

Mars Science Laboratory (MSL) Software Interface Specification DAN Reduced Data Record (RDR)

Version 1.0 JPL D-38122 SIS-SCI018-MSL

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TBD ITEMS

SECTION/PAGE	TBD ITEM	RESPONSIBILITY

TABLE OF CONTENTS

CHANGE LOG	3
TBD ITEMS	4
Table of Contents	5
ACRONYMS AND ABBREVIATIONS	7
 INTRODUCTION. 1.1 Purpose and Scope	8 8 8 ory 9 9
 2. Data Product Characteristics and Environment	9 9 .12 .13
 2.3.2 Data Product Generation	. 14 . 14 . 14 . 14 . 19
2.4.5 PDS Standards 2.4.6 Time Standards 2.4.7 Coordinate Systems 2.4.8 Data Storage Conventions 2.5 Data Validation	. 19 . 19 . 20 . 21 . 21
 3. Detailed Data Product Specifications. 3.1 Data Format Descriptions 3.1.1 DERIVED_ENGINEERING. 3.1.2 DERIVED_PASSIVE. 3.1.3 DERIVED ACTIVE. 3.1.4 AVERAGED PASSIVE. 3.1.5 AVERAGED ACTIVE. 3.2 Label and Header Descriptions. 3.2.6 PDS Label. 3.2.7 PDS Table Object. 	.21 22 .22 .22 .23 .23 .23 .23 .23 .23 .23
 4. Applicable Software. 4.1 Utility Programs. 4.2 Applicable PDS Software Tools	24 .24 .24
5. Data 5.1 DAN RDR Data Columns	25 .25
6. ExampleS of DAN RDR PDS Labels.6.1 Derived Engineering Label	30 . 30

6.2 Derived Passive Label	.34
6.3 Derived Active Label	. 39
6.4 Averaged Passive Label	.44
6.5 Averaged Active Label	.51
	70
7. Appendix – A	59

ACRONYMS AND ABBREVIATIONS

ASCII	American Standard Code for Information Interchange
CODMAC	Committee on Data Management and Computation
CETN	Counts of Epithermal Neutrons
CTN	Counts of Thermal Neutrons
DAN	Dynamic Albedo of Neutrons
DE	DAN Electronics
EDR	Experiment Data Record
FDD	Functional Design Document
FEI	File Exchange Interface
GDS	Ground Data System
ΙΟΤ	Instrument Operations Team
JPL	Jet Propulsion Laboratory
LPL	Lunar and Planetary Laboratory
MER	Mars Exploration Rovers
MIPL	Multi-mission image Processing Laboratory
MSL	Mars Science Laboratory
NAIF	Navigation and Ancillary Information Facility
NASA	National Aeronautics and Space Administration
ODL	Object Description Language
ODS	MSL's Operations Data Store
OPGS	Operations Products Generation Sub-system
PDS	Planetary Data System
PHX	Mars Phoenix Lander
PNG	Pulsing Neutron Generator
RDR	Reduced Data Record
RMC	Rover Motion Counter
RTO	Real Time Operations (MSL terminology)
SCLK	Spacecraft Clock
SIS	Software Interface Specification
TBD	To Be Defined/Determined

1. INTRODUCTION

1.1 Purpose and Scope

The purpose of this Software Interface Specification (SIS) is to provide suppliers and consumers of the Mars Science Lander's (MSL) Dynamic Albedo of Neutrons (DAN) instrument with a detailed description of DAN's Reduced Data Records (RDR). It does not cover any lower-level products, which are collectively known as Experimental Data Records (EDR). They will be covered by a separate SIS, provided by the OPGS (JPL).

This SIS includes descriptions of higher order DAN science and the special engineering data products.

The users for whom this SIS is intended for are the scientists who will analyze the data, including those associated with the MSL Project, DAN instrument engineers, and other users in the general planetary science community.

1.2 Contents

This SIS provides a very high level description of how DAN works/operates. It also describes, at high level, how the DAN data product is acquired by the instrument and how it is processed, formatted, labeled, and uniquely identified on the ground.

The document discusses standards used in generating the product and software tools which may be used to access the information. The data product structure and organization is described in sufficient detail to enable a user to read the product. Finally, an example of the product's PDS label is provided.

1.3 Applicable Documents and Constraints

This Data Product SIS is responsive to the following MSL documents:

- 1. Mars Exploration Program Data Management Plan, Arvidson et al., Rev. 4.0, June 15, 2011.
- 2. Mars Science Laboratory Archive Generation, Validation and Transfer Plan, Joy Crisp, JPL D-35281, May 28, 2010.
- 3. Planetary Data System Standards Reference, JPL D-7669 part 2, version 3.8, February 27, 2009.
- 4. Planetary Archive Preparation Guide, JPL D-31224, Version 1.4, April 1, 2010, http://pds.jpl.nasa.gov/tools/archiving.html.
- 5. DAN FDD, JPL D-34220, MSL 375-1230
- 6. Mars Science Laboratory Software Interface Specification DAN Experiment Data Record, JPL D-38113, SIS-SCI1014-MSL, to be completed.
- Mars Exploration Program Data Management Plan, Arvidson et al., Rev. 4.0, June 15, 2011.
- 8. MSL DAN Science Team and PDS Geosciences Node Interface Control Document (ICD), Susan Slavney and Alberto Behar, Version 3.0, July 26, 2010.

- 9. Mars Science Laboratory Dynamic Albedo of Neutrons RDR Archive Volume Software Interface Specification, Karl Harshman, September 28, 2011.
- 10. The Dynamic Albedo of Neutrons (DAN) Experiment for NASA's 2009 Mars Science Laboratory Litvak et al., 2008

This SIS is meant to be consistent with the contract negotiated between the MSL Project and the Instrument Principal Investigator (PI) in which reduced data records (RDR) and documentation (SIS) are explicitly defined as deliverable products.

1.4 Relationships with Other Interfaces

Changes to this DAN SIS document will affect the following products, software, and/or documents.

Name	Type P-product S-software D-document	Owner
DAN RDRs	Р	U of A
DAN_RDR_gen	S	U of A
DAN UA database schema	Р	U of A
Other DAN Programs/Products/Documents	P/S/D	DAN Science Team

Table 1: Product and Software Interfaces to this SIS

2. DATA PRODUCT CHARACTERISTICS AND ENVIRONMENT

2.1 Instrument Overview

The Dynamic Albedo of Neutrons (DAN) is an active/passive neutron spectrometer that measures the abundance and depth distribution of H- and OH-bearing materials (e.g., adsorbed water, hydrated minerals) in a shallow layer (~1 m) of Mars' subsurface along the path of the MSL rover. In active mode, DAN measures the time decay curve (the "dynamic albedo") of the neutron flux from the subsurface induced by its pulsing 14 MeV neutron source (Figure 1 shows an example). A detailed description of the DAN instrument and scientific investigation can be found in Litvak et al. (2008). The experiment is contributed by the Federal Space Agency of Russia.



Figure 1: Numerical simulations of the neutron count rate versus time (i.e., die-away curve) for the unshielded (left, CTN) and shielded (middle CETN) detectors as a function of water abundance. The right panel shows the difference between the two count rates.

The science objectives of the DAN instrument are as follows: 1) Detect and provide a quantitative estimation of the hydrogen in the subsurface throughout the surface mission; 2) Investigate the upper <0.5 m of the subsurface and determine the possible layering structure of hydrogen-bearing materials in the subsurface; 3) Track the variability of hydrogen content in the upper soil layer (~1 m) during the mission by periodic analysis; and 4) Track the variability of neutron radiation background (neutrons with energy < 100 keV) during the mission by periodic analysis.

The DAN instrument is expected to be used during rover traverses (e.g., during short stops at ~1 m intervals) and while the rover is parked. Short-duration (< 2 min) measurements will provide a rough estimate of the water-equivalent hydrogen distribution with an accuracy of ~1% by weight. Longer-duration (~30 min) measurements are necessary to derive the vertical distribution of water-equivalent hydrogen with an accuracy of 0.1-0.3% by weight. DAN performs layering structure analyses of the Martian sub-surface, to measure the distribution of H- and OH-bearing materials, with a vertical resolution of < 1 m and horizontal resolutions of 0.5 - 100 m along the path of the rover.

DAN has three different modes of operations: Standby, Passive, and Active.

- STANDBY: Low voltage electronics are on, no science observations.
- PASSIVE: Background observations collected
- ACTIVE: Neutron pulses are produced and science observations collected.



Figure 2: DAN PNG, Pulsing Neutron Generator



Figure 3: DE, DAN Detector



Figure 4: Location of DAN DE and PNG on rover

2.2 Data Product Overview

DAN's Reduced Data Records (RDR), NASA Level 1-A and 1B products, are generated by the DAN Team from the EDR data products, which are produced by OPGS at JPL.

