6
	Cra	STA 6
	•Rake - rim	STA 6
	•Doc spl - variety, cover	STA 6
	Talus	STA 6
	•Doc spl - variety, dk mtl	STA 6
	•Sgl core	STA 6
	PANS	STA 6
	•Stereo - base ⊥ contours	STA 6

EVA 3
1+30

(1) CDR/LMP - RAKE sample

[A] Rocks Bag # _____

Soil Bag # _____

[B] Rocks Bag # _____

Soil Bag # _____

1+40

(1) CDR/LMP - EMU Check

	CDR	LMP
02		
FLAGS		
PRESS		
COOL		

1+50

CREW EVA CUFF CHECKLIST

VOICE DATA

CDR-13	STA 6 CLOSEOUT	SFP Rcdr - ON-
	TGE - READ -	TV cam; Mode sw - 1 - (FM/WD)
EVA-3	1+59 TRAV TO STA 7-11min (093/0.8)	LGA = OBS (frames, tools)
	2+10 210/3.5 STA 7 (47 min)	
11-8-72	Park	
	H=045 STOP SLP Rcdr - OFF-	Mode sw - 2 - (FM/TV)
	HGA; Dust	gnomon/scoop
	Polar filter	(1/125)
	TGE - GRAV -	

EVA 3

1+50

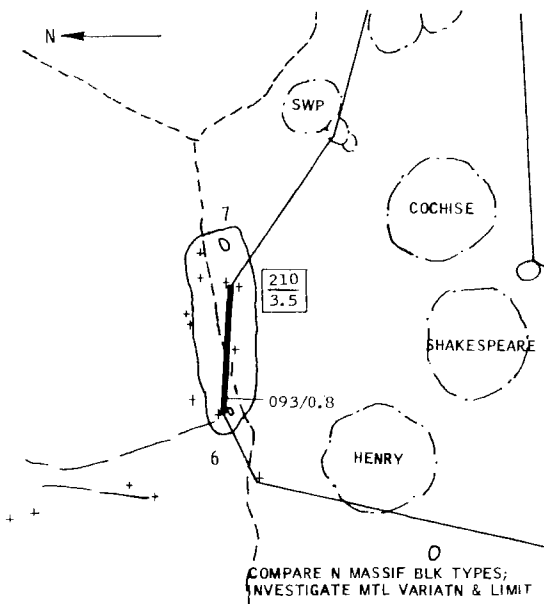
- (1) CDR - TGE Read _____
- (1) CDR/LMP - Mag/Frame
- CDR ___/___
- LMP ___/___
- (1) CDR/LMP - SEP RCDR - ON
- (1) CDR - LGA Azimuth _____ 090°
- (1) CDR - LRV underway MARK _____

2+00

- (1) CDR/LMP - LRV: Speed _____
- Amps _____

2+10

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CREW EVA CUFF CHECKLIST

VOICE DATA

11-8-72
EVA-3
LMP-13

STA 6 CLOSEOUT
TGE - READ - SEP Rcdr -ON-
TV cam; Mode sw - 1 - (PMI/WB)
LGA = 085 (frames, tools)

1459 TRAV TO STA 7-11min (093/0.8)
•Btks - variatn
•Contact - chgs
•Cra - reg, tal, mt) strat

2+10 210/3.5 STA 7 (47 min)
Park
H-045 [STOP] SEP Rcdr -OFF-
Mode sw - 2 - (FW/TV)
HGA: Dust gnomon/scoop
TGE - GRAV -

TRAV STA 7

11-8-72
EVA-3
CDK-15

STA 7 (47 MIN) 210/3.5
OBSERVATION
•Btks - variety, trks
•mtl - compare
•Sequence - cover
•Misc - gls

•Doc spl - strat, tex
•Doc spl - pre mtl)
•Doc spl - strat, tex
•Short spec - pers shadow
•Stereos - base, L contours
SCULP H
(100, 100; 100, 200)
BAGS

STA 7

EVA 3
2+10

- (1) CDR - Station 7 Arrival
- (1) CDR/LMP - SEP RCDR - OFF
- (1) CDR - LRV Data

HEADING		Temp Bat 1	
BEARING		Temp Bat 2	
DISTANCE		Temp LF mtr	
RANGE		Temp RF mtr	
Amp-Hr Bat 1		Temp LR mtr	
Amp-Hr Bat 2		Temp RR mtr	

(1) CDR - Verify Dusting

(1) CDR/LMP - TGE - GRAV

(1) CDR/LMP - Pan Locations

2+20

(1) CDR/LMP - RAKE Sample

[A] Rocks Bag # _____

Soil Bag # _____

[B] Rocks Bag # _____

Soil Bag # _____

2+30

CREW EVA CUFF CHECKLIST

VOICE DATA

LMP-15	STA 7 (47 MIN) 210/3.5	
	OBSERVATION	
	•Blks - variety, trks	
	•Mtl - compare	
	•Sequence - cover	
	•Misc - gls	
EVA-3	Blks	
	•Doc spl - variety, tex	
	•(E-W split - pre mtl)	
	Mtl	
	•Trench - strat, tex	
	•Doc spl - strat	
	•Short can - perm shadow	
	Pans	
	•Stereo - base L contours	
	•Polar - SCULP II	
	(020-100; 140-220)	
	Remove filter	
11-B-72	Sum - MASSIF	

EVA 3
2+30

2+40

(1) CDR/LMP - EMU Check

	CDR	LMP
O2		
FLAGS		
PRESS		
COOL		

(1) LMP - Polar Filter on Camera

Reset camera 1/125

Pos 1 - Pan LCR

LCR

LCR

Pos 2 - Pan LCR

LCR

LCR

Discard filter reset

Camera 1/250

2+50

CREW EVA CHECKLIST

EVA 3

VOICE DATA

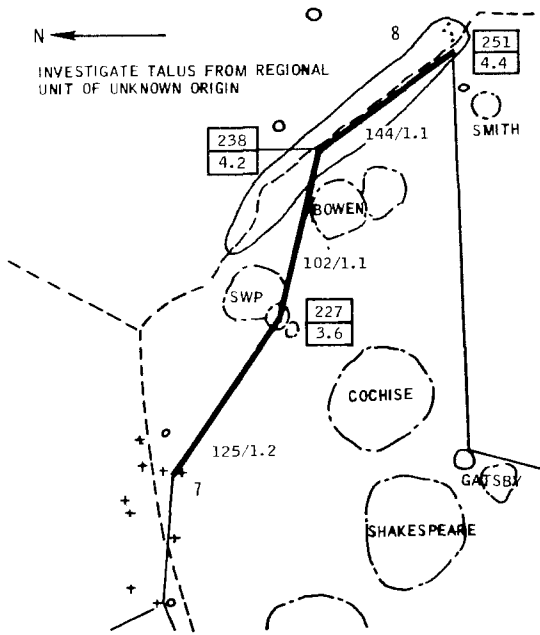
STA 7 CLOS. OUT
 TGE - READ - SEP Rcdr - ON-
 TV - cam; Mode sw - 1 (PHI/WB)
 LGA - 130 (frame, tools)
 TRAV TO STA 8 - 13min (125/3.4)
 • WESSEX CLIFF - contact
 • Mt - cleft, variatn, xport
 • SCULP H - tal lin, flts, blks
 trks, organ
 • COCHISE - subflr, rim mtl
 • Cra - sources, reg
 • BOWEN - cleft in N. rim
 C 238/4.2 STA 8 (47 MIN)
 Stop T b1f5/ert cra
 Fair H=270 iAV UPDATE then:
 H=045 STOP SEP Rcdr -OFF-
 Modr sw - 2 - (FM-TV)
 BGA, Dust gnomon/rake
 TGE - GRAV - /scoop

2+50

- (1) CDR - TGE Read _____
- (1) CDR/LMP - Mag/Frame
 CDR _____/_____
 LMP _____/_____
- (1) CDR/LMP - SEP RCDR - ON
- (1) CDR - LGA Azimuth 115°
- (1) CDR - LRV underway
 MARK _____

3+00

- (1) CDR/LMP - LRV Speed _____
 Amps _____

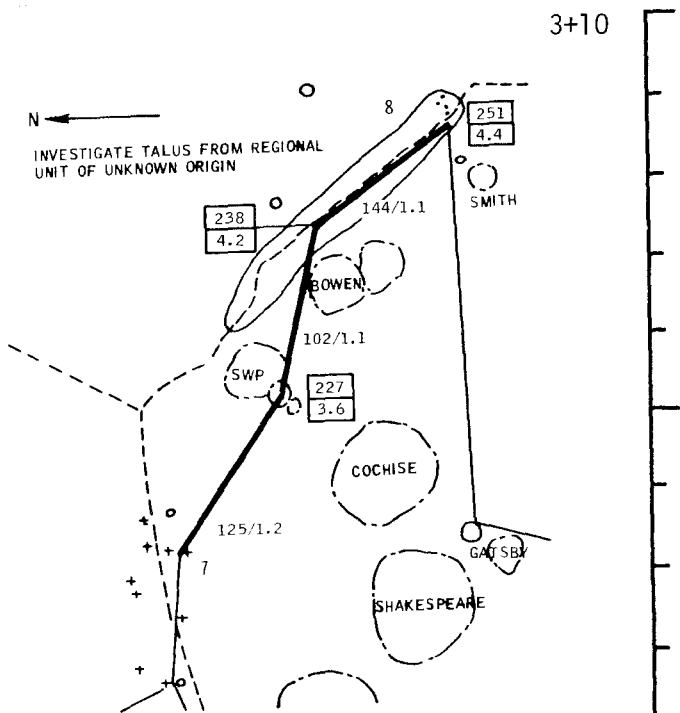


3+10

CREW EVA CHECKLIST

VOICE DATA

EVA 3



Capcom - Heading - 270°
for NAV update at Station 8

3+20

- (1) CDR - Station 8 Arrival
- (1) LMP - SEP Recorder - OFF
- (1) CDR - LRV Data

HEADING		Temp Bat 1	
BEARING		Temp Bat 2	
DISTANCE		Temp LF mtr	
RANGE		Temp RF mtr	
Amp-Hr Bat 1		Temp LR mtr	
Amp-HR Bat 2		Temp RR mtr	

STA 7 CLOS-DUT
 TGE READ - SEP Rcdr -ON-
 TV cam; Mode sw - 1 (PMT/WB)
 LGA = 130 (frame, tools)
 2:57 TRAV TO STA 8-13min (125/3.4)
 • WESSEX CLIFF - contact
 • Mt1 - cleft, variatin, xport
 • SCULP H - tal lim, flts, biks
 trks, organ
 • COCHISE - subflr, rim mtl
 • Cra - sources, req
 • BOWEN - cleft in N. rim
 off 238, 4.2 STA 8 (47 MIN)
 Stop SE BIKS/hrt cra
 Fav. H=270 NAV UPDATE then:
 H=045 STOP SEP Rcdr -OFF-
 Mode sw - 2 - (FM-TV)
 hba, Dust gnomon/rake
 Tol - GRAV - /scoop

SSD	ROLL	PITCH
COMPUTED NAV HEADING		

- (1) CDR/LMP - TGE GRAV
- (1) CDR - Verify Dusting
- (1) CDR/LMP - Pan locations

3+30

CREW EVA CHECKLIST

VOICE DATA

EVA 3

11-8-72	EVA-3	CDR-19	<p>STA 8 (47 min) 238/4.2</p> <p><u>OBSERVATIONS</u></p> <ul style="list-style-type: none"> •Blks - variety, trks, SCULP H •Cra - strat •Talus - variety, cover, reg •Mtl - contact <p>Blks (or Cra Rim)</p> <ul style="list-style-type: none"> •Doc spl - variety, tex •Rake(Kg) - btw blk, or cra rim <p>Mtl</p> <ul style="list-style-type: none"> •Fench - strat, tex •Doc spl - strat <p>Pans</p> <p>Stereo base//contours</p> <p>Sum - SCULP H</p>	8 VIS
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3+30

(1) CDR/LMP - RAKE Sample

[A] Rocks Bag # _____

Soil Bag # _____

3+40

[B] Rocks Bag # _____

Soil Bag # _____

3+50

MISSION: APOLLO 17
 EVA: 3

DATE: NOV. 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
	3+30			
<u>RAKE/SOIL SAMPLE</u>		<u>RAKE/SOIL SAMPLE</u>		
<u>DOCUMENTED SAMPLES</u>	3+40	<u>DOCUMENTED SAMPLES</u>		
<u>TRENCH</u>		<u>TRENCH</u>		
Photo Pan	3+50	Photo Pan		

CREW EVA CHECKLIST

VOICE DATA

EVA 3

CDR-21	STA 8 CLOSEOUT	TRAV STA
	TGE - READ - SEP Rcdr - ON- TV cam; Mode sw - 1 - (PMI/WB) LGA = 255 (frame, tool)	6
EVA-3	3+57 TRAV TO STA 9-16min (267/2.5)	TRAV STA
	250/4.1 SMITH - struct •Mtl - compare •Cra - reg, mtl strat 246/3.4 Dk Cra - source •COCHISE - subflr, rim mat'l	
11-8-72	4+13 235/2.3 STA 9 (30 MIN)	TRAV STA
	Park at RE rim H=045 [STOP] SEP Rcdr -OFF- Mode sw - 2 - (FM/TV) HGA; Dust gnonon/splr Walk to rim VANSLRG /scoop	

3+50

(1) CDR/LMP - Mag/frame

CDR ____/____

LMP ____/____

(1) CDR - TGE Read _____

(1) CDR/LMP - SEP RCDR - ON

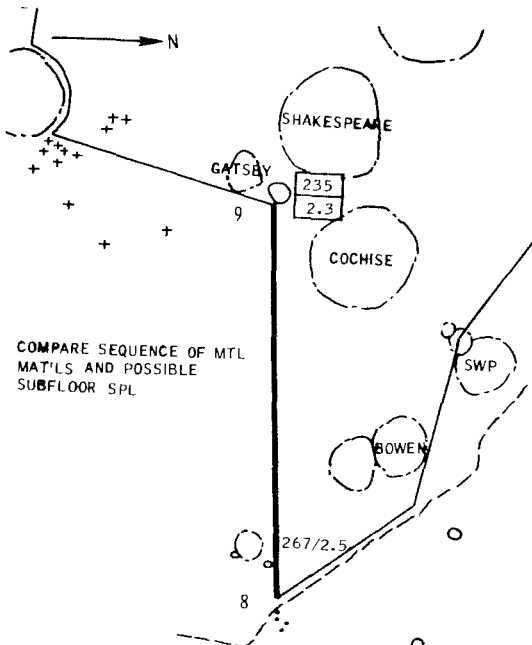
(1) CDR - LGA Azimuth 255°

- LRV Heading ____

- Torque Gyro

(1) CDR - LRV Underway MARK ____

4+00



(1) CDR/LMP - EMU Check

	CDR	LMP
O2		
FLAGS		
PRESS		
COOL		

4+10

MISSION: APOLLO 17
 EVA: 3

DATE: NOV. 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	S R E C O R M.	TASK FUNCTION	
				L M P	C D R
	3+50				
Report film Counter		Read TGE Report film Counter			
Load up LRV - samples, scoop, rake, gnomon					
TURN SEP RECORDER ON Verify gate latched		LCRU mode sw - 1 Position TV aft, horiz.			
Mount LRV		Torque gyro as required Position LGA <u>255°</u>			
Fasten seatbelt					
Go to STATION 9		Go to STATION 9 Report LRV Underway			
	4+00				
	4+10				

CREW EVA CHECKLIST

VOICE DATA

EVA 3

4+10

(1) CDR/LMP - LRV Speed _____
 Amps _____

LMP-21	STA 8 CLOSEOUT	TRAV STA 6
	TGE - READ - SEP Recdr -ON- TV cam; Mode sw - 1 - (PM1/WB) LGA = 255 (frame, tools)	
EVA-3	3+57 TRAV TO STA 9-16min (267/2.5) 250/4.1 SMITH - struct •ME1 - compare •Cra - reg, mt1 strat 246/3.4 Dk Cra - source •COCHISE - subflr, rim mat'l	TRAV STA 6
T1-8-72	4+13 235/2.3 STA 9 (30 MIN) Park at NE rim Hr-045 STOP SEP Recdr -OFF- Mode sw - 2 - (RFV/TV) HGA; Dust gnamn/splr Walk to rim VANSERG /scoop	

(1) CDR - Station 9 Arrival _____
 (1) LMP - SEP Recorder - OFF _____
 (1) CDR - LRV Data _____

HEADING	Temp Bat 1
BEARING	Temp Bat 2
DISTANCE	Temp LF mtr
RANGE	Temp RF mtr
Amp-Hr Bat 1	Temp LR mtr
Amp-HR Bat 2	Temp RR mtr

(1) CDR - Verify Dusting
 (1) CDR/LMP - TGE GRAV

4+20

(1) CDR/LMP - Pan locations

CDR-23	STA 9 (30 MIN) 235/2.3	STA 9
	OBSERVATIONS •Pan - cover, deposits, strat •Halls - strat, subflr, bench •Floor - tex, blk types •Misc - xenos, gls	
EVA-3	Doc •Doc spl - variety, strat •Rad spl - ejecta, strat •Pan - partial stereo	STA 9
T1-8-72	ME1 •Trench - strat, tex •Doc spl - variety, strat Pan 500 mm - N.MASSIF-blks & trails	

4+30

CREW EVA CHECKLIST

VOICE DATA

EVA 3

LMP-23	STA 9 (30 MIN) 235/2.3	STA 9
	OBSERVATIONS	
	•Rim - cover, deposits, strat •Walls - strat, subflr, bench •Floor - origin, tex, blk types •Misc - xenos, gls	
EVA-3	Cra	STA 9
	•Doc spl - variety, strat •Rad spl - ejecta, strat •Pan - partial stereo	
	Mel	
11-B-72	•Trench - strat, tex •Doc spl - variety, strat	STA 9
	Pan	
	500 mm - N MASSIF - BLKS & TRAILS	

4+30

(1) CDR/LMP - EMU Check

	CDR	LMP
O2		
FLAGS		
PRESS		
COOL		

CDP-5	STA 9 CLOSEOUT	TRAV STA 10
	TGE - READ - SEP Rcdr -ON-	
	TV cam; Mode sw - 1 (PM/HB) LGA = 195 (frames, tools)	
EVA-3	4+43 TRAV TO STA 10-24min (193/1.5)	TRAV STA 10
	237/2.2 GATSBY Cluster	
	•M1 - variatn •Cra - req, sources •Lin Dep - trends, character 248/1.9 LRV spl 261/1.6 Begin blk field •Blks - variety, tex, dynam	
11-B-72	5+57 271/1.6 STA 10 (47 MIN)	TRAV STA 10
	Park near Blks & rim	
	H-D45 STOP SEP Rcdr -OFF- Mode sw - 2 - (FM/TV) HGA: Dust gnomon/scoop TGE - GRAV -	

(1) CDR/LMP - TGE RDG _____

4+40

(1) CDR/LMP - Mag/frame

CDR _____/_____

LMP _____/_____

(1) LMP - SEP Recorder - ON

(1) CDR - LGA Azimuth 195°

(1) CDR - LRV Underway MARK _____

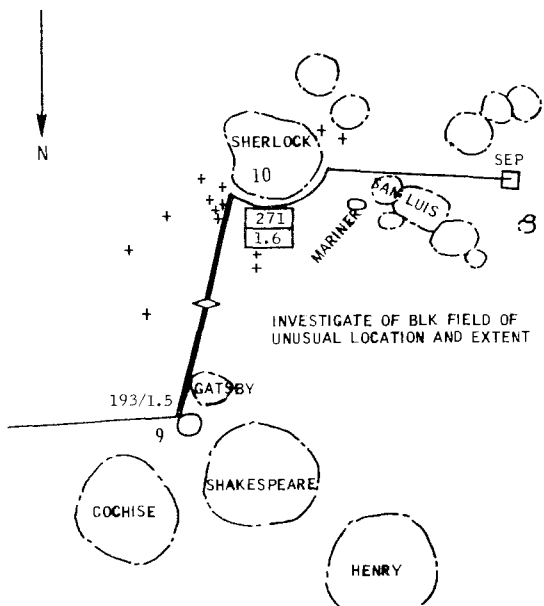
(1) LMP - Samples Bag # _____

(1) CDR - NAV data

HEADING	
BEARING	
DISTANCE	
RANGE	

4+50

200



MISSION: APOLLO 17
 EVA: 3

DATE: NOV. 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	SPEC C A M	TASK FUNCTION	
				LMP	CDR
	4+30				
Radial Samples		Radial Samples			
Stereo Pan					
Report film counter		Read TGE Report film counter			

Load up LRV - samples, scoop, rake gnomon	4+40	LCRU mode sw - 1 Position TV aft, horiz. Mount LRV Fasten seatbelt			
Verify gate latched SEP Recorder - ON Mount LRV		Position LGA <u>195°</u>			
Fasten seatbelt		Power up LRV			

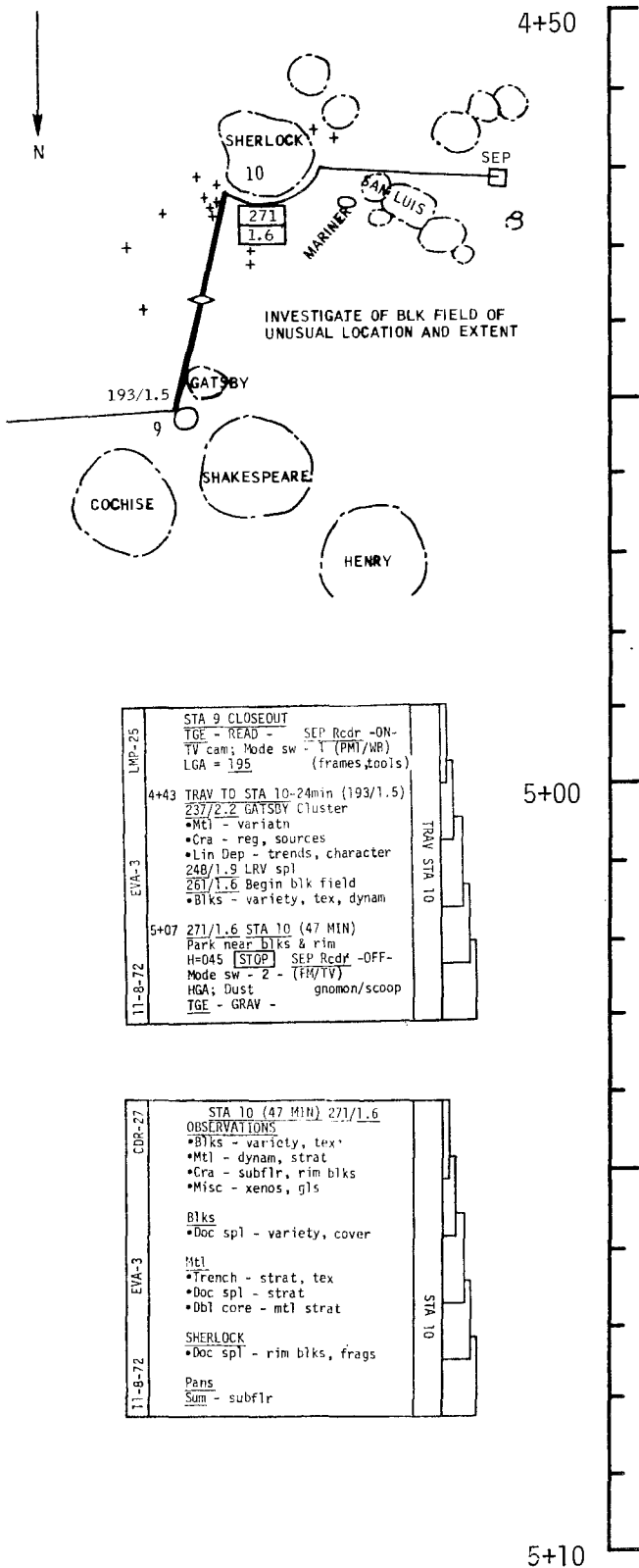
Go to STATION 10		Go to STATION 10			
		Report LRV underway			

<u>LRV SAMPLE</u> Collect sample		<u>LRV SAMPLE</u> Stop LRV			
	4+50				

CREW EVA CHECKLIST

VOICE DATA

EVA 3



(1) CDR - LRV Underway MARK _____

(1) CDR - STATION 10 Arrival _____

(1) CDR - LRV Data

HEADING		Temp Bat 1	
BEARING		Temp Bat 2	
DISTANCE		Temp LF mtr	
RANGE		Temp RF mtr	
Amp-Hr Bat 1		Temp LR mtr	
Amp-HR Bat 2		Temp RR mtr	

11-8-72 LMP-25
EVA-3
11-8-72

STA 9 CLOSEOUT
TGE - READ - SEP Rcdr - ON-
TV cam; Mode sw - 1 (PM/NR)
LGA = 195 (frames, tools)

4+43 TRAV TO STA 10-24min (193/1.5)
237/2.2 GATSBY Cluster
•Mtl - variatn
•Cra - reg, sources
•Lin Dep - trends, character
248/1.9 LRV spl
261/1.6 Begin blk field
•Blks - variety, tex, dynam

5+07 271/1.6 STA 10 (47 MIN)
Park near blks & rim
H=045 [STOP] SEP Rcdr - OFF-
Mode sw - 2 - (FR/TV)
HGA; Dust gnomon/scoop
TGE - GRAV -

5+00

- (1) LMP - SEP Recorder - OFF
- (1) CDR - Verify Dusting
- (1) CDR - TGE - GRAV

11-8-72 CDR-27
EVA-3
11-8-72

STA 10 (47 MIN) 271/1.6

OBSERVATIONS
•Blks - variety, tex
•Mtl - dynam, strat
•Cra - subflr, rim blks
•Misc - xenos, gls

Blks
•Doc spl - variety, cover

Mtl
•Trench - strat, tex
•Doc spl - strat
•Dbl core - mtl strat

SHERLOCK
•Doc spl - rim blks, frags

Pans
Sum - subflr

(1) CDR/LMP - Pan locations

5+10

CREW EVA CHECKLIST

VOICE DATA

EVA 3

5+10

(1) CDR/LMP - Core tube no's.

Upper _____

Lower _____

5+20

5+30

11-B-72	EVA-3	LMP-27	STA 10 (A7 MID) 7/1/1.6	
			OBSERVATIONS	
			<ul style="list-style-type: none"> •Blks - variety, tex •Mtl - dynam, strat •Cra - subflr, rim blks •Misc - xenos, gls 	
			STA 10	
Blks				
•Doc spl - variety, cover				
			STA 10	
Mtl				
<ul style="list-style-type: none"> •Trench - strat, tex •Doc spl - strat •Dbl core - mtl strat 				
			STA 10	
SHERLOCK				
•Doc spl - rim blks, frags				
			STA 10	
Pans				
Sum - subflr				

MISSION: APOLLO 17
 EVA: 3

DATE: NOV. 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	SEQ CAM	TASK FUNCTION	
				LMP	CDR
	5+10				
Observations		Observations			
<u>CORE SAMPLE</u> Get out two core tubes (SCB 7) & assemble to ext. handle (rake) report core tube no's		<u>CORE SAMPLES</u>			
		Assist LMP			
Drive core tubes		Photo core sample			
	5+20				
Disassemble, ram, and cap core tubes		Assist LMP			
Stow SCB 7					
Documented samples		Documented samples			
	5+30				

CREW EVA CHECKLIST

VOICE DATA

EVA 3

5+30

EVA-3	STA 10 CLOSEOUT	TRAV LM CLOSEOUT
	13E - READ - SEP Rcdr - ON- Get EP 2	
EVA-3	TV cam; Mode sw - 1 - (PM1/WD)	TRAV LM CLOSEOUT
	LGA = 310 (frame, tools)	
	5+43 TRAV TO LM-22min (273/2.0)	
	270/1.1 NW rim SHERLOCK subflr, compare, sum *ME1 - compare, sum	
EVA-3	274/1.2 MARINER	TRAV LM CLOSEOUT
	274/0.7 SAN LUIS	
	Δ 270/0.1 EP 2 - part pan *Cra - req, sum	
11-8-72	5+09 EVA 3 CLOSEOUT	
	Cam to LMP Footpan	
	Get CDR SCB 7	
	Discard unused equip [HGA	
	SCB 7 to gate	

(1) CDR/LMP - EMU Check

	CDR	LMP
02		
FLAGS		
PRESS		
COOL		

(1) CDR/LMP - TGE RDG _____

(1) CDR/LMP - Mag/Frame

CDR _____ / _____

LMP _____ / _____

5+40

(1) LMP - EP#2 - "SAFE"

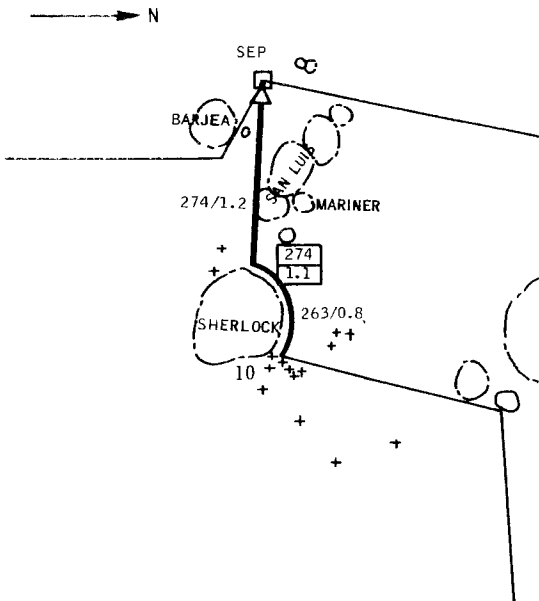
(1) CDR - LGA Azimuth 270°

(1) CDR - LRV Underway MARK _____

(1) CDR/LMP - LRV Speed _____

Amps _____

5+50



MISSION: APOLLO 17
 EVA: 3

DATE: NOV. 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	SEQ CAM	TASK FUNCTION	
				LMP	CDR
	5+30				
		Read TGE - close lid			
Report film counter		Report film counter			
	-----5+40-----				
Load up LRV - samples, scoop, rake, gnomon		LCRU mode sw - 1			
Verify gate latched		Position TV aft, horiz.			
Get EP#2 - verify "safe"		Mount LRV			
Mount LRV-EP#2 on lap		Fasten seatbelt			
Fasten seatbelt		Position LGA <u>270°</u>			
	-----	Power up LRV			
Return to LM		Return to LM			
		Report LRV underway			
	5+50				

CREW EVA CUFF CHECKLIST

VOICE DATA

11-8-72 CDR-29
 STA 10 CLOSEOUT
 TGE - READ - SEP Rcdr -ON-
 Get EP 2
 TV cam; Mode sw - 1 - (PM1/WB)
 LGA = 310 (frame, tools)
 EVA-3
 5+43 TRAV TO LM-22min (273/2.0)
 270/1.1 NW rim SHERLOCK
 subflr, compare, sum
 •Mtl - compare, sum
 274/1.1 MARINER
 274/0.7 SAN LUIS
 Δ 270/0.1 EP 2 - part pan
 •Cra - reg, sum
 11-8-72 MT AVRIL

EVA 3
 5+50

6+05 EVA 3 CLOSEOUT
 Park LRV 15' NW MESA
 H = 225
 [STOP] + Volts
 [GET SCB 7
 Cam to CDR footpan
 Mode sw - 3 - (TV RNT)
 HGA
 SCB 8 (LMP) & 7 to +Z pad
 Doff PLSS harness
 TGE to surface
 TGE - GRAV [ETB
 SEP Rcdr:
 •Pwr sw - OFF -
 •Read temp
 •Remove OSEA to CDR seat
 11-8-72 CDR-30
 EVA-3
 11-8-72

6+00

11-8-72 LMP-30
 STA 10 CLOSEOUT
 TGE - READ - SEP Rcdr -ON-
 Get EP 2
 TV cam; Mode sw - 1 - (PM1/WB)
 LGA = 310 (frame, tools)
 EVA-3
 5+43 TRAV TO LM-22min (273/2.0)
 270/1.1 NW rim SHERLOCK
 subflr, compare, sum
 •Mtl - compare, sum
 274/1.1 MARINER
 274/0.7 SAN LUIS
 Δ 270/0.1 EP 2 - part pan
 •Cra - reg, sum
 6+05 EVA 3 CLOSEOUT
 Cam to LMP Footpan
 Get CDR SCB 7
 Discard unused equip [HGA
 SCB 7 to gate
 11-8-72 LMP-30
 EVA-3
 11-8-72

6+10

(1) LMP - EP#2 - "SAFE"

(1) CDR - NAV Data

HEADING	
BEARING	
DISTANCE	
RANGE	

(1) CDR - LRV Underway MARK _____

(1) LMP - Rpt 70mm mag/frame
 _____/_____

(1) CDR - Arrival at LM

(1) CDR - LRV Displays :Volts ____ (1) ____ (2)

HEADING		Temp Bat 1	
BEARING		Temp Bat 2	
DISTANCE		Temp LF mtr	
RANGE		Temp RF mtr	
Amp-Hr Bat 1		Temp LR mtr	
Amp-HR Bat 2		Temp RR mtr	

(1) CDR - TGE GRAV

CREW EVA CUFF CHECKLIST

VOICE DATA

6+05 EVA-3 CLOSEOUT
 Park LRV 15° NW MESA
 H = 225
 [STOP] + Volts
 [GET SCB 7
 Cam to CDR footpan
 Mode sw - 3 - (TV RMT)
 HGA
 SCB 8 (LMP) & 7 to +Z pad
 Doff PLSS harness
 TGE to surface
 TGE - GRAV [ETB
 SEP Rcvr:
 • Pwr sw - OFF -
 • Read temp
 • Remove DSEA to CDR seat

Get Cosmic Ray Exp
 • Sun side first
 • Mate halves & bag
 • Stow in ETB
 5 LRV VIP [N. FLUX
 MOUNT Cam
 [RESET then OFF
 Drive to VIK site
 H = 102 Dist = 0.1
 Park H = 270 @ Brg = 282
 [STOP]

LRV Cms:
 • Bus B, D - Open
 • Aux CB bypass - ON
 LCRU
 • Pwr sw - EXT
 Dust:
 • TV lens, TV, TCU
 • LRV batt covers & open
 • LRV batts (if dirty)
 LCRU
 Tether brush
 LCRU Link - 100% Open
 Cover LCRU C/D panel with
 65% blanket
 HGA
 Pos LMP cam vert on seat
 (CDR underseat)

Hold still [REMOVE SCB 8
 Doff PLSS harness
 Underseat spls to Big Bag
 Big Bag & SCB 3 to +Z pad
 Contain Sample under D/S
 • DB1 bag
 • Stow in Big Bag
 To CDR Seat:
 • LMP cam
 • Maps
 ETB to CDR footpan [SEP
 Stow ETB: [DSEA
 • SEP DSEA
 • All mags except CDR cam
 • Maps
 LMP Cam under LMP seat
 ETB to LEC hook

ETB Check
 • 6 Mags
 • DSEA
 • Maps
 • Cosmic Ray Exp
 Get Cosmic Ray Exp
 • Sun side first
 • Mate halves & bag
 • Stow in ETB
 N. FLUX RECOVER [LRV RIP
 • Walk to site
 • Retrieve probe
 • De-mate sections
 • Lower section - OFF -, cap
 • Upper section - OFF -
 • N. Flux to launch bag
 (MESA LH) at LM
 • Place on +Z strut

EVA 3
 6+10

(1) CDR/LMP - Disposition of LRV Samples & FSR's

(1) CDR - SEP Temp _____

RCVR OFF _____

(1) LMP - ETB PACK

• MAPS _____

• LMP CAM MAG _____

• 4 MAGS _____/_____

(1) CDR - Cosmic Ray collected

MARK _____ (Shade)

MARK _____ (Sun)

6+20

(1) CDR - LRV Underway

H = 102°

D = 0.1 km

Park H = 270°

Bearing = 282°

(1) CDR - LRV CB'S OPEN
 EXC. Bus A, C & Aux

AUX CB BYPASS - ON

LCRU Mode sw - 3

LCRU Power sw - EXT

6+30

MISSION: APOLLO 17
 EVA: 3

DATE: NOV. 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
TRANSFER UNDER SEAT SAMPLER TO BIG ROCK BAG	6+10	PLACE TGE ON SURFACE		
HANG BIG BAG TO LADDER HOOK		<u>TGE</u> - PRESS 'GRAV'		
TAKE ETB TO CDR FOOTPAN		RETRIEVE COSMIC RAY		
PACK ETB: <ul style="list-style-type: none"> • MAPS • MAG FROM LMP CAMERA • MAG FROM 500 CAMERA • 4 MAGS FROM UNDER SEAT • SEP DSEA (LEAVE LMP CAM UNDER CDR SEAT)		COLLECT HALF ON STRUT & THEN HALF ON HINGE - REASSEMBLE		
TAKE ETB TO LM, HOOK TO LEC <u>WALK OUT TO ALSEP</u>		BAG COSMIC RAY & PLACE IN ETB		
		OPEN GEOPALLET		
		READ SEP TEMP - RCVR SW - 'OFF'		
		PULL LANYARD & OPEN SEP CASE		
		RELEASE CATCH, DISCONNECT LEAD		
		REMOVE DSEA		
		HAND DSEA TO LMP OR PLACE ON SEAT		
		CLOSE GEOPALLET		
		<u>LRV FINAL DISPOSITION</u>		
	6+20	PUT ON CDR CAMERA		
		MOUNT LRV - RESET NAV		
		FASTEN SEATBELT		
		DRIVE TO V.I.P. SPOT		
		H = 102°		
		DISTANCE = 0.1 KM		
		PARK HEADING = 270° ON		
		BEARING 282°		
CHECK LMS SHIELD FLAT GO TO NFE SITE		POWER DOWN LRV		
ENGAGE JACK ON NFE ROD		DISMOUNT LRV		
JACK NFE OUT OF GROUND		LRV CB's - OPEN BUS B & D		
		SW AUX CB BYPASS - 'ON'		
		LCRU POWER SW - 'EXT'		
		ALIGN HGA		
DEMATE 2 SECTIONS	6+30			