DAN RDRs consist of clusters of calibrated data records, time-ordered, and grouped together. Each RDR will have a unique PDS label file, also known as a PDS detached label, which provides all the Meta and Ancillary data for each DAN data product. The pair of files, DAN binary data, and its PDS label, is collectively referred to as an RDR. In other words, an RDR is always made up of two files, named identically with only different file extensions, ".DAT" and ".LBL".

As part of the RDR generation, older RDRs are replaced by newer and better calibrated versions. Since RDRs are generated from EDRs, if new EDRs become available RDRs may need to be regenerated. A regenerated version is identified in the product's PDS label by an incremented product version ID and a later product generation time.

2.3 Data Processing

2.3.1 Data Processing Level

The DAN RDR data set is assigned the PDS Data Set ID "MSL-M-DAN-3/4-RDR-V1.0". The processing level numbers are from the "Committee on Data Management and Computation (CODMAC) data level numbering system (Table 2).

NASA	CODMAC	Description
Packet data	Raw - Level 1	Telemetry data stream as received at the ground station, with science and engineering data embedded.
Level-0	Edited - Level 2	Instrument science data (e.g., raw voltages, counts) at full resolution, time ordered, with duplicates and transmission errors removed.
Level 1-A	Calibrated - Level 3	Level 0 data that have been located in space and may have been transformed (e.g., calibrated, rearranged) in a reversible manner and packaged with needed ancillary and auxiliary data (e.g., radiances with the calibration equations applied).
Level 1-B	Resampled - Level 4	Irreversibly transformed (e.g., resampled, remapped, calibrated) values of the instrument measurements (e.g., radiances, magnetic field strength).
Level 1-C	Derived - Level 5	Level 1A or 1B data that have been resampled and mapped onto uniform space-time grids. The data are calibrated (i.e., radiometrically corrected) and may have additional corrections applied (e.g., terrain correction).
Level 2	Derived - Level 5	Geophysical parameters, generally derived from Level 1 data, and located in space and time

 Table 2: Processing Levels for Science Data Sets

NASA	CODMAC	Description
		commensurate with instrument location, pointing, and sampling.
Level 3	Derived - Level 5	Geophysical parameters mapped onto uniform space-time grids.

2.3.2 Data Product Generation

The DAN RDR data products will be generated by the University of Arizona using the data processing software, DAN_RDR_gen. The RDR data products will be calibrated data derived from EDR data products and formatted according to this RDR SIS.

Data derived using SPICE kernels will be included in the RDR data products

2.3.3 Data Flow

The DAN RDR data products generated by the U of A will be created from EDR products provided from OPGS through MIPL's File Exchange Interface (FEI) system and data derived using SPICE kernels acquired from NAIF. After a data validation period, the DAN RDR data products will be delivered to the Planetary Data System on a pre-determined schedule.

The DAN RDRs will be generated at least one month prior to the scheduled delivery date. The DAN RDR data will be reprocessed if new EDR data are received or if better calibrations are available.

The total estimated volume of the RDRs over the course of the MSL mission is 1 Gigabyte.

2.3.4 Labeling and Identification

There is a file-naming scheme adopted for the MSL image and non-image data products. The scheme applies to the EDR and RDR data products. The file naming schemes adhere to the Level II 36.3 filename convention approved by PDS in 2009.

The primary attributes of the filename nomenclature are:

- a) Uniqueness It must be unique unto itself without the file system's directory path. This protects against product overwrite as files are copied/moved within the file system and external to the file system, if managed correctly.
- b) Metadata
 It should be comprised of metadata fields that keep file bookkeeping and sorting intuitive to the human user. Even though autonomous file processing will be managed via databases, there will always be a human-in-the-loop that puts a premium on filename intuition. Secondly, the metadata fields should be smartly selected based on their value to ground processing tools, as it is less CPU-intensive to extract information from the filename than from the label.

NOTE: The metadata information in the filename also resides in the product label.

The metadata fields have been selected based on MER and PHX lessons learned. In general, the metadata fields are arranged to achieve:

- a) Sortability At the beginning of the filename resides a primary time oriented field such as Spacecraft Clock Start Count (SCLK). This allows for sorting of files on the MSL file system by spacecraft data acquisition time as events occurred on Mars.
- b) Readability An effort is made to alternate integer fields with ASCII character fields to optimize differentiation of field boundaries for the human user.

Each DAN product has a detached PDS label associated with the DAN data file. The file-naming scheme for the DAN data products is:



where,

- Instr = (2 alpha character) Instrument ID, denoting the source MSL science or engineering
 instrument that acquired the data.
 Valid values for Instrument ID's are:
 "DN" DAN
- **Config** = (1 alphanumeric) Instrument Configuration, an operational attribute of the Instrument that assists in characterizing the data. Valid values:

	Configuration			
Instrument	Values Description			
DAN ("DN")	it is being set to either " A " or " B "	A-side configuration, B-side configuration		

spec = (1 character) Special Processing flag, applicable to RDRs on a case-by-case basis.

Special Processing	EDR Value	RDR Value
None know	""	" "
Special method types A - Z	n/a	" A" - "Z"

sclk = (9 alphanumeric) Spacecraft Clock Start Count, in units of seconds.
 Which specific SCLK is used depends on the instrument but is generally expected to be the time the data was acquired. For the DAN EDRs the SCLK provided in the .emd (Data product metadata file) file will be used.

The valid values, in their progression, are as follows (non-Hex):

Range 00000000 thru 99999999 - "00000000", "00000001", ... "999999999" Range 100000000 thru 1099999999 - "A00000000", "A00000001", ... "A999999999" Range 1100000000 thru 1199999999 - "B00000000", "B00000001", ... "B99999999" • • Range 3500000000 thru 3599999999 - "Z00000000", "Z00000001", ... "Z999999999"

prod = (3 char) Product Type identifier.

This field has the following rule-of-thumb:

Beginning **"E"** - Type of **E**DR, which is a raw data product. Beginning **"R"** - Type of **R**DR, which is a reduced product.

Valid values for DAN Product identifiers are listed below:

Product Type Description	Value
Active EDR	"EAC"
Passive EDR	"EPA"
Standby EDR	"EST"
Derived Engineering RDR	"REN"
Derived Passive RDR	"RPA"
Derived Active RDR	"RAC"
Averaged Passive RDR	"RAP"
Averaged Active RDR	"RAA"

sol = (4 alphanumeric) Sol, or Mars Solar Day. It is converted from the SCLK using LMST

(Local Mean Solar Time).

NOTE: If the first character is an underscore ("_") then the remaining 3 characters denote the day of year (DOY). This format will be used during cruise.

The valid values, in their progression, are as follows (non-Hex):

Range 0000 thru 9999 - "0000", "0001", … "9999" Range 10000 thru 10999 - "A000", "A001", … "A999" Range 11000 thru 11999 - "B000", "B001", … "B999" • • • Range 35000 thru 35999 - "Z000", "Z001", … "Z999"

site = (3 alphanumeric) Site location count, from the RMC.

This field has the following rules-of-thumb:

If value is any 3 alphanumeric characters then content represents Site index extracted from RMC, or 3 underscores (denoting value is out-of-range),.

The valid Site values, in their progression, are as follows (non-Hex):

```
Range 000 thru 999 - "000", "001", … "999"
Range 1000 thru 1099 - "A00", "A01", … "A99"
Range 1100 thru 1199 - "B00", "B01", … "B99"
•
•
Range 3500 thru 3599 - "Z00", "Z01", … "Z99"
```

drive = (4 alphanumeric) Drive (position-within-Site) location count, from the Rover Motion Counter (RMC).

This field has the following rules-of-thumb:

If value is any 4 alphanumeric charactersthen content represents Drive index extracted from RMC, or 4 underscores (denoting value is out-of-range),.

The valid Drive values, in their progression, are as follows (non-Hex):

Range 0000 thru 9999 -	"0000", "0001", "9999"
Range 10000 thru 10999 -	"A000", "A001", "A999"
Range 11000 thru 11999 -	"B000", "B001", … "B999"
	•
	•
	•
Range 35000 thru 35999 -	"Z000", "Z001", … "Z999"
Range 36000 thru 36099 -	"AA00", "AA01", "AA99"
Range 36100 thru 36199 -	"AB00", "AB01", "AB99"
	•
	•
	•
Range 38500 thru 38599 -	"AZ00", "AZ01", … "AZ99"
Range 38600 thru 38699 -	"BA00", "BA01", "BA99"
Range 38700 thru 38799 -	"BB00", "BB01", "BB99"

```
Range 41100 thru 41199 - "BZ00", "BZ01", ... "BZ99"
Range 41200 thru 41299 - "CA00", "CA01", ... "CA99"
Range 65400 thru 65499 - "LIOO", "LIO1", ... "LI99"
Range 65500 thru 65535 - "LJ00", "LJ01", ... "LJ35"
```

req id = (7 alphanumeric) - Request ID

In the case of DAN this files is currently not being used, and therefore it will always have a value of all underscores ("___ _"). It is maintained as a placeholder, and to maintain consistency with MSL file-naming nomenclature.

Valid values:

who

(1 alpha character) Product Producer ID identifies the institution that generated the = product.

This field has the following rules-of-thumb:

Producer - If value is "P" (for Flight) or "Y" (for Engineering), the provider of the product is the Principal Investigator. Except for MIPL as the provider ("M" for Flight or "Z" for Engineering), the remaining characters are assigned to Co-investigator providers at the discretion of the P.I. and will be identified in due time. Within the instrument of the P.I., characters are unique. Across instruments, characters are reusable.

Venue			hu Droducer
Flight Model	Eng. Model		by Producer
" M "	" Z "	MIPL (OPGS at JPL)	
"P"	" Y "	Principal Investigator	of Instrument
		Instrument SAM REMS DAN RAD CheMin CA) APXS SA/SPaH	Principal Investigator GSFC (Goddard, MD) Ministry of Education & Science (Spain) Federal Space Agency (Russia) SwRI (Boulder, CO) Ames Research Center (Mountain View, Max-Planck Institute (Germany)
" A " - "L"	"Q" - "X"	Co-Investigators (to b UA generated.	e identified by P.I. per instrument) A for

See the following table of valid values:

ver = (1 alphanumeric) Version identifier.

The valid values, in their progression, are as follows (non-Hex):

- "1", "2", ... "9", "0" Range 1 thru 10

Range 11 thru 36 - "**A**", "**B**", ... "**Z**" Range 37 and higher - "_" (underscore)

The Version number increments by one whenever an otherwise-identical filename would be produced. Note that not every version need exist, e.g. versions 1, 2 and 4 may exist but not 3. In general, the highest-numbered Version represents the "best" version of that product.

NOTE: To be clear, this field increments independently of all fields, including the Special Processing field.

ext = (2 to 3 alpha characters) Product type extension.

Valid values for nominal operations data products:

- "DAT" Non-imaging binary instrument data
- "LBL" Detached label in PDS format

Example #1: DNA_351797691RPA_0550000000_____P1.DAT

Where,

instr	=	"Ľ)N" =	=	DAN
config	=		" A " =	=	TBD (Instrument configuration for now)
spec	=		"_" =	=	TBD
sclk	=		""	=	Spacecraft Clock Start Count of 351797691 sec.
prod	=	"RF	•Ā" =	=	"R"-RDR, "PA"-Passive
sol	=	"_0	55" ÷	=	Day-of-Year 55 (Cruise)
site	=	" 0	00 " =	=	Site 0
drive	=	"00	00 " =	=	Position (Drive) 0
reqestID	=	"		=	unused
who	=		" P " =	=	Produced by LPL at the University of Arizona
ver	=		"1" =	=	Version 1
ext	=	"DA	\T " =	=	Indicates this file contains data, and not label info (LBL).

2.4 Standards Used in Generating Data Products

2.4.5 PDS Standards

The DAN data product complies with PDS standards for file formats and labels, as specified in the PDS Standards Reference .(Applicable Document 3)

2.4.6 Time Standards

The following time standards and conventions are used throughout this document, as well as the MSL project for planning activities and identification of events.

Time Format	Definition
SCET	Spacecraft event time. This is the time when an event occurred on- board the spacecraft, in UTC. It is usually derived from SCLK.
SCLK	Spacecraft Clock. This is an on-board 64-bit counter, in units of nano-seconds and increments once every 100 milliseconds. Time zero corresponds to midnight on 1-Jan-1980.
ERT	Earth Received Time. This is the time when the first bit of the packet containing the current data was received at the Deep Space (DSN) station. Recorded in UTC format.
Local Solar Time	Local Solar Time (LST). This is the local solar time defined by the local solar days (sols) from the landing date using a 24 "hour" clock within the current local solar day (HR:MN:SC). Since the Mars day is 24h 37m 22s long, each unit of LST is slightly longer than the corresponding Earth unit. LST is computed using positions of the Sun and the landing site from SPICE kernels. If a landing date is unknown to the program (e.g. for calibration data acquired on Earth) then no sol number will be provided on output LST examples: SOL 12 12:00:01 SOL 132 01:22:32.498 SOL 29
RCT	Record Creation Time. This is the time when the first telemetry packet, containing a give data, set was created on the ground. Recorded in UTC format.
True Local Solar Time	This is related to LST, which is also known as the mean solar time. It is the time of day based on the position of the Sun, rather than the measure of time based on midnight to midnight "day". TLST is used in all MIPL/OPGS generated products.
SOL	Solar Day Number, also known as PLANET DAY NUMBER in PDS label. This is the number of complete solar days on Mars since landing. The landing day therefore is SOL zero.

2.4.7 Coordinate Systems

The following coordinate systems are used within the project to refer to the position of the Rover and its instruments.

Coordinate System	Origin	Orien	tation
Local Level	Same as payload frame,	+X	North
	and it moves with the	+Z	down along gravity vector

	Rover	+Y East	
Payload Frame	At the shoulder of the Robotic Arm. Attached and moves with the Rover	 +X along Rover -X (po into the work space) +Z down along Rover (waxis) +Y along Rover -Y 	vertical
Site Frame	Same as payload frame when first defined and never moves relative to Mars. Possible to define multiple site frames in case the Rover moves/slips.	Same as local level	
Rover Frame	Attached to Rover	Attached to Rover	

2.4.8 Data Storage Conventions

DAN RDR products will be stored as binary files containing IEEE floating-point values, bigendian integers and ASCII character strings. For every DAN RDR there will be a detached PDS label file. The detached PDS labels for DAN RDRs are stored as ASCII text, with each keyword definition terminated by ASCII carriage-return and line-feed characters. The RDR products are defined in section 5. The PDS label keywords are described in Appendix-A.

Each DAN RDRs will contain fixed length records but the length can differ depending on the type of RDR. When necessary, records will be padded with extra bytes of 0x00. Label keywords will provide necessary information to determine the size and organization of the binary records.

2.5 Data Validation

The DAN RDRs, as with all other MSL RDRs, are subject to PDS peer review.

Validation of DAN RDR products during production will be performed according to specifications in the MSL Archive Plan. The DAN Team will validate the science content of the data products, and the PDS Geosciences Node will validate the products for compliance with PDS standards and for conformance with the design specified in this SIS.

Validation of the MSL RDRs will fall into two primary categories: automated and manual. Automated validation will be performed on every RDR product produced for the mission. Manual validation will only be performed on a subset.

Validation of DAN RDRs will be performed by the DAN Team as a part of the archiving process, and will be done simultaneously with the archive volume validation. Validations performed will include such things as verification that the checksum in the label matches a calculated checksum for the data product (i.e., that the data product included in the archive is identical to that produced by the real-time process), a validation of the PDS syntax of the label, a check of the label values against the database and against the index tables included on the

archive volume, and checks for internal consistency of the label items. The latter include such things as verifying that the product creation date is later than the earth received time. As problems are discovered and/or new possibilities identified for automated verification, they will be added to the validation procedure.

Manual validation of the data will be performed both as spot-checking of data throughout the life of the mission, and comprehensive validation of a subset of the data (for example, a couple of days' worth of data). A human will view these products. The DAN Team will validate the science content of the data products, and the PDS Geosciences Node will validate the products for compliance with PDS standards and for conformance with the design specified in this SIS.

3. DETAILED DATA PRODUCT SPECIFICATIONS

When powered, the DAN instrument is in one of three states: STANDBY, PASSIVE, or ACTIVE. Onboard, the DAN instruments can generate different data packets depending on the state of the instrument.

Five RDR products will be produced, DERIVED_ENG, DERIVED_PASSIV, DERIVED_ACTIVE, AVERAGED_PASSIV and AVERAGED_ACTIVE Each is defined in the following sections. The DAN RDR file naming convention will uniquely identify each data product. See Section 2.3.4 for detail description of the DAN file naming convention.

The structure of the DAN RDR consists of a detached ASCII PDS label and a binary data file as shown in Figure 3.1.

Detached ASCII PDS Label

DAN Binary Data File ()

Figure 3.1: The DAN RDR consists of two files.

3.1 Data Format Descriptions

Appendix A includes the table for binary data column definitions to the byte level.

3.1.1 DERIVED_ENGINEERING

Derived Engineering are the raw DN values from the 6 temperature sensors converted to Celsius. Each EDR record contains these temperatures and therefore a time series dataset can be constructed over the entire time DAN is operating. This data product also contains the states of the two high voltages for the detectors and also the two discriminator values for each of the two detectors (CTN and CETN).

3.1.2 DERIVED_PASSIVE

The Derived Passive data products are in a one to one correspondence with the EDR Passive data products. Each data product has counts for each detector summed over channels 1 to 16 and background counts for the collection period as well as location and time information.

3.1.3 DERIVED ACTIVE

The Derived Active data set is in a one to one correspondence with the EDR Active data set. This data set has the detector counts summed over channels 1 to 16 for each of the 64 spectra in the EDR set. It also contains the background counts for each of the 64 spectra as well as location and time information.