EVA 3

6+30

11-8-72	EVA-3	LRV cbs: • Bus B, D - Open • Aux CB bypass - ON LCRU: • Pwr sw - EXT Dust: • TV lens, JV, TCU • LRV batt covers & open • LRV batts (if dirty) • LCRU Tether brush LCRU blink - 100% Open Cover LCRU C/D panel with • 65% blanket HGA Pos LMP cam vert on seat (CDR underseat)	CDR-32
		F.30 Get EP 3 SEP Xmtr - OFF - Deploy EP 3, end of • W SEP Ant • Locator to LM Ret to LM Cam to ETB TGE - READ - Dust EMU's Stow PLSS ants (CDR/LMP) Brush to ladder hook	EVA-3

- (1) LMP - NFE lower & upper Sections - OFF
- (1) CDR - Batt covers open
LCRU 100% open
Panel covered
Brush tethered
- (1) CDR - Verify Dusting

- (1) CDR - EP 3 - "SAFE"
- (1) CDR/LMP - EMU Check

	CDR	LMP
02		
FLAGS		
PRESS		
COOL		

- (1) CDR - SEP XMTR - OFF

6+40

11-8-72	EVA-3	ETB Check • 6 Hags • DSEA • Maps • Cosmic Ray Exp *Get Cosmic Ray Exp* • Sun side first • Mate halves & bag • Stow in ETB N. FLUX RECOVER (LRV RIP) • Walk to site • Retrieve probe • De-mate sections • Lower section - OFF -, cap • Upper section - OFF - • N. Flux to launch bag (MESA LH) at LM • Place on #2 strut	LMP-31
		Dust EMU's • Stow PLSS ants (CDR/LMP) Climb Ladder Receive SCB 7 & N. Flux from CDR INGRESS w/SCB 7 & N Flux bag Interim stow bags 16mm cam - OFF - TRACK LITE TEST cb (16) LTG TRACK - Close - EXTERIOR LTG sw - TRACK - OBSLRVL EXTERIOR LTG sw OFF - cb (16) LTG TRACK - Open -	LMP-32

- (1) CDR - EP 3 - "SAFE"
- Pins pulled

- (1) CDR - Mag in ETB _____

- (1) CDR - TGE Read _____
TGE - OFF

6+50

MISSION: APOLLO 17
 EVA: 3

DATE: NOV. 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	LCRUTV	TASK FUNCTION	
				LMP	CDR
GET CAP FROM RACK & TURN LOWER SECTION OFF	6+30	DUST TV, TV LENS, TCU			
SCREW CAP ON LOWER SECTION		DUST LRV BATT COVERS OPEN COVERS			
TURN UPPER SECTION OFF		DUST LRV BATTERIES			
BAG SECTIONS IN THERMAL BAG		DUST LCRU - 100% OPEN TETHER DUST BRUSH			
RETURN TO LM WITH NFE		RIP OFF 65% BLANKET COVER LCRU PANEL			
		PROP LMP CAM WITH LENS STRAIGHT UP			
		GET EP 3 FROM GEOPALLET - VERIFY "SAFE"			
PUT NFE ON MESA TABLE UNSTOW BAG, L SIDE MESA		WALK TO SEP TRANSMITTER			
TRANSFER NFE TO BAG, LEAN BAG AGAINST +Z STRUT		SW TRANSMITTER POWER - OFF WALK TO W REEL SEP ANT ARRAY			
	6+40				
POLICE AREA - KICK LOOSE GEAR UNDER LM		<u>DEPLOY EP 3</u> VERIFY EP "SAFE" PULL 3 PINS (DISCARD) EXTEND EP ANTENNA PLACE EP ON SURFACE PHOTO 7' DNSUN TO LM f11/250 <u>RETURN TO LM</u>			
		TAKE MAG OFF CAM INSTALL DARK SLIDE (MESA TABLE) PLACE IN ETB DOFF CAMERA READ TGE			
<u>CLEAN EMU'S</u>		<u>CLEAN EMU'S</u>			
ASSIST CDR		DUST LMP'S EMU			
DUST CDR'S EMU		ASSIST LMP			
STOW PLSS ANTENNAS	6+50	STOW PLSS ANTENNAS			

CREW EVA CUFF CHECKLIST

VOICE DATA

11-8-72	EVA-3	FINAL TRANSFER CHECK: •SCB 3,7,8 •Big Bag •N. Flux •SEP DSEA •Mags •Cosmic Ray •ETB Hand SCB 7 & N. Flux to LMP Check Track Light	CDR-34
		EVA-3	
11-8-72	EVA-3	Carry SCB 3, 4 & Big Bag to porch - hand in Pull ETB up - hand in INGRESS 6+57 Close Hatch 6+58 Repress	CDR-33

11-8-72	EVA-3	Dust EMU's •Stow PLSS ants (CDR/LMP) Climb Ladder Receive SCB 7 & N.Flux from CDR INGRESS w/SCB 7 & N Flux bag Interim stow bags 16mm cam - OFF - TRACK LITE TEST cb (16) LTG TRACK - Close - EXTERIOR LTG sw - TRACK - OBSERVL EXTERIOR LTG sw - OFF - cb (16) LTG TRACK - Open -	LMP-32
		EVA-3	
11-8-72	EVA-3	Receive from CDR •SCB 8 •SCB 3 •Big Bag •ETB Interim stow bags Assist CDR 6+57 Close hatch 6+58 Repress	LMP-33

EVA 3

6+50 (1) CDR/LMP - PLSS antennas stowed

TRANSFER LIST:

SCB 7

SCB 8

SCB 3

SRB

ETB

Neutron Flux

(1) LMP - Hatch Closed _____

(1) CDR - Cabin Repress _____

7+00

MISSION: APOLLO 17
 EVA: 3

DATE: NOV. 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	L C R U I T V	
			TASK FUNCTION	
			L	C
			M	D
			P	R
	6+50			
<u>INGRESS</u>		READ TGE TO MCC		
CLIMB LADDER		SHUT OFF TGE		
RECEIVE NFE & SCB 7 FROM CDR		HAND NEUTRON FLUX & SCB 7 TO LMP		
INGRESS WITH NFE & SCB 7				
DO TRACKING LIGHT TEST:		CHECK TRACKING LIGHT ON		
CB (16) LTG TRACK - CLOSE -		REPORT TO MCC		
EXTERIOR LTG SW - TRACK -				
EXTERIOR LTG SW - OFF -				
CB (16) LTG TRACK - OPEN -		CLIMB LADDER WITH SCB 3, 8, AND BIG BAG		
RECEIVE & STOW SCB 3, 8, & BIG BAG OUT OF WAY		PASS BAGS TO LMP		
		PULL UP ETB		
RECEIVE & STOW ETB		PASS ETB TO LMP		
ASSIST CDR		DROP LEC & <u>INGRESS</u>		
CLOSE HATCH				
<u>REPRESS OPERATIONS</u>		CLOSE HATCH		
		<u>REPRESS OPERATIONS</u>		
	7+00			



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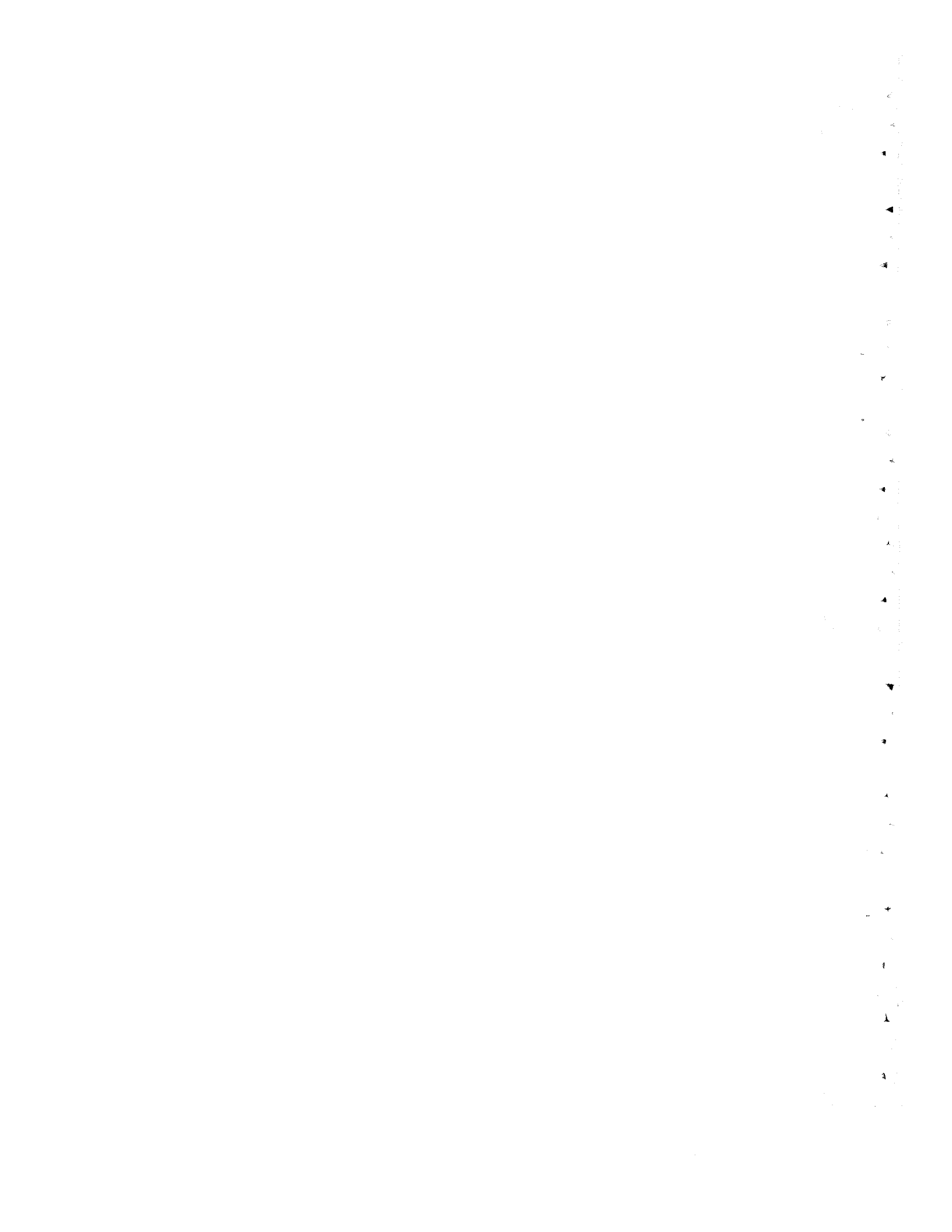
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- 3.6. The sixth item is a list of items, including:
- 3.7. The seventh item is a list of items, including:
- 3.8. The eighth item is a list of items, including:
- 3.9. The ninth item is a list of items, including:
- 3.10. The tenth item is a list of items, including:

3.4 SAMPLING



3.4 SAMPLING AND SPECIAL PROCEDURES

At each of the station stops on the traverses planned for Apollo 17, the crew performs certain tasks over and over again. These are sample gathering procedures that have been standardized in crew training, both in field trips and suited procedures practice at KSC and MSC. The nominal procedures are given in the familiar time line format, but the reader should understand that the crew can and will modify these techniques to fit the circumstances and time constraints, in accord with the principal criteria to

- (a) Collect samples representative of the different materials and geological formations present at the site.
- (b) Provide sufficient photographic documentation, description, and location data to permit after flight analysis to reconstruct the geological setting of the sample -- a sample without a context has lost much of its value.
- (c) Protect these samples for return to earth.

The timelines following are based on Apollo 16 actual times. These tasks are summarized in Table 3.4-1.

The main EVA time lines of sections 3.1, 3.2, and 3.3 simply list these repetitive sampling tasks. The actual procedures for them are to be found in this section.

TABLE 3.4-1
 SAMPLING AND SPECIAL PROCEDURES
 TASK TIMES

<u>TASK</u>	<u>APOLLO 16 ACTUAL</u>
1. GEOLOGICAL DESCRIPTION (BEFORE TASKS BEGUN)	5 MINUTES
2. EXPLORATORY TRENCH (DIG ONLY)	3
3. RAKE SAMPLE (WITH SOIL)	8
4. DOCUMENTED SAMPLE	3
5. SINGLE CORE SAMPLE	5
6. DOUBLE CORE SAMPLE	11
7. CSVC (WITH SINGLE CORE)	9

MISSION: APOLLO 17
 2. EXPLORATORY TRENCH

DATE: SEPT 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
TAKE LOCATOR PHOTO LRV IN BKGND XSUN f8, 1/250, 15 FT	0	SELECT AREA TO BE SAMPLED - PLACE GNOMON		
USE SCOOP, DIG TRENCH 3-8 IN. DEEP 20° OFF SUNLINE				
TAKE AFTER PHOTO DNSUN f11, 1/250, 11 FT		TAKE AFTER PHOTOS STEREO PR X-SUN f8, 1/250, 7 FT		
IF SAMPLES TAKEN: USING SCOOP COLLECT SOIL SAMPLES FROM INSIDE TRENCH & SURFACE		IF SAMPLES TAKEN: GET SAMPLE BAGS, REPORT NO'S, HOLD BAGS FOR OTHER TO FILL		
	5			
*SAMPLE DOCUMENTATION ADAPTATION OF STAN- DARD DOC. SAMPLE PROCEDURE - i.e. NO LOCATOR, "BEFORE" SHOTS LIMITED TO 1 OR 2.				
	10			

MISSION: APOLLO 17

DATE: SEPT 1972

3. RAKE SAMPLE

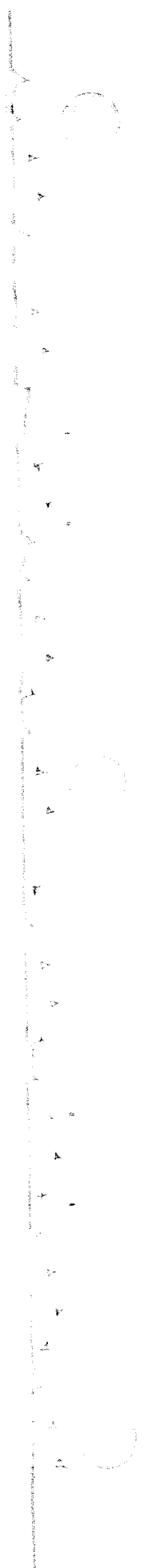
LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
	0	SELECT AREA FOR OPTIMUM ROCK DISTRIBUTION & PLACE GNOMON		
REMOVE RAKE/XT HANDLE FROM LRV				
HAND RAKE TO CDR		DESCRIBE AREA & RELATE TO SURROUNDING TERRAIN		
TAKE BEFORE PHOTO DNSUN f11, 1/250, 11ft		TAKE XSUN STEREO PR f8, 1/250, 7ft		
MAKE READY SAMPLE BAG, REPORT NUMBER HOLD BAG FOR CDR TO FILL		USE RAKE & COLLECT 1 KG OF ROCKS 3/8" TO 1 1/2" DIA (~ 1 SAMPLE BAG FULL)		
CLOSE & SEAL SAMPLE BAG STOW IN SCB (CDR PLSS)				
COLLECT 1 KG FINES (1 BAG FULL) PRISTINE AREA		GET SAMPLE BAG READY, REPORT NUMBER HOLD FOR LMP TO FILL		
	5			
TAKE LOCATOR SHOT, LRV OR LAND-MARK IN BKGROUND f8, 1/250, 15 ft (focus 74)		CLOSE SAMPLE BAG, SEAL & STOW IN SCB (LMP PLSS)		
STOW RAKE BACK ON LRV		TAKE AFTERSHOT, X-SUN f8, 1/250, 7 ft		

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LMP	CDR
Describe sample	0	Describe sample & place gnomon down-sun with pointer leg at sample & color chart at 45° to sun	PRE-EGRESS OPERATIONS	PRE-EGRESS OPERATIONS
Take down-sun photo at f11, 1/250, 11 ft		Take stereo pair X-sun at f8, 1/250, 7 ft		
Prepare sample bag (id reqd) & report bag number		Collect sample		
Seal sample bag and place in collection bag		Take X-sun after photo f8, 1/250, 7 ft		
*Take locator photo using LRV in background X-sun at f8, 1/250, 15 ft		Describe area of sample		
NOTE: Locator photo may be taken before sampling		Pick up gnomon		
Proceed to next sample	5	Proceed to next sample		
<p>*This locator photo procedure assumes that a panorama is taken at each sampling site, showing the position of the LRV. This photo may consist of LMP's turning in place after his down-sun "before" photo to take the locator of the LRV</p>				

MISSION: APOLLO 17
 EVA: 5. CORE TUBE SAMPLE

DATE: SEPT 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	TASK FUNCTION	
			LEAD	COORD
Remove core tube from CDR's sample bag	0	Place gnomon nearby	PRE-EGRESS OPERATIONS	PRE-EGRESS OPERATIONS
Assemble core tube/ext handle - report number		Remove hammer from LMP PLSS tool carrier		
Hold core tube upright on surface and press into surface by hand		Take stereo pair X-sun f8, 1/250, 7 ft		
Drive tube into surface (comment on difficulty)		Photo tube & LRV f8, 1/250, 15 ft (locator)		
Remove core from surface				
Assist CDR		Obtain core tube cap from LMP PLSS & cap tube		
Get extension handle from CDR & install scoop		Remove core tube from ext hndl Pull follower pin Get core tube tool & seat core follower against core		
		Stow core in collection bag stow core tube tool & hammer		
Proceed to next sample	5	Pick up gnomon		
		Proceed to next sample		
<p>NOTE: Double core tube procedures are similar to the above except that the cap of the lower tube must be removed to mate the lower tube to the upper tube. The caps are replaced when the tubes are disassembled and the follower on each tube is seated with tool. The double core is rammed as a unit before the tubes are disassembled. A double core requires an additional six minutes.</p>				



3.5 PHOTOGRAPH

3.5

PHOTOGRAPHY DATA

Figure 3.5-1 summarizes the various kinds of photographic routines the crew goes through in the course of their lunar surface operations.

The photographic techniques utilized for documented samples and for documenting core tube samples are very similar to those used in Apollo 16. That is, for a documented sample, the CDR takes a cross-sun stereo pair from 7 feet before sampling while the LMP takes a down-sun photo from 11 feet. The CDR then takes an after photo cross-sun from 7 feet and the LMP takes a cross-sun location photo from 15 feet with the LRV in the background. This procedure assumes that a photo panorama is taken at each science site, showing the position of the LRV. To document a core tube sample, a cross-sun stereo pair from 7 feet and a location photograph from 15 feet will be taken after the core tube is embedded in the surface.

The diagram depicting ALSEP layout documentation shows the path the LMP follows to carry out this task.

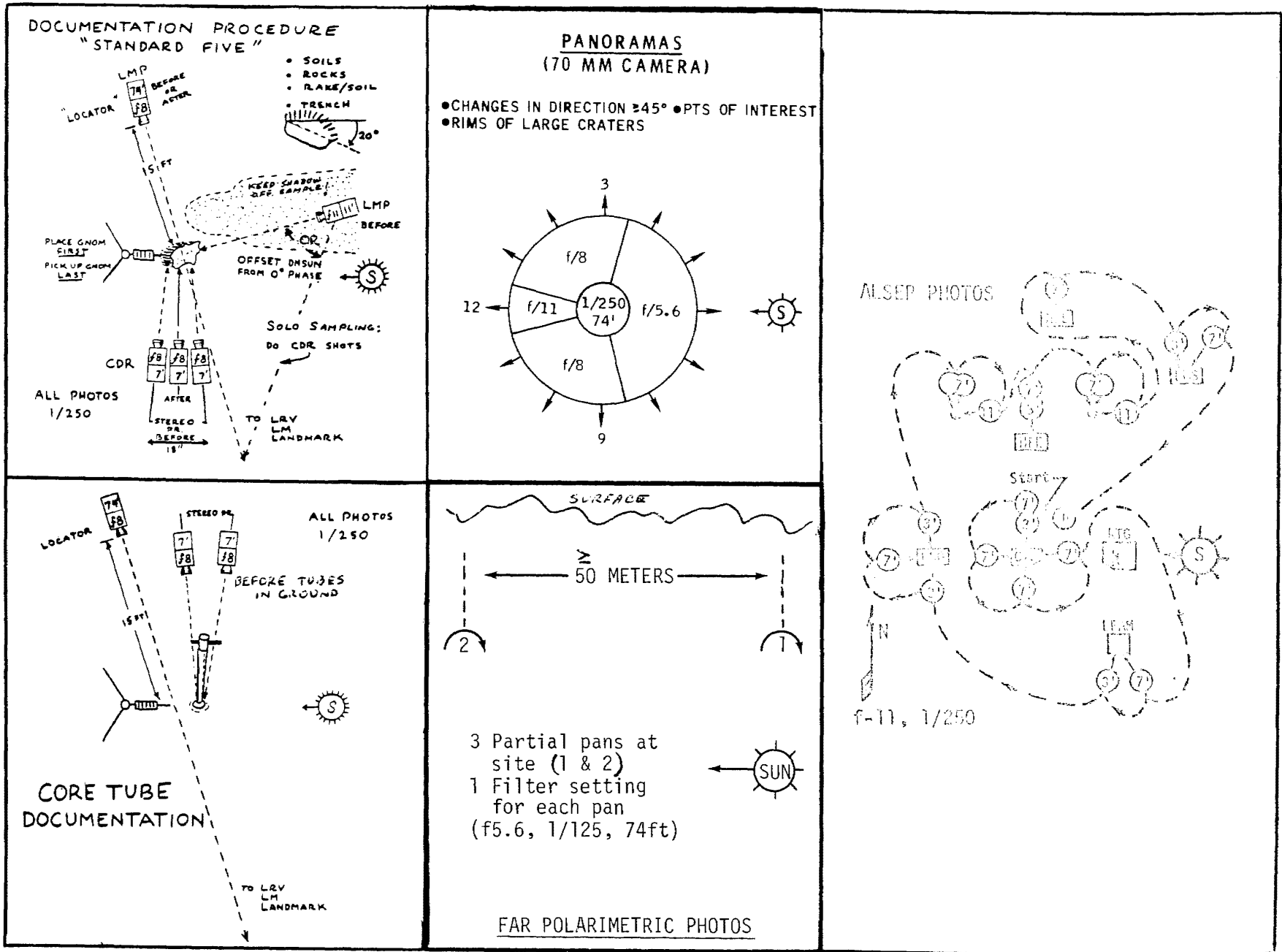


Figure 3.5-1 Lunar Surface Photo Data

Handwritten notes and symbols, including a large circle at the top and a large circle at the bottom. The text is mostly illegible due to blurriness and low contrast.

3.6 EXPERIMENT



3.6 LUNAR SURFACE EXPERIMENTS - DEPLOYMENT & EQUIPMENT DATA

Figure 3.6-1 illustrates the LM Descent Stage stowage locations for the lunar surface scientific equipment. Detailed data on ALSEP experiments is contained in Section 3.6.1. The astrophysical experiments (Cosmic Ray and neutron flux) and the geophysical experiments (Traverse Gravimeter and Surface Electrical Properties) are contained in section 3.6.2.

Other lunar surface equipment is discussed and described in Section 3.6.3.

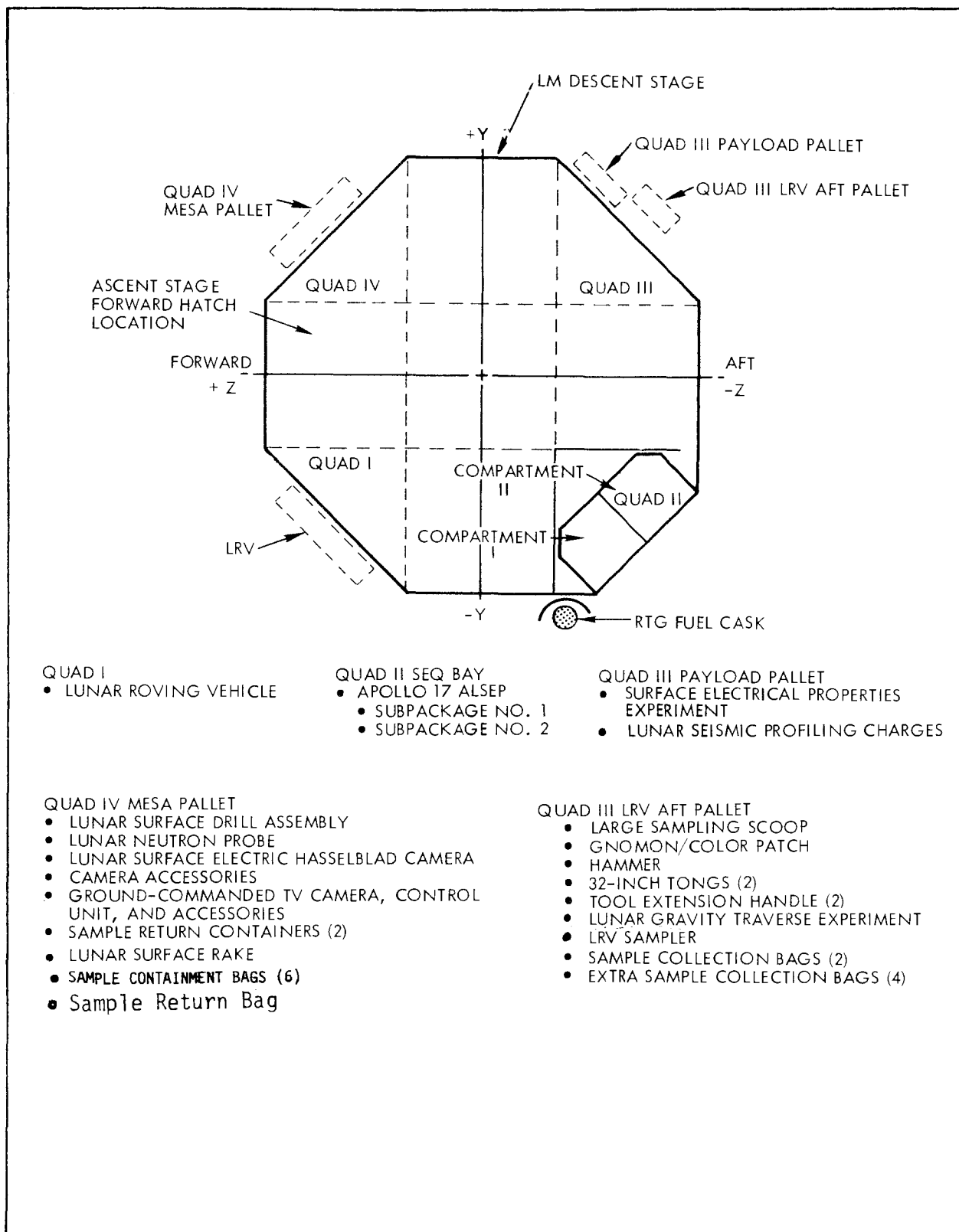
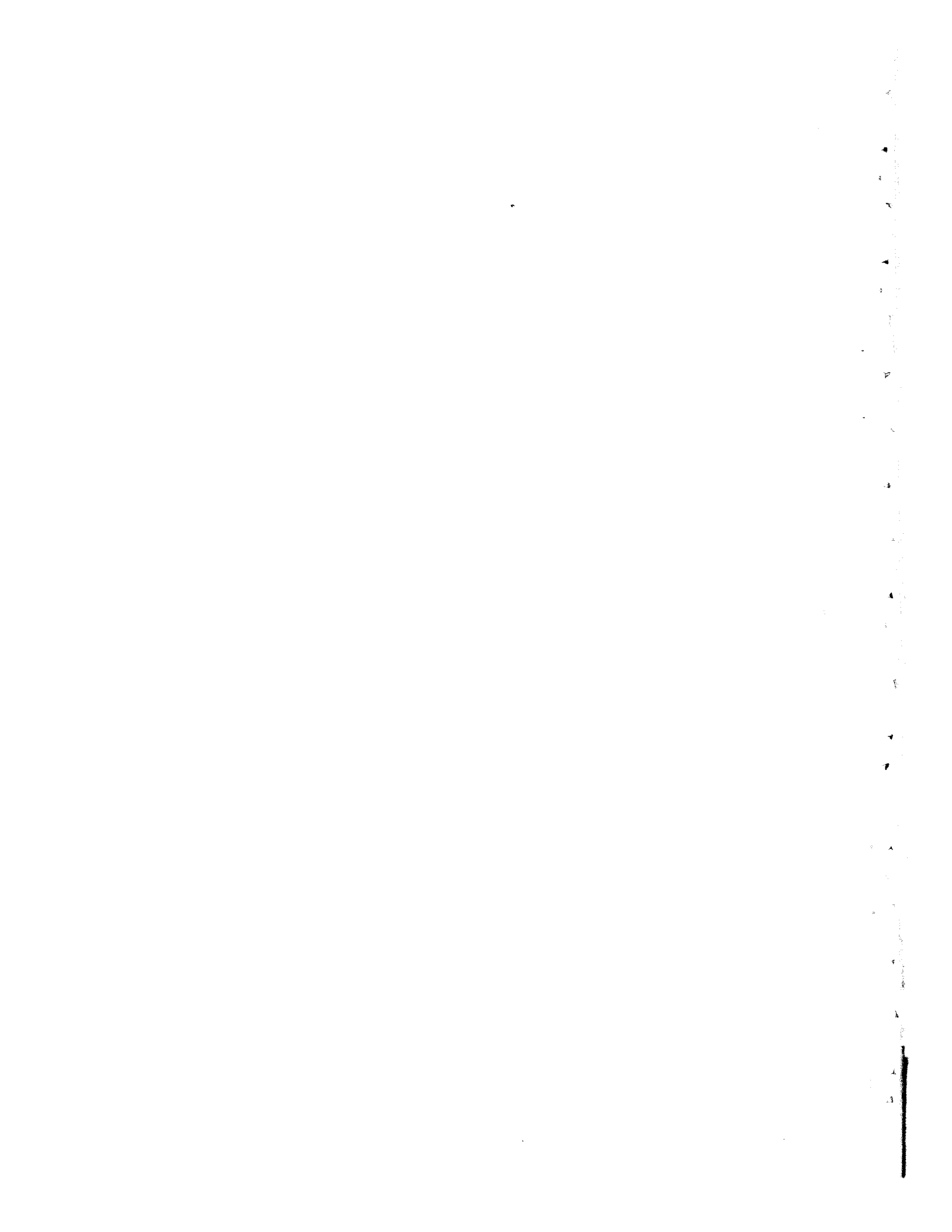


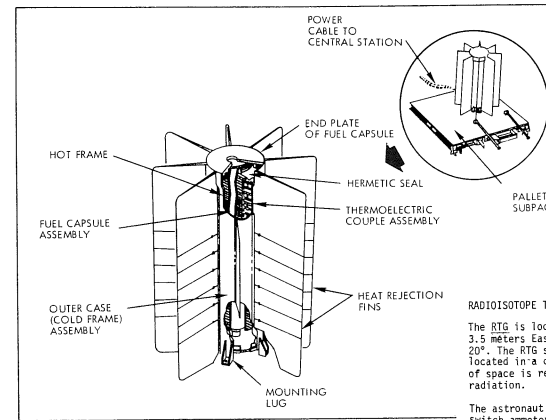
Figure 3.6-1 LM DESCENT STAGE STOWAGE OF SCIENTIFIC GEAR

3.6.1 ALSEP Deployment And Equipment Data

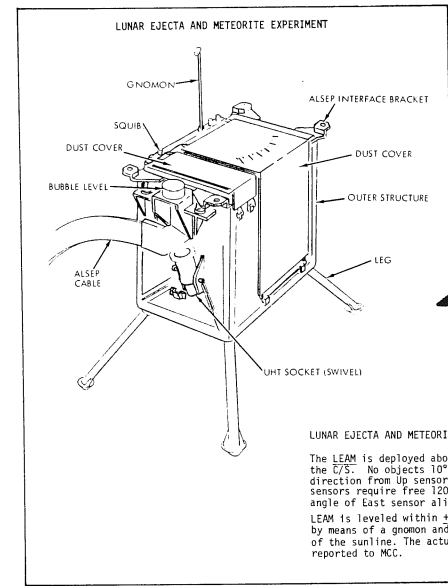
The ALSEP deployment site is selected in a location not less than 100 meters due West of the LM such that the LM ascent engine blast will not create a dust cloud or otherwise disturb the deployed experiments. The ALSEP site should be fairly level and relatively free of boulders and craters which may interface with nominal deployment procedures or thermal characteristics. The experiments and central station should not be deployed in a shadow, near a large boulder nor in a crater. Pertinent ALSEP experiment deployment data is summarized in Figure 3.6-2.

The deployment layout is shown in Figure 3.6-3.

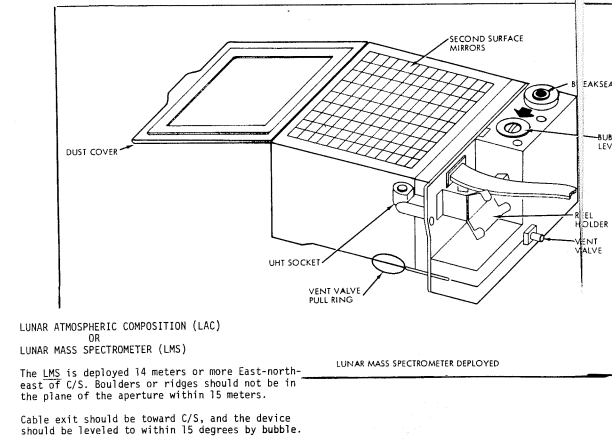




RADIOISOTOPE THERMOELECTRIC GENERATOR (RTG)
 The RTG is located approximately 3 to 3.5 meters East, 20° North of the C/S, within ± 5° of the plane of the ecliptic using the UHT as a gnomon. The RTG is located in a deep space is required for effective heat radiation.
 The astronaut will connect the RTG to the switch at the proper time.

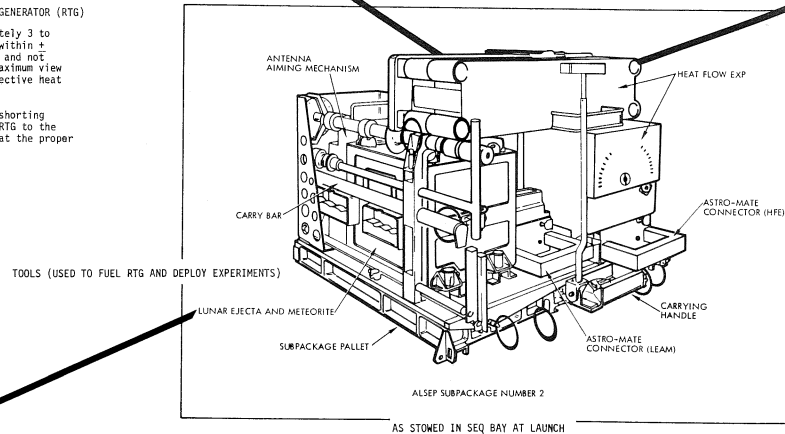


LUNAR EJECTA AND METEORITE EXPERIMENT (LEAM)
 The LEAM is deployed about 8 meters Southeast of the C/S. No objects 10° or higher in any azimuth direction from the sensor on top. East and West sensors require a 120° field of view with an angle of East sensor aligned 20° North of East. The LEAM is leveled within ± 5° with bubble, and aligned by means of a gnomon and compass rose to within ± 5° of the sunline. The actual alignment reading is reported to MCC.

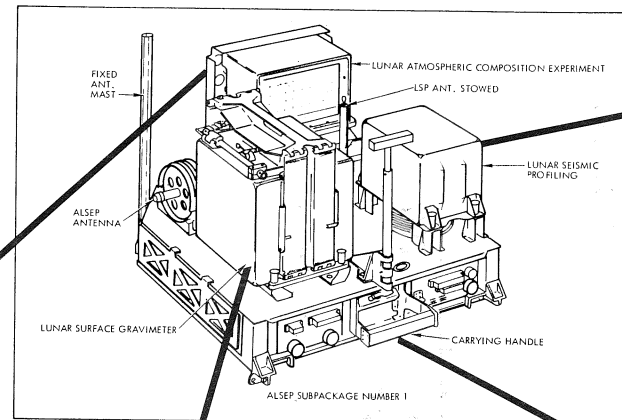


LUNAR ATMOSPHERIC COMPOSITION (LAC) OR LUNAR MASS SPECTROMETER (LMS)
 The LMS is deployed 14 meters or more East-northeast of C/S. Boulders or ridges should not be in the plane of the aperture within 15 meters.
 Cable exit should be toward C/S, and the device should be leveled to within 15 degrees by bubble.