3.1.4 AVERAGED PASSIVE

An Averaged Passive data product contains the average counts over some time period of passive measurements. Derived Passive data products are used to calculate the average of the given time period. The time periods will coincide with passive measurements during a travser from location A to location B. This data product also contains the background counts for the given time period as well as an error and normalization factor. It also contains spatial and temporal information over which the data was taken.

3.1.5 AVERAGED ACTIVE

An Averaged Active data product contains the average counts over some time period of active measurements. The Derived Active data products are used to calculate the average of the given time period. The time periods will coincide with active measurements during a time the rover is stopped. This data product also contains the background counts for the given time period as well as an error and normalization factor. It also contains spatial and temporal information over which the data was taken.

3.2 Label and Header Descriptions

3.2.6 PDS Label

DAN products have detached PDS labels. A PDS label is object-oriented and describes the objects in the data file. The PDS label contains keywords for product identification and for table object definitions. The label also contains descriptive information needed to interpret or process the data objects in the file.

PDS labels are written in Object Description Language (ODL). PDS label statements have the form of "keyword = value". Each label statement is terminated with a carriage return character (ASCII 13) and a line feed character (ASCII 10) sequence to allow the label to be read by many

operating systems. Pointer statements with the following format are used to indicate the location of data objects in the file:

$$^{Object} = location$$

where the carat character ($^$, also called a pointer) is followed by the name of the specific data object. The location is the starting record number for the data object within the file.

Each PDS keyword defined for the DAN label will always be included in the label. If a keyword does not have a value, a value of N/A will be given as the keyword value.

Per PDS rules, "N/A" is used when a keyword exists, but it does not apply to a particular data, and "UNKNOWN" or UNK is used when a value of an applicable keyword cannot be determined at the time the PDS label was generated.

3.2.7 PDS Table Object

The TABLE object is a uniform collection of rows containing ASCII or binary values stored in columns. The INTERCHANGE_FORMAT keyword is used to distinguish between TABLEs containing only ASCII columns and those containing binary data. DAN RDR products are stored as binary tables. Each field is defined as a fixed-width COLUMN object; the value of the COLUMNS keyword is the total number of COLUMN objects defined in the label. All TABLE objects must have fixed-width records.

4. APPLICABLE SOFTWARE

4.1 Utility Programs

None

4.2 Applicable PDS Software Tools

PDS-labeled images and tables can be viewed, but not manipulated with the program NASAView, developed by the PDS Engineering Node, and are available for a variety of computer platforms. They can be obtained directly from the PDS at http://pds.nasa.gov/tools/nasa-view.shtml.

5. DATA

5.1 DAN RDR Data Columns

This table lists the columns in all DAN RDR data files in alphabetical order. The format of each type of data file, including column positions, sizes, data types, units, and full descriptions, can be found in the format files (*.FMT) in the LABEL directory.

		Length		
Column Name	Data Type	in bytes	Description	Appears In
			"Latitude in Mars fixed coordinates at the beginning	
BEGIN_LATITUDE	IEEE_REAL	4	of the frame."	DP, AP, AA
			"Longitude in Mars fixed coordinates at the	
BEGIN_LONGITUDE	IEEE_REAL	4	beginning of the frame."	DP, AP, AA
			"Average counts for CETN detector over collection	
CETN_AVERAGE	IEEE_REAL	4	duration."	AP, AA
				DP, DA,
CETN_BKGD	IEEE_REAL	4	"Background counts for CETN detector (counts)."	AP, AA
			"Counts gathered in CETN detector during frame	
CETN_COUNTS	IEEE_REAL	4	interval."	DP, DA
			"Error in counts in CETN detector over collection	
CETN_ERROR	IEEE_REAL	4	duration."	AP <i>,</i> AA

		Length		1
Column Name	Data Type	in bytes	Description	Appears In
CETN_NORM	IEEE_REAL	4	"Normalization in counts for CETN detector for collection duration."	AP, AA
COLLECTION_DURATION	MSB_UNSIGNED_INTEGER	4	"Value of collection time in seconds."	DP, AA, AP, DA
CTN_AVERAGE	IEEE_REAL	4	"Average Counts in CTN detector over duration."	AP, AA
CTN_BKGD	IEEE_REAL	4	"Background counts for CTN detector (counts)."	DP, DA, AP, AA
CTN_COUNTS	IEEE_REAL	4	"Counts gathered in CTN detector during frame interval."	DP, DA
CTN_ERROR	IEEE_REAL	4	"Error in counts in CTN detector over duration."	AP, AA
CTN_NORM	IEEE_REAL	4	"Normalization in counts for CTN detector over duration."	AP, AA
DAN_TIME	MSB_UNSIGNED_INTEGER	4	"DAN instrument time in milliseconds since last power up."	DP, DE
DSC_LEVEL_CETN	MSB_UNSIGNED_INTEGER	1	"The CETN Discriminator level 0 = low, 1 = high."	DE

Column Name	Data Type	Length in bytes	Description	Appears In
		in bytes		rippears m
DSC_LEVEL_CTN	MSB_UNSIGNED_INTEGER	1	"The CTN Discriminator level 0 = low, 1 = high."	DE
END DAN TIME	MSB UNSIGNED INTEGER	4	"DAN time at end of collection in milliseconds."	DA, AP, AA
			" Planetocentric Latitude in Mars fixed coordinates at	
END_LATITUDE	IEEE_REAL	4	the end of the frame."	DP, AA, AP
			"Dispete contribute in Mars fixed	
END LONGITUDE	IEEE REAL	4	coordinates at the end of the frame."	DP. AP. AA
				, ,
			"UTC time at the end of the collection interval,	DP, DA,
END_UTC	CHARACTER	23	stored as yyyy-mm-ddThh:mm:ss.sss."	AP, AA
HV LEVEL CETN	MSB UNSIGNED INTEGER	1	"The CFTN HV level 0 = off 2 = high 3 = low "	DF
		-		
HV_LEVEL_CTN	MSB_UNSIGNED_INTEGER	1	"The CTN HV level 0 = off, 2 = high, 3 = low."	DE
		1	" Planetocentric Latitude in Mars fixed coordinates "	DA
		4		DA
			Planetocentric east Longitude in Mars fixed	
LONGITUDE	IEEE_REAL	4	coordinates."	DA

		Length		
Column Name	Data Type	in bytes	Description	Appears In
NUM PNG PULSES	IEEE REAL	4	interval."	DA, AA
			"Pulsing Neutron Generator frequency of pulsing in	
PNG_FREQUENCY	MSB_UNSIGNED_INTEGER	1	counts."	DA, AA
START_DAN_TIME	MSB_UNSIGNED_INTEGER	4	"DAN time at beginning of interval in milliseconds."	DA, AP, AA
		20	"UTC time at the start of the collection interval,	DP, DA,
START_UTC	CHARACTER	23	stored as yyyy-mm-dd1nn:mm:ss.sss.	AP, AA
TFMP1	IFFF RFAL	4	"PNG temperature in Celsius."	DF
		-		
TEMP2	IEEE_REAL	4	" High voltage board temperature in Celsius."	DE
ТЕМРЗ	IEEE_REAL	4	" FPGA temperature in Celsius."	DE
ΤΕΜΦΑ	IFFE REAL	л	" Analog board #1 temperature, in Celsius "	DE
		4		
TEMP5	IEEE_REAL	4	" Analog board #2 temperature in Celsius."	DE

Column Name	Data Type	Length in bytes	Description	Appears In
TEMP6	IEEE_REAL	4	" Case temperature in Celsius."	DE
TIME_BIN_DURATION	IEEE_REAL	4	"Duration in microseconds for each time bin."	DA, AA
TIME_BIN_START	IEEE_REAL	4	"Start time in microseconds for each time bin."	DA, AA
UTC	CHARACTER	23	stored as yyyy-mm-ddThh:mm:ss.sss."	DE

6. EXAMPLES OF DAN RDR PDS LABELS

6.1 Derived Engineering Label

PDS_VERSION_ID	=	PDS3
/* FILE DATA ELEMENTS */		
RECORD_TYPE	=	FIXED_LENGTH
RECORD_BYTES	=	5663
FILE_RECORDS	=	21
/* IDENTIFICATION DATA ELEMENTS	*,	/
DATA_SET_ID	=	"MSL-M-DAN-3/4-RDR-V1.0"
COMMAND_SEQUENCE_NUMBER	=	0
INSTRUMENT_HOST_ID	=	MSL
INSTRUMENT HOST NAME	=	"MARS SCIENCE LABORATORY"
INSTRUMENT NAME	=	"DYNAMIC ALBEDO OF NEUTRONS"
MSL:REQUEST ID	=	4932
PLANET DAY NUMBER	=	"42"
PRODUCT CREATION TIME	=	2010-10-27T22:19:47.000
PRODUCT ID	=	
"DNA 351797691REN 0550000000		P1.DAT"
PRODUCT TYPE	=	DAN RDR EN
PRODUCT VERSION ID	=	"1.0"
RELEASE ID	=	"1"
ROVER MOTION COUNTER	=	(0, 0, 0, 0, 0, 0, 0, 0)
ROVER MOTION COUNTER NAME	=	(SITE, DRIVE, POSE, ARM, CHIMRA,
		DRILL, RSM, HGA)
SEQUENCE ID	=	"1036288"
SEQUENCE VERSION ID	=	"()"
SPACECRAFT CLOCK START COUNT	=	"340477575.18840"
SPACECRAFT CLOCK STOP COUNT	=	"340563425 23451"
START TIME	=	2012-289T05:10:16.868
STOP TIME	=	2012-289T06.04.10 232
TARGET NAME	=	MARS
	_	"DNA 351797691REN 0550000000 P1
.DAT"		
OBJECT	=	TABLE
COLUMNS	=	1213
INTERCHANGE FORMAT	=	BINARY
ROW BYTES	=	5663
ROWS	=	21
DESCRIPTION	=	11
This table contains converte	ed	engineering data
as observed by the Mars Scie	end	ce Laboratory (MSL) Dynamic Albedo of
Neutron Detector (DAN).		
Detailed descriptions for t	ne	parameters defined below are

```
contained in the DAN RDR SIS document .
The complete column definitions are contained in the following
external
file found in the LABEL directory of the archive volume.
"
^STRUCTURE = "DAN_RDR_DERIVED_ENG.FMT"
END_OBJECT = TABLE
END
```

6.1.1 Derived Engineering FORMAT FILE ("DAN RDR DERIVED ENG.FMT")

```
OBJECT = COLUMN
   COLUMN NUMBER = 1
  NAME = DAN TIME
  DATA TYPE = MSB UNSIGNED INTEGER
  BYTES = 4
  START BYTE = 1
  UNIT = MILLISECONDS
   DESCRIPTION = "DAN instrument time in milliseconds since last power
up."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 2
  NAME = UTC
  DATA TYPE = CHARACTER
  BYTES = 23
  START BYTE = 5
   DESCRIPTION = "UTC time at the start of the collection interval,
   stored as yyyy-mm-ddThh:mm:ss.sss."
END OBJECT = COLUMN
OBJECT = COLUMN
   NAME = TEMP1
  COLUMN NUMBER = 3
  BYTES = 4
   DATA TYPE = IEEE REAL
   START BYTE = 28
```

```
UNIT = "DEGREES CELSIUS"
   DESCRIPTION = "PNG temperature in Celsius."
END OBJECT = COLUMN
OBJECT = COLUMN
   NAME = TEMP2
   COLUMN NUMBER = 4
   BYTES = 4
   DATA TYPE = IEEE REAL
   START BYTE = 32
   UNIT = "DEGREES CELSIUS"
   DESCRIPTION = "High voltage board temperature in Celsius."
END OBJECT = COLUMN
OBJECT = COLUMN
   NAME = TEMP3
   COLUMN NUMBER = 5
  BYTES = 4
  DATA_TYPE = IEEE_REAL
   START BYTE = 36
   UNIT = "DEGREES CELSIUS"
   DESCRIPTION = "FPGA temperature in Celsius.."
END OBJECT = COLUMN
OBJECT = COLUMN
   NAME = TEMP4
   COLUMN_NUMBER = 6
   BYTES = 4
   DATA TYPE = IEEE REAL
   START BYTE = 40
   UNIT = "DEGREES CELSIUS"
   DESCRIPTION = "Analog board #1 temperature in Celsius."
END OBJECT = COLUMN
OBJECT = COLUMN
  NAME = TEMP5
```

```
COLUMN NUMBER = 7
   BYTES = 4
   DATA_TYPE = IEEE_REAL
   START_BYTE = 44
   UNIT = "DEGREES CELSIUS"
   DESCRIPTION = "Analog board #2 temperature in Celsius."
END OBJECT = COLUMN
OBJECT = COLUMN
   NAME = TEMP6
   COLUMN NUMBER = 8
   BYTES = 4
   DATA_TYPE = IEEE_REAL
   START BYTE = 48
   UNIT = "DEGREES CELSIUS"
   DESCRIPTION = "Case temperature in Celsius."
END OBJECT = COLUMN
OBJECT = COLUMN
   NAME = HV LEVEL CTN
   COLUMN NUMBER = 9
   BYTES = 1
   DATA_TYPE = MSB_UNSIGNED INTEGER
   START BYTE = 52
   DESCRIPTION = "The CTN HV level 0 = off, 2 = high, 3 = low"
END OBJECT = COLUMN
OBJECT = COLUMN
   NAME = HV LEVEL CETN
   COLUMN NUMBER = 10
   BYTES = 1
   DATA TYPE = MSB UNSIGNED INTEGER
   START BYTE = 53
   DESCRIPTION = "The CETN HV level 0 = off, 2 = high, 3 = low"
END_OBJECT = COLUMN
```

INSTRUMENT NAME

```
OBJECT = COLUMN
   NAME = DSC LEVEL CTN
   COLUMN NUMBER = 11
   BYTES = 1
   DATA TYPE = MSB UNSIGNED INTEGER
   START BYTE = 54
   DESCRIPTION = "The CTN Discriminator level 0 = low, 1 = high."
END OBJECT = COLUMN
OBJECT = COLUMN
   NAME = DSC LEVEL CETN
   COLUMN NUMBER = 12
   BYTES = 1
   DATA TYPE = MSB UNSIGNED INTEGER
   START BYTE = 55
   DESCRIPTION = "The CETN Discriminator level 0 = low, 1 = high."
END OBJECT = COLUMN
OBJECT = COLUMN
   NAME = LST
   COLUMN NUMBER = 13
   BYTES = 8
   DATA TYPE = CHARACTER
   START BYTE = 56
   DESCRIPTION = "Local solar time at start of period, 'hh:mm:ss'."
END OBJECT = COLUMN
6.2 Derived Passive Label
PDS VERSION ID
                                     = PDS3
/* FILE DATA ELEMENTS */
                                    = FIXED_LENGTH
= 8671
RECORD TYPE
RECORD BYTES
                                     = 21
FILE RECORDS
/* IDENTIFICATION DATA ELEMENTS */
DATA_SET_ID = "MSL-M-DAN-3/4-RDR-V1.0"

COMMAND_SEQUENCE_NUMBER = 0

INSTRUMENT_HOST_ID = MSL

INSTRUMENT_HOST_NAME = "MARS_SCIENCE_LABORATORY"

INSTRUMENT_NAME = "DYNAMIC_ALBEDO_OF_NEUTPON
```

= "DYNAMIC ALBEDO OF NEUTRONS"

MSL:REQUEST_ID = 324 PLANET_DAY_NUMBER = "42" PRODUCT_CREATION_TIME = 2010-10-27T22:19:47.000 PRODUCT_ID -PRODUCT ID "DNA_351797691RPA_0550000000_____P1.DAT" = DAN RDR PA PRODUCT TYPE PRODUCT VERSION ID = "1. $\overline{0}$ " = "1" RELEASE ID ROVER_MOTION_COUNTER = (0,0,0,0,0,0,0) ROVER_MOTION_COUNTER_NAME = (SITE, DRIVE, POSE, ARM, CHIMRA, ROVER_MOTION_COLLDRILL, KDP1, HOH,SEQUENCE_ID= "1036288"SEQUENCE_VERSION_ID= "0"SPACECRAFT_CLOCK_START_COUNT= "340477575.18840"SPACECRAFT_CLOCK_STOP_COUNT= "340492323.21101"START_TIME= 2012-289T05:10:16.868CTOD_TIME= 2012-289T06:05:11:21.545 = MARS TARGET NAME ^TABLE "DNA_351797691RPA 0550000000 P1.DAT" OBJECT = TABLE COLUMNS = 1212 INTERCHANGE_FORMAT = BINARY ROW_BYTES = 8671 ROWS = 21 DESCRIPTION = " This table contains converted neutron count data as observed by the Mars Science Laboratory (MSL) Dynamic Albedo of Neutron Detector (DAN). Detailed descriptions for the parameters defined below are contained in the DAN RDR SIS document. The complete column definitions are contained in an external file found in the LABEL directory of the archive volume. = "DAN RDR DERIVED PASSIV.FMT" ^STRUCTURE = TABLE END OBJECT END