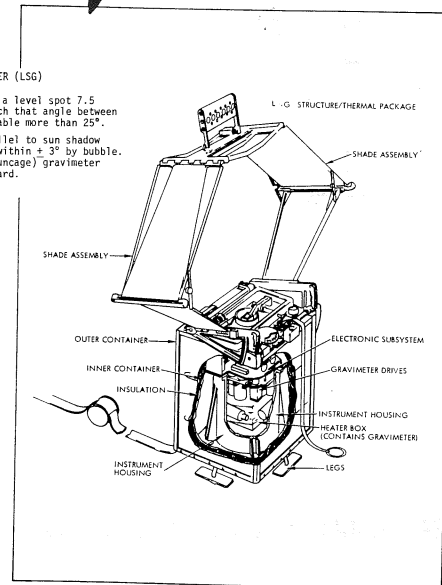
ELECTRIC GENERATOR (RTG)
 The RTG is located approximately 3 to 3.5 meters East, 20° North of the C/S, within ± 5° of the plane of the ecliptic using the UHT as a gnomon. The RTG is located in a deep space is required for effective heat radiation.
 The astronaut will connect the RTG to the switch at the proper time.



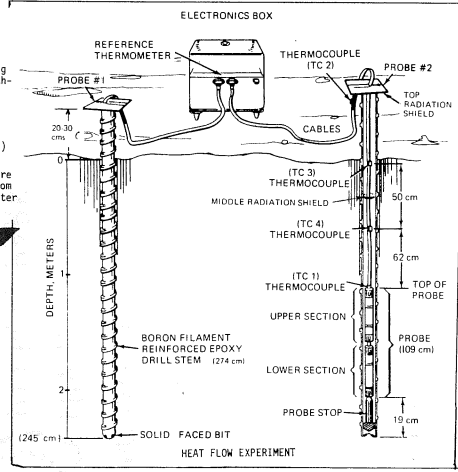
TOOLS (USED TO FUEL RTG AND DEPLOY EXPERIMENTS)
 AS STOWED IN SEQ BAY AT LAUNCH



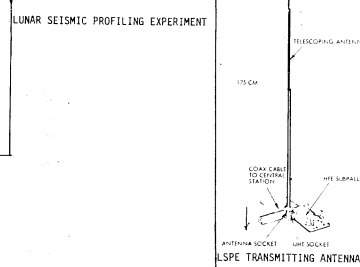
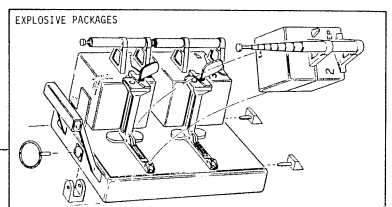
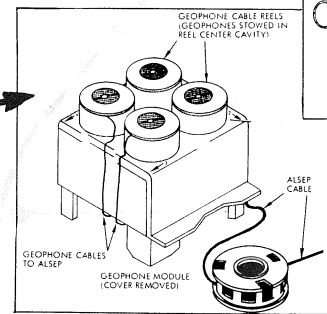
LUNAR SURFACE GRAVIMETER (LSG)
 The LSG is deployed on a level spot 7.5 meters West of C/S, such that angle between LSG and LSP antenna cable more than 25°. Plane of sunshade parallel to sun shadow within ± 3°, leveled within ± 3° by bubble. Crewman must release (uncage) gravimeter gimbal by pulling lanyard.



HEAT FLOW EXPERIMENT (HFE)
 The HFE is deployed 8 to 10 meters North of C/S, and aligned within ± 5° of the plane of the ecliptic using the UHT as a gnomon, and leveled within ± 5° using a bubble level. The HFE probes are deployed 5 to 6 meters from the electronics package and a minimum of 12 meters from the RTG. The HFE probe holes are drilled with the Apollo Lunar Surface Drill (ALSD) within 15° of vertical and should be 3 or more diameters from boulders more than 1 meter across, 1.5 diameter from rims of fresh craters more than 1 meter across.



LUNAR SEISMIC PROFILING EXPERIMENT (LSPE)
 LSPE Geophone deployment calls for a T-array with the geophone module (terminal box) some 9 meters South of the C/S.
 Alignment of arms of the array is within ± 3° determined by sighting along markers flags at each geophone. See Fig. 3.6-3 for array distances.
 Each geophone to be vertical within 7 degrees. Complete loss of data occurs if geophone off vertical by 15° or more.
 LSPE Antenna is deployed on discarded HFE launch pallet 12 meters NW of C/S. Antenna is extended to 2 meter height.
 LSPE Explosive Package (EP) deployment is covered in the Traverse sections of this Document.



CENTRAL STATION (C/S)
 The Central Station is deployed East of the RTG, leveled within ± 5° of vertical using bubble level and aligned within ± 5° of East - West using a gnomon and a partial compass rose on the C/S. When sunshield is deployed the sides face East, West.
 The ALSEP Antenna is attached to the C/S and must be leveled to within 0.5° of vertical using the bubble level and aligned within ± 0.5° of the sunline as determined by the sun shadow reference line. The crewman then verifies the latitude and longitude settings, and corrects as required.

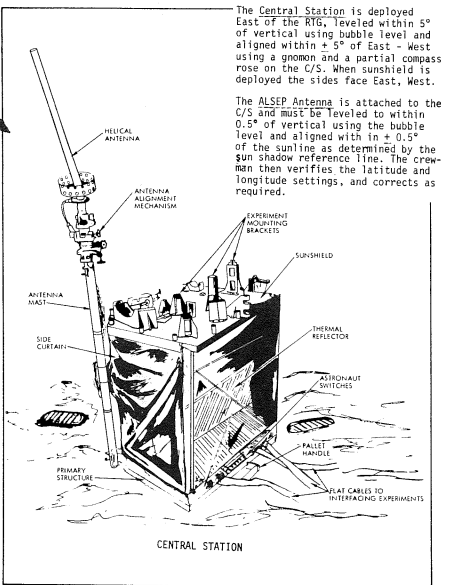
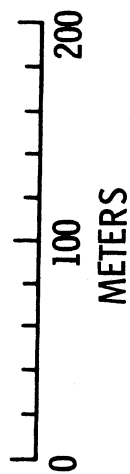
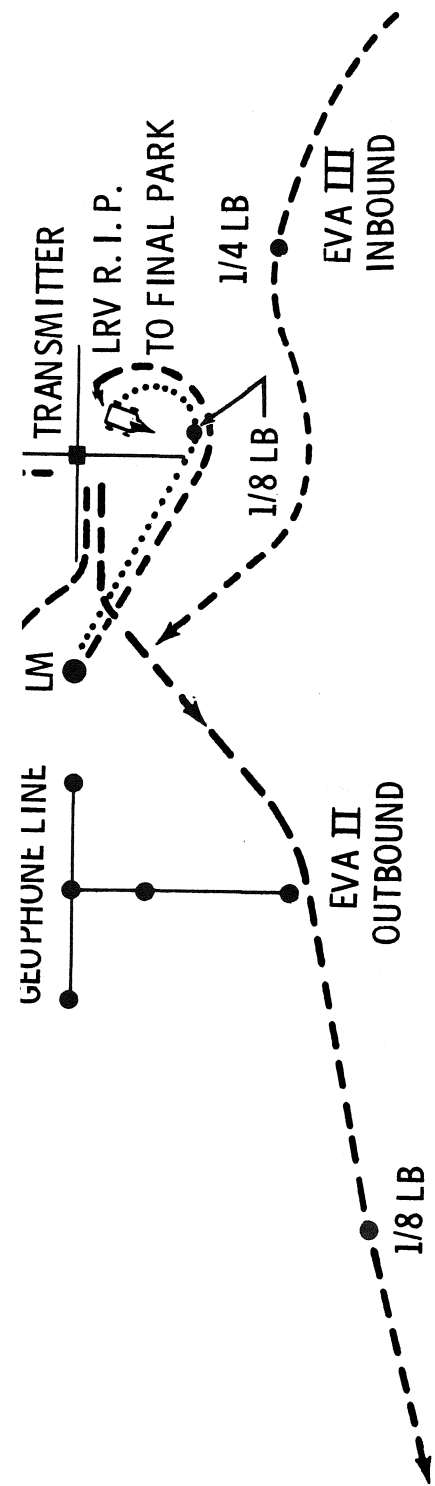
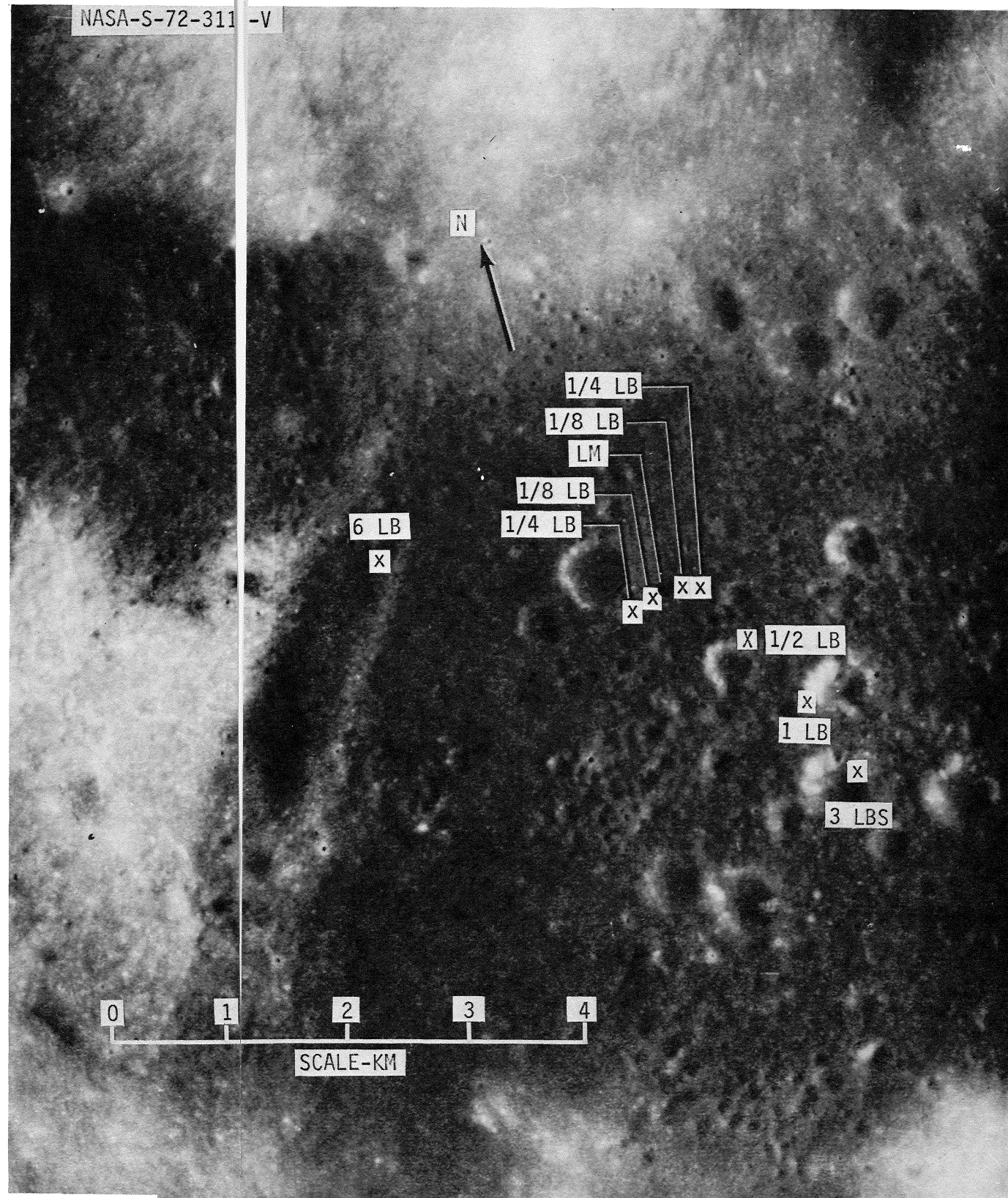


FIGURE 3.6-2 ALSEP DEPLOYMENT DATA



Detail of LSPE Charge Deployment Plan in LM Area.



Location of Lunar Seismic Profiling Experiment explosive charges.

FIGURE 3.6-2A LUNAR SEISMIC PROFILING EXPERIMENT EXPLOSIVE CHARGE DEPLOYMENT

LSPE EP DETONATION PLAN

EP NUMBER	TRANSPORT MODULE NO.	EP CHARGE SIZE-POUNDS	DEPLOYMENT - DISTANCE - KILOMETERS FROM NEAR - EST GEO - PHONES			NOMINAL DEPLOYMENT TIME - HR: MIN		DETONATION TIME*	
			MAX.	MIN.	PLAN.	EVA	EVA TIME	AFTER DEPLOYMENT - HOURS: MIN.	AFTER LM LIFTOFF - HOURS: MIN.
6	2	1	1.3	0.9	1.3	1	4:20	90:45	23:42
5	2	3	2.4	2.0	2.3	1	5:31	91:45	25:53
7	2	1/2	0.9	0.7	.8	1	5:50	92:45	27:12
4	2	1/8	0.2	TBD	.2	2	:57	90:45	42:49
1	1	6	2.7	2.1	2.4	2	5:17	91:45	48:09
8	1	1/4	.38	.20	.25	2	6:12	93:45	51:04
2	1	1/4	.38	.20	.25	3	5:59	92:45	73:21
3	1	1/8	0.2	TBD	.2	3	6:40 (after LRV park at V.I.P.)	93:45	75:02

Note: The times given above are based on the following planned Mission Event GET times:

Landing	113:02
Start EVA 1	116:40
Start EVA 2	139:10
Start EVA 3	162:40
LM Liftoff	188:03
TEI	236:40

*Based on nominal timer; specification allows + 27 minutes tolerance.

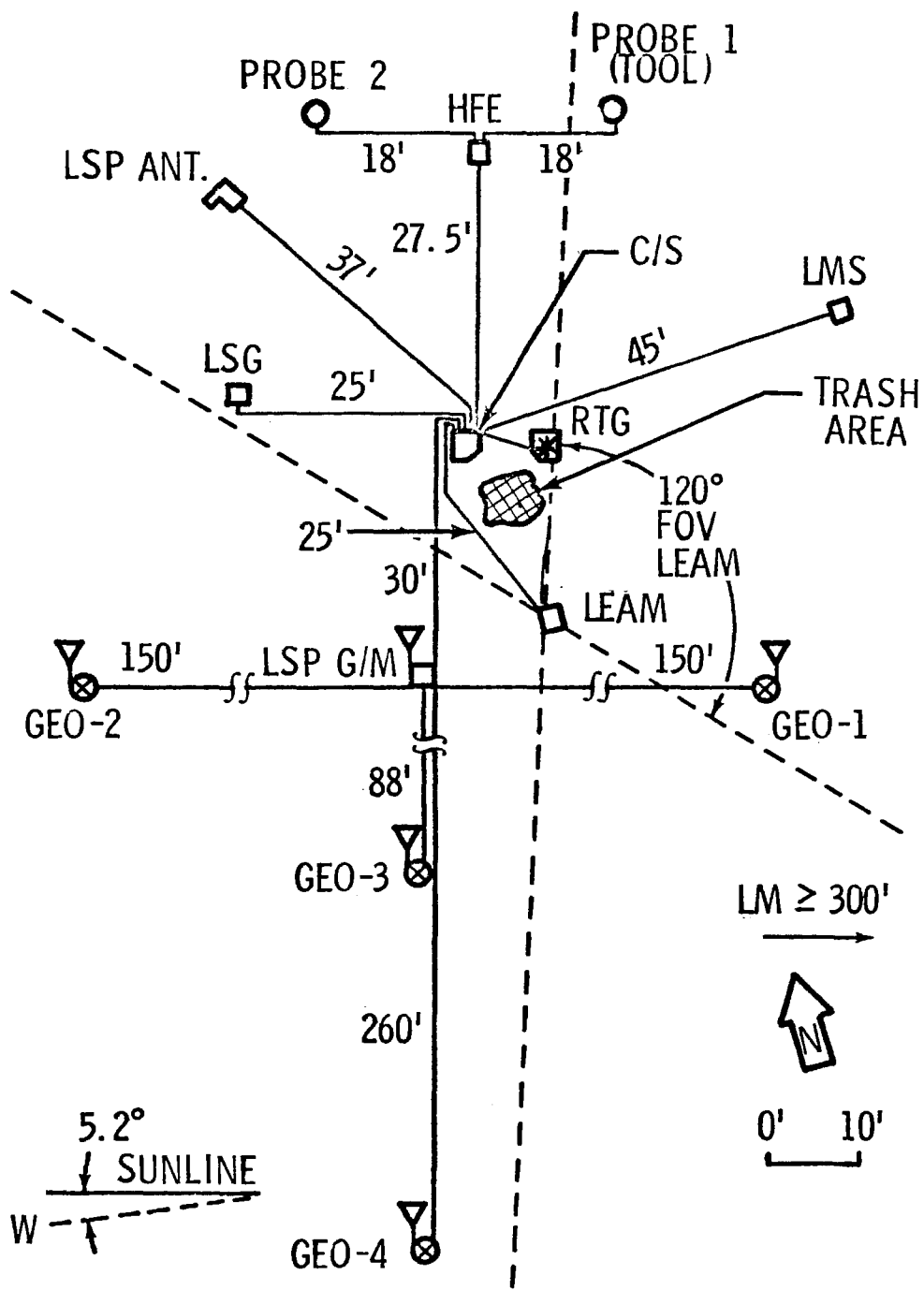
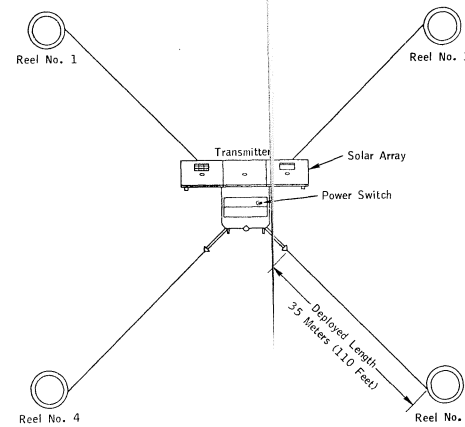
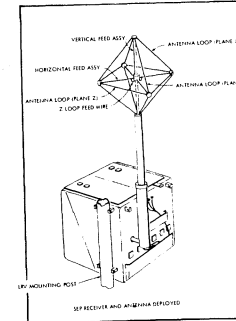
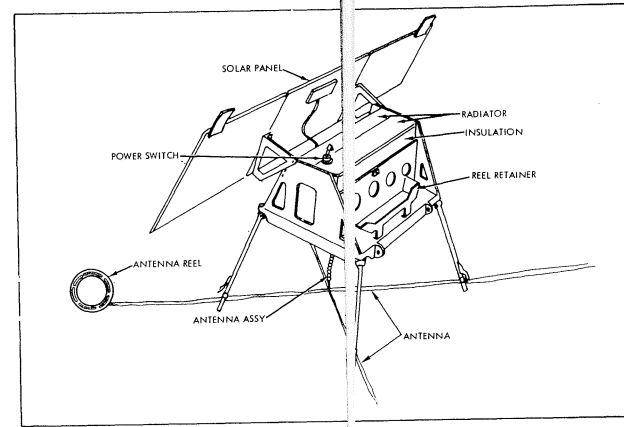


Figure 3.6-3 APOLLO 17 ALSEP DEPLOYMENT

3.6.2 Astrophysical and Geophysical Equipment Data

Figure 3.6-4 depicts the experiments in this category and includes a brief description of the experiment, as well as general constraints.



SURFACE ELECTRICAL PROPERTIES (SEP)

The SEP obtains data about the rf energy transmission, absorption, and reflection characteristics of the lunar surface and subsurface for use in modelling the upper layers of the moon. The presence of water, and the in situ electrical properties of lunar material are also studied.

SEP TRANSMITTER

Stowed on an equipment pallet, Quad III. Has X-array orthogonal dipole antennae. SEP uses 6 frequencies from 1 to 32 MHz, with a power of 2 - 3.75 watts. Lifetime is 66 hours in ON position, 57 hours in STANDBY (sun away from solar array).

X-array is deployed to four cardinal points of compass--N.E.S.W.

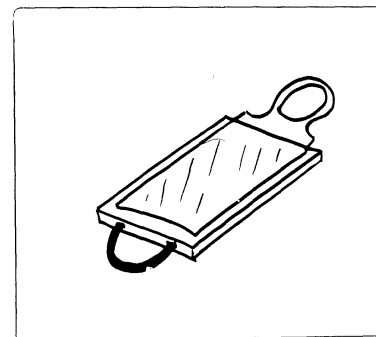
SEP RECEIVER

Stowed on an equipment pallet, Quad III. Receiver is mounted on back of LRV between geopallet and LMP seat.

SEP receiver is high gain superheterodyne unit which outputs an audio signal to a tape recorder. Battery life is 116 walt-hrs at 12vdc. Heat rejection by optical solar reflector (OSR).

Unit is turned on EVA 2, placed in STANDBY at station stops longer than 30 minutes.

At end of EVA 3, tape recorder recovered and returned to earth.



COSMIC RAY EXPERIMENT

The Cosmic Ray Experiment is a small device stowed in the ascent stage at launch. The unit consists of two parts which fit together. One part goes in shade of LW and samples deep space, the other is in full sun, and gathers data on the solar wind, and other solar particles.

TRAVERSE GRV

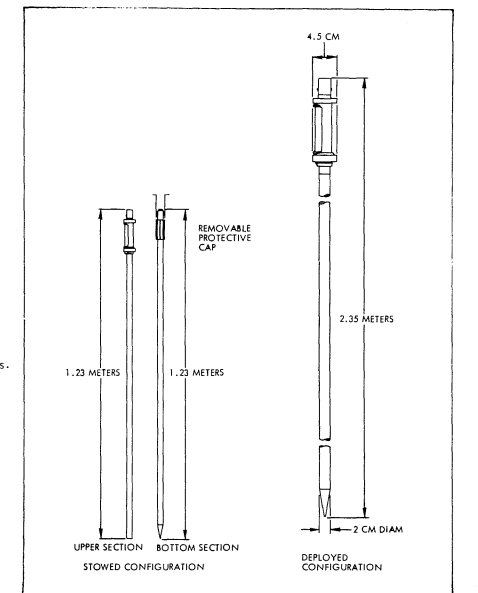
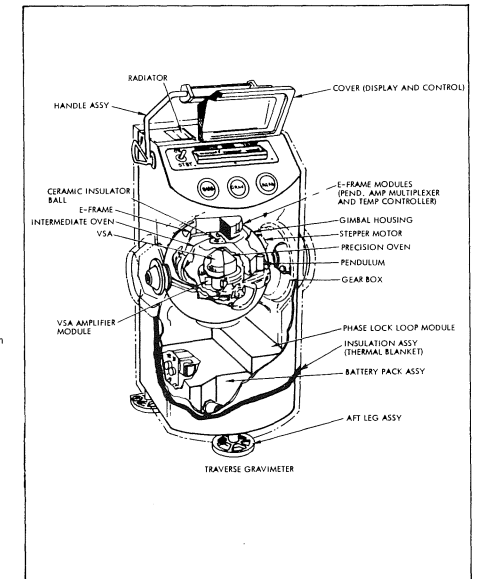
TRAVERSE GRAVIMETER EXPERIMENT (TGE)

The TGE makes a survey of the general landing site gravitational characteristics, relative to the value at the LM. The TGE will also provide data on the relative value of gravity at a known place on the moon and on the earth to establish the relationship between the two.

The TGE uses a Vibrating String Accelerometer (VSA) as a sensor. It can measure in two modes -- GRAV or normal, or BIAS or inverted.

The TGE rides on the back of the LRV, on the Geopallet. A measurement is made at each station on all three EVA's, plus baseline measurements at the LM (two are off-LRV BIAS + GRAV).

The TGE's automatic sequence includes self-leveling (1st 30 sec. of cycle) then 1 to 2 minutes measurement time. The TGE outputs to a digital readout section which stores the data until convenient for a crewman to read it. The TGE must be left undisturbed during its operating cycle.



NEUTRON FLUX EXPERIMENT (NFE)

This experiment measures rates of neutron capture as function of depth of track in surface, also measures energy spectra.

The astronaut moves a control on each section to uncover the capture surfaces. He joins the two halves together, and inserts NFE down hole left by core drilling.

Minimum exposure time is 24 hours. Minimum separation from RTG is 25 meters. The NFE must be thermally protected to keep temperature below 70° C. Desired depth is 2 meters.

FIGURE 3.6-4 ASTROPHYSICAL & GEOPHYSICAL EXPERIMENTS

3.6.3 Other Lunar Surface Equipment

The illustration in Figure 3.6-5 summarizes the lunar surface geology equipment and supporting gear. Those items marked (*) are normally stowed on the LMP'S tool harness although they can also be stowed in the areas shown. Figure 3.6-6 has some larger sketches of geological equipment. These units are the same as those used on Apollo 16.

Figure 3.6-7 and -8 depict the Deep Core taken with the Apollo Lunar Surface Drill. Figure 3.6-9 and -10 illustrate the contents of each Sample Return Container.

Finally, Figure 3.6-11 shows what the well-dressed Lunar Surface Astronaut will wear on Apollo 17.