6.2.1 Derived Passive FORMAT FILE

OBJECT = COLUMN COLUMN_NUMBER = 1 NAME = DAN_TIME DATA TYPE = MSB UNSIGNED INTEGER

```
BYTES = 4
   START BYTE = 1
   DESCRIPTION = "DAN instrument time in milliseconds since last
                  power up."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 2
   NAME = UTC TIMESTAMP
   DATA TYPE = CHARACTER
   BYTES = 23
   START BYTE = 5
   DESCRIPTION = "UTC time at the start of the collection interval,
   stored as yyyy-mm-ddThh:mm:ss.sss."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 3
   NAME = BEGIN LATITUDE
   DATA TYPE = IEEE REAL
   BYTES = 4
   START BYTE = 28
   UNIT = DEGREE
   DESCRIPTION = "Latitude in Mars fixed coordinates at the beginning
   of the frame, in degrees."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 4
   NAME = BEGIN LONGITUDE
   DATA TYPE = IEEE REAL
   BYTES = 4
   START BYTE = 32
   UNIT = DEGREE
   DESCRIPTION = "Easting Longitude in Mars fixed coordinates at the
beginning
```

```
of the frame, in degrees."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 5
   NAME = END LATITUDE
   DATA TYPE = IEEE REAL
   BYTES = 4
   START BYTE = 36
   UNIT = DEGREE
   DESCRIPTION = "Latitude in Mars fixed coordinates at the end
   of the frame, in degrees."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 6
   NAME = END LONGITUDE
   DATA TYPE = IEEE REAL
  BYTES = 4
   START BYTE = 40
   UNIT = DEGREE
   DESCRIPTION = "Easting Longitude in Mars fixed coordinates at the end
   of the frame, in degrees."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 7
   NAME = COLLECTION DURATION
   DATA TYPE = IEEE REAL
   BYTES = 4
   START BYTE = 44
   UNIT = SECOND
   DESCRIPTION = "Value of collection time register, length of time
   in seconds."
END OBJECT = COLUMN
```

```
OBJECT = COLUMN
   COLUMN NUMBER = 8
   NAME = CTN_BKGD
   DATA_TYPE = IEEE REAL
  BYTES = 4
   START BYTE = 48
   UNIT = COUNT
   DESCRIPTION = "Background counts for CTN detector (counts)."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN_NUMBER = 9
   NAME = CTN_COUNTS
   DATA_TYPE = IEEE_REAL
   BYTES = 4
   START BYTE = 52
   UNIT = COUNT
   DESCRIPTION = "Sum of Counts gathered in CTN detector during frame
   interval."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 10
   NAME = CETN BKGD
   DATA TYPE = IEEE REAL
   BYTES = 4
   START_BYTE = 56
   UNIT = COUNT
   DESCRIPTION = "Background counts for CETN detector (counts)."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 11
   NAME = CETN_COUNTS
   DATA_TYPE = IEEE_REAL
   BYTES = 4
```

```
38
```

```
START_BYTE = 60
UNIT = COUNT
DESCRIPTION = "Sum of Counts gathered in CETN detector during frame
interval."
END_OBJECT = COLUMN
OBJECT = COLUMN
NAME = LST
COLUMN_NUMBER = 12
BYTES = 8
DATA_TYPE = CHARACTER
START_BYTE = 64
DESCRIPTION = "Local solar time at start of period, 'hh:mm:ss'."
```

END_OBJECT = COLUMN

6.3 Derived Active Label

PDS_VERSION_ID	= PDS3
/* FILE DATA ELEMENTS */ RECORD_TYPE RECORD_BYTES FILE_RECORDS	= FIXED_LENGTH = 13551336 = 21
/* IDENTIFICATION DATA ELEMENTS DATA_SET_ID COMMAND_SEQUENCE_NUMBER INSTRUMENT_HOST_ID INSTRUMENT_HOST_NAME INSTRUMENT_NAME MSL:REQUEST_ID PLANET_DAY_NUMBER PRODUCT_CREATION_TIME PRODUCT_ID	<pre>*/ = "MSL-M-DAN-3/4-RDR-V1.0" = 0 = MSL = "MARS SCIENCE LABORATORY" = "DYNAMIC ALBEDO OF NEUTRONS" = 5213 = "42" = 2010-10-27T22:19:47.000 =</pre>
"DNA_351797691RAC_0550000000 PRODUCT_TYPE PRODUCT_VERSION_ID RELEASE_ID	P1.DAT" = DAN_RDR_AC = "1.0" = "1"
ROVER_MOTION_COUNTER ROVER_MOTION_COUNTER_NAME	<pre>= (0,0,0,0,0,0,0,0) = (SITE, DRIVE, POSE, ARM, CHIMRA, DRILL, RSM, HGA)</pre>
SEQUENCE_ID SEQUENCE_VERSION_ID SPACECRAFT_CLOCK_START_COUNT SPACECRAFT_CLOCK_STOP_COUNT START_TIME STOP_TIME	<pre>= "1036288" = "0" = "340477575.18840" = "340479563.22311" = 2012-289T05:10:16.868 = 2012-289T05:21:11.454</pre>
TARGET_NAME	= MARS

^TABLE "DNA 351797691RAC 0550000000 P1.DAT" OBJECT = TABLE = 1514 COLUMNS INTERCHANGE FORMAT = BINARY ROW BYTES = 13551336 ROWS = 21 = " DESCRIPTION This table contains converted neutron count data during neutron pulsing as observed by the Mars Science Laboratory (MSL) Dynamic Albedo of Neutron Detector (DAN). Detailed descriptions for the parameters defined below are contained in the DAN RDR SIS document. The complete column definitions are contained in an external file found in the LABEL directory of the archive volume. ... ^STRUCTURE = "DAN RDR DERIVED ACTIV.FMT" = TABLE END OBJECT END

6.3.1 Derived Active FORMAT FILE

```
OBJECT = COLUMN
COLUMN_NUMBER = 1
NAME = DAN_TIME
DATA_TYPE = MSB_UNSIGNED_INTEGER
BYTES = 4
START_BYTE = 1
UNIT = MILLISECONDS
DESCRIPTION = "DAN time at beginning of interval."
END_OBJECT = COLUMN
OBJECT = COLUMN
COLUMN_NUMBER = 2
NAME = UTC_TIMESTAMP
DATA_TYPE = CHARACTER
BYTES = 23
START_BYTE = 5
```

```
DESCRIPTION = "UTC time at the start of the collection interval,
   stored as yyyy-mm-ddThh:mm:ss.sss."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 3
   NAME = LATITUDE
   DATA TYPE = IEEE REAL
   BYTES = 4
   START BYTE = 28
   UNIT = DEGREE
   DESCRIPTION = "Latitude in Mars fixed coordinates."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 4
   NAME = LONGITUDE
   DATA TYPE = IEEE REAL
  BYTES = 4
   START BYTE = 32
   UNIT = DEGREE
   DESCRIPTION = "Easting Longitude in Mars fixed coordinates."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 5
   NAME = COLLECTION DURATION
   DATA TYPE = MSB UNSIGNED INTEGER
   BYTES = 4
   START BYTE = 36
   UNIT = SECOND
   DESCRIPTION = "Value of collection time register, length of time
   in seconds."
END OBJECT = COLUMN
OBJECT = COLUMN
```

```
COLUMN NUMBER = 6
   NAME = NUM PNG PULSES
   DATA TYPE = MSB UNSIGNED INTEGER
   BYTES = 4
   START BYTE = 40
   UNIT = COUNT
   DESCRIPTION = "number of PNG pulses during data collection interval."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 7
   NAME = PNG_FREQUENCY
   DATA TYPE = MSB UNSIGNED INTEGER
   BYTES = 1
   START BYTE = 44
   UNIT = COUNT
   DESCRIPTION = "Pulsing Neutron Generator frequency of pulsing."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 8
   NAME = TIME BIN DURATION
   DATA TYPE = MSB UNSIGNED INTEGER
   BYTES = 4
   START BYTE = 45
   UNIT = MICROSECOND
   DESCRIPTION = "duration in microseconds for each time bin."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 9
   NAME = TIME BIN START
   DATA TYPE = MSB UNSIGNED INTEGER
   BYTES = 256
   START BYTE = 49
   ITEMS = 64
```

```
ITEM BYTES = 4
   UNIT = MICROSECOND
   DESCRIPTION = "start time in microseconds for each time bin."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 10
   NAME = CTN BKGD
   DATA TYPE = IEEE REAL
   BYTES = 256
   START BYTE = 305
   ITEMS = 64
   ITEM BYTES = 4
   UNIT = COUNTS
   DESCRIPTION = "Background counts for each of 64 CTN detector spectra
   (counts)."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 11
   NAME = CTN COUNTS
   DATA TYPE = IEEE REAL
   BYTES = 256
   START BYTE = 561
   ITEMS = 64
   ITEM BYTES = 4
   UNIT = COUNTS
   DESCRIPTION = "Counts gathered in CTN detector for each of the 64
   spectra during frame interval."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 12
   NAME = CETN BKGD
   DATA_TYPE = IEEE_REAL
   BYTES = 256
```

```
ITEMS = 64
   ITEM BYTES = 4
   START_BYTE = 817
   UNIT = COUNTS
   DESCRIPTION = "Background counts for each of the 64 CETN detector
   (counts)."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 13
   NAME = CETN_COUNTS
   DATA_TYPE = IEEE_REAL
   BYTES = 256
   ITEMS = 64
   ITEM BYTES = 4
   START BYTE = 1073
   UNIT = COUNTS
   DESCRIPTION = "Counts gathered in CETN detector for each of the 64
   specta during frame interval."
END OBJECT = COLUMN
OBJECT = COLUMN
   NAME = LST
   COLUMN NUMBER = 14
  BYTES = 8
   DATA_TYPE = CHARACTER
   START BYTE = 1329
   DESCRIPTION = "Local solar time at the start of interval, 'hh:mm:ss'."
END OBJECT = COLUMN
```

6.4 Averaged Passive Label

PDS_VERSION_ID	= PDS3
/* FILE DATA ELEMENTS */	
RECORD TYPE	= FIXED LENGTH
RECORD_BYTES	$= 10612\overline{2}$

= 21 FILE RECORDS /* IDENTIFICATION DATA ELEMENTS */ /* IDENTIFICATION DATA ELEMENTS */
DATA_SET_ID = "MSL-M-DAN-3/4-RDR-V1.0"
COMMAND_SEQUENCE_NUMBER = 0
INSTRUMENT_HOST_ID = MSL
INSTRUMENT_HOST_NAME = "MARS SCIENCE LABORATORY"
INSTRUMENT_NAME = "DYNAMIC ALBEDO OF NEUTRONS"
MSL:REQUEST_ID = 2131
PLANET_DAY_NUMBER = "42"
PRODUCT_CREATION_TIME = 2010-10-27T22:19:47.000
PRODUCT_ID = PRODUCT ID "DNA 351797691RAP_0550000000_____ P1.DAT" PRODUCT_TYPE = DAN_RDR_AP PRODUCT_VERSION_ID = "1.0" = "1" RELEASE ID RELEASE ID ROVER_MOTION_COUNTER = (0,0,0,0,0,0,0,0) ROVER_MOTION_COUNTER_NAME = (SITE, DRIVE, POSE, ARM, CHIMRA, DDITT_DSM_HCL) ROVER_MOTION_COUNTER_NAME= (SITE, DRIVE, FOSE, AND
DRILL, RSM, HGA)SEQUENCE_ID= "1036288"SEQUENCE_VERSION_ID= "0"SPACECRAFT_CLOCK_START_COUNT= "340477575.18840"SPACECRAFT_CLOCK_STOP_COUNT= "340470323.23321"START_TIME= 2010-289T05:10:16.868" STOP TIME = 2012-289T05:12:17.121 TARGET NAME = MARS ^TABLE "DNA 351797691RAP 0550000000 P1.DAT" = TABLE OBJECT COLUMNS = 1719INTERCHANGE_FORMAT = BINARY ROW_BYTES _ = 106122ROWS = 21 DESCRIPTION = " This table contains converted neutron averaged counts data during neutron passive operations as observed by the Mars Science Laboratory (MSL) Dynamic Albedo of Neutron Detector (DAN). Detailed descriptions for the parameters defined below are contained in the DAN RDR SIS document. The complete column definitions are contained in an external file found in the LABEL directory of the archive volume. ^STRUCTURE = "DAN RDR AVERAGE PASSIV.FMT" = TABLE END OBJECT END

5.3.1 Averaged Passive FORMAT FILE

```
OBJECT = COLUMN
  COLUMN NUMBER = 1
  NAME = START DAN TIME
   DATA TYPE = MSB UNSIGNED INTEGER
  BYTES = 4
   START BYTE = 1
   UNIT = MILLISECONDS
   DESCRIPTION = "DAN time at beginning of average interval."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 2
  NAME = END_DAN_TIME
   DATA TYPE = MSB UNSIGNED INTEGER
  BYTES = 4
   START BYTE = 5
   UNIT = MILLISECONDS
   DESCRIPTION = "DAN time at end of average interval."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN NUMBER = 3
  NAME = START UTC
  DATA TYPE = CHARACTER
  BYTES = 23
  START BYTE = 9
   DESCRIPTION = "UTC time at the start of the collection interval,
   stored as yyyy-mm-ddThh:mm:ss.sss."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 4
   NAME = END UTC
   DATA TYPE = CHARACTER
   BYTES = 23
   START BYTE = 32
   DESCRIPTION = "UTC time at the end of the collection interval,
```

```
stored as yyyy-mm-ddThh:mm:ss.sss."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 5
  NAME = BEGIN LATITUDE
   DATA TYPE = IEEE REAL
  BYTES = 4
   START BYTE = 55
  UNIT = DEGREE
   DESCRIPTION = "Latitude in Mars fixed coordinates at the beginning
   of the frame, in degrees."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 6
  NAME = BEGIN LONGITUDE
   DATA TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 59
  UNIT = DEGREE
  DESCRIPTION = "Easting Longitude in Mars fixed coordinates at the
beginning
   of the frame, in degrees."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN NUMBER = 7
  NAME = END LATITUDE
  DATA TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 63
  UNIT = DEGREE
   DESCRIPTION = "Latitude in Mars fixed coordinates at the end
   of the frame, in degrees."
END OBJECT = COLUMN
```

OBJECT = COLUMN

```
COLUMN NUMBER = 8
  NAME = END LONGITUDE
   DATA TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 67
  UNIT = DEGREE
   DESCRIPTION = "Easting Longitude in Mars fixed coordinates at the end
   of the frame, in degrees."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN NUMBER = 9
  NAME = COLLECTION_DURATION
   DATA TYPE = MSB UNSIGNED INTEGER
  BYTES = 4
  START BYTE = 71
  UNIT = SECOND
   DESCRIPTION = "Value of collection time register, length of time
  in seconds."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 10
  NAME = CTN AVERAGE
  DATA TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 75
  UNIT = COUNT
   DESCRIPTION = "Average Counts in CTN detector over duration."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 11
   NAME = CTN BKGD
   DATA TYPE = IEEE REAL
   BYTES = 4
   START BYTE = 79
```

```
UNIT = COUNT
   DESCRIPTION = "Background counts for CTN detector (counts)."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 12
  NAME = CTN ERROR
   DATA TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 83
  UNIT = COUNT
   DESCRIPTION = "Error in CTN detector over duration."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 13
  NAME = CTN NORM
   DATA TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 87
  UNIT = COUNT
   DESCRIPTION = "Normalization for CTN detector over duration."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 14
  NAME = CETN AVERAGE
   DATA TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 91
  UNIT = COUNT
   DESCRIPTION = "Average counts for CETN detector over duration."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN NUMBER = 15
  NAME = CETN BKGD
```

```
DATA TYPE = IEEE REAL
  BYTES = 4
   START BYTE = 95
  UNIT = COUNT
   DESCRIPTION = "Background counts for CETN detector (counts)."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 16
  NAME = CETN ERROR
  DATA_TYPE = IEEE_REAL
  BYTES = 4
  START_BYTE = 99
  UNIT = COUNT
  DESCRIPTION = "Error in CETN detector over duration."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN NUMBER = 17
  NAME = CETN_NORM
  DATA TYPE = IEEE REAL
  BYTES = 4
   START BYTE = 103
  UNIT = COUNT
   DESCRIPTION = "Normalization for CETN detector for duration."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN NUMBER = 18
  NAME = START_LST
  DATA TYPE = CHARACTER
  BYTES = 8
   START BYTE = 107
   DESCRIPTION = "Local solar time at start of period, 'hh:mm:ss'."
END OBJECT = COLUMN
OBJECT = COLUMN
```

```
COLUMN_NUMBER = 19
NAME = END_LST
DATA_TYPE = CHARACTER
BYTES = 8
START_BYTE = 115
DESCRIPTION = "Local solar time at end of period, 'hh:mm:ss'."
END OBJECT = COLUMN
```

6.5 Averaged Active Label

PDS_VERSION_ID	= PDS3
/* FILE DATA ELEMENTS */	
RECORD_TYPE	= FIXED_LENGTH
RECORD_BYTES	= 119135
FILE_RECORDS	= 21
/* IDENTIFICATION DATA ELEMENTS	*/
DATA_SET_ID	= "MSL-M-DAN-3/4-RDR-V1.0"
COMMAND_SEQUENCE_NUMBER	= 0
INSTRUMENT_HOST_ID	= MSL
INSTRUMENT_HOST_NAME	= "MARS SCIENCE LABORATORY"
INSTRUMENT_NAME	= "DYNAMIC ALBEDO OF NEUTRONS"
MSL:REQUEST_ID	= 3321
PLANET_DAY_NUMBER	= "42"
PRODUCT CREATION TIME	= 2010-10-27T22:19:47.000
PRODUCT ID	=
"DNA 351797691RAA 0550000000	P1.DAT"
PRODUCT TYPE	= DAN RDR AA
PRODUCT VERSION ID	= "1.0"
RELEASE ID	= "1"
ROVER MOTION COUNTER	= (0, 0, 0, 0, 0, 0, 0, 0, 0)
ROVER MOTION COUNTER NAME	= (SITE, DRIVE, POSE, ARM, CHIMRA,
SEQUENCE ID	= "1036288"
SEQUENCE VERSION ID	= "0"
SPACECRAFT CLOCK START COUNT	= "340477575.18840"
SPACECRAFT CLOCK STOP COUNT	= "340481123.22311"
START TIME	= 2012-289T05:10:16.868
STOP TIME	= 2012-289T05:12:22:213
TARGET NAME	= MARS
^TABLE	=
"DNA_351797691RAA_0550000000	P1.DAT"
OBJECT	= TABLE
COLUMNS	= 2123
INTERCHANGE FORMAT	= BINARY
ROW BYTES -	= 119135
ROWS	= 21