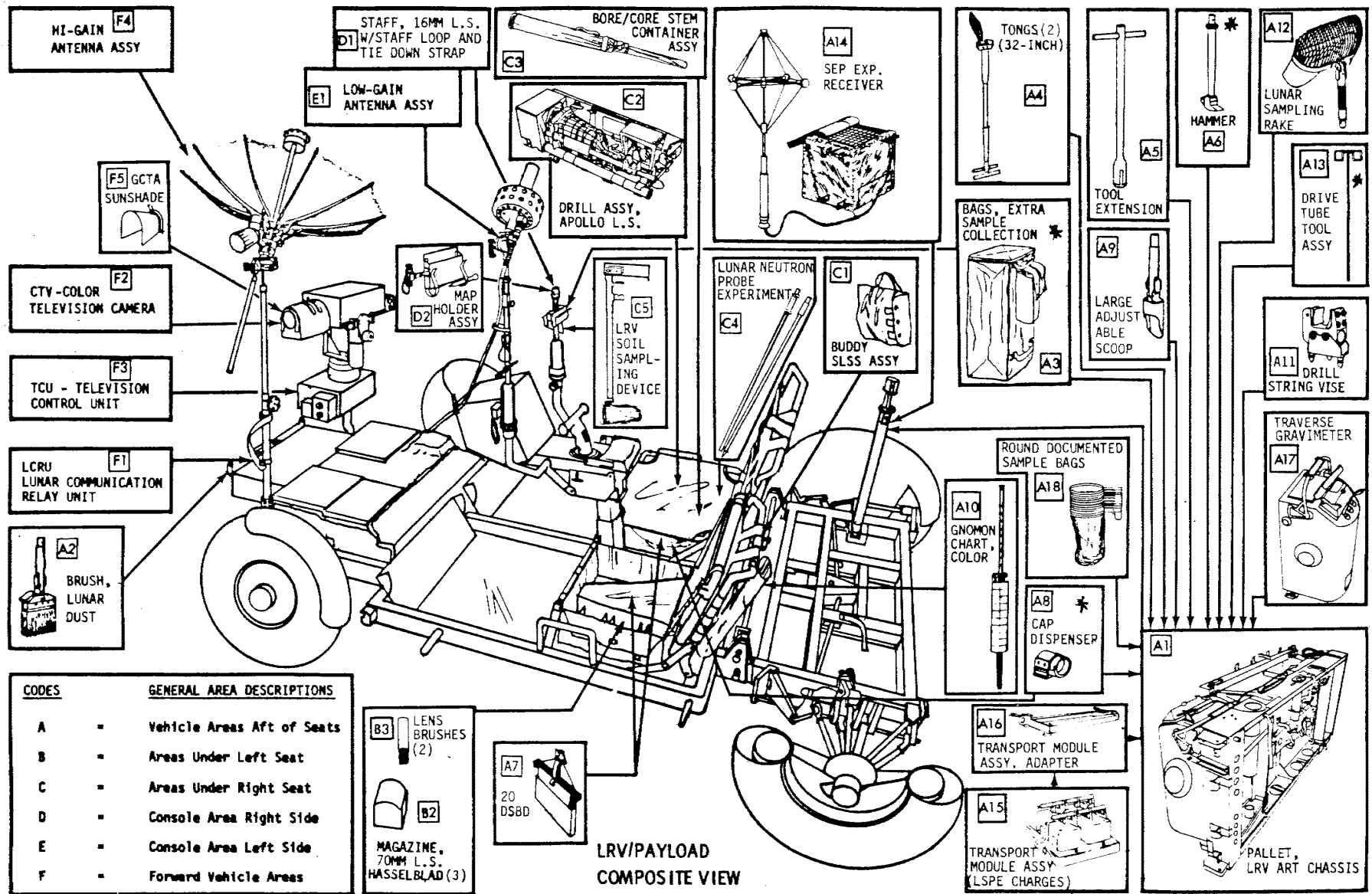


FIGURE 3.6-5 LUNAR FIELD GEOLOGY EQUIPMENT STOWAGE ON LRV

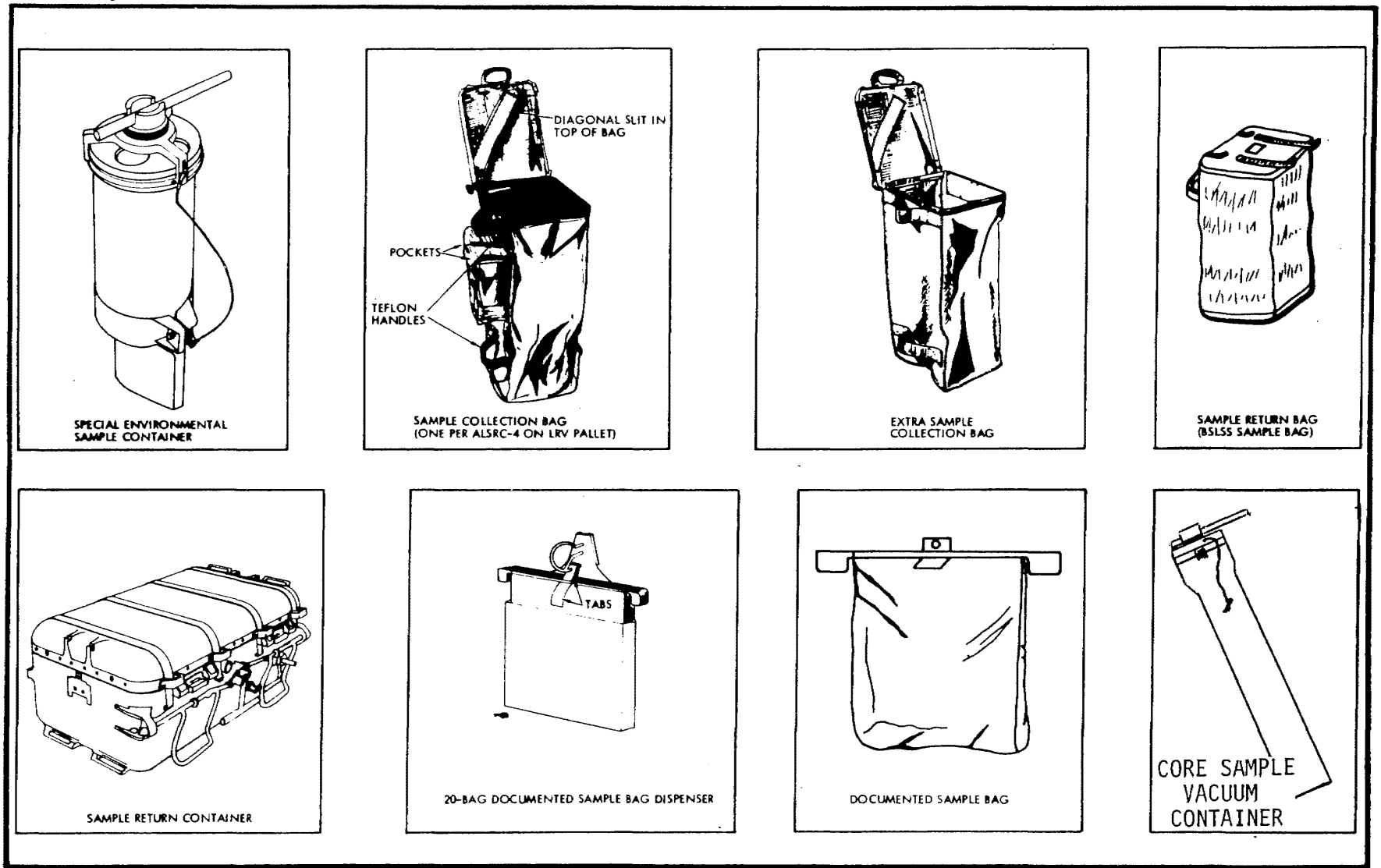


FIGURE 3.6-6 LUNAR GEOLOGY SAMPLE CONTAINERS

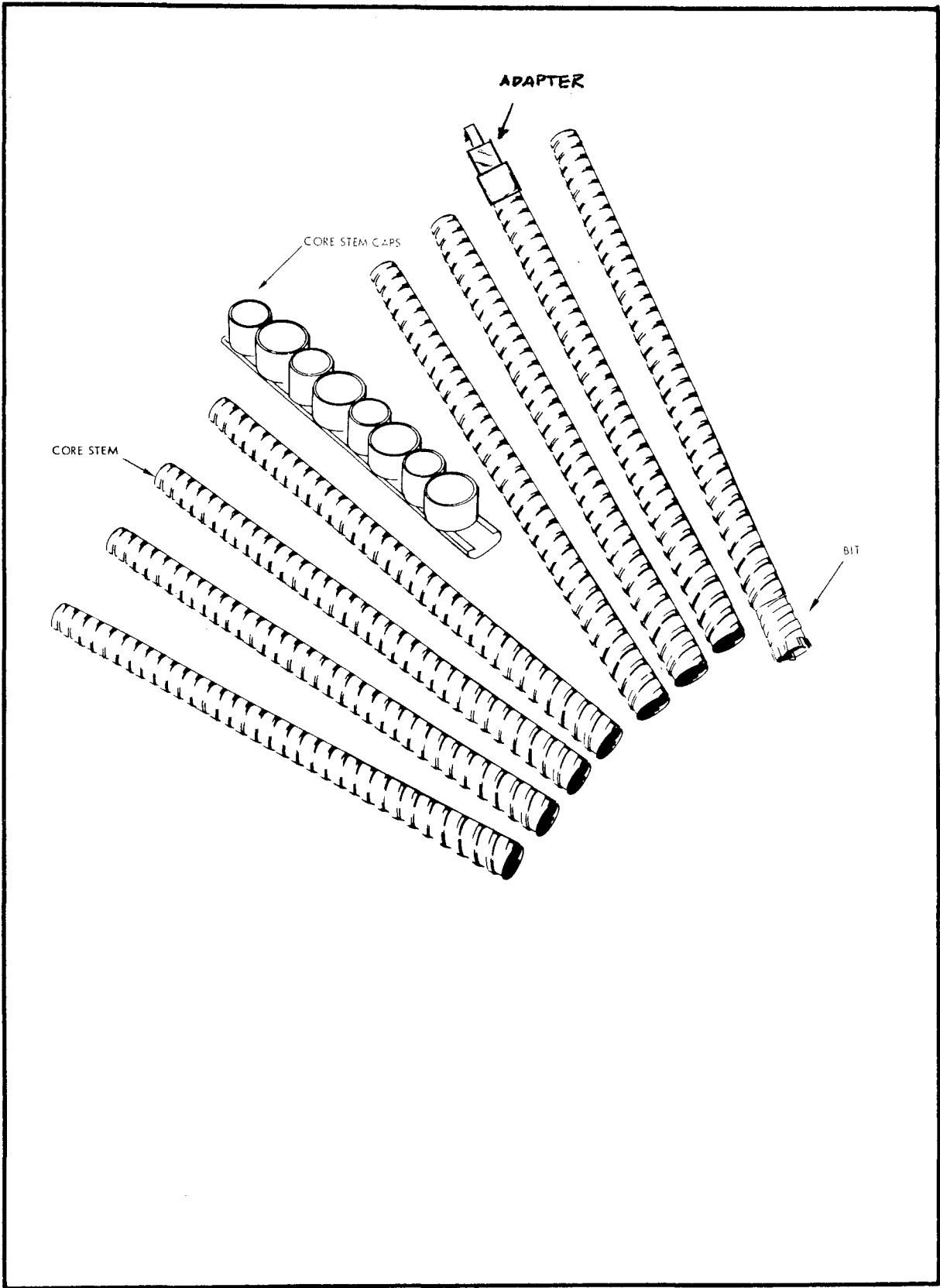


FIGURE 3.6-7 LUNAR SURFACE DRILL CORE STEMS & CAPS

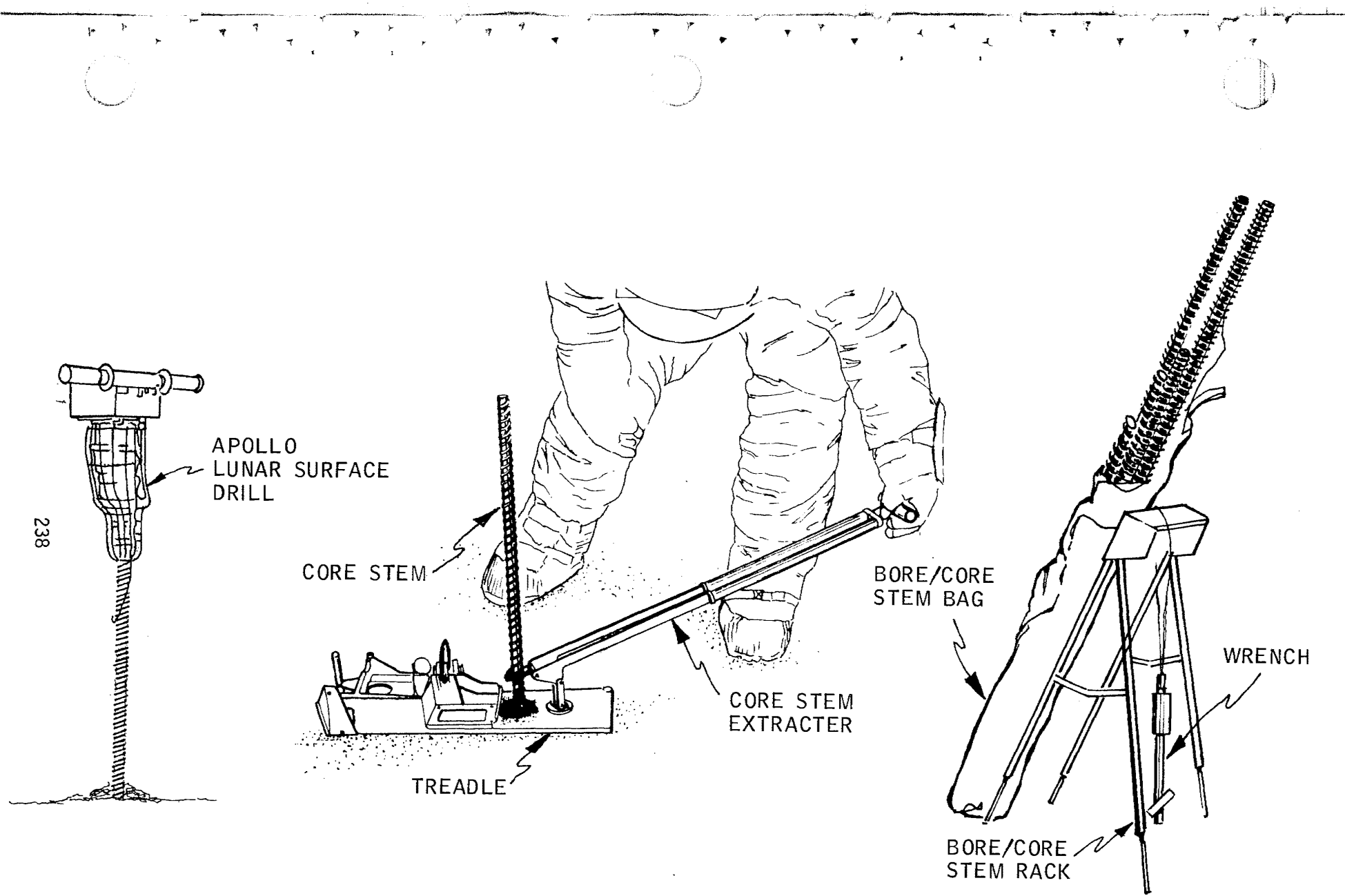


FIGURE 3.6-8 LUNAR SURFACE BORING & CORING HARDWARE

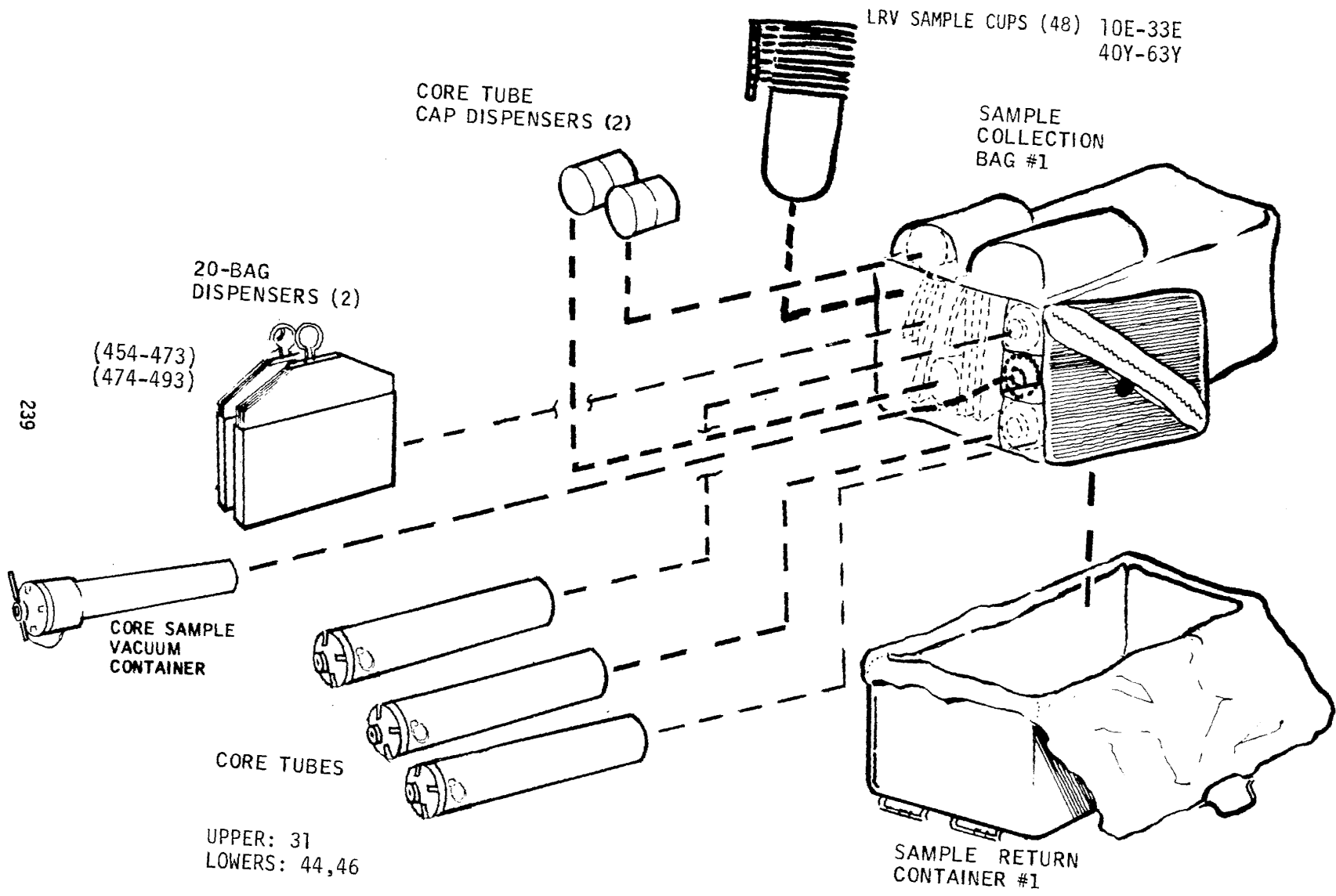


FIGURE 3.6-9 GEOLOGY SAMPLING ITEMS STOWED IN SRC # 1

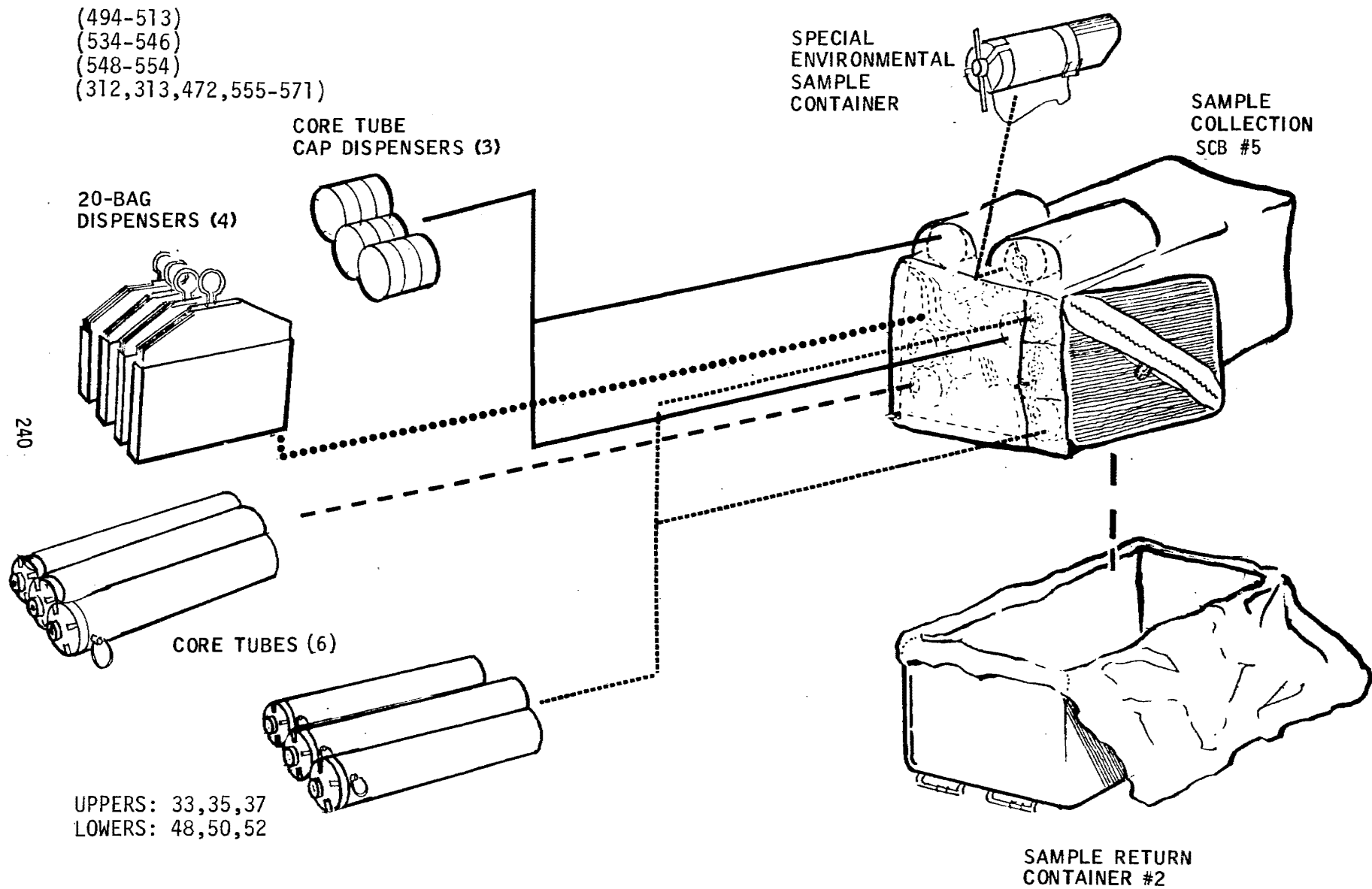
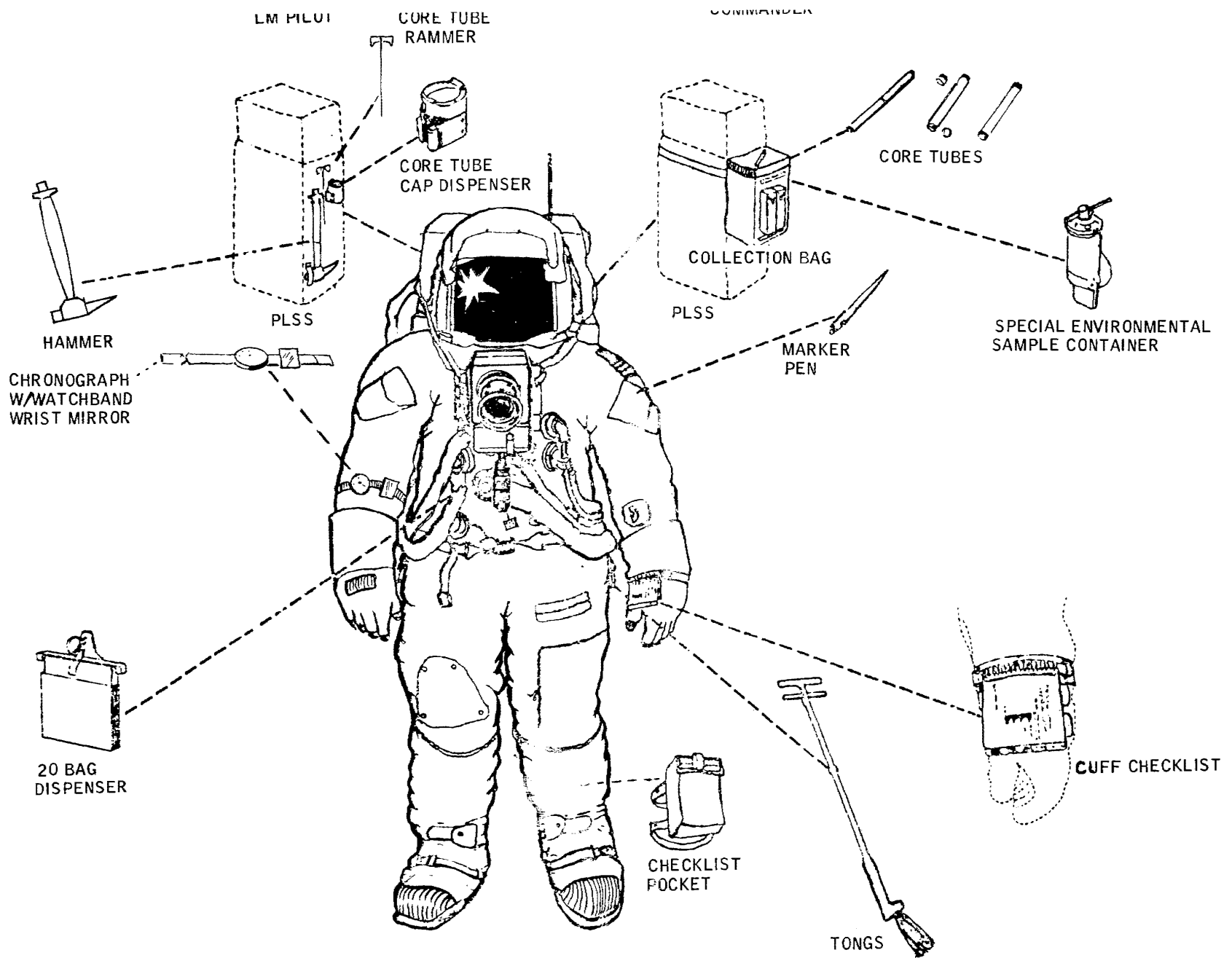


FIGURE 3.6-10 GEOLOGY SAMPLING ITEMS STOWED IN SRC # 2

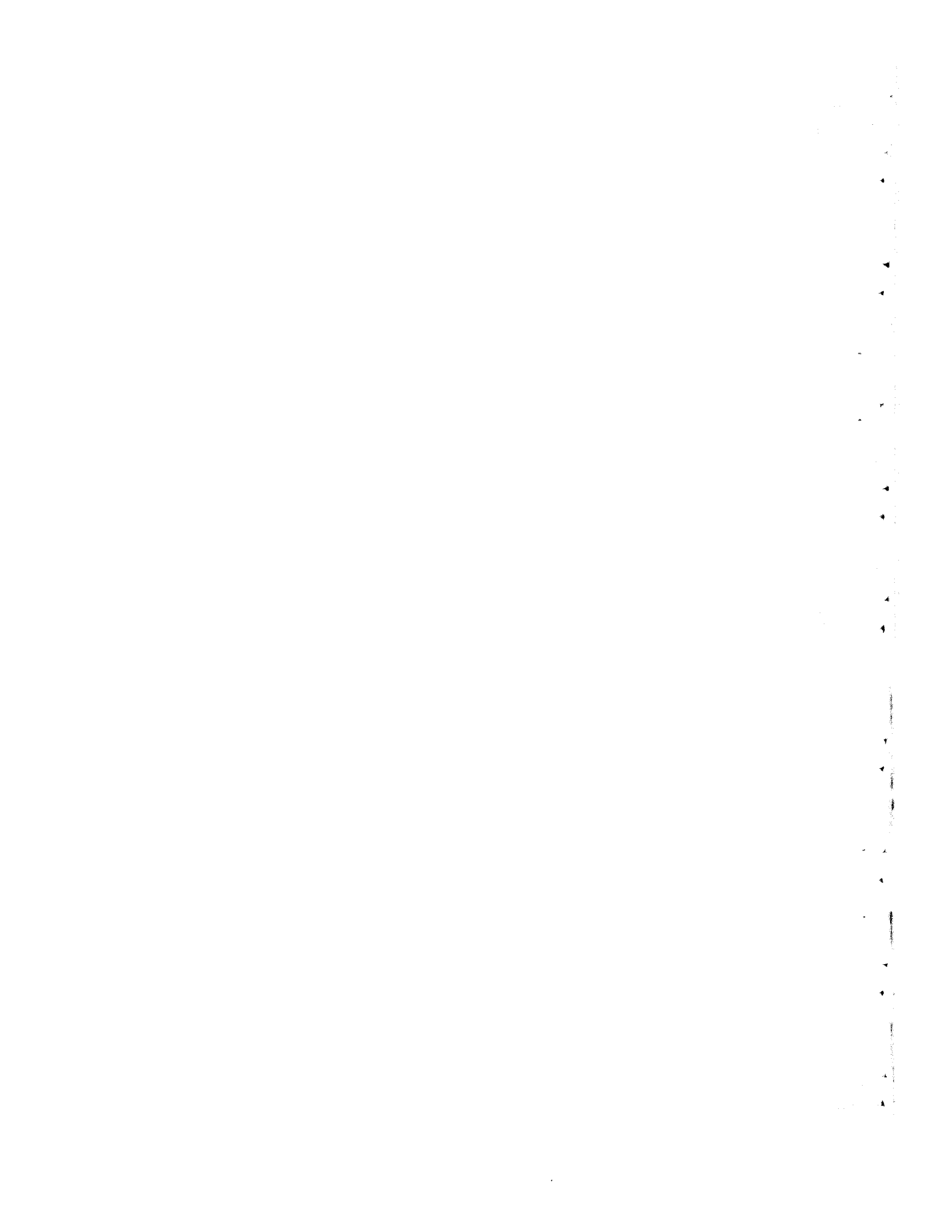


241

FIGURE 3.6-11 LUNAR SURFACE EQUIPMENT STOWED ON EMU

1. 2. 3. 4. 5. 6. 7. 8. 9. 10. 11. 12. 13. 14. 15. 16. 17. 18. 19. 20. 21. 22. 23. 24. 25. 26. 27. 28. 29. 30. 31. 32. 33. 34. 35. 36. 37. 38. 39. 40. 41. 42. 43. 44. 45. 46. 47. 48. 49. 50. 51. 52. 53. 54. 55. 56. 57. 58. 59. 60. 61. 62. 63. 64. 65. 66. 67. 68. 69. 70. 71. 72. 73. 74. 75. 76. 77. 78. 79. 80. 81. 82. 83. 84. 85. 86. 87. 88. 89. 90. 91. 92. 93. 94. 95. 96. 97. 98. 99. 100.

3.7 EQUIPME



3.7 LUNAR SURFACE EQUIPMENT MANAGEMENT

This section provides listings of lunar surface equipment with respect to their location at selected points during the three EVA's. The selected points are as follows:

| <u>EVA</u> | <u>EVENT</u> | <u>TABLE NO.</u> |
|------------|--------------------------------------|------------------|
| 1 | : PRE-ALSEP LOADUP AT LM | 3.7-1 |
| 1 | : PRE-ALSEP LRV CREW CONFIGURATION | |
| 1 | : PRE-GEOLOGY LRV CREW CONFIGURATION | |
| 1 | : ARRIVAL AT LM | |
| 1 | : TRANSFERS TO MESA & LM | |
| 1 | : FINAL EVA 1 CONFIGURATION | |
| 2 | : PRE-GEOLOGY LOADUP AT LM | 3.7-2 |
| 2 | : PRE-GEOLOGY LRV-CREW CONFIGURATION | |
| 2 | : ARRIVAL AT LM | |
| 2 | : TRANSFERS TO MESA & LM | |
| 2 | : FINAL EVA 2 CONFIGURATION | |
| 3 | : PRE-GEOLOGY LOADUP AT LM | 3.7-3 |
| 3 | : PRE-GEOLOGY LRV-CREW CONFIGURATION | |
| 3 | : ARRIVAL AT LM | |
| 3 | : TRANSFERS TO MESA & LM | |
| 3 | : FINAL EVA 3 CONFIGURATION | |

These three tables are combined for sake of clarity on one sheet. Table 3.7-4 lists the loose equipment left on the lunar surface during the course of the lunar stay on Apollo 17.

Table 3.7-5 lists equipment transfer items during all three EVA's, both to the surface and into the ascent stage of the LM.

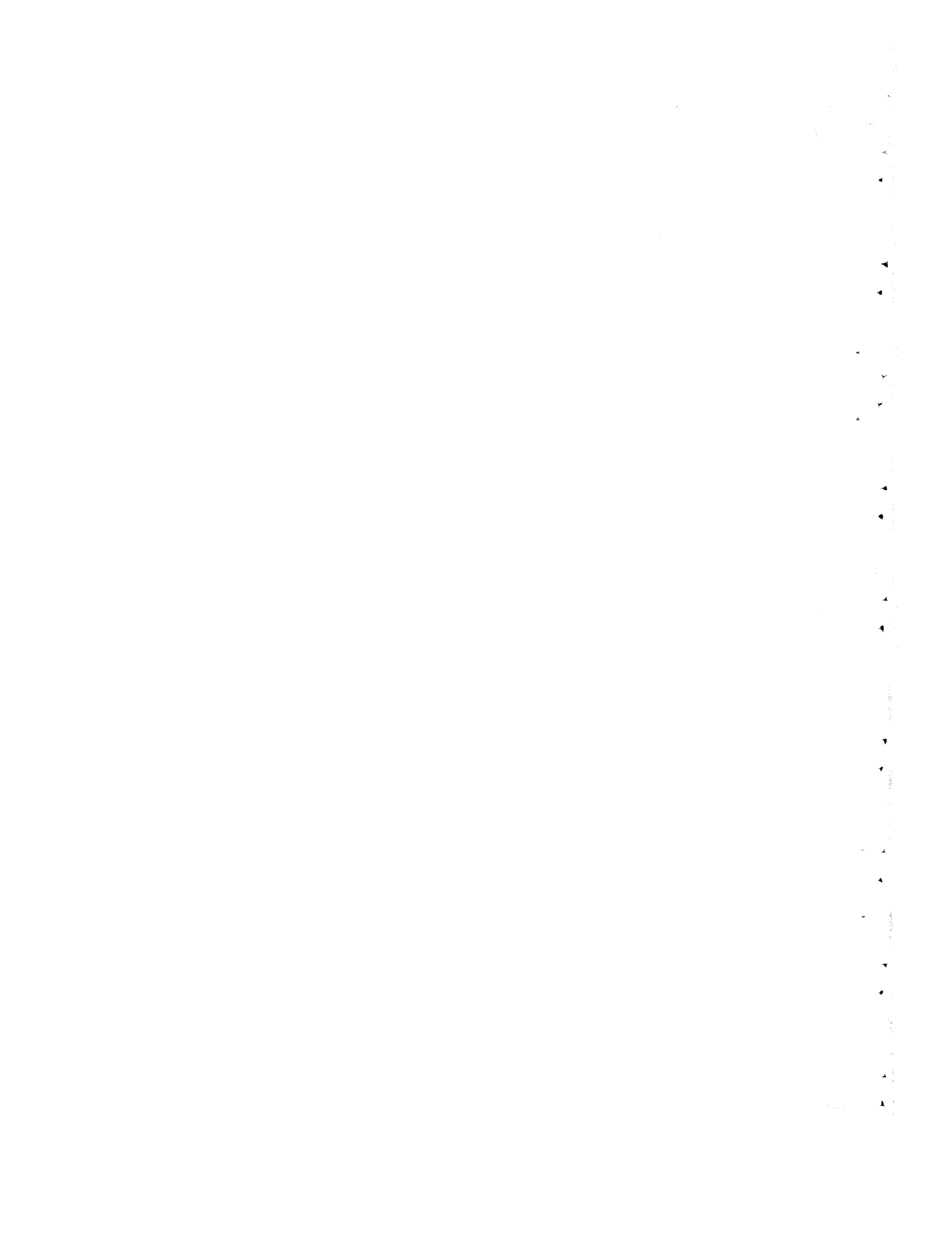


TABLE 37.1: EVA 1 EQUIPMENT MANAGEMENT

TABLE 37.2: EVA 2 EQUIPMENT MANAGEMENT

TABLE 37.3: EVA 3 EQUIPMENT MANAGEMENT

| ITEM | INITIAL PRE-ALSEP LOADUP AT LM | | FINAL PRE-ALSEP LRV-CREW CONFIGURATION | PRE-GEOLOGY LRV-CREW CONFIGURATION | ARRIVAL AT LM | TRANSFERS TO MESA & LM | FINAL EVA 1 CONFIGURATION | INITIAL PRE-GEOLOGY LOADUP AT LM | | PRE-GEOLOGY LRV-CREW CONFIGURATION | ARRIVAL AT LM | TRANSFERS TO MESA & LM | FINAL EVA 2 CONFIGURATION | INITIAL PRE-GEOLOGY LOADUP AT LM | | PRE-GEOLOGY LRV-CREW CONFIGURATION | ARRIVAL AT LM | TRANSFERS TO MESA & LM | FINAL CONFIGURATION | ITEM | | | | | | | | | | | | | |
|---|--------------------------------|-----------------|---|---|---------------|---|---------------------------|----------------------------------|--------------|------------------------------------|-----------------------|------------------------|---------------------------|----------------------------------|-------------|------------------------------------|----------------|------------------------|---------------------|---|------------------|-------------|------------|------------|------------|------------|------------|------------|------------|------------|------------|------------|------------|
| | ORIGIN | DESTINATION | | | | | | ORIGIN | DESTINATION | | | | | ORIGIN | DESTINATION | | | | | | ORIGIN | DESTINATION | | | | | | | | | | | |
| [EVA 1]
ETB
LMP 70 MM CAM
MAG ALPHA
MAG BRAVO
MAG CHARLIE
MAG GOLF
MAG HOTEL
MAP PKG (EVA 1)
HOLDER W/CHECKLIST
SUN COMPASS
BSLSS
LENS BRUSHES (2)
20 DSBD BRACKETS (2)
COSMIC RAY EXP
500 MM CAM
MAG ROMEO | LMP CAM | UNDER CDR SEAT | ON LMP (USED)
ON CDR
ON LMP
ON ACC STAFF | ON LMP
(USED) UNDER CDR SEAT
ON CDR
ON LMP | ON LMP | ETB TO A/S
ETB TO A/S
ETB TO A/S
ETB TO A/S
ETB TO A/S | [Hatched] | (ON CDR CAM) ETB | LMP SEAT/PAN | ON LMP
ON CDR
ON LMP | (USED) UNDER CDR SEAT | ETB TO A/S | [Hatched] | ETB | ON LMP | ON LMP
ON CDR
ON LMP | UNDER CDR SEAT | DISCARDED* | [Hatched] | LMP 70 MM CAM
MAG ALPHA
MAG BRAVO
MAG CHARLIE
MAG GOLF
MAG HOTEL
MAP PKG (EVA 1)
HOLDER W/CHECKLIST
SUN COMPASS
BSLSS
LENS BRUSHES (2)
20 DSBD BRACKETS (2)
COSMIC RAY EXP
500 MM CAM
MAG ROMEO | [EVA 1] | | | | | | | | | | | | |
| | | CDR CAM | | | ON CDR | ON CDR | | | ETB TO A/S | | ETB TO A/S | ETB TO A/S | | | ETB TO A/S | | ETB TO A/S | ETB TO A/S | | | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | |
| | | UNDER CDR SEAT | | | ON LMP | ON LMP | | | ETB TO A/S | | ETB TO A/S | ETB TO A/S | | | ETB TO A/S | | ETB TO A/S | ETB TO A/S | | | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S | ETB TO A/S |
| MESA
SRC 1
CDR 70 MM CAM
BORE/CORE STEM PKG
ALSD
FLAG
ECS L10H CANISTER
RAKE
CORE STEM BAG
NEUTRON FLUX EXPERIMENT
PALLET 1
SAMPLE RETURN BAGS (6) | MESA | ON MESA TABLE | UNDER CDR SEAT | ON CDR
BORE STEMS-IN GND
CORE STEMS-AT MESA
(DISCARDED)
IN GROUND | ON CDR | TO A/S
ETB TO A/S
CORE STEM BAG TO A/S
PALLET 1 TO A/S
TO A/S
TO A/S
ETB TO A/S | [Hatched] | LMP SEAT/PAN | ON CDR | ON CDR
ON LMP
ON LMP | (USED) UNDER CDR SEAT | ETB TO A/S | [Hatched] | ETB | ON CDR | ON CDR
ON LMP
ON LMP | ON CDR | DISCARDED* | [Hatched] | SRC 1
CDR 70 MM CAM
BORE/CORE STEM PKG
ALSD
FLAG
ECS L10H CANISTER
RAKE
CORE STEM BAG
NEUTRON FLUX EXPERIMENT
PALLET 1
SAMPLE RETURN BAGS (6) | MESA | | | | | | | | | | | | |
| | | CDR SEAT | | | ON LMP SEAT | ON LMP SEAT | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | |
| | | ON LMP SEAT | | | ON LMP SEAT | ON LMP SEAT | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S |
| SCB 1
SCB 2
SCB 3 | GEO PALLET | TOOL GATE | ON CDR PLSS
ON LMP PLSS | ON CDR PLSS
ON LMP PLSS | ON CDR PLSS | SRC 1 TO A/S
TO A/S | [Hatched] | LMP SEAT/PAN | ON CDR PLSS | ON CDR PLSS
ON LMP PLSS | (USED) UNDER CDR SEAT | ETB TO A/S | [Hatched] | ETB | ON CDR PLSS | ON CDR PLSS
ON LMP PLSS | ON CDR PLSS | DISCARDED* | [Hatched] | SCB 1
SCB 2
SCB 3 | GEO PALLET & MSL | | | | | | | | | | | | |
| | | ON ACC STAFF | | | ON ACC STAFF | ON ACC STAFF | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | | |
| | | ON ACC STAFF | | | ON ACC STAFF | ON ACC STAFF | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S |
| GEO PALLET & MSL
ALSEP PKG 1
ALSEP PKG 2
SEP XMTR
SEP RCVR
EP #6
EP #5
EP #7
EP #4 | GEO PALLET | SURFACE SURFACE | LMP CARRY
LMP CARRY | DEPLOYED
DEPLOYED | DEPLOYED | [Hatched] | [Hatched] | LMP FOOT PAN | DEPLOYED | ON LMP LAP
ON LMP LAP | (USED) UNDER CDR SEAT | ETB TO A/S | [Hatched] | GEO PALLET | ON LMP LAP | ON LMP LAP
ON LMP LAP | DEPLOYED | DISCARDED* | [Hatched] | ALSEP PKG 1
ALSEP PKG 2
SEP XMTR
SEP RCVR
EP #6
EP #5
EP #7
EP #4 | GEO PALLET & MSL | | | | | | | | | | | | |
| | | QUAD 3 | | | QUAD 3 | QUAD 3 | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | |
| | | QUAD 3 | | | QUAD 3 | QUAD 3 | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S |
| SCB 1
20 DSBD BAG PACKS (2)
CAP DISPENSERS (2)
CORE TUBE (U)
CORE TUBE (L)
CORE TUBE (L)
CSVC
LRV SAMPLER CUP SETS (4)
LRV SAMPLER | GEO PALLET | TOOL GATE | ON CDR PLSS
ON LMP PLSS | ON CDR PLSS
ON LMP PLSS | ON CDR PLSS | DISCARDED
SRC 1 TO A/S
SRC 1 TO A/S
UNDER SEAT | [Hatched] | LMP SEAT/PAN | ON CDR PLSS | ON CDR PLSS
ON LMP PLSS | (USED) UNDER CDR SEAT | ETB TO A/S | [Hatched] | GEO PALLET | ON LMP PLSS | ON LMP PLSS
ON LMP PLSS | ON LMP PLSS | EXPENDED | [Hatched] | 20 DSBD BAG PACKS (2)
CAP DISPENSERS (2)
CORE TUBE (U)
CORE TUBE (L)
CORE TUBE (L)
CSVC
LRV SAMPLER CUP SETS (4)
LRV SAMPLER | SCB 1 | | | | | | | | | | | | |
| | | TOOL GATE | | | TOOL GATE | TOOL GATE | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | |
| | | TOOL GATE | | | TOOL GATE | TOOL GATE | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S |
| [EVA 2]
ETB
MAG DELTA
MAG INDIA
MAG JULIET
MAG KILO
MAP PKG (EVA 2)
POLARIZING FILTER | ETB | UNDER CDR SEAT | ON CDR CAM
(USED)
ON LMP CAM | ON CDR CAM
(USED)
ON LMP CAM | ON CDR CAM | ETB TO A/S
ETB TO A/S
ETB TO A/S
ETB TO A/S | [Hatched] | LMP SEAT/PAN | ON CDR CAM | ON CDR CAM
(USED)
ON LMP CAM | (USED) UNDER CDR SEAT | ETB TO A/S | [Hatched] | ETB | ON CDR CAM | ON CDR CAM
(USED)
ON LMP CAM | ON CDR CAM | DISCARDED | [Hatched] | MAG DELTA
MAG INDIA
MAG JULIET
MAG KILO
MAP PKG (EVA 2)
POLARIZING FILTER | ETB | | | | | | | | | | | | |
| | | UNDER CDR SEAT | | | ON CDR CAM | ON CDR CAM | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | |
| | | UNDER CDR SEAT | | | ON CDR CAM | ON CDR CAM | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S |
| MESA
SRC 2
PALLET 2
LCRU BATT | MESA | MESA TABLE | ON LMP PLSS
ON CDR PLSS | ON LMP PLSS
ON CDR PLSS | ON LMP PLSS | EXPENDED
IN SCB 5 | [Hatched] | LMP SEAT/PAN | ON LMP PLSS | ON LMP PLSS
ON CDR PLSS | (USED) UNDER CDR SEAT | ETB TO A/S | [Hatched] | MESA | ON LMP PLSS | ON LMP PLSS
ON CDR PLSS | ON LMP PLSS | DISCARDED | [Hatched] | SRC 2
PALLET 2
LCRU BATT | MESA | | | | | | | | | | | | |
| | | ON LMP PLSS | | | ON LMP PLSS | ON LMP PLSS | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | | |
| | | ON LMP PLSS | | | ON LMP PLSS | ON LMP PLSS | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S |
| GEO PALLET
SCB 4
SCB 5
SCB 6
SCB 7
EP #1
EP #8
EP #2
EP #3 | GEO PALLET | TOOL GATE | ON LMP PLSS
ON CDR PLSS | ON LMP PLSS
ON CDR PLSS | ON LMP PLSS | EXPENDED
EXPENDED | [Hatched] | LMP SEAT/PAN | ON LMP PLSS | ON LMP PLSS
ON CDR PLSS | (USED) UNDER CDR SEAT | ETB TO A/S | [Hatched] | GEO PALLET | ON LMP PLSS | ON LMP PLSS
ON CDR PLSS | ON LMP PLSS | EXPENDED | [Hatched] | SCB 4
SCB 5
SCB 6
SCB 7
EP #1
EP #8
EP #2
EP #3 | GEO PALLET | | | | | | | | | | | | |
| | | TOOL GATE | | | TOOL GATE | TOOL GATE | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | |
| | | TOOL GATE | | | TOOL GATE | TOOL GATE | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S |
| SCB 5
20 DSBD BAG PACKS (2)
20 DSBD BAG PACKS (2)
CAP DISPENSER
CAP DISPENSER
CAP DISPENSER
CORE TUBE (U)
CORE TUBE (U)
CORE TUBE (U)
CORE TUBE (L)
CORE TUBE (L)
CORE TUBE (L)
SESC | GEO PALLET | TOOL GATE | ON LMP PLSS
ON CDR PLSS | ON LMP PLSS
ON CDR PLSS | ON LMP PLSS | EXPENDED
EXPENDED | [Hatched] | LMP SEAT/PAN | ON LMP PLSS | ON LMP PLSS
ON CDR PLSS | (USED) UNDER CDR SEAT | ETB TO A/S | [Hatched] | GEO PALLET | ON LMP PLSS | ON LMP PLSS
ON CDR PLSS | ON LMP PLSS | EXPENDED | [Hatched] | 20 DSBD BAG PACKS (2)
20 DSBD BAG PACKS (2)
CAP DISPENSER
CAP DISPENSER
CAP DISPENSER
CORE TUBE (U)
CORE TUBE (U)
CORE TUBE (U)
CORE TUBE (L)
CORE TUBE (L)
CORE TUBE (L)
SESC | SCB 5 | | | | | | | | | | | | |
| | | TOOL GATE | | | TOOL GATE | TOOL GATE | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S |
| | | TOOL GATE | | | TOOL GATE | TOOL GATE | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S |
| [EVA 3]
ETB
MAG ECHO
MAG FOXTROT
MAG IMA
MAG MIKE
MAG NOVEMBER
MAP PKG (EVA 3)
SCB 8
SAMPLE RETURN BAG | ETB | UNDER CDR SEAT | ON CDR CAM
(USED)
ON LMP CAM | ON CDR CAM
(USED)
ON LMP CAM | ON CDR CAM | ETB TO A/S
ETB TO A/S
ETB TO A/S | [Hatched] | LMP SEAT/PAN | ON CDR CAM | ON CDR CAM
(USED)
ON LMP CAM | (USED) UNDER CDR SEAT | ETB TO A/S | [Hatched] | ETB | ON CDR CAM | ON CDR CAM
(USED)
ON LMP CAM | ON CDR CAM | DISCARDED | [Hatched] | MAG ECHO
MAG FOXTROT
MAG IMA
MAG MIKE
MAG NOVEMBER
MAP PKG (EVA 3)
SCB 8
SAMPLE RETURN BAG | ETB | | | | | | | | | | | | |
| | | UNDER CDR SEAT | | | ON CDR CAM | ON CDR CAM | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S |
| | | UNDER CDR SEAT | | | ON CDR CAM | ON CDR CAM | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | | TO A/S | TO A/S | | | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S | TO A/S |

KEY: [Hatched] NO CHANGE IN STATUS OR LOCATION IN THIS BLOCK.
 [Hatched] NO FURTHER CHANGE IN STATUS OR LOCATION DURING REST OF EVA'S.

*MAYBE ON 500 CAM

*ONE OF THESE TO BE LEFT LENS UP FOR LONG-TERM EXPERIMENT

TABLE 3.7-4 LOOSE EQUIPMENT LEFT ON LUNAR SURFACE

1. Jettison During EVA-1: (In a Jettison Bag)
 2 OPS Pallets
 3 Arm rests
 Camera Bag & padding

2. Discarded On Lunar Surface During EVA-1
 Misc Pip Pins and Fastenings
 Thermal Covers
 MESA Brackets
 ALSEP RTG Dome Removal Tool and Fuel Transfer Tool
 ALSEP Subpallet
 Lunar Surface Drill, Treadle, Rack & Extractor Assy
 ALSEP Dust Cover (pkg. 1)
 LCRU/GTCA Pallet
 Pallet 1
 SRC Dust Skirt and Seal Protector
 Bore/Core stems bag & protectors
 Core Tube Cap Dispenser

3. Operational Equipment Deployed and Left On EVA-1
 Flag
 TV Camera, LCRU, TCU, HGA, LGA
 LRV
 ALSEP: LSG, LSPE, LMS, LEAM, HFE
 3 Explosive Packages
 Quad III Pallet with hand tools and TGE
 SEP Receiver and Transmitter
 Neutron Flux Exp.
 Cosmic Ray Exp.(option)

4. Jettison During EVA-2
 1 LM ECS LiOH Cartridge and Canister
 2 PLSS Batteries
 2 PLSS LiOH Cartridges and Canisters

5. Discarded on Lunar Surface During EVA-2
 EVA-2 Pallet
 1 Core Tube Cap Dispenser
 SRC Dust Skirt and Seal Protector
 LSPE Pallet 1

6. Operational Equipment Deployed and Left on EVA-2
 3 Explosive Packages
 Cosmic Ray Experiment

7. Jettisoned During EVA-3 (In Jettison Bag)
 2 PLSS Batteries
 2 PLSS LiOH Cartridges and Canisters
 2 LCG (SPARES)

8. Discarded on Lunar Surface During EVA-3
 LRV w/TV, TCU, LCRU, 1-LCRU Battery
 Hand Tool Gate w/tools
 Gnomon
 Polarizing Filter
 2-70mm Data Camera w/Bracket, Handle, Trigger
 500mm Data Camera
 Accessory Staff
 Lunar Equipment Conveyor
 2 lens Brushes
 BSLSS
 Dust Brush
 Unused Documented Sample Bags
 Reseau Plate Covers (2)
 Sun Compass
 TGE
 SEP RCVR
 LRV Sample Assy
9. Operational Equipment Deployed and Left On EVA-3
 2 Explosive Packages
10. Jettisoned to Lunar Surface After EVA-3
 2 PLSS
 TIED IN ISS
 2 pr Lunar Boots
 2 RCU
 Retractable Tethers
 1 Armrest
11. Jettisoned to Lunar Surface Prior to L/O
 2 ICG
 2 Hammocks
 Sleep Restraint
 Waste Receptacle
 Helmet/EVA Int. Stow.
 ETB
 2 LCG Adapters
 1 LM ECS LiOH cartridge and Cannister
12. Discarded after LM A/S Launch
 1-LM Descent Stage

TABLE 3.7-5 EQUIPMENT TRANSFERRED BETWEEN ASCENT STAGE/SURFACE/
ASCENT STAGE

1. Transferred to Surface EVA-1
ETB and Contents:
Mags (70mm)B,C,G,H
500mm Camera with Mag R
LMP 70mm Camera with Mag A
Map Pkg for EVA 1
Map Holder
LRV Checklist
2 Lens brushes, Tape, Scissors
2 Bag dispenser Brackets
Sun Compass
BSLSS (with Spare OPS Antenna Kit)
Cosmic Ray Experiment
Empty EVA-1 Pallet

2. Transferred into Ascent Stage EVA-1
ETB and Contents:
Mags A,B, H,R
2 70mm cameras w/Mags C&G
Map Pkg for EVA-1
6 - Sample Containment Bags
SRC 1
SCB 2
Core Stems (8) in Bag
EVA-1 Pallet with ECS LiOH cannister

3. Transferred to Surface EVA-2
ETB and Contents:
Mags D,I,J,K,R,B
2-70mm Cameras w/Mags C&H
Map Pkg for EVA 2
Polarizing Filter
Empty EVA-2 Pallet

4. Transferred into Ascent Stage EVA-2
EVA 2 Pallet
ETB and Contents:
Mags C,H,I,J,R,B
2-70mm cameras w/Mags D&K
Map Pkg for EVA 2
SRC 2
SCB 4
SCB 6

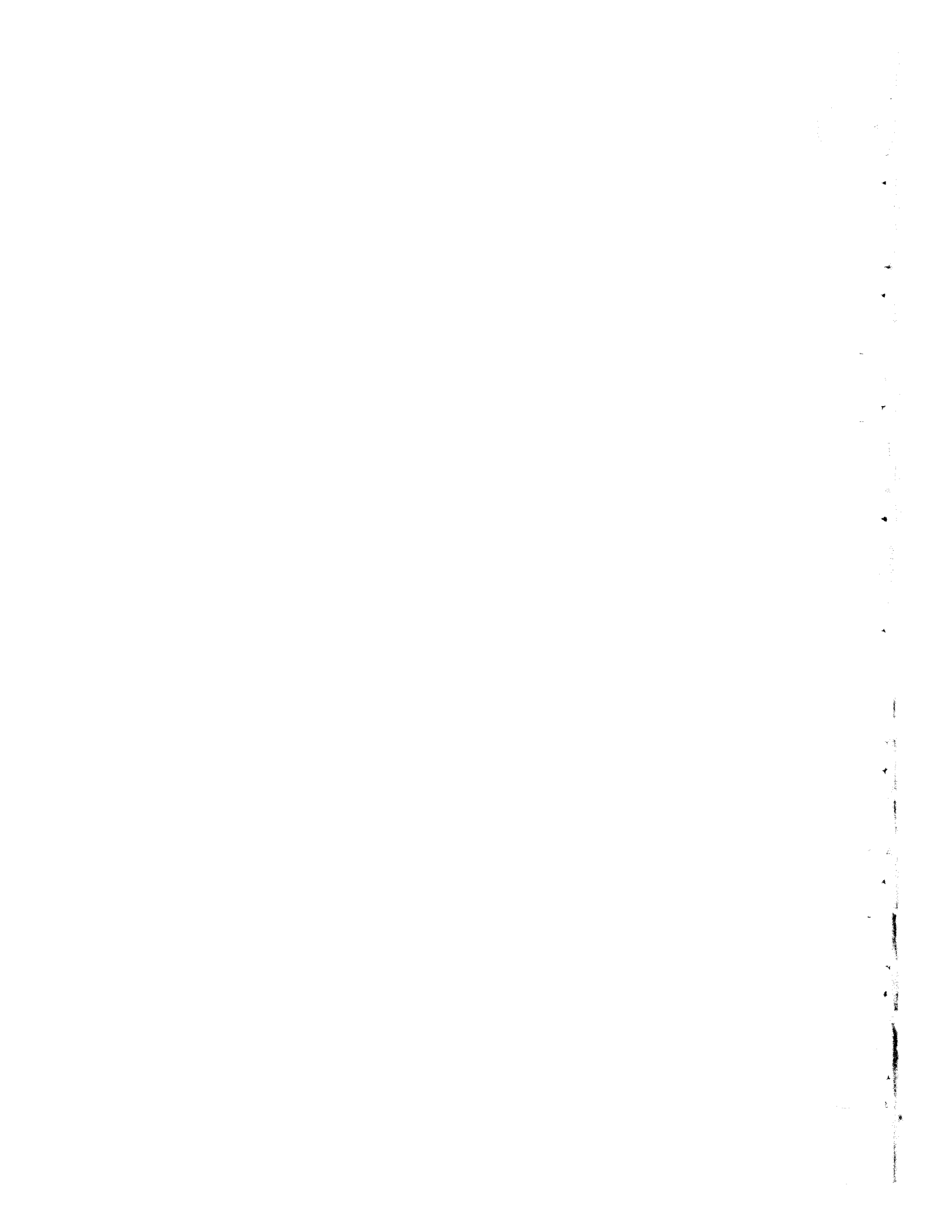
TABLE 3.7-5 CONT'D

5. Transferred to Surface EVA-3
ETB and Contents:
Mags F,K,M,N,R,D
2-70mm cameras w/Mags E&L
Map Pkg for EVA 3

6. Transferred into Ascent Stage EVA-3
ETB and Contents:
Mags E,F,L,M,N,R,D,K
Map Pkg for EVA 3
Cosmic Ray Experiment
DSEA
SCB 3
SCB 7
SCB 8
Sample Return Bag
Neutron Flux Experiment

Handwritten notes and symbols, including a large '3' and various small markings.

3.8 L



3.8 LUNAR ROVER VEHICLE

The Apollo 17, J-3, mission is the third to use a vehicle to transport the crew and equipment on extended geology traverses. The benefits derived from using the LRV during the geology traverses include:

- 1) Decreased metabolic rates while driving,
- 2) Decreased traverse time between geology sites,
- 3) Increased communications capability, and
- 4) Increased equipment transportation capability.

The intent of this section is to provide operational data relative to the LRV systems, operations, performance and constraints. In addition, a section is provided showing the decal and checklist used in operating the vehicle on the lunar surface.

3.8.1 Systems

The LRV (see figure 3.8-1) is a four wheel, electrically powered, crew controlled, vehicle designed to accommodate two crewmen and stowed ancillary equipment (see figure 3.5-1 LRV stowage) for lunar surface traverses. Control of the LRV during the traverse is effected by either of the two crewmen operating the hand controller located between them. The functions of the hand controller are shown in figure 3.8-3. The crewman in the left seat nominally has a control advantage since the "T" handle is biased in his direction.

Selection of power sources for the steering motors (2) and the drive motors (4), monitoring of parameters and operation of the navigation system is possible by either crewman using the control and display console. The functions of the control and display console which are not intuitively obvious are briefly described in figure 3.8-4. For a complete description of the LRV systems refer to the Lunar Roving Vehicle Operations Handbook.

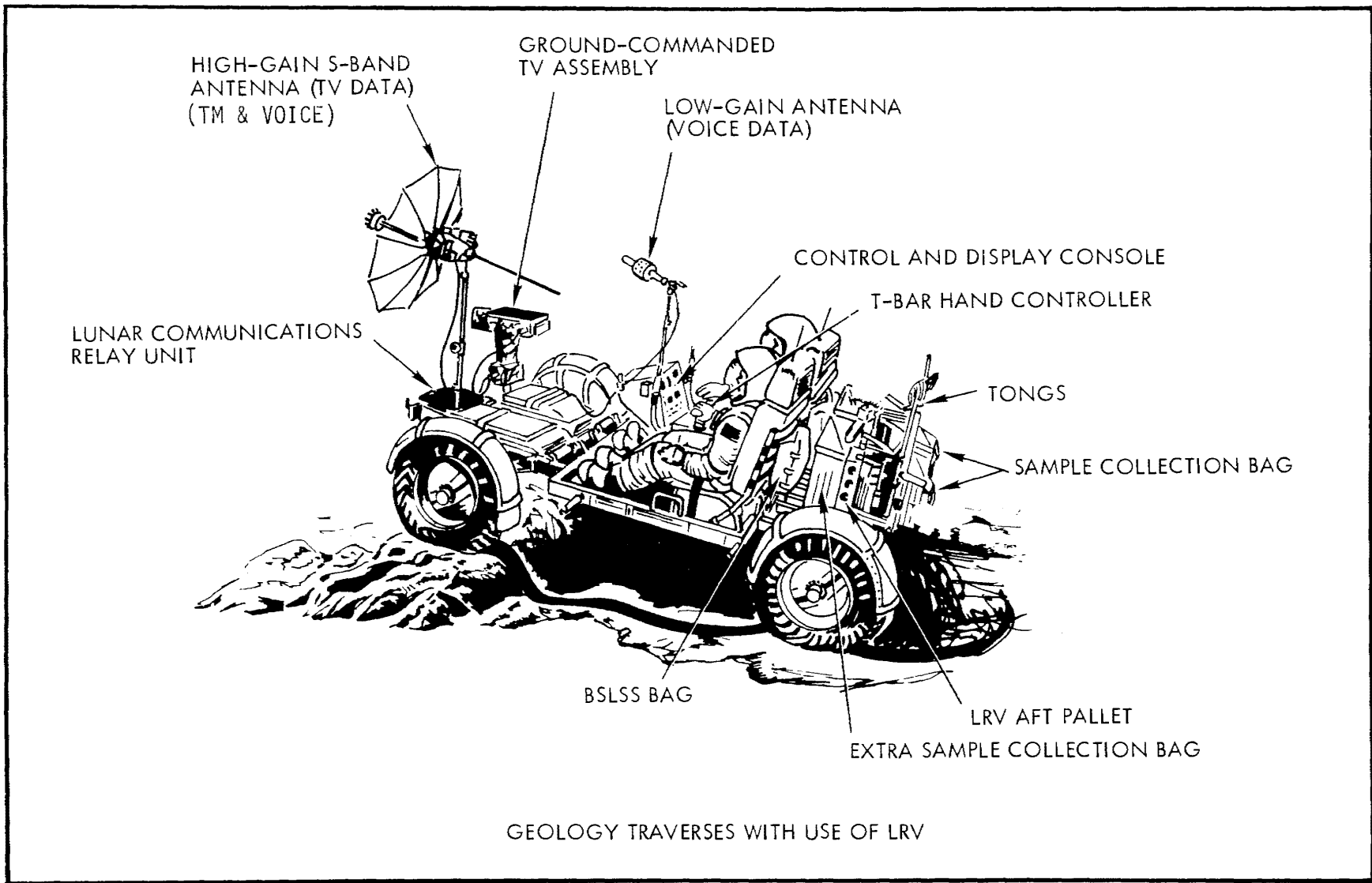
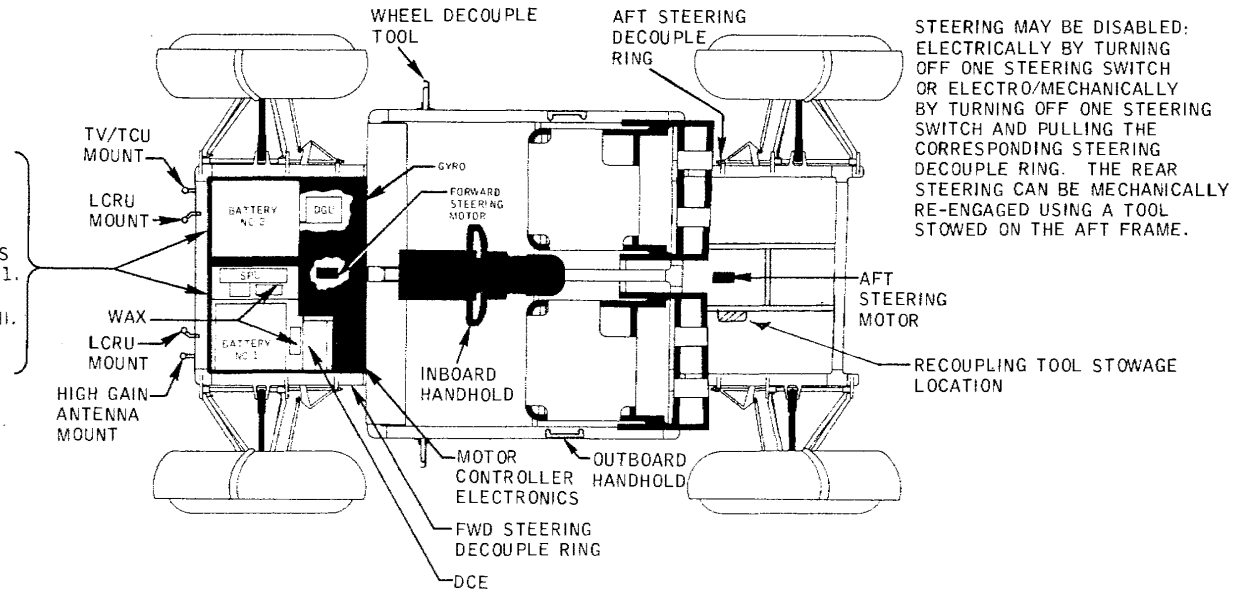
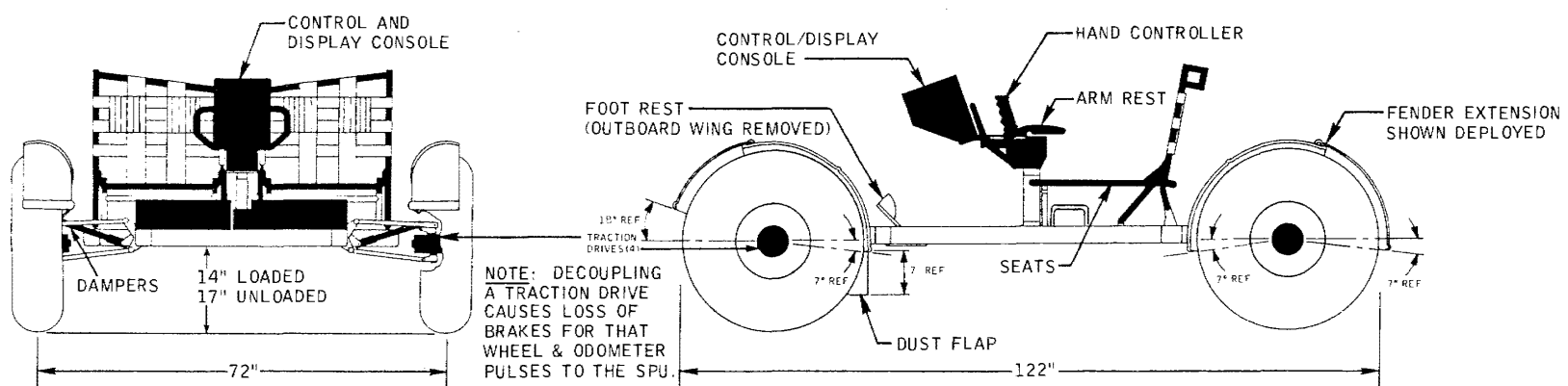


FIGURE 3.8-1 LUNAR ROVING VEHICLE (LRV)

BATTERY DUST COVERS NOT SHOWN -
 BATTERY NO. 2 COVER MUST BE OPENED
 BY PULLING UP ON INBOARD SIDE TO LATCH
 OPEN AND COVERS ONLY BATTERY NO. 2.
 BATTERY NO. 1 COVER IS LARGER AND COVERS
 THE SPU AND DCE AS WELL AS BATTERY NO. 1.
 BOTH COVERS ARE OPENED AT LRV FINAL
 SHUT-DOWN AT THE END OF EVA'S I, II, AND III.



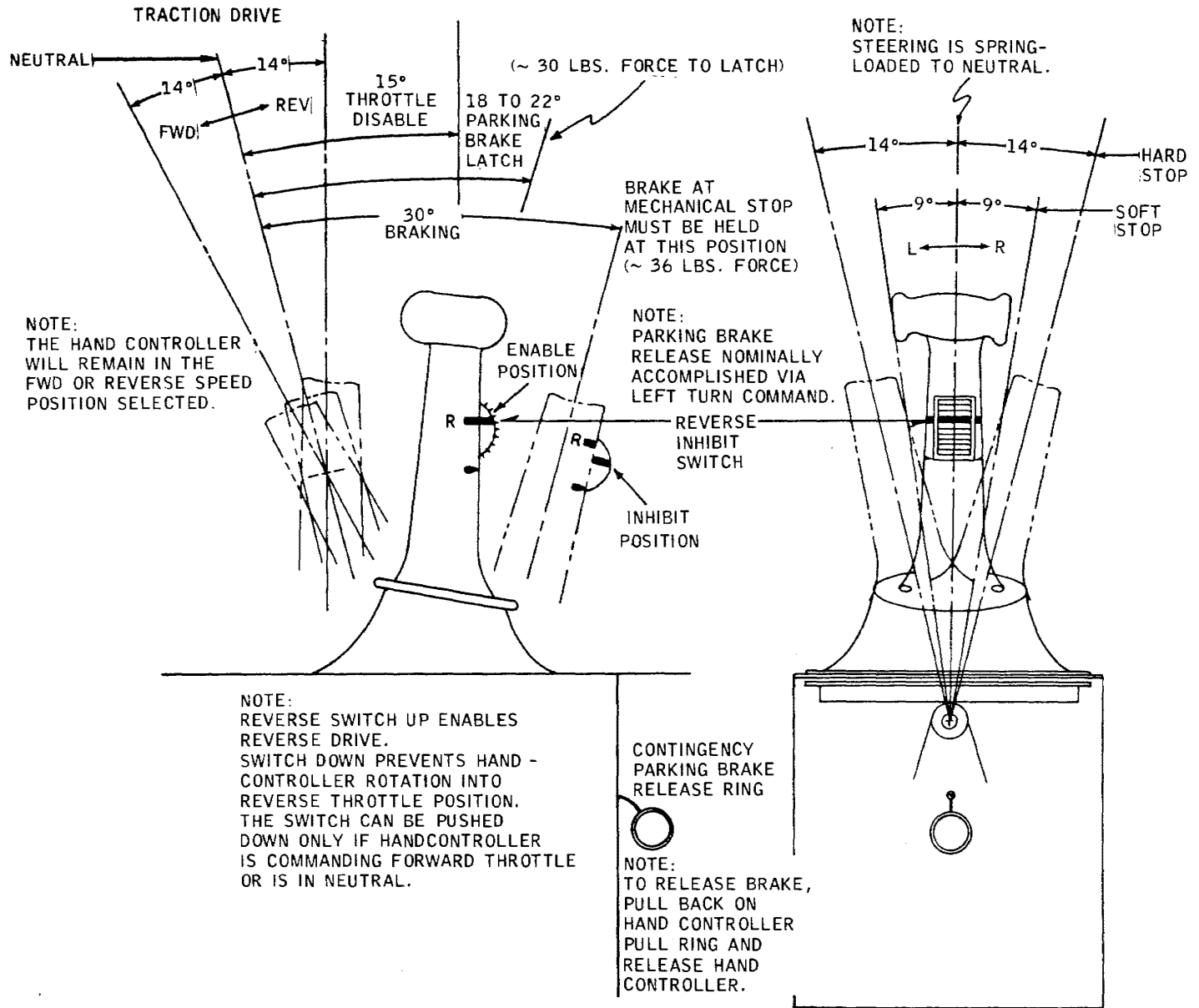
STEERING MAY BE DISABLED:
 ELECTRICALLY BY TURNING
 OFF ONE STEERING SWITCH
 OR ELECTRO/MECHANICALLY
 BY TURNING OFF ONE STEERING
 SWITCH AND PULLING THE
 CORRESPONDING STEERING
 DECOUPLE RING. THE REAR
 STEERING CAN BE MECHANICALLY
 RE-ENGAGED USING A TOOL
 STOWED ON THE AFT FRAME.



NOTE: DECOUPLING
 A TRACTION DRIVE
 CAUSES LOSS OF
 BRAKES FOR THAT
 WHEEL & ODOMETER
 PULSES TO THE SPU.

CAUTION: USE ONLY
 THE WHEEL DECOUPLE
 TOOL TO DECOUPLE OR
 TO RECOUPLE THE
 DRIVE UNIT.

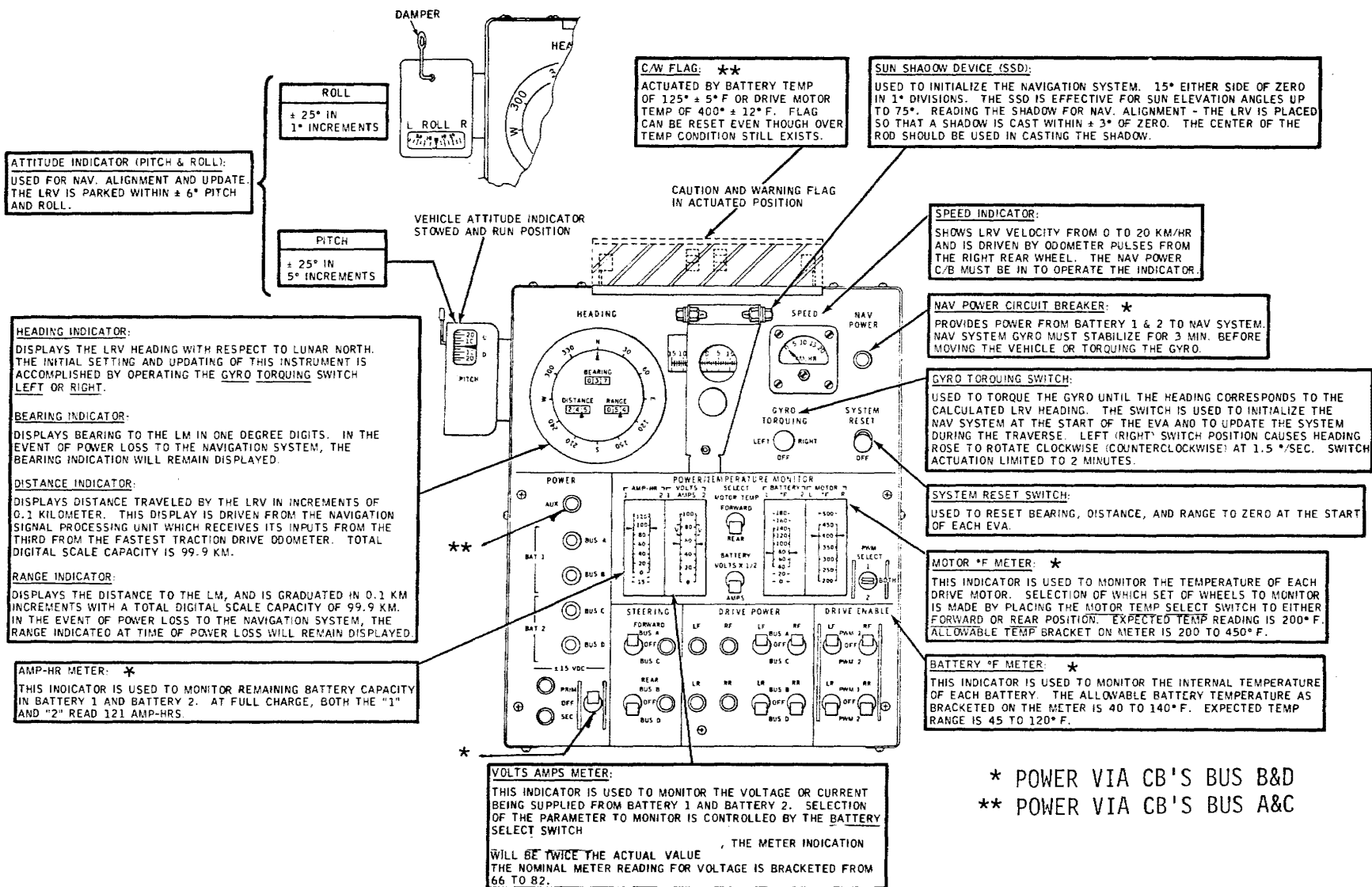
FIGURE 3.8-2 LRV SYSTEMS



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FIGURE 3.8-3 LRV HANDCONTROLLER FUNCTIONS

FIGURE 3.8-4 LRV CONTROL AND DISPLAY FUNCTIONS



3.8.2 Operations

The following table is a compendium of the functions performed on and with the LRV during the lunar surface EVA operations. As such, it is designed to supplement data on LRV operations as specified in the integrated EVA vertical timelines, by providing detail procedures. The delineation of these functions is by EVA and the procedures referenced within each function are given in chronological order.

TABLE 3.8-1

LRV OPERATIONAL FUNCTIONS

| EVA-1 | FUNCTION | PROCEDURE |
|-------|-----------------------|---------------|
| | Deploy and set-up | Table 3.8-2 |
| | LRV Power-up | Table 3.8-3.A |
| | Navigation Alignment | Table 3.8-4 |
| | Geology/Science Sites | |
| | A) Nominal | Table 3.8-5.A |
| | B) Nav update | Table 3.8-5.B |
| | LRV close-out | Table 3.8-5.A |
| EVA-2 | LRV power-up | Table 3.8-3.B |
| | Navigation Alignment | Table 3.8-4 |
| | Geology/Science Sites | |
| | A) Nominal | Table 3.8-5.A |
| | B) Nav Update | Table 3.8-5.B |
| | LRV close-out | Table 3.8-6.B |
| EVA-3 | Navigation Alignment | Table 3.8-4 |
| | Geology/Science Sites | |
| | A) Nominal | Table 3.8-5.A |
| | B) Nav Update | Table 3.8-5.B |
| | LRV close-out | Table 3.8-6.C |

TABLE 3.8-2
LRV OFF-LOAD FROM LM AND LRV SET-UP

1. Release LRV insulation blanket, verify outrigger cables taut and chassis parallel.
2. Inspect right and left walking hinge latches to verify indicator marks aligned.
3. Release contingency deployment tool velcro. Remove and stow tool.
4. Release left hand deployment tape stowed in nylon bag attached to lower left support arm by velcro tapes.
5. Stow left hand deployment tape by draping it over a LM landing strut for convenient future access.
6. Release deployment cable from teflon clips on left side of LRV center chassis and deploy cable.
7. Release right hand deployment tape stowed in nylon bag attached to lower right support arm by velcro tape. Hold tape and move away from LRV deployment area.
8. Ascent LM ladder and pull LRV deployment D-handle. Verify LRV moves outward from LM about 4 degrees.
9. Descend LM ladder. Grasp deployment cable, monitor deployment activity and maintain tension on deployment cable.
10. Pull right hand deployment tape. Verify LRV rotates outward from LM.
11. Continue to pull right hand tape. When the tape marks appear (the vehicle is outboard at about 45 degrees) verify that:
 - (a) Tension on aft deployment cable is released.
 - (b) Aft chassis unfolds and locks in position.
 - (c) Rear wheels unfold and tethered rear wheel struts fall free.
 - (d) Forward chassis is released from console post and returns to 35 degree position. (Rotates in toward LM)
12. Continue to pull right hand tape. Verify that:
 - (a) Center/aft chassis rotates until rear wheels contact lunar surface.
 - (b) Rear wheels slide on surface permitting center/aft chassis to move away from LM.

NOTE: If wheels fail to slide, deployment cable may be pulled to permit center/aft chassis to move away from LM.

13. Continue to pull right hand tape. Verify that:
 - (a) Rear wheels are on the surface.
 - (b) Forward chassis continues to unfold and locks in position.
 - (c) Forward wheels unfold.
 - (d) Slack in outrigger cables (outer braked reel cables) and in 45° cable.
14. Release right hand tape and at chassis RR grasp outer braked reel cable and remove cable pin and discard cable and pin outside work area.
15. At chassis LR grasp outer braked reel cable and remove cable pin and discard cable and pin outside work area.
16. Pull left hand tape. Verify that forward chassis lowers until all wheels contact lunar surface and support vehicle weight and 45° cable is slack.

NOTE: If wheels fail to slide, deployment cable may be pulled to move LRV away from LM.
17. Coil deployment cable and remove cable release pin and chassis delatch fitting pin. Discard cable and deployment hardware outside of work area (right).
18. Pull saddle release cable verify telescoping rods drop free (left).
19. Erect LRV geology pallet mounting post (right).
-(SEE NOTE 1)-
20. Deploy rear fender extension (right and left).
21. Check rear hinge pins engaged (right and left).
22. Check rear steering decouple ring sealed (right).
23. Release inboard hand hold tie down (left).
24. Erect seats (release seat tie down straps) (right and left).
25. Attach seat support leg velcro strap to outboard handhold (right and left).
26. Lower arm rest (right).
27. Pull attitude indicator and C&W pins and discard (left).
28. Pull console "T" handle and rotate 90°; lower console while raising inboard handhold (right and left).
29. Lock console/handhold in place, T handle 90°, velcro T handle strap (right and left).

30. Remove tripod and stow toehold (wheel decouple tool) (right and left).
31. Release velcro tiedowns and erect footrest and velcro in place (right and left).
32. Check front hinge pins engaged (right and left).
33. Check fwd steering seal intact (left).
34. Deploy front fender extension (right and left).
35. Verify battery covers closed (right and left).

NOTE 1: The vehicle may be picked up by both crewmen and turned away from the LM prior to vehicle set-up (i.e., prior to step 19).

TABLE 3.8-3A
POWER-UP (EVA-1)

1. Check hand controller operation.
2. Set parking brake and Verify Reverse INHIBIT Switch - DOWN.
3. BUS A, BUS B, BUS C, BUS D Circuit Breakers - CLOSE.
4. Report BAT 1 and BAT 2 AMP-HR indications.
5. Report BAT 1 and BAT 2 AMPS indications.
6. BATTERY Switch - VOLTS x 1/2.
7. Report BAT 1 and BAT 2 VOLTS indications.
8. BATTERY Switch - AMPS.
9. Report BAT 1 and BAT 2 temp (°F) indications.
10. Report motor temps (LF, RF, LR, RR).
11. Aux CB - CLOSE
12. ± 15 VDC PRIM and SEC Circuit Breakers - CLOSE.
13. STEERING FORWARD AND REAR Circuit Breakers - CLOSE.
14. DRIVE POWER LF, RF, LR, RR Circuit Breakers - CLOSE.
15. PWM SELECT Switch - BOTH. (Verify)
16. DRIVE ENABLE LF and RF Switches - PWM 1.
17. DRIVE ENABLE LR and RR Switches - PWM 2.
18. ± 15 VDC Switch - SEC.
19. STEERING FORWARD Switch - BUS A.
20. STEERING REAR Switch - BUS D.

CAUTION

The hand controller should be in park brake position and the drive enable switches must be set to an active PWM prior to setting any drive power switch to an energized bus. If the drive power switch is turned on and the corresponding drive enable switch is not selected to an active PWM, then full power will be applied to the corresponding drive motor when the hand controller is released from brake position. Should this condition occur, the hand controller should be immediately returned to park brake position.

21. DRIVE POWER LF and RF Switches - BUS A.
22. DRIVE POWER LR AND RR Switches - BUS D.
- *23. Release parking brake and place reverse INHIBIT switch - UP position.
- NOTE: The LRV driver may now back away from LM. LRV driver should request other crewman to direct and monitor any backing operations from an off-vehicle position.
- *24. Stop LRV and set parking brake. Reset Reverse INHIBIT Switch (push switch DOWN).
25. Release parking brake and drive to MESA area for equipment loading.
26. Stop LRV and set brake.
27. \pm 15 VDC SW - OFF

*Omit Steps 23 & 24 if the LRV has been picked up and turn facing away from the LM.

TABLE 3.8-3B
POWER-UP (EVA-2&3)

1. Close LRV covers as required and press on covers to mate velcro.
2. Check hand controller set parking brake and Verify Reverse INHIBIT Switch - DOWN.
3. BUS A, BUS B, BUS C, BUS D Circuit Breakers - CLOSE.
4. NAV POWER CB - CLOSE (Verify) (Do not Torque gyro or move LRV for 1-1/2 min.).
5. AUX CB - CLOSE (Verify).
6. Report BAT 1 and BAT 2 AMP-HR indications.
7. Report BAT 1 and BAT 2 VOLTS indications.
8. Report BAT 1 and BAT 2 AMPS indications.
9. Report BAT 1 and BAT 2 temp (°F) indications.
10. Report drive motor temps (LF, RF, LR, RR).
11. Verify PWM SELECT Switch - BOTH.
12. Verify DRIVE ENABLE LF and RF Switches - PWM 1.
13. Verify DRIVE ENABLE LR and RR Switches - PWM 2.
14. ± 15 VDC Switch - PRIM
15. Release parking brake and Drive to nav alignment site.

TABLE 3.8-4
NAVIGATION ALIGNMENT

1. Drive LRV to area level within $\pm 6^\circ$ of zero for pitch and roll.
2. Deploy Sun Shadow Device (SSD).
3. Park heading down sun within $\pm 3^\circ$ SSD.

Hand controller to parking brake position
Power down (± 15 VDC SW - OFF)

4. Report SSD, pitch and roll readings.
5. Stow SSD and attitude indicator.
6. Move SYSTEM RESET switch momentarily to RESET and return to OFF position.
7. Verify bearing, distance & range indicators zero.
8. Operate GYRO TORQUING switch to LEFT or RIGHT position to correct HEADING indicator as required.
9. Power-up LRV. (± 15 VDC SW - PRIM).

TABLE 3.8-5A
GEOLOGY/SCIENCE SITE NOMINAL

1. Stop LRV and set hand controller in parking brake position; Neutral throttle, reverse inhibit switch - down.
2. Power down as follows:
 - (a) ± 15 VDC Switch - OFF.
3. Report LRV readings in the following ORDER:
 - (a) Heading
 - (b) Bearing
 - (c) Distance
 - (d) Range
 - (e) Amp-Hr Batt 1
 - (f) Amp-Hr Batt 2
 - (g) Temp Batt 1
 - (h) Temp Batt 2
 - (i) Temp LF motor *
 - (j) Temp RF motor *
 - (k) Temp LR motor *
 - (l) Temp RR motor *
4. LCRU mode switch:
 - (a) 3 (TV RMT) (near the LM) or,
 - (b) 2 (FM/TV) (on the traverse)
5. Align HGA via AGC meter and sight.
6. Dust CTV, TCU and LCRU.
7. Perform science requirements.
8. Return to LRV.
9. Stow Gnomon.
10. LCRU mode switch to 1 (PM1/WB).
11. Mount LRV and fasten seat belt.
12. Verify handcontroller in parking brake position and reverse inhibit switch down.
13. ± 15 VDC switch - PRIM.
14. Release parking brake.

*These four readings may be given as "all low" if the temps do not drive the needle off the peg.

TABLE 3.8-5B
GEOLOGY/SCIENCE SITE-NAV UPDATE

1. Drive to area level within $\pm 6^\circ$ of zero for pitch and roll.
2. Deploy SSD and head down sun within $\pm 3^\circ$ SSD.
3. Stop LRV and set hand controller in parking brake position.
Reverse inhibit switch - down.
4. Report SSD, pitch and roll readings.
5. Stow SSD and attitude indicator.
6. Power down as follows:
 - (a) ± 15 VDC Switch - OFF.
7. Report LRV readings in the following ORDER:
 - (a) Heading
 - (b) Bearing
 - (c) Distance
 - (d) Range
 - (e) Amp-Hr Batt 1
 - (f) Amp-Hr Batt 2
 - (g) Temp Batt 1
 - (h) Temp Batt 2
 - (i) Temp LF motor *
 - (j) Temp RF motor *
 - (k) Temp LR motor *
 - (l) Temp RR motor *
8. LCRU mode Switch:
 - (a) 3 (TV RMT) (near the LM) or,
 - (b) 2 (FM/TV) (on the traverse)
9. Align HGA via AGC meter and SIGHT.
10. Dust CTV, TCU and LCRU.
11. Perform stop science requirements.
12. Return to LRV.
13. Stow Gnomon.
14. LCRU mode switch to 1 (PM1/WB).

15. Mount LRV and fasten seat belt.
16. Verify hand controller in parking brake position and reverse inhibit switch down.
17. Report heading and Torque Gyro to Houston update as required.
18. ± 15 VDC switch - PRIM.
19. Release parking brake.

*These temps may be reported as "all low" if temps do not drive needle off the peg.

TABLE 3.8-6A

EVA-1 Closeout

1. Position LRV near MESA, 30 feet from LM - Cross sun, Heading = 012° set parking brake and verify REVERSE INHIBIT switch - DOWN.
2. Report BEARING, DISTANCE, & RANGE.
3. ± 15 VDC switch - OFF.
4. Report LRV readings in following order:
 - (a) Amp-Hr Batt 1
 - (b) Amp-Hr Batt 2
 - (c) Temp Batt 1
 - (d) Temp Batt 2
 - (e) Temp LF motor *
 - (f) Temp RF motor *
 - (g) Temp LR motor *
 - (h) Temp RR motor *
5. LCRU mode sw - 3 (TV RMT).
6. Align Hi-gain Ant.
7. Dust CTV, TCU & LCRU.
8. Prior to LM ingress.
 - (a) LCRU power switch - OFF
 - (b) LCRU thermal blanket - place 35% , blanket over mirrors (i.e., 65% of mirrors showing).
 - (c) LRV battery covers - OPEN & dust LRV mirrors as required. (Dust LCRU mirrors).
 - (d) BUS A, BUS B, BUS C, & bus D cb's - OPEN.

*These temps may be reported as "all low" if temps do not drive needle off the peg.

TABLE 3.8-6B

EVA-2 Closeout

1. Position LRV near MESA, 30 feet from LM - Cross sun, Heading - .017° set parking brake and verify REVERSE INHIBIT switch - DOWN.
2. Report BEARING, DISTANCE and RANGE.
3. ± 15 VDC switch - OFF
4. Report LRV readings in following order:
 - (a) Amp-Hr Batt 1
 - (b) Amp-Hr Batt 2
 - (c) Temp Batt 1
 - (d) Temp Batt 2
 - (e) Temp LF motor*
 - (f) Temp RF motor*
 - (g) Temp LR motor*
 - (h) Temp RR motor*
5. LCRU mode sw - 3 (TV RMT).
6. Align Hi-gain Ant.
7. Dust CTV, TCU, & LCRU.
8. Prior to LM ingress:
 - (a) LCRU power switch - OFF
 - (b) LCRU thermal blanket - 100% open. (verify)
 - (c) LRV covers open and LRV mirrors dusted as required (Dust LCRU mirrors).
 - (d) BUS A, BUS B, BUS C, & BUS D CB's - OPEN.

*These temps may be reported as "ALL LOW" if temps do not drive needle off the peg.

TABLE 3.8-6C

EVA-3 Closeout

1. Position LRV near MESA - Set parking brake and verify REVERSE INHIBIT switch - DOWN.
2. Report BEARING, DISTANCE and RANGE.
3. + 15 VDC switch - OFF.
4. Report LRV readings in following order:
 - (a) Amp-Hr Batt 1
 - (b) Amp-Hr Batt 2
 - (c) Temp Batt 1
 - (d) Temp Batt 2
 - (e) Temp LF motor*
 - (f) Temp RF motor*
 - (g) Temp LR motor*
 - (h) Temp RR motor*
5. LCRU mode switch - 3 (TV RMT).
6. Align Hi-gain Ant.

NOTE: Off-load equipment and then drive to final LRV parking site.
7. LCRU mode switch - 1 (PM1/WB).
8. Ingress LRV verify parking brake, reverse inhibit switch - DOWN.
9. + 15 VDC switch - PRIM.
10. NAV RESET switch to RESET momentarily then to - OFF.
11. Verify BEARING, DISTANCE and RANGE - ZERO.
12. Drive on a HEADING of 102° until the DISTANCE indicator reads 0.1 km; BEARING indicator should read 282°. Turn left to a HEADING OF 225° and stop at outbound tracks.

13. Set parking brake.
14. \pm 15 VDC switch - OFF.
15. NAV POWER CB - OPEN.
16. BUS B and BUS D CB's - OPEN (Note BUS A & BUS C CB's remain closed).
17. AUX power CB - CLOSED (Verify).
18. AUX power by pass sw - ON.
19. LCRU mode sw - 3 (TV RMT).
20. Align Hi-gain Ant.
21. Peel 65% LCRU blanket - and install over control panel.
22. Dust CTV & TCU.
23. LRV battery covers - OPEN.
24. Dust LRV mirrors as required.
25. Dust LCRU mirrors.

*These temps may be reported as "ALL LOW" if temps do not drive needle off the peg.

3.8.3 Performance and Constraints

The purpose of this section is to provide LRV performance, constraints and operating limitations which are of general interest.

Detailed performance and constraint characteristics may be found in the LRV Operations Handbook, Appendix A.

Velocity, steering and braking capabilities and limitations are shown in figures 3.8-5, 3.8-6 and 3.8-7, respectively.

Slopes, positive or negative, significantly effect the LRV characteristic. An observation that can be made from these figures is that increasing slopes-decrease speed, improve steering and dynamic stability, and stopping distance as compared to a 0° slope. Figure 3.8-8 is intended to further refine the data provided in figure 3.8-7 to include the effects of various hand controller braking positions on stopping distance vs slopes for 8 km/hour.

Table 3.8-7 is compendium of LRV operating limits, constraints, and requirements of crew operation. These are generally presented without comment.

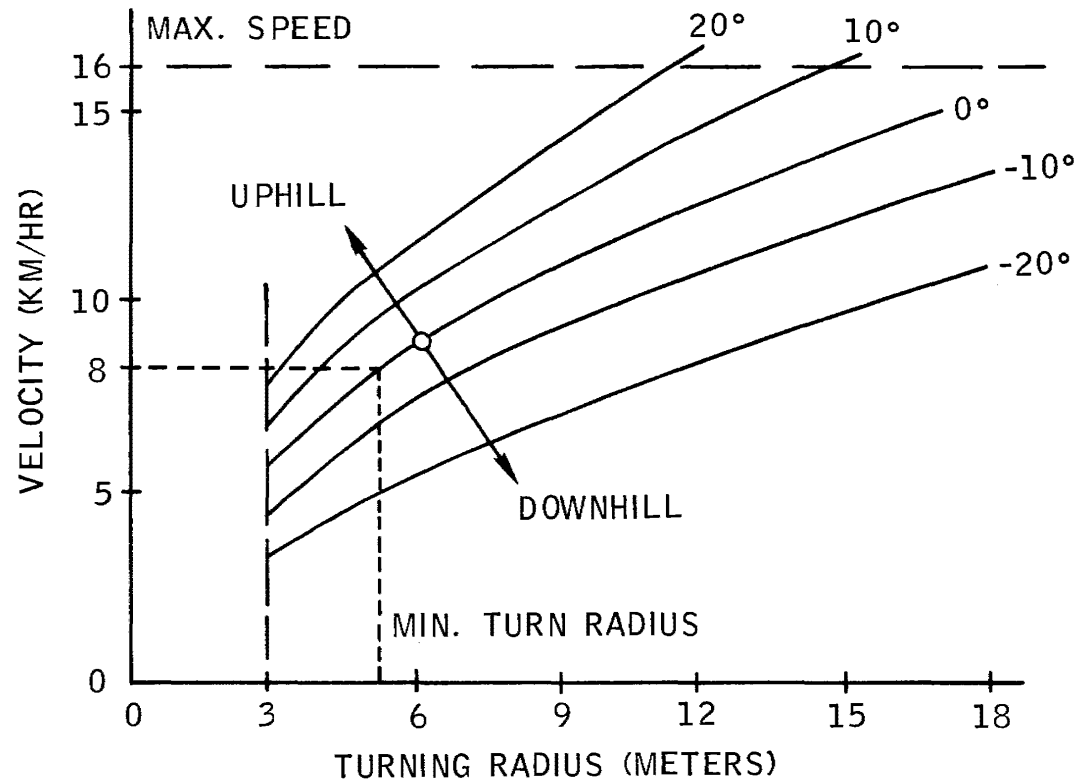
APOLLO 17 LRV VELOCITY CONSTRAINTS (KPH)

| CONSTRAINTS | SLOPE | SMOOTH MARE | ROUGH UPLANDS |
|--|-----------|--------------------|---------------|
| SPEED
CAPABILITY | 0° | 11.53 | 11.12 |
| TORQUE
LIMITED | 5°
10° | 8.64
7.28 | 8.55
7.23 |
| SUSPENSION | | 16 | 10 |
| LIMIT
LOADS | | 12" BUMP AT 14 KPH | |
| CONTROLLABILITY
13° SIDE SLIP ANGLE | | 6m TURN AT 5.5 KPH | |
| | | 12m TURN AT 10 KPH | |

NOTE: MID RANGE P.S.D.
1.5 FACTOR OF SAFETY ON SUSPENSION LOAD

FIGURE 3.8-6

DYNAMIC STABILITY - STEERING STABILITY



COEFFICIENT OF FRICTION: $\mu = 0.6$

EXAMPLE: ON LEVEL GROUND AT 8 KM/HR,
SLIDING BEGINS AT A TURN RADIUS
OF 5.2 METERS.

FIGURE 3.8-7
STOPPING DISTANCE VERSUS INITIAL
VELOCITY FOR VARIOUS SLOPES

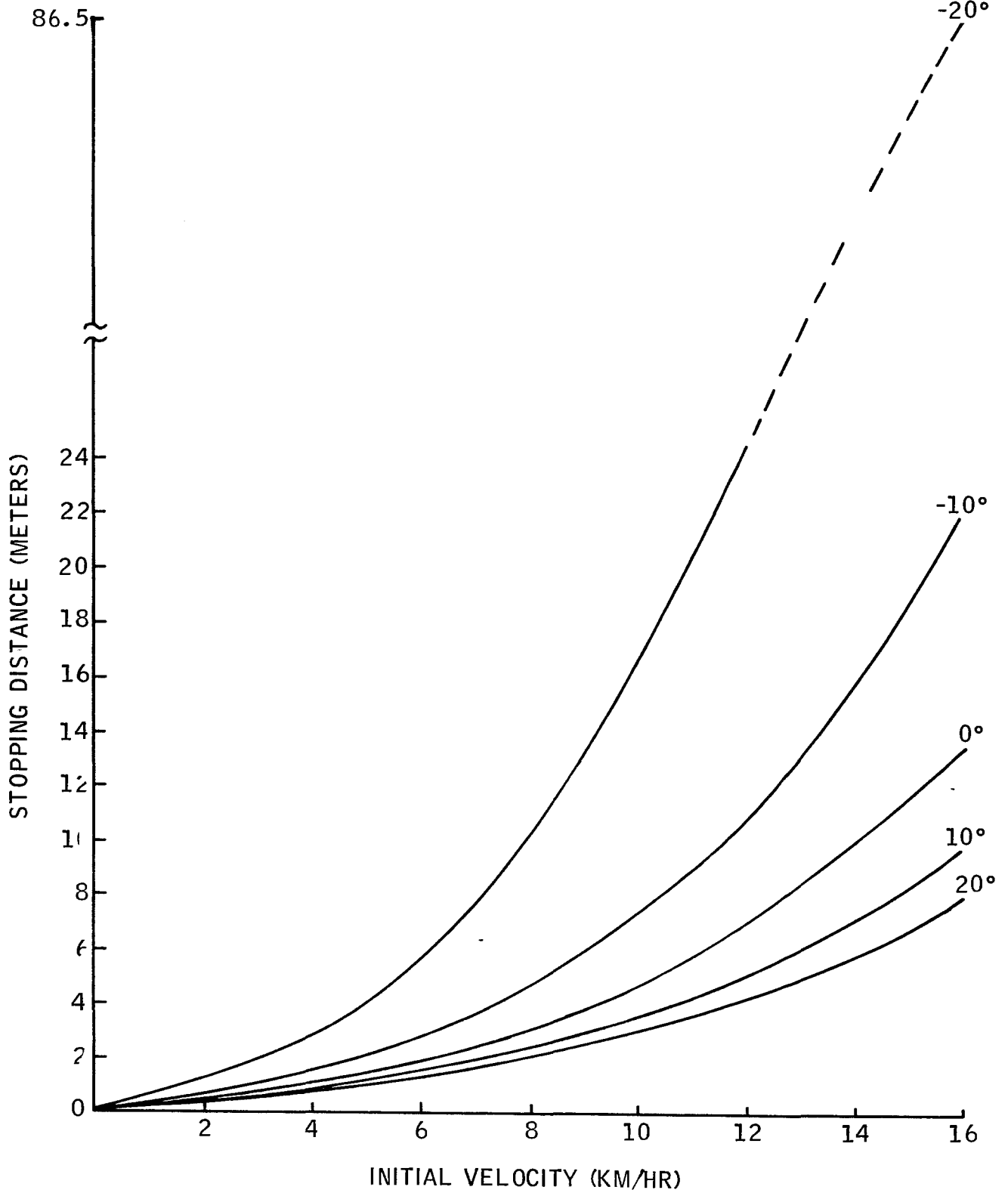


FIGURE 3.8-8

LRV STOPPING DISTANCE VS. HANDCONTROLLER PULL FORCE FOR 8 KM/HR

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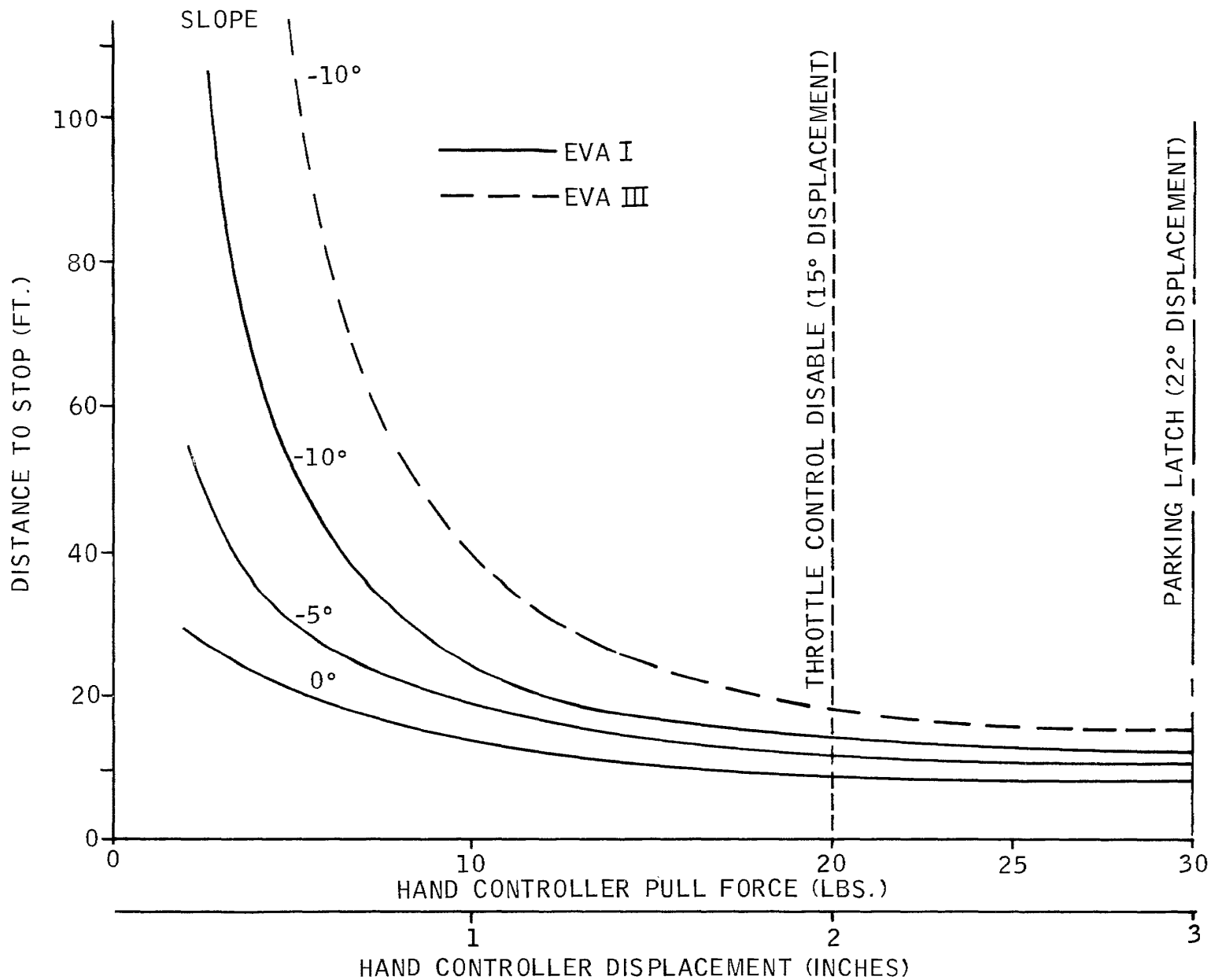


TABLE 3.8-7

LRV Operating Limits, Constraints & Requirements

1. The LRV velocity should not exceed 5 km/hour while traversing to the ALSEP site with the ALSD on the LMP seat.
2. The NAV power circuit breaker must be closed for at least 1-1/2 minutes before torquing the gyro or repositioning the LRV.
3. The navigation system gyro must not be torqued continuously for more than two (2) minutes.

NOTE: Since the heading indicator torques at a rate of 1.5°/sec the heading could be torqued 180° in 2 minutes.

4. To minimize heading errors for navigation system initial alignment and updates, the LRV should be parked such that the pitch and roll is within $\pm 6^\circ$ of zero, (roll being the most critical) and the Sun Shadow Devices (SSD) within $\pm 3^\circ$.
5. The attitude indicator and the SSD should be read to MCC within the tolerances noted below to minimize heading errors:
Pitch within 2-1/2°, Roll within 1° and SSD within 1°. Further the shadow cast on the SSD scale should be read from the center of the rod.
6. Park the LRV cross sun heading North between EVA's in the sun light and at least 30 feet from the LM:
 - (a) END of EVA-1 - HEADING = 012°
 - (b) END of EVA-2 - HEADING = 017°
7. Open the LRV battery covers at the end of each EVA.
8. The LCRU thermal blankets will be open (i.e. % of mirror showing) as per the following schedule:
 - (a) EVA-1, EVA-2, & EVA-3 - 100%
 - (b) Between EVA's 1&2 - 65%
 - (c) Between EVA's 2&3 - 100%
 - (d) Subsequent to EVA-3 - 100%
9. The LRV will be parked at the conclusion of EVA 3 as per the following parameters:
 - (a) Distance 300 ft \pm 25 ft
 - (b) LRV to LM Bearing $\underline{282^\circ}$
 - (c) LRV Heading 225°

10. Caution: While driving, an open-operating corridor shall be maintained on either side of the LRV. For a velocity of 8 km/hour the driving corridor should be 17 feet. Possible condition: guard against steering failures.
11. Caution: The drive enable switches must be set to an active PWM prior to setting any drive power switch to an energized bus. If the drive power switch is turned on and the corresponding drive enable switch is not selected to an active PWM, then full power will be applied to the corresponding drive motor when the hand controller is released from brake position.
12. Warning: The EMU should not brush against the LRV wire wheels at any time. This constraint is to protect the man and the suit not the LRV. Possible condition: Wire breakage on wheel.
13. Warning: The gloved hand is not to be used to decouple or recouple a traction drive unit. The decouple tool is specifically provided for this operation. Possible condition: Overtemp drive unit.
14. Hi-gain antenna sighting/LRV Heading: Coarse alignment (6°) of LCRU Hi-gain antenna may be made at any LRV parking heading by use of the AGC meter. Fine alignment (2.5°) via the optical sight is dependent upon the LRV heading as follows:

| <u>LRV Heading</u> | <u>Optical Sighting</u> |
|--------------------------------------|--|
| 1) 340° - 210° | good - not more than
30 secs of crew time |
| 2) 210° - 280°
and
325° - 340° | marginal - more than 30 secs
of crew time |
| 3) 280° - 325° | not possible |

15. The LRV mirrors (eg Battery 1, Battery 2, SPU and DCE) shall be dusted at the end of each EVA if there is dust visible or if 10% of the mirrored surface is covered with dust clumps.
16. The TV cameras will be manually positioned horizontal, CW and pointing aft by the crew at the end of each science site.
17. The maximum down slope velocity for slopes greater than 12° shall be 4 Km per hour. This may require braking for extend driving times. The brakes should be applied as required to slow the vehicle and then relaxed (i.e., do not drag the brakes nor panic stop the LRV).

3.8.4 Decals and Checklists

The LRV Operations Decal located on the console immediately ahead of the LRV handcontroller is shown in figure 3.8-9. The LRV/LCRU Malfunction Procedures Checklist shown in figure 3.8-10 is included as part of the onboard Flight Data File and is stowed in the LRV mapholder.

| POWER UP | STOP | START |
|--|---|---|
| CHECK HAND CONT'L OPS
BRAKE - ON, REV - DOWN
CB'S - CLOSE (EX NAV)
HOU: ALL DISPLAYS
PWM SELECT - BOTH | BRAKE - ON, REV - DOWN
+15 VDC - OFF
LOW GAIN ANT - ADJUST
HOU: NAV, AMP HRS, TEMPS | LCRU - 1 (PM 1/WB)

LOW GAIN ANT - ADJUST
+15 VDC - PRIM |
| DRIVE ENABLE:
FWD - PWM 1
REAR - PWM 2
+ 15 VDC - SEC | LCRU: NEAR LM-3 (TV RMT)
ON TRAV-2 (FM/TV)
DUST: TV, TCU, LCRU | <div data-bbox="1354 592 1522 625" style="border: 1px solid black; padding: 2px; text-align: center;">EVA 3 FINAL</div> LRV CB - OPEN (EX AUX,
BUS A&C - CLOSED)
AUX CB BYPASS - ON |
| STEERING:
FWD - BUS A
REAR - BUS D | <div data-bbox="1018 665 1228 698" style="border: 1px solid black; padding: 2px; text-align: center;">NAV INITIALIZE</div> *LRV-LEVEL, HEAD DOWN SUN
NAV CB-CLOSE (1-1/2 MIN)
NAV RESET - RESET & OFF
BRNG, DIST, RNG - ZERO | LCRU: POWER - EXT
MODE-3 (TV RMT) |
| DRIVE POWER:
FWD - BUS A
REAR - BUS D | *HOU: SSD,PITCH,ROLL,HDG
*GYRO TORQUE TO HOU UPDATE
*STOW - SSD & VAI | ALIGN HGA
DUST: TV, TV LENS, TCU,
LRV BAT & LCRU |
| | * = <div data-bbox="1029 941 1186 974" style="border: 1px solid black; padding: 2px; text-align: center;">NAV UPDATE</div> | LCRU COVER - 100% OPEN |

Figure 3.8-9 LRV Operations Decal

Figure 3,8-10

LOSS OF VOICE COMM with MSFN (LCRU)

LCRU:

LGA: AGC <2

MODE - FM/TV (HGA) - - - - - LGA or Rcvr 1
 CB LRV AUX - Close
 POWER - alt. pos. (INT/EXT) - - - - - 16.8V Batt Power or DC - DC Converter

AGC >2 & POWER >1

MODE-PM1/NB (LGA) - - - - - Downlink Sig Proc
 MODE-FM/TV (HGA) - - - - - S-B Xmtr or Rcvr 1 Audio

Traverse Mode: Swap Ant Connectors
 MODE-PM2/NB (LGA)

AGC >2 & POWER <1

CB LCRU - CLOSE - - - - - 28V Overload

If CB opens: MODE-FM/TV (HGA)
 CB LCRU - Close - - - - - S-Band Xmtr Short
 CB LRV AUX - Close
 POWER - EXT - - - - - CB/Switch Short

Traverse Mode: Swap Ant Connectors
 MODE-PM2/NB (LGA)

CB LRV AUX - Close
 POWER - alt. pos. (INT/EXT) - - - - - 28V Batt Power or DC - DC Converter

HGA: AGC <2.5

MODE-PM1/WB (LGA) - - - - - HGA or Rcvr 2
 CB LRV AUX - Close
 POWER - alt. pos. (INT/EXT) - - - - - 16.8V Batt Power or DC - DC Converter

AGC >2.5 & POWER >1

MODE - PM2/NB (HGA) - - - - - Downlink Sig Proc

MODE - PM1/WB (LGA) - - - - - S-B Xmtr or Rcvr 2 Audio

AGC >2.5 & POWER <1

CB LCRU - Close - - - - - 28V Overload

If CB Opens: MODE - PM1/WB(LGA)
 CB LCRU - Close - - - - - S-Band Xmtr Short

CB LRV AUX - Close
 POWER - alt. pos. (INT/EXT) - - - - - 28V Batt Power or DC - DC Converter

Figure 3.8-10
LRV MALF. PROCEDURE

LOW ACCELERATION OR LOW SPEED

- | | |
|---|-----------------------------|
| 1. Cycle hand controller (fwd/rev/fwd) - - - - - | Intermittent Contacts |
| 2. Check motor temps. if any motor temp.
unbalanced high (> 50°):
Affected wheel - DRIVE POWER Sw — OFF - - - - - | Motor Short |
| If motor continues to heat:
While driving - decouple wheel - - - - - | Traction Drive Binding |
| 3. Set parking brake
DRIVE ENABLE Sw (4) - PWM 1 - - - - - | PWM 2 Failure |
| | PWM SELECT Sw - PWM 1 |
| 4. Set parking brake
DRIVE ENABLE Sw (4) - PWM 2 - - - - - | PWM 1 Failure |
| | PWM SELECT Sw - PWM 2 |
| 5. DRIVE POWER Sw (4) - alt. pos. - - - - - | Bus A (D) Failure |
| | STEERING Sw (2) - alt. pos. |
| 6. LF,RF DR PWR Sw - BUS A
LR,RR DR PWR Sw - BUS B - - - - - | Batt 2 Failure |
| | REAR STEERING Sw - BUS B |
| 7. LF,RF DR PWR Sw - BUS C
LR,RR DR PWR Sw - BUS D - - - - - | Batt 1 Failure |
| | FWD STEERING Sw - BUS C |
| 8. Restore normal configuration per power-up decal. Monitor motor temps.
frequently. Perform step 2 if motor temp. unbalance occurs. | |

LOSS OF STEERING AND DRIVE FROM ALL WHEELS

- | | |
|--|-------------------|
| 1. +15 VDC Sw - alt. pos. - - - - - | +15 VDC Circuitry |
| 2. Set Parking Brake
DRIVE ENABLE Sw (4) - PWM 2
PWM SELECT Sw - PWM 2
+15 VDC CB (2) - close - - - - - | PWM 1 Shorted |
| 3. Set Parking Brake
DRIVE ENABLE Sw (4) - PWM 1
PWM SELECT Sw - PWM 1
+15 VDC CB (2) - close - - - - - | PWM 2 Shorted |
| 4. DRIVE POWER Sw (4) - OFF (individually)
+15 VDC CB (2) - close - - - - - | DCE Shorted |
| 5. STEERING POWER Sw (2) - OFF (individually)
+15 VDC CB (2) - close - - - - - | Steering Shorted |

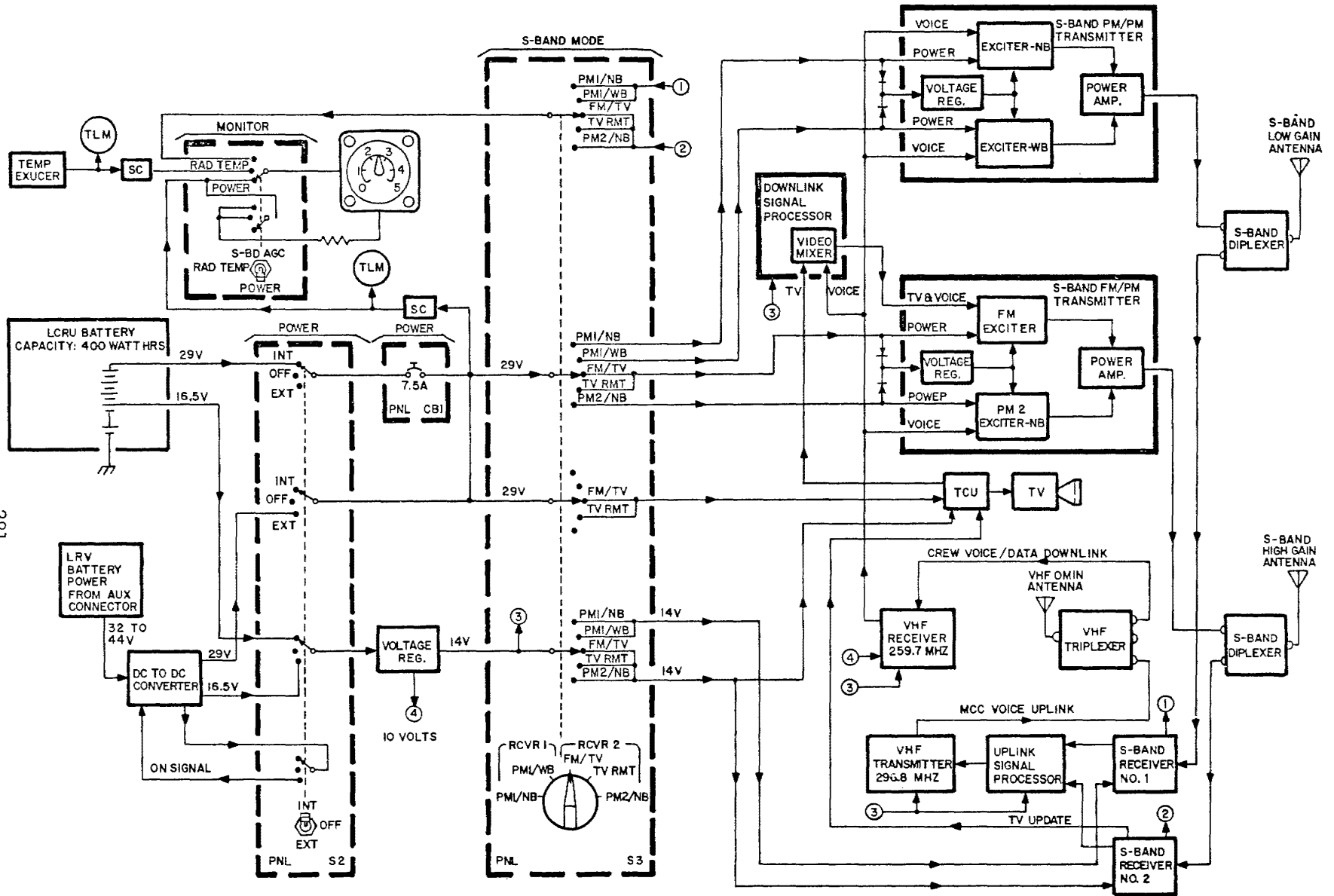


FIGURE 3.8-12 LCRU SYSTEM SCHEMATIC



4.0 APPEND:

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4.0 APPENDIX

4.1 ABBREVIATIONS AND ACRONYMS

ALSD Apollo Lunar Surface Drill
ALSEP Apollo Lunar Surface Experiments Packages
A/S Ascent Stage (of the LM)

BB Boyd Bolt (fasteners on ALSEP)
BRB Big Rock Bag (Sample Return Bag - CFE)
BSLSS Buddy Secondary Life Support System

CDR Commander
CRE Cosmic Ray Experiment
C/S Central Station
CSVC Core Sample Vacuum Container
CTV Color Television (Camera)

D/S Descent Stage (of the LM)
DSBD Documented Sample Bag Dispenser

ECS Environmental Control System
EMU Extravehicular Mobility Unit
EP Explosive Package
ETB Equipment Transfer Bag
EVA Extravehicular Activity

GCTA Ground Controlled Television Assembly

HBW High-speed Black and White Film
HCEX High-speed Color Exterior Film
HEDC Hasselblad Electric Data Camera
HFE Heat Flow Experiment
HGA High-Gain Antenna

ICG Internal Cover Garment
ISS Interim Stowage Shelf

LACE Lunar Atmospheric Composition Experiment (same as LMS, *qui vide*)
LCG Liquid Cooled Garment
LCRU Lunar Communication Relay Unit
LEAM Lunar Ejecta and Meteorites Experiment
LEC Lunar Equipment Conveyor
LGA Low Gain Antenna

LiOH Lithium Hydroxide
 LM Lunar Module
 LMP Lunar Module Pilot,
 LMS Lunar Mass Spectrometer
 LRV Lunar Roving Vehicle
 LSG Lunar Surface Gravimeter
 LSPE Lunar Seismic Profiling Experiment

 Mag Magazine (for 70 mm)
 MCC Mission Control Center
 MESA Modularized Equipment Stowage Assembly
 MSFN Manned Space Flight Network
 NAV Navigation System (on the LRV)
 NFE Neutron Flux Experiment

 OPS Oxygen Purge System

 PLSS Primary Life Support System
 PRA Parabolic Reflector Assembly

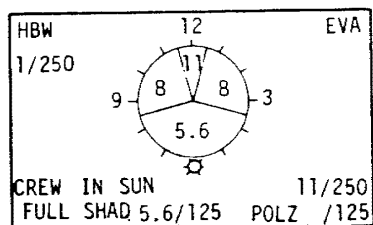
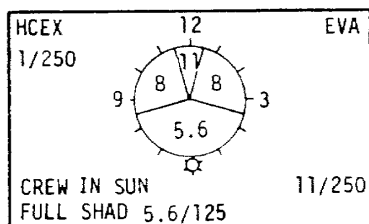
 RCU Remote Control Assembly
 RHSC Right Hand Side Console
 RTG Radio-isotope Thermoelectric Generator

 SCB Sample Collection Bag
 SEP Surface Electrical Properties (Experiment)
 SEQ Scientific Equipment
 SESC Special Environmental Sample Container
 SRC Sample Return Container
 SSD Sun Shadow Device (on RLV)
 SSE Space Support Equipment (system for deploying LRV)
 SRB Sample Return Bag (Same as Big Rock Bag)
 TCU Television Control Unit
 TD Touchdown

 UHT Universal Handling Tool (from ALSEP)

4.2 EQUIPMENT DECALS

Decals are provided as required to supplement the crew cuff check lists and to provide detailed information for tasks that require step-by-step operations. Figure 4.2-1 shows the decals for the lunar surface cameras and the ALSD.



These decals are affixed to the CDR
and LMP Hasselblad Electric Data Cameras.

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1. PUSH SWITCH TO TEST
2. PULL PIN 2 (LEFT SIDE)
3. TURN LOCK 3(BOTTOM RIGHT)CCW
4. TURN LOCK 4(RIGHT SIDE)CCW
PULL UP-PULL LANYARD TO RIGHT
5. REMOVE & INSTALL HANDLE-BLACK
PIN UP
6. REMOVE RACK - LIFT VERTICALLY
7. PUSH LEG FROM CLIP
8. EXTEND & LOCK LEGS (3)
9. PLACE RACK ON SURFACE
10. PULL PIN 5 - SWING COLLAR UP
11. REMOVE DRILL

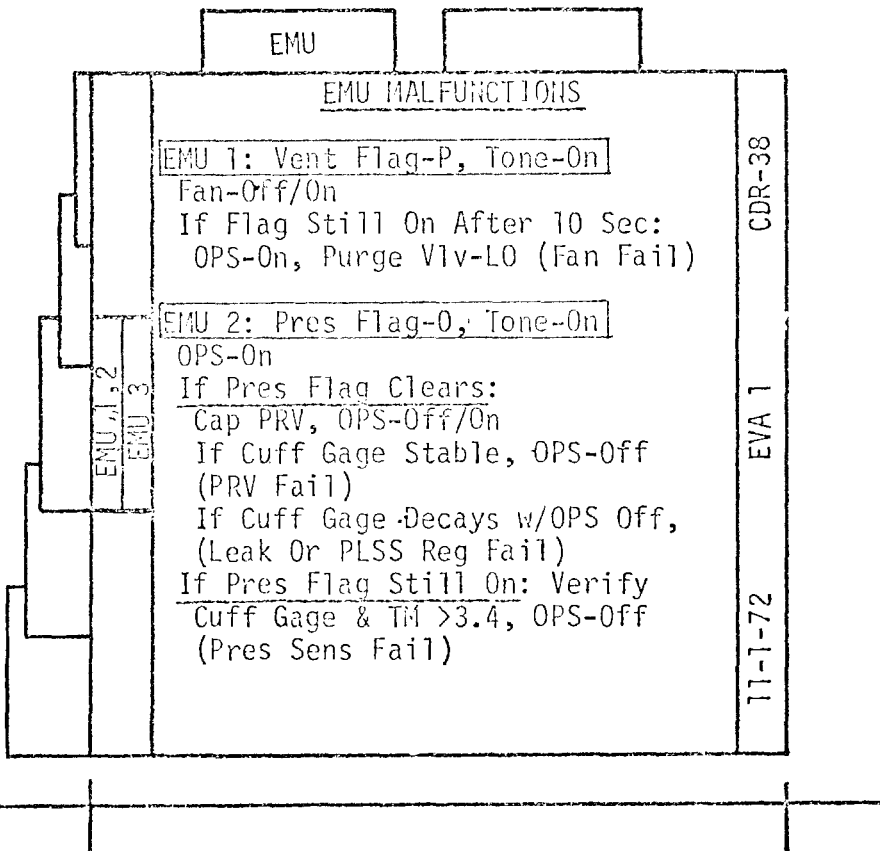
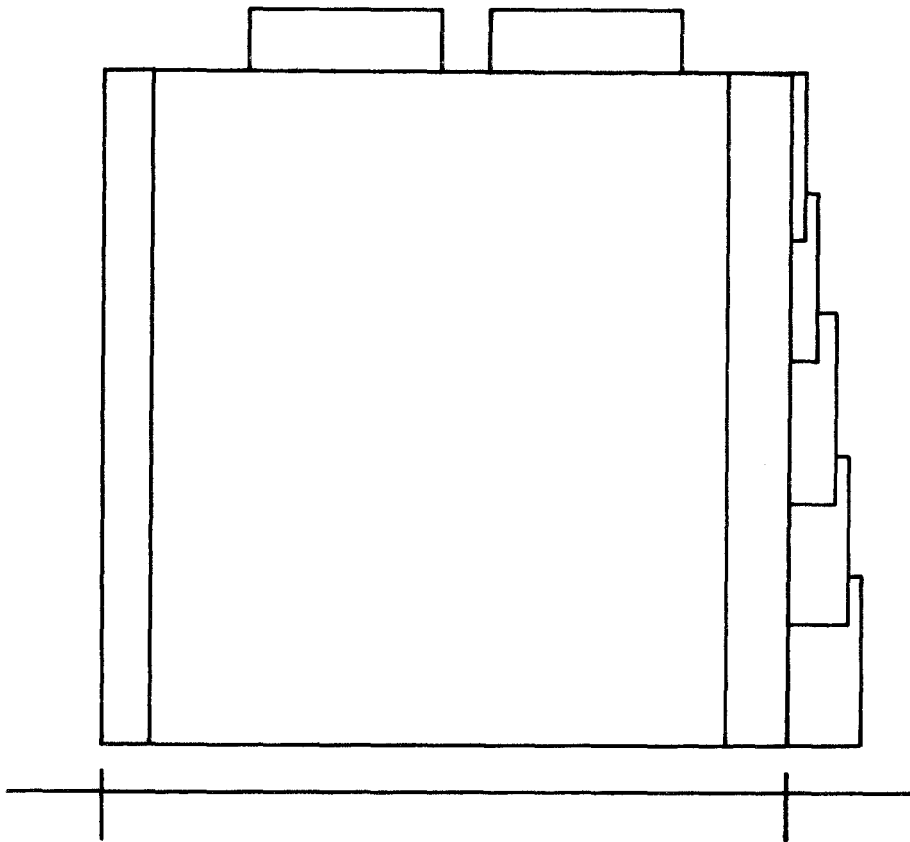
These decals are affixed to the Lunar
Surface Drill thermal cover.

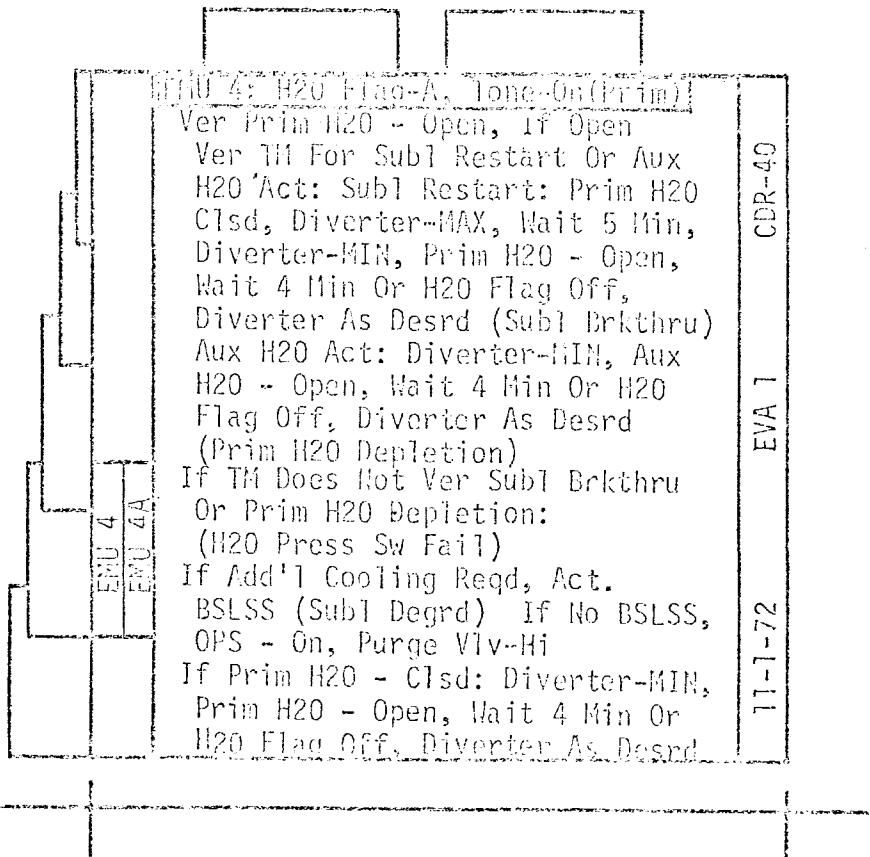
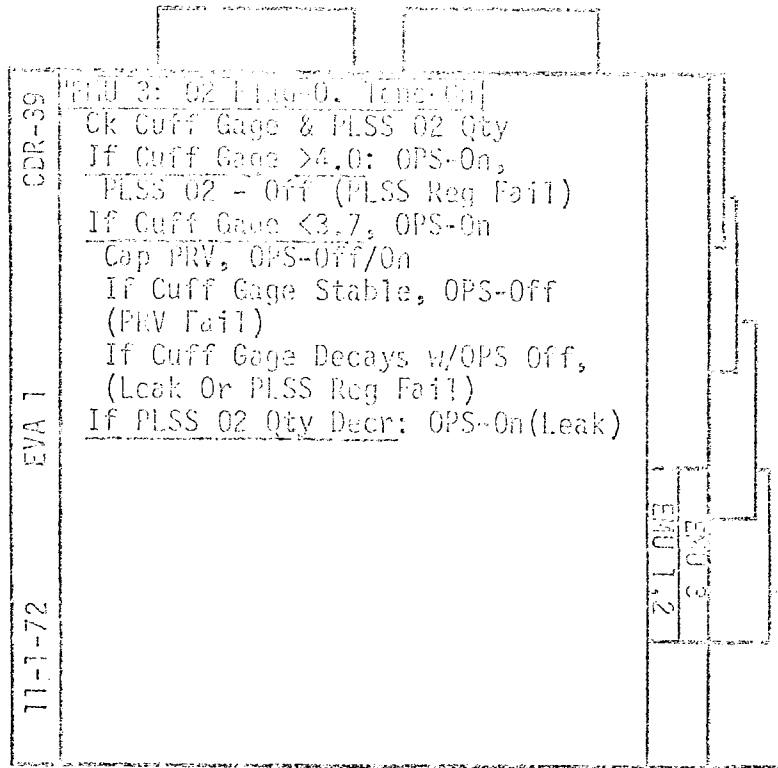
**REMOVE THERMAL COVER
BEFORE DRILLING**

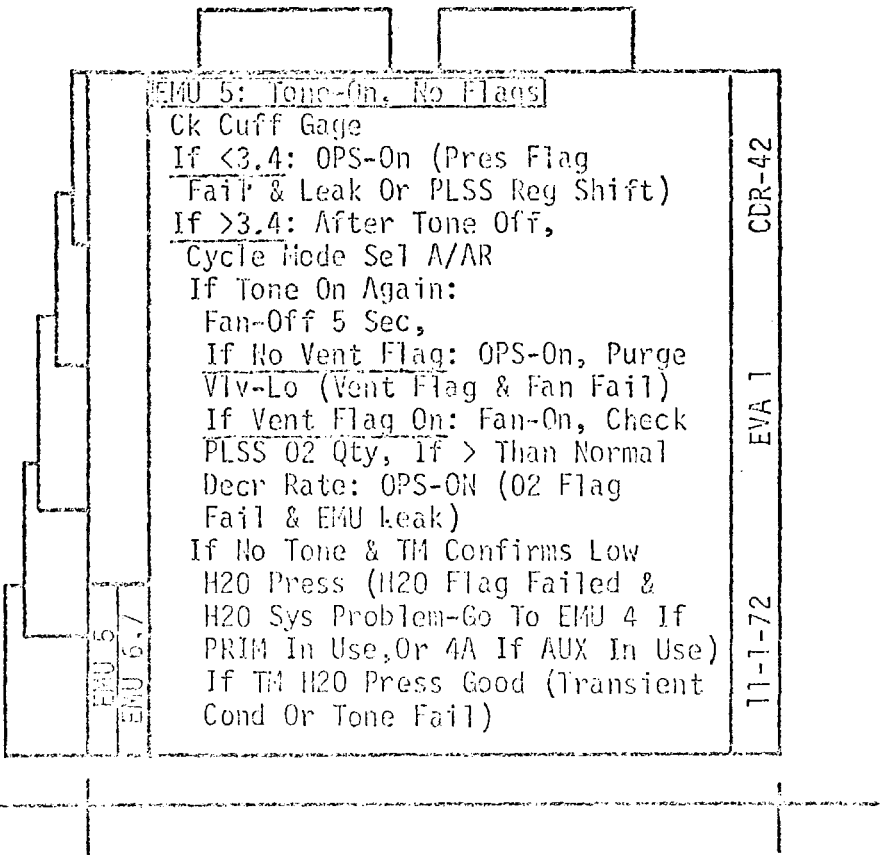
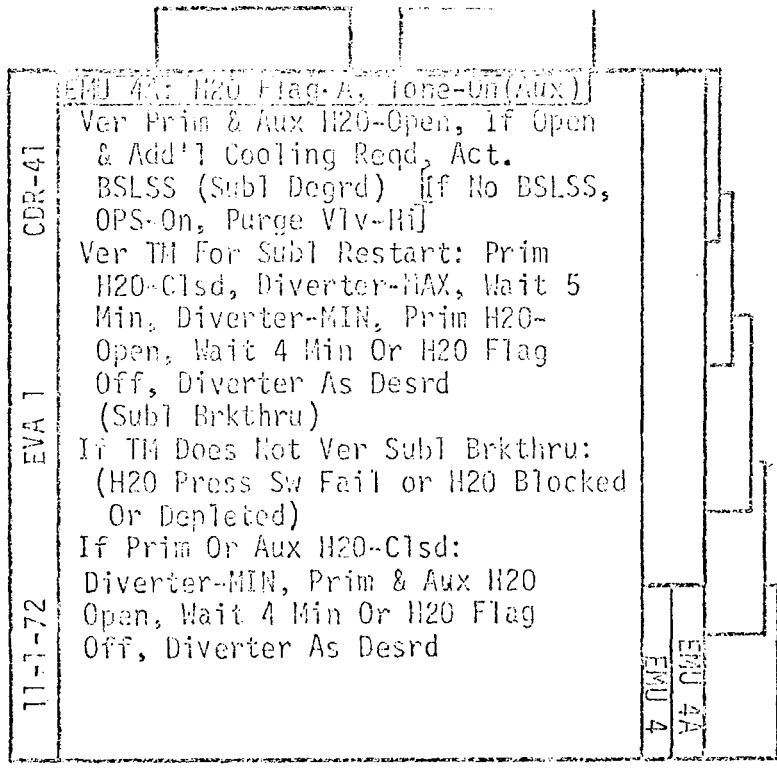
FIGURE 4.2-1 EQUIPMENT DECALS

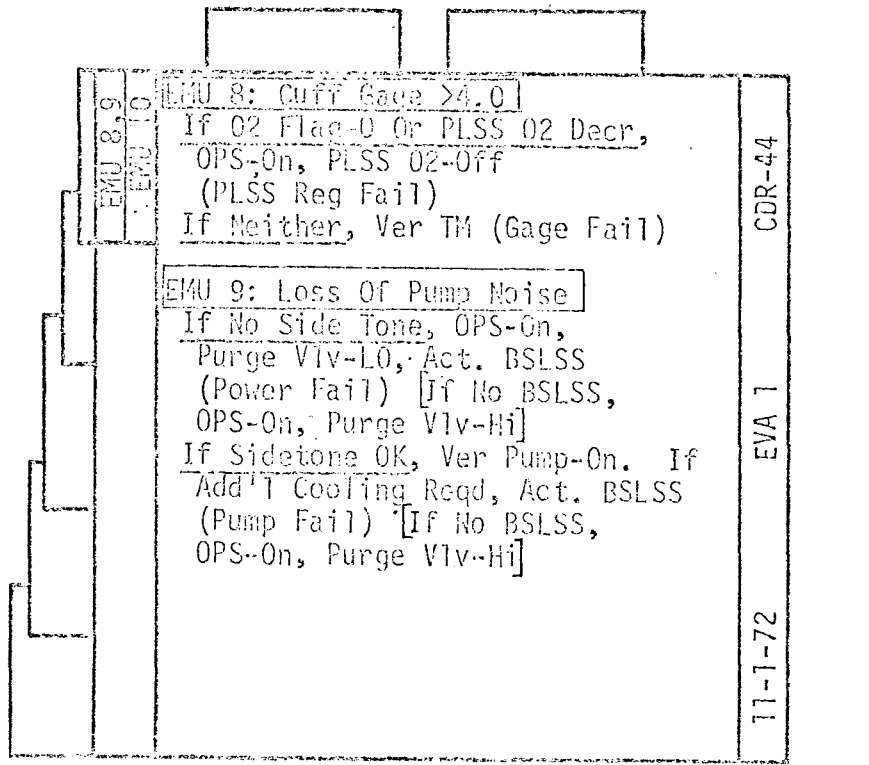
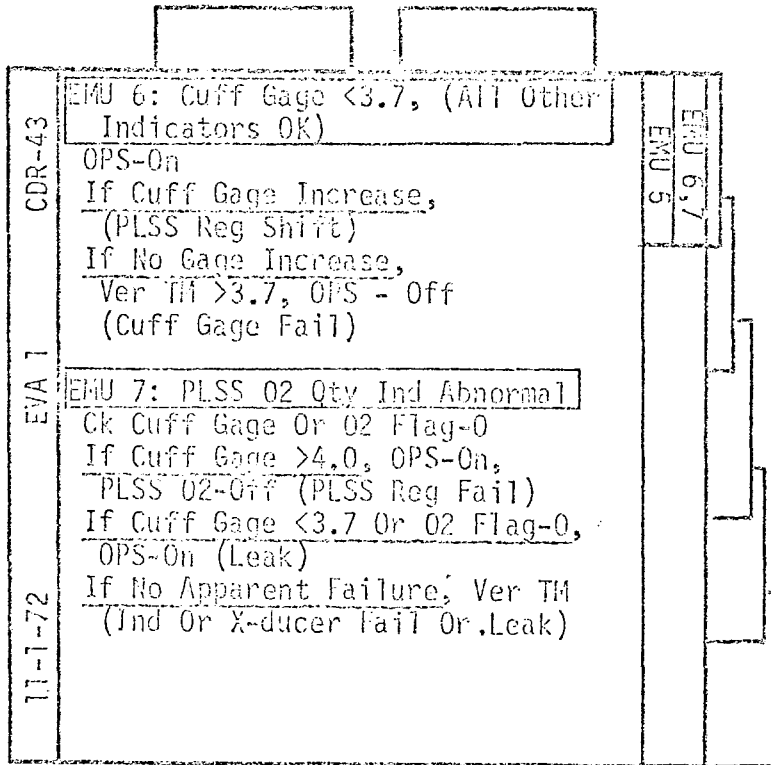
4.3 EMU MALFUNCTION PROCEDURES

The following Cuff Checklist pages contain the malfunction crew procedures for eleven (11) EMU malfunctions, for loss of voice communications through the LCRU on the LRV and BSLSS donning, activation and doffing procedures. These pages are included as the last section in both the CDR and LMP Cuff Checklist.

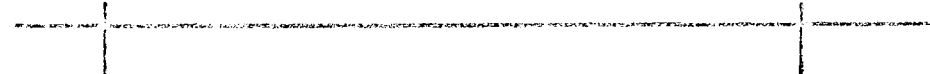






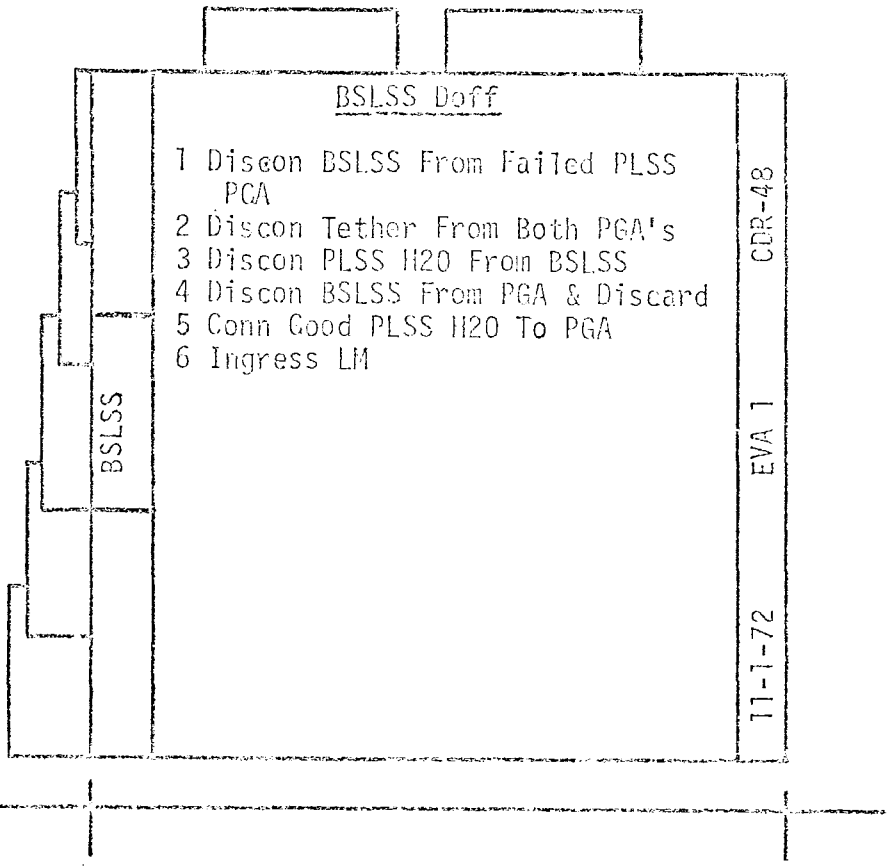
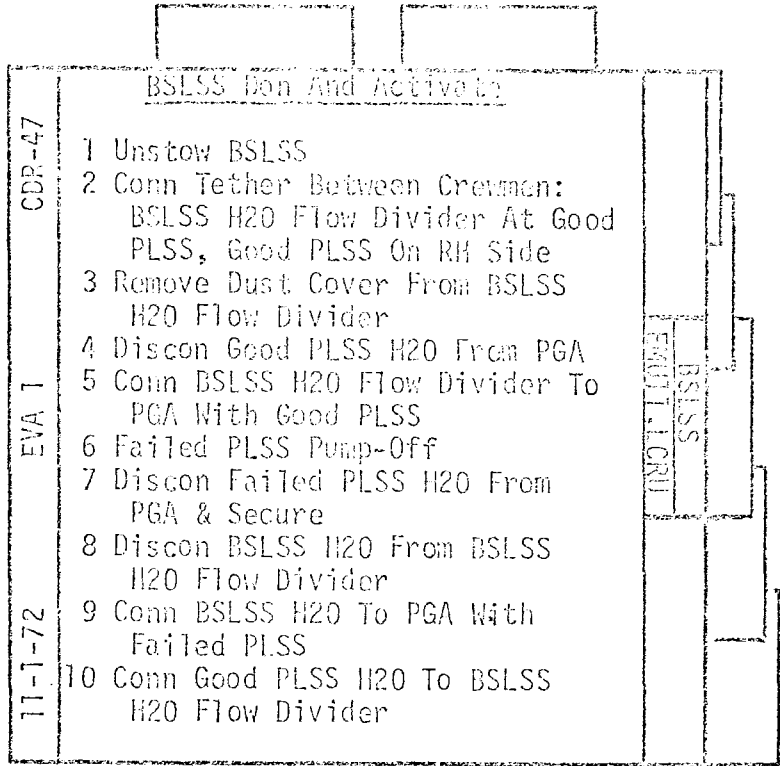


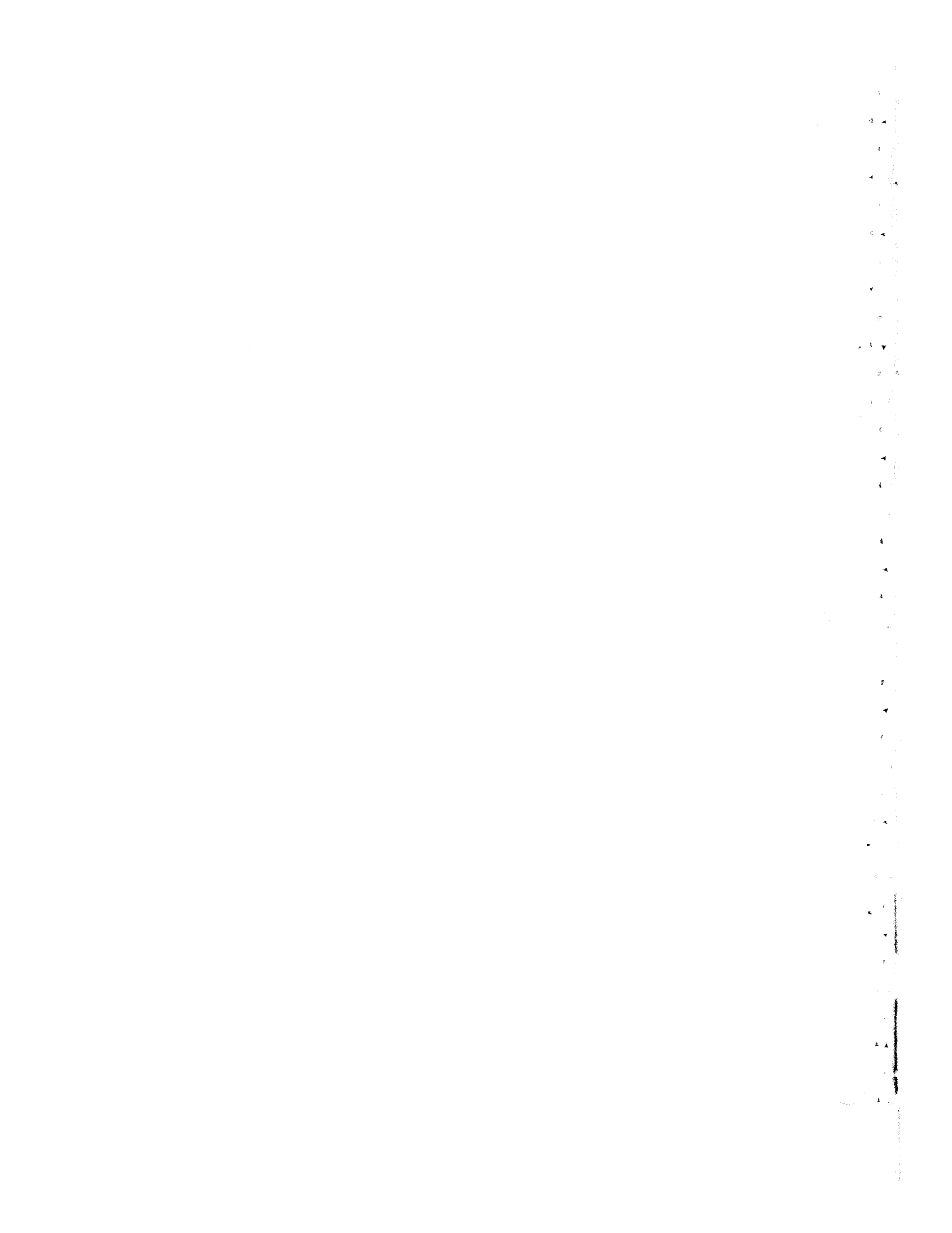
| | | |
|--------|---|-------------------|
| CDR-45 | <p>1010: Cooling Malfunction:</p> <p>Ver Diverter-HIGH & Pump-On</p> <p>Ver Prim & (If On Aux) Aux H2O</p> <p>Open: If Open, Act. Gas Trap</p> <p>5 Sec, Wait 3 Min, If Add'l</p> <p>Cooling Req'd, Act. BSLSS (Flow</p> <p>Restr, Subl Or Pump Degr'd, Or</p> <p>Heat Leak) [If No BSLSS,</p> <p>GPS-On, Purge Vlv-Hi]</p> | 6.8.01H
01.01E |
| | <p>EVA 1</p> <p>Ver TM For Aux H2O Act: Diverter</p> <p>MIN, Aux H2O-Open, Wait 4 Min,</p> <p>Diverter As Desrd (Prim H2O</p> <p>Depletion)</p> | |
| | <p>11-1-72</p> <p>If Prim Or (If On Aux) Aux H2O</p> <p>Clsd: Diverter-HIGH, Prim & (If</p> <p>On Aux) Aux H2O-Open, Wait 4</p> <p>Min, Diverter As Desrd</p> <p>(H2O Flag Fail)</p> | |



| | | |
|---------|---|--------|
| CDR-46 | <p>1011: Loss Of Voice Comm (LII)</p> <p>Ck VoT Controls (Wheel A-Hou,</p> <p>Blade-B-EVA)</p> <p>Cycle PTT Sw-MAIN & HIGH</p> <p>CDR Mode Sel To B, LMP To A</p> <p>(Hand Signals)</p> <p>If No Comm, CDR To A, LMP To B</p> | CDR-46 |
| | <p>LCRU 1: Loss Of Voice Comm (LCRU)</p> <p>If no comm between crewmen,</p> <p>perform LRU 11.</p> <p>If no comm with STDII:</p> <p>Ck Ver Control (Wheel-A-Hou)</p> <p>Repoint LCRU antenna</p> <p>Select alternate mode--</p> <p>Mode - PM1/WB or FM/TV</p> <p>Point selected antenna</p> <p>LCRU cb - close</p> <p>LRV AUX cb - close</p> <p>LCRU POWER Sw - alt pos (INT/EXT)</p> | |
| EVA 1 | | |
| 11-1-72 | | |







4.4 TRAVERSE PLANNING PARAMETERS

Note: Section 4.4 has been prepared in its entirety by the Operations Analysis Branch, Systems Engineering Division, Apollo Spacecraft Program Office

EVA TRAVERSE PLANNING PARAMETERS

The purpose of this appendix is to provide a summary reference source for primary data used in lunar surface traverse planning. These data are those that have been generally concurred with for use in current lunar surface operations planning and study. Officially approved data for each mission ultimately appear in the Apollo Spacecraft Operational Data Books, Flight Mission Rules and the Flight Plan. Prior to that time, these EVA traverse planning parameters will be updated periodically through the Lunar Surface Operations Planning Meetings.

Primary lunar surface traverse planning data presented herein are categorized for each reference with the organization and person responsible for the data indicated at the bottom of each page, along with the official data source reference.

APOLLO 17 PLANNING PARAMETERS

1. Crewmen Parameters

1.1 Metabolic Rates¹, \dot{Q}_M

- a. Riding on LRV 550 Btu/Hr
- b. Working
 - (1) Overhead and ALSEP Activities 1050 Btu/Hr
 - (2) Geological Station Activities 950 Btu/Hr
- c. Contingency Walking

| Duration | Walking Speed ²
(Average) | Metabolic Rate
Including 20-Percent
Uncertainty |
|-----------------------------------|---|---|
| | Over Uncorrected
Map Distance | |
| Up to 1 Hour
Total Return Time | 3.6 Km/Hr | 1560 Btu/Hr |
| Return Requiring
Over 1 Hour | 2.7 Km/Hr | 1290 Btu/Hr |

d. Normal Walking (Average)

2.5 Km/Hr, Uncorrected Map Distance, 1000 Btu/Hr

1.2 Respiratory Quotient 0.90

1.3 Time in Pressurized PGA³

Uninterrupted time in a pressurized PGA should be limited to 7 hours of nominal EVA.

Responsible Organization: Medical Operations Division/DD

Point of Contact: J. F. Zieglschmid, MD; Ext. 42
 R. G. Zedekar/Cg3; Ext. 3091

Official Data Sources: ¹SODB, Vol. II, LM Data Book, Part 1, Table 4.3-2, page 4.3-13

³SODB, Vol. IV, EMU Data Book, Operational Constraints and Limitations, page 3.2-3, EPG-11

APOLLO 17 PLANNING PARAMETERS

2. PLSS Parameters

2.1 PLSS Battery

| | | |
|-----------------------|--------------------------------|-----------------|
| a. Battery Capability | | 25.4 Amp-Hours |
| b. Battery Voltage | | 16.8 Volts dc |
| c. TM Usable | | 20.92 Amp-Hours |
| (1) Pre-EVA Checkout | 1.2 Amp-Hours | |
| (2) Post-EVA Reserve | 1.43 Amp-Hours | |
| (3) TM Inaccuracy | 1.85 Amp-Hours
at 7.6 Hours | |
| d. Usage Rate | | 2.7 Amps |

Responsible Organization: Crew Systems Division/EC

Point of Contact: J. L. Gibson; Ext. 2352

Official Data Sources: SODB, Vol. IV, EMU Data Book, EMU Consumables
Tables 4.0-3A and 4.0-3B

APOLLO 17 PLANNING PARAMETERS

2. PLSS Parameters (Continued)

2.2 Primary Oxygen Supply

| | | |
|--|--|---|
| a. POS Bottle Volume | 378 Cu In. | |
| b. Full Charge | <u>(EVA 1)</u> | <u>(EVA 2 or 3)</u> |
| | 1432 Psia @ 70°F
1.860 Lb
(Z = 0.9485) | 1395 Psia @ 70°F
1.810 Lb
(Z = 0.950) |
| c. EMU Pressurization | 70 Psia
0.091 Lb | |
| d. LM Repress | 25 Psia
0.031 Lb | |
| e. TM Inaccuracy | 48 Psia
0.060 Lb | |
| f. Minimum Regulation Pressure | 145 Psia
0.180 Lb | |
| g. O ₂ Reserve at Normal Working Rate | 76 Psia
0.095 Lb | |
| h. Total Usable O ₂ | 1.403 Lb | 1.353 Lb |

2.3 EMU O₂ Leak Rates

| | |
|----------|-------------|
| a. EVA 1 | 0.020 Lb/Hr |
| b. EVA 2 | 0.028 Lb/Hr |
| c. EVA 3 | 0.035 Lb/Hr |

Responsible Organization: Crew Systems Division/EC

Point of Contact: J. L. Gibson; Ext. 2352

Official Data Sources: SODB, Vol. IV, EMU Data Book, EMU Consumables Tables 4.0-3A and 4.0-3B, and Mission Appendix

APOLLO 17 PLANNING PARAMETERS

2. PLSS Consumables (Continued)

2.4 O₂ Usage Rate $1.627 \times 10^{-4} (\dot{Q}_M) + \text{EMU Leak Rate}$

2.5 PLSS Feedwater

| | | |
|---|----------------|---|
| a. Feedwater Loading | | 11.90 Lb |
| (1) Main Tank | 8.50 Lb | |
| (2) Aux. Tank | 3.40 Lb | |
| b. Transport Loop Makeup (EVA 1 only if PLSS launched with feedwater) | | 0.13 Lb |
| c. Non-Expellable | | 0.09 Lb |
| d. Slave Water | | 0.63 Lb |
| e. Usable Leftover Slave Water (EVA 2 or 3) | | 0.30 Lb |
| f. Reserve at Normal Working Rate | | Provided by slave water and thermal inertia |
| g. Heat of Sublimation | | 1038 Btu/Lb |
| h. Usable Feedwater | <u>(EVA 1)</u> | <u>(EVA 2 or 3)</u> |
| | 10.86 Lb | 11.29 Lb |
| | 11,273 Btu | 11,719 Btu |

Responsible Organization: Crew Systems Division/EC

Point of Contact: J. L. Gibson; Ext. 2352

Official Data Sources: SODB, Vol. IV, EMU Data Book, EMU Consumables Tables 4.0-3A and 4.0-3B, and Mission Appendix

APOLLO 17 PLANNING PARAMETERS

2. PLSS Parameters (Continued)

2.6 EMU Heat Leak, \dot{Q}_{h1} ¹

| EVA | I | II | III |
|-------------|--------|-----------|-----------|
| T=0 Launch | 0 RLP* | +135 RLP* | +200 RLP* |
| T+24 Launch | TBD | TBD | TBD |

*RLP - Rough Lunar Plain

2.7 Feedwater Usage Rate²

a. Cooling Rate, $\dot{Q}_T = 1.26 \dot{Q}_M + 153 \text{ Btu/Hr} + \dot{Q}_{h1}$

b. Feedwater, $\dot{W}_{H_2O} = \frac{\dot{Q}_T}{1038 \text{ Btu/Lb } H_2O}$

2.8 PLSS LiOH Capability³

a. Nominal Loading

(1) Total CO₂ Absorption, No Thermal Soak 10,900 Btu

(2) Total CO₂ Absorption, Thermal Soak 8,400 Btu

b. Usage Rate

Crew Metabolic Rate

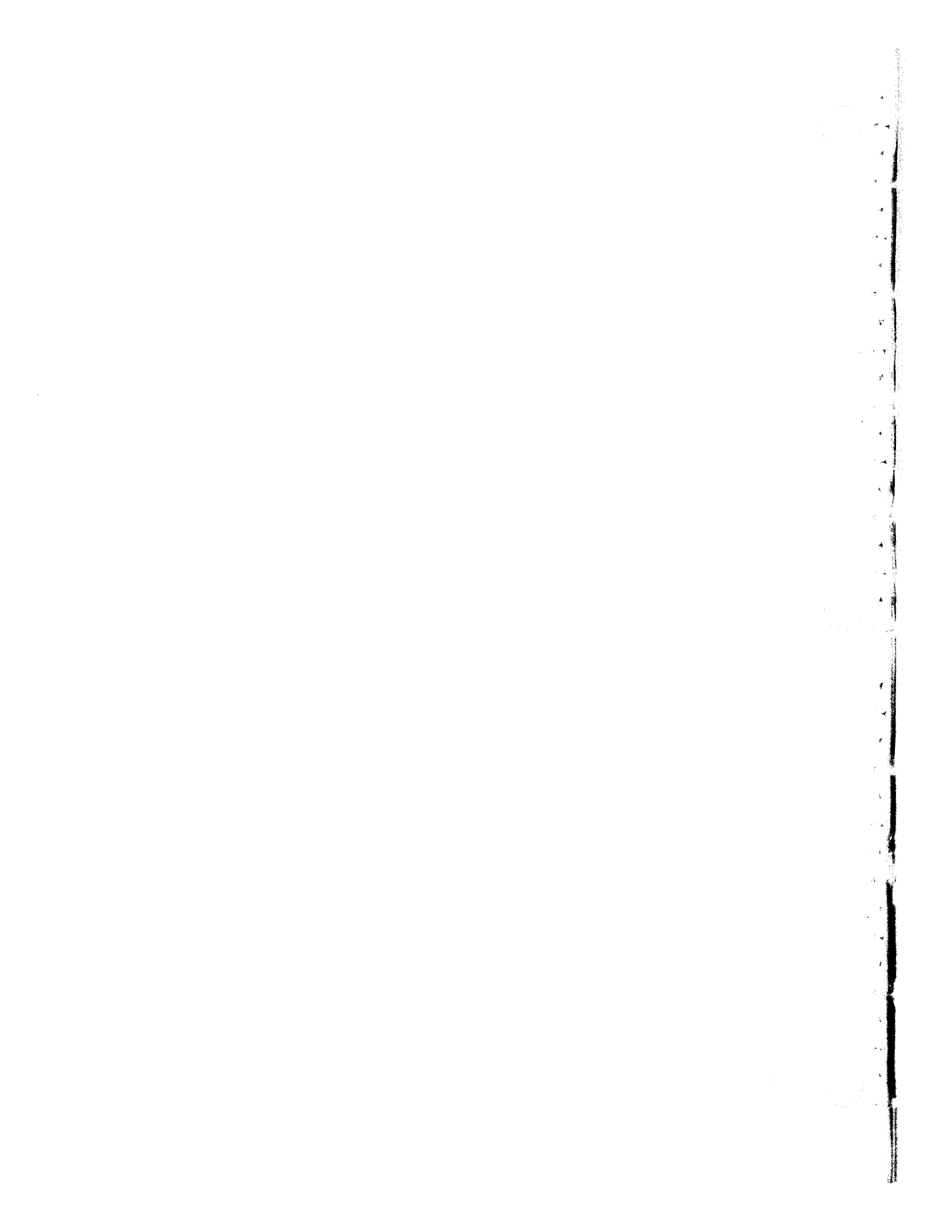
Responsible Organization: Crew Systems Division/EC

Point of Contact: J. L. Gibson, Ext. 2352

Official Data Sources: ¹SODB, Vol. IV, EMU Data Book, EMU Heat Leaks, Figure 4.0-1 and Mission Appendix

²SODB, Vol. IV, EMU Data Book, page 4.5-66, Figure 4.5-44

³SODB, Vol. IV, EMU Data Book, EMU Consumables, Tables 4.0-3A and 4.0-3B



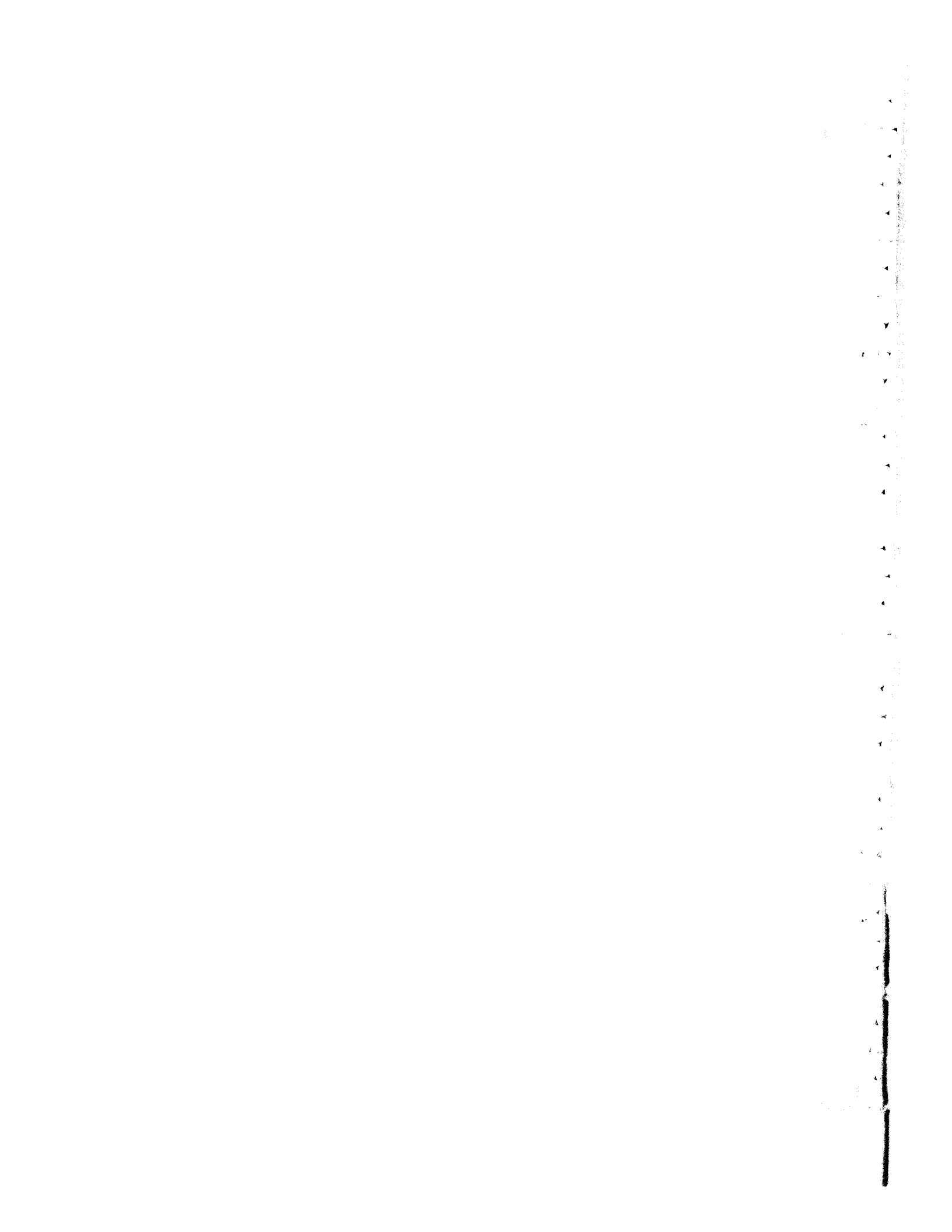
4.5 REFERENCES AND BACKGROUND MATERIAL

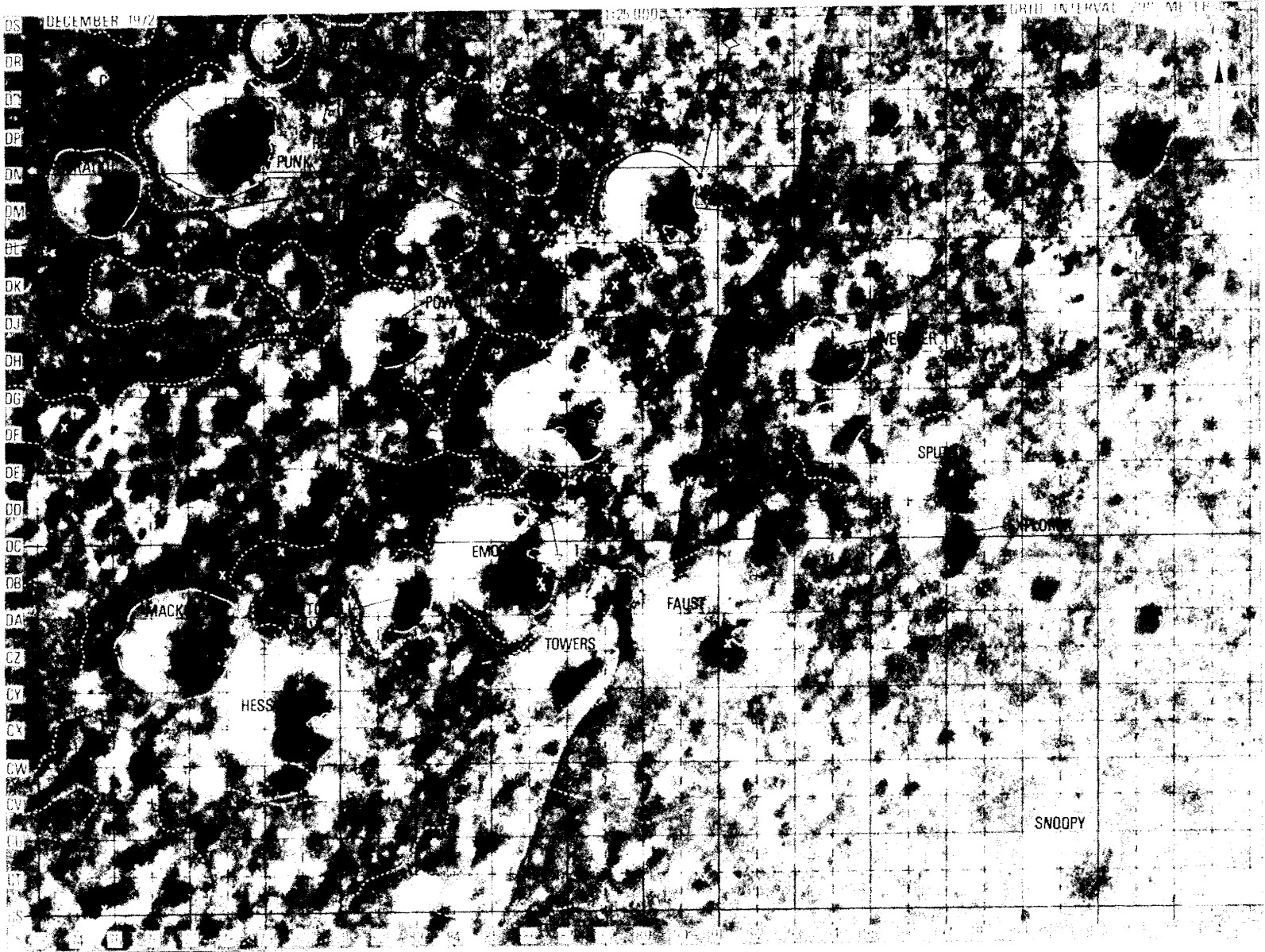
1. Mission Science Planning Document (Apollo Mission J-3, Apollo 17: Science and Applications Directorate, NASA-MSC dtd July 16, 1972
2. Mission Requirements, J-3 Type Mission, Lunar Landing: Apollo Spacecraft Program Office, NASA-MSC dtd March 16, 1972 (Basic) Revision A, dtd July 5, 1972 (MSC-05180)
3. ALSEP Data Book: Bendix Aerospace Corp. BSR3335 (MSC No. ALSEP MP-07) dtd 7-17-72
4. ALSEP Systems Handbook (Apollo 17, ALSEP 5, Array E) : Flight Control Division, NASA-MSC dtd Aug 8, 1972
5. APOLLO 17 Traverse Planning Data (2nd Edition): Apollo Spacecraft Program Office, NASA-MSC dtd Sept 1, 1972
6. Apollo Operations Handbook-Extravehicular Mobility Unit: Vol.II Operational Procedures MSC-01372-2; Vol.IV, Rev. 2, SNA-8-d-027 (IV) REV. Crew Systems Division, NASA-MSC

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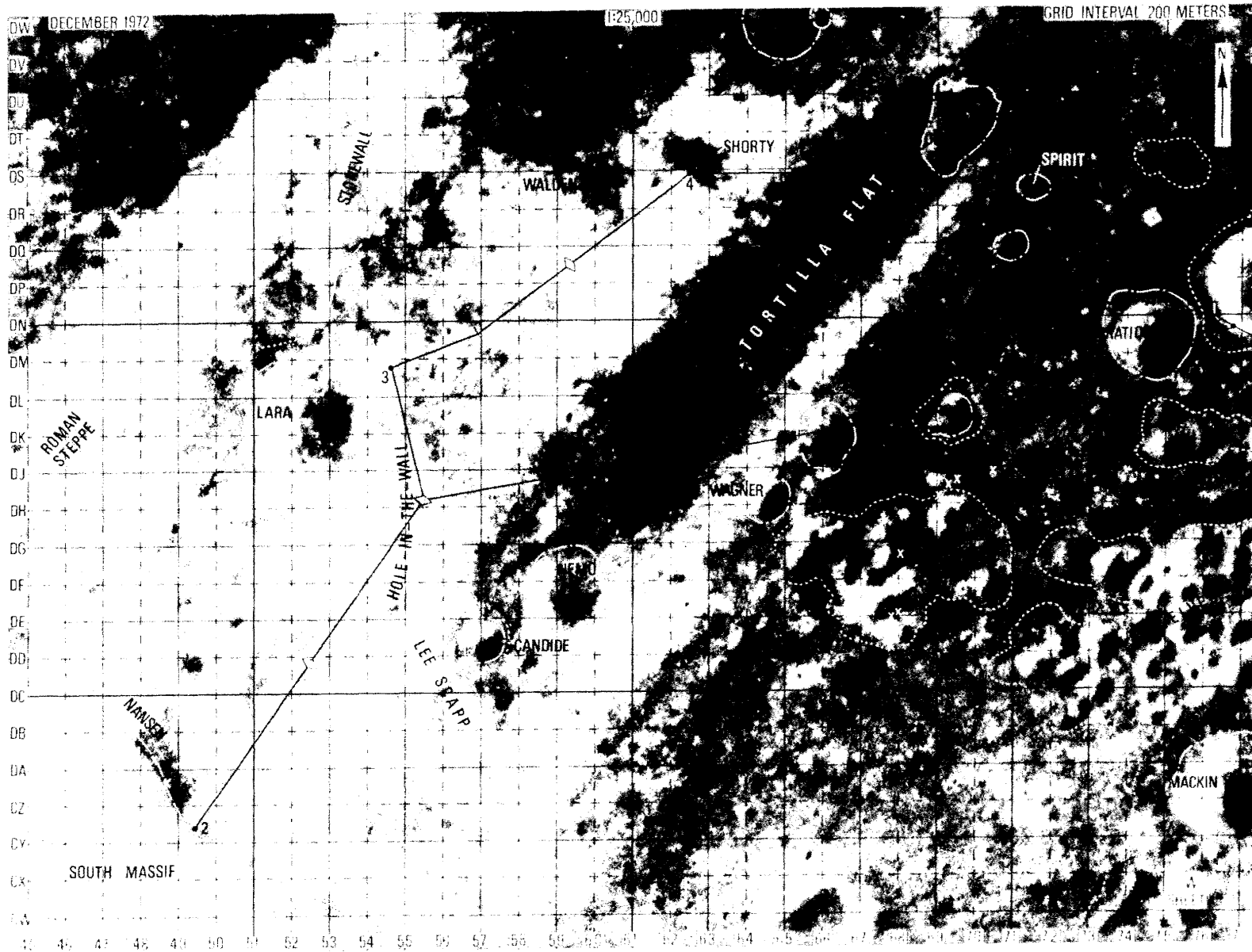
SPECIAL SUPPLEMENT

The following maps are reproductions of the Flight Data File maps that the Apollo 17 crew will transfer to the surface and use during their sorties at Taurus-Littrow. Each map is two-sided: one side shows the traverse as an overlay on a photo-map of the part of the site; the other side is a topographic map with navigational information. Both sides give place names which, for the most part, are informal designations given by the crew to aid them in describing their findings and location during lunar surface operations.

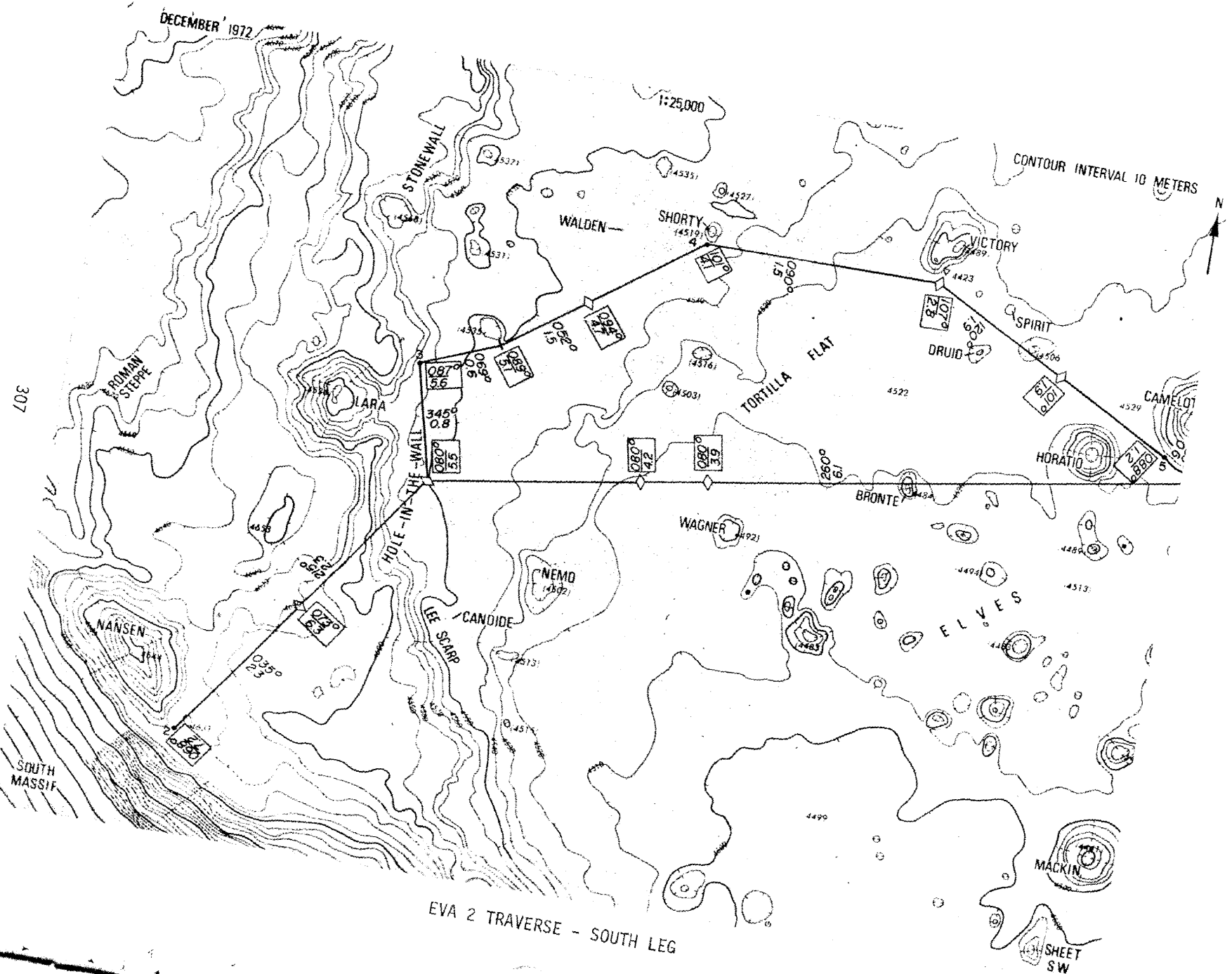




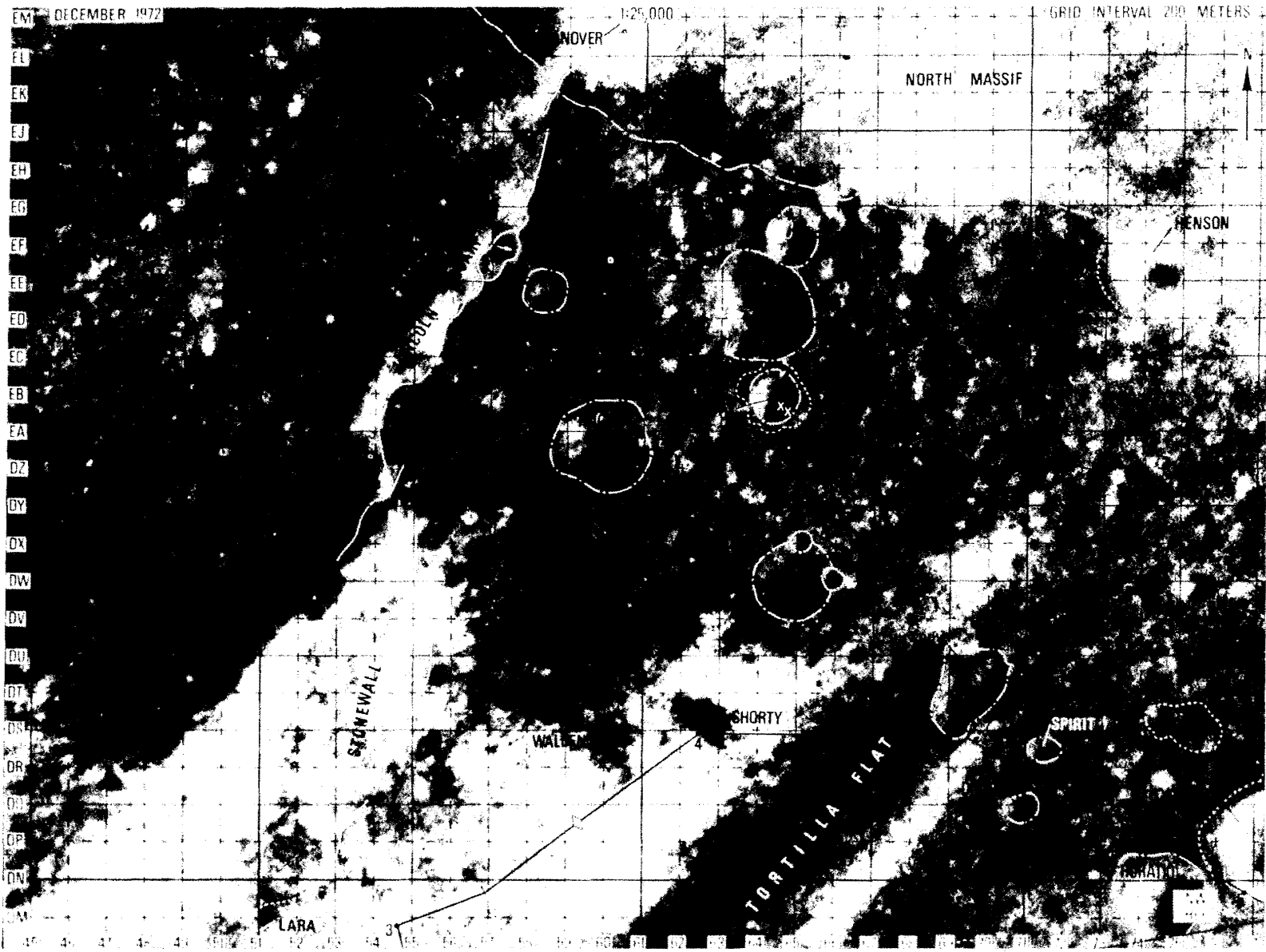
EVA 1 TRAVERSE TO STATION 1



EVA 2 TRAVERSE - SOUTH LEG



EVA 2 TRAVERSE - SOUTH LEG

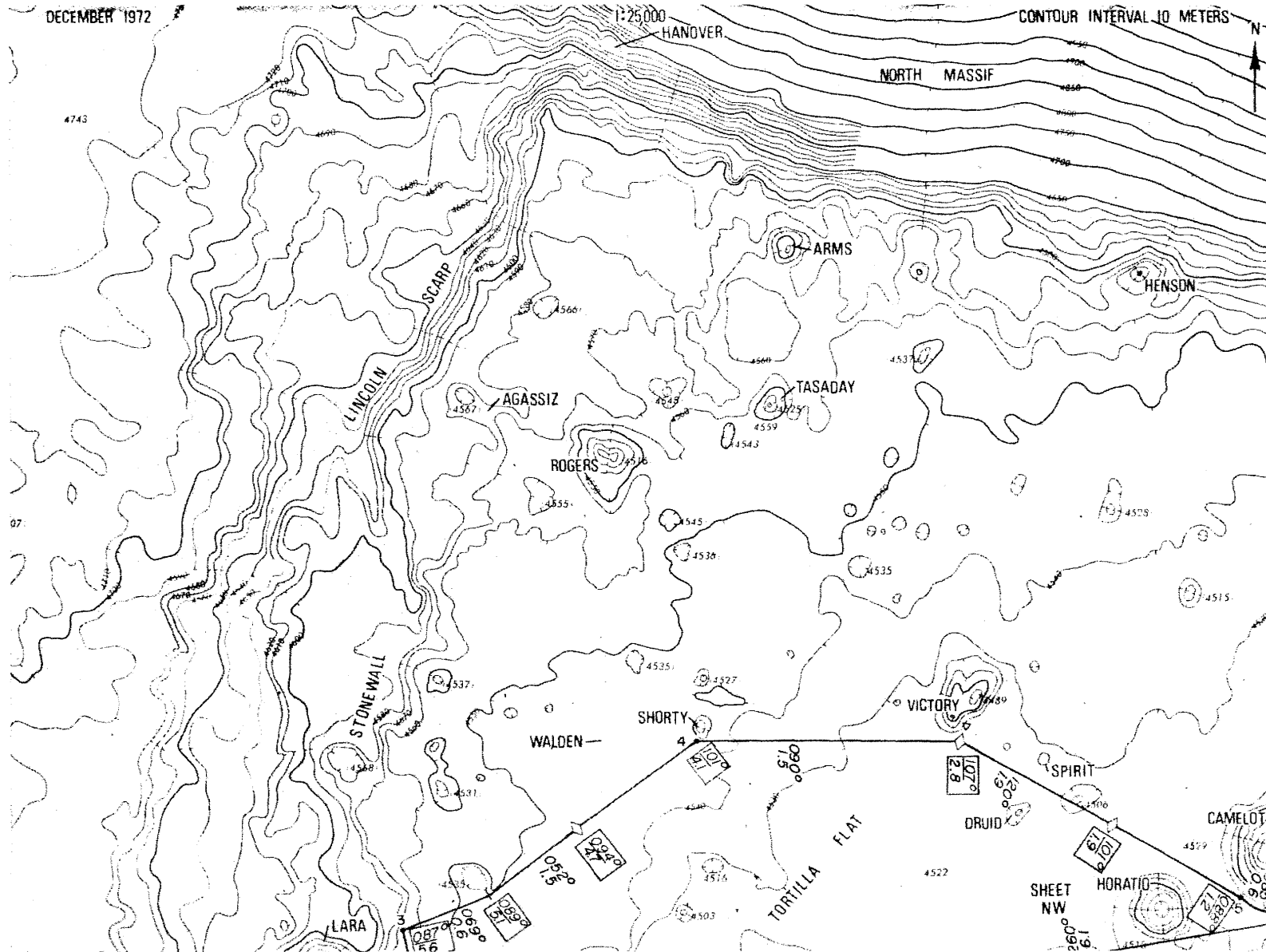


EVA 2 TRAVERSE - NORTH LEG

DECEMBER 1972

1:25,000

CONTOUR INTERVAL 10 METERS



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EVA 2 TRAVERSE - NORTH LEG

DECEMBER 1972

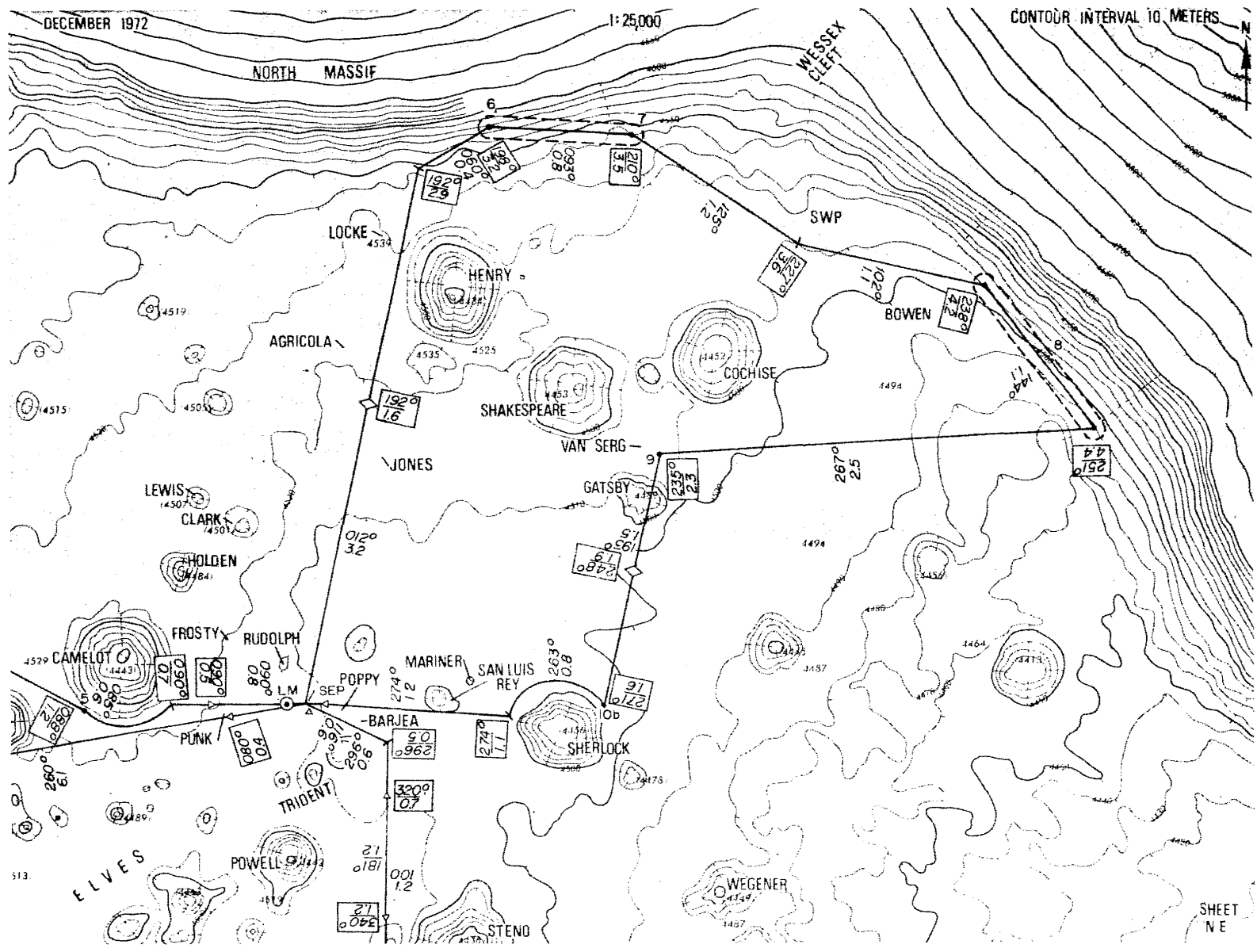
1:25,000

CONTOUR INTERVAL 10 METERS

NORTH MASSIF

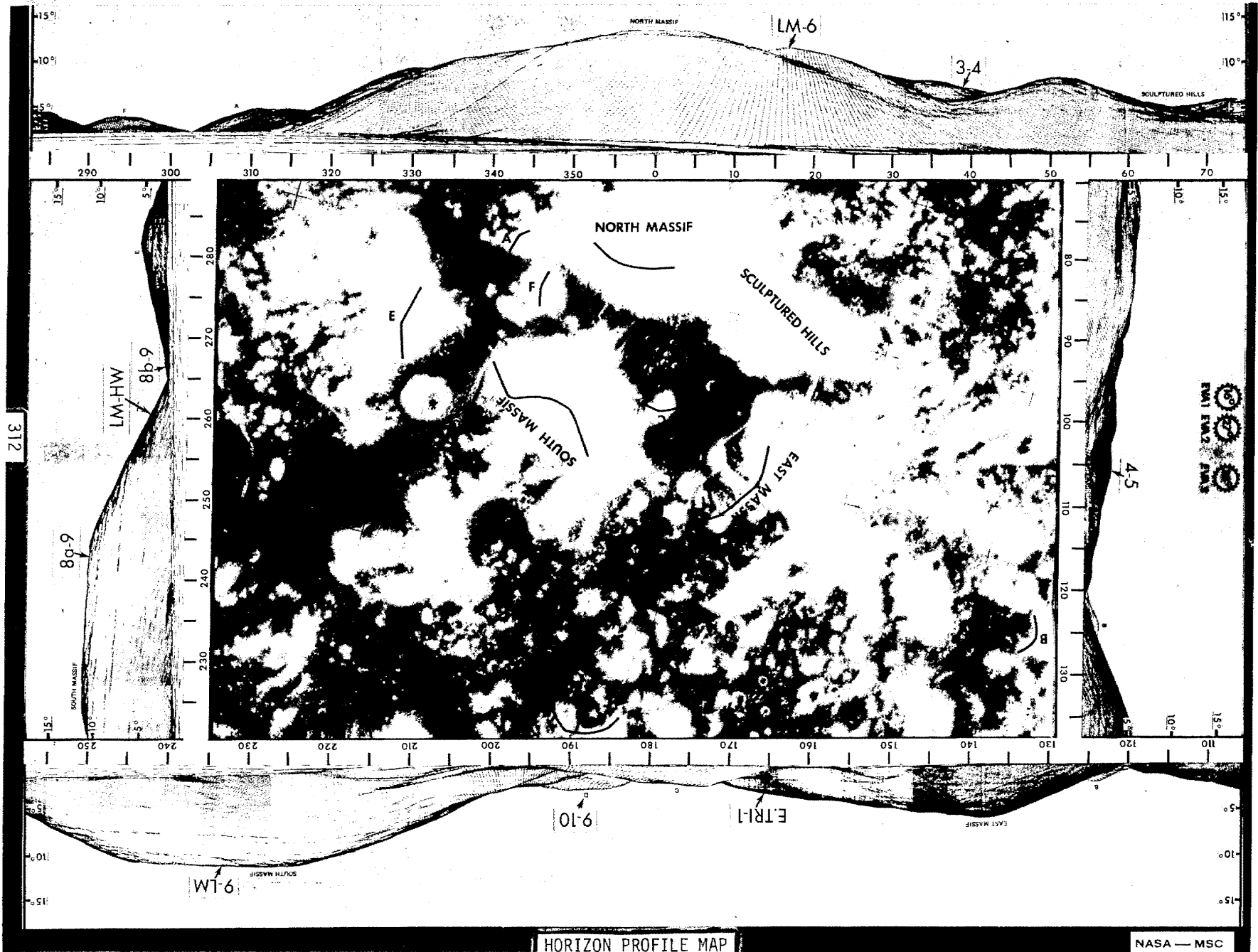
MESSEY CLEFT

311



EVA 3 TRAVERSE

SHEET N E



HORIZON PROFILE MAP

312

4 427