= " DESCRIPTION This table contains converted neutron count data during neutron pulsing as observed by the Mars Science Laboratory (MSL) Dynamic Albedo of Neutron Detector (DAN). Detailed descriptions for the parameters defined below are contained in the DAN RDR SIS document. The complete column definitions are contained in an external file found in the LABEL directory of the archive volume. ... ^STRUCTURE = "DAN RDR AVERAGE ACTIV.FMT" END OBJECT = TABLE END

5.3.1 Averaged Active FORMAT FILE

```
OBJECT = COLUMN
   COLUMN NUMBER = 1
  NAME = START DAN TIME
  DATA TYPE = MSB_UNSIGNED_INTEGER
  BYTES = 4
  START BYTE = 1
  UNIT = MILLISECONDS
   DESCRIPTION = "DAN time at beginning of average."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN NUMBER = 2
  NAME = END_DAN_TIME
   DATA TYPE = MSB UNSIGNED INTEGER
  BYTES = 4
   START BYTE = 5
   UNIT = MILLISECONDS
   DESCRIPTION = "DAN time at end of averaging interval."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 3
  NAME = START UTC
   DATA TYPE = CHARACTER
```

```
BYTES = 23
   START BYTE = 9
   DESCRIPTION = "UTC time at the start of the averaging interval,
   stored as yyyy-mm-ddThh:mm:ss.sss."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 4
  NAME = END UTC
  DATA TYPE = CHARACTER
  BYTES = 23
  START BYTE = 32
   DESCRIPTION = "UTC time at the end of the averaging interval,
   stored as yyyy-mm-ddThh:mm:ss.sss."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN NUMBER = 5
  NAME = BEGIN LATITUDE
  DATA_TYPE = IEEE_REAL
  BYTES = 4
  START BYTE = 55
  UNIT = DEGREE
   DESCRIPTION = "Latitude in Mars fixed coordinates at the beginning
   of the frame, in degrees."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN NUMBER = 6
  NAME = BEGIN LONGITUDE
  DATA TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 59
   UNIT = DEGREE
   DESCRIPTION = "Easting Longitude in Mars fixed coordinates at the
beginning
   of the frame, in degrees."
END OBJECT = COLUMN
```

```
OBJECT = COLUMN
   COLUMN NUMBER = 7
  NAME = END LATITUDE
   DATA_TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 63
  UNIT = DEGREE
   DESCRIPTION = "Latitude in Mars fixed coordinates at the end
  of the frame, in degrees."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 8
  NAME = END LONGITUDE
   DATA TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 67
  UNIT = DEGREE
   DESCRIPTION = "Easting Longitude in Mars fixed coordinates at the end
   of the frame, in degrees."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 9
  NAME = COLLECTION DURATION
   DATA TYPE = MSB UNSIGNED INTEGER
  BYTES = 4
  START BYTE = 71
  UNIT = SECOND
   DESCRIPTION = "Value of collection time register, length of time
  in seconds."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN NUMBER = 10
   NAME = NUM PNG PULSES
```

JPL D-38122, SIS-SCI019-MSL

```
DATA TYPE = MSB UNSIGNED INTEGER
   BYTES = 4
   START BYTE = 75
  UNIT = COUNT
   DESCRIPTION = "number of PNG pulses during data collection interval."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 11
  NAME = PNG FREQUENCY
   DATA_TYPE = MSB_UNSIGNED_INTEGER
  BYTES = 1
  START_BYTE = 79
  UNIT = COUNT
   DESCRIPTION = "Pulsing Neutron Generator frequency of pulsing."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN NUMBER = 12
  NAME = TIME_BIN_DURATION
  DATA TYPE = IEEE REAL
  BYTES = 4
   START BYTE = 80
  UNIT = MICROSECONDS
   DESCRIPTION = "duration in microseconds for each time bin."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN NUMBER = 13
  NAME = TIME BIN START
   DATA_TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 84
   UNIT = MICROSECONDS
   DESCRIPTION = "start time after the pulse in microseconds for
   each time bin."
END OBJECT = COLUMN
```

```
OBJECT = COLUMN
  COLUMN NUMBER = 14
  NAME = CTN_AVERAGE
  DATA TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 88
  UNIT = COUNT
   DESCRIPTION = "Average Counts in CTN detector over duration."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN_NUMBER = 15
  NAME = CTN BKGD
  DATA TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 92
  UNIT = COUNT
   DESCRIPTION = "Background counts for CTN detector (counts)."
END_OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 16
  NAME = CTN ERROR
  DATA TYPE = IEEE REAL
  BYTES = 4
   START BYTE = 96
  UNIT = COUNT
   DESCRIPTION = "Average Error in CTN detector over interval."
END_OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 17
  NAME = CTN NORM
   DATA TYPE = IEEE REAL
   BYTES = 4
   START BYTE = 100
```

```
UNIT = COUNT
   DESCRIPTION = "Normalization for CTN detector over duration."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 18
  NAME = CETN AVERAGE
  DATA TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 104
  UNIT = COUNT
   DESCRIPTION = "Average counts for CETN detector over duration."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 19
  NAME = CETN BKGD
   DATA TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 108
  UNIT = COUNT
   DESCRIPTION = "Background counts for CETN detector (counts)."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 20
  NAME = CETN ERROR
   DATA TYPE = IEEE REAL
  BYTES = 4
  START BYTE = 112
  UNIT = COUNT
   DESCRIPTION = "Error in CETN detector over duration."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN NUMBER = 21
  NAME = CETN NORM
```

```
DATA_TYPE = IEEE_REAL
  BYTES = 4
  START BYTE = 116
  UNIT = COUNT
   DESCRIPTION = "Normalization for CETN detector for duration."
END OBJECT = COLUMN
OBJECT = COLUMN
   COLUMN NUMBER = 22
  NAME = START_LST
  DATA_TYPE = CHARACTER
  BYTES = 8
  START_BYTE = 120
   DESCRIPTION = "Local solar time at start of period, 'hh:mm:ss'."
END OBJECT = COLUMN
OBJECT = COLUMN
  COLUMN NUMBER = 23
  NAME = END_LST
  DATA_TYPE = CHARACTER
  BYTES = 8
  START BYTE = 128
   DESCRIPTION = "Local solar time at end of period, 'hh:mm:ss'."
END OBJECT = COLUMN
```

7. APPENDIX – A

Keyword Name	Definition	Туре
PDS_VERSION_ID	Specifies the version number of the PDS standards document that is valid when a data product label is created. Values for the PDS_version_id are formed by appending the integer for the latest version number to the letters 'PDS'.	String
/* FILE DATA ELEMENTS */	Comment	
RECORD_TYPE	Specifies the record format of a file, such as FIXED_LENGTH. Note: In the PDS, when RECORD_TYPE is used in a detached label file, it always describes its corresponding detached data file and not the label file itself. The use of RECORD_TYPE along with other file- related data elements is fully described in the PDS Standards Reference.	String
RECORD_BYTES	Specifies the number of bytes in a physical file record, including record terminators and separators. Note: In the PDS, the use of record_bytes, along with other file- related data elements is fully described in the Standards Reference.	integer
FILE_RECORDS	Specifies the number of physical file records, including both label records and data records. Note: In the PDS the use of FILE_RECORDS along with other file-related data elements is fully described in the Standards Reference.	integer
/* IDENTIFICATION DATA FLEMENTS */	Comment	

Keyword Name	Definition	Туре
DATA_SET_ID	A unique alphanumeric identifier for a	string(40
	data set or a data product. The)
	DATA_SET_ID value for a given data	
	set or product is constructed according	
	to flight project naming conventions. In	
	most cases the DATA_SET_ID is an	
	abbreviation of the	
	DATA_SET_NAME.	
	Note: In the PDS, the values for both	
	DATA SET ID and	
	DATA SET NAME are constructed	
	according to standards outlined in the	
	Standards Reference.	
COMMAND_SEQUENCE_NUMBER	Specifies a numeric identifier for a	String
	sequence of commands sent to a	
	spacecraft or instrument.	
	Note: For MSL, this is the common 1	
	note: For MSL, this is the command	
	generating command within the	
	specified sequence	
INSTRUMENT HOST ID	Specifies a unique identifier for the host	String
	where an instrument is located. This	Sumg
	host can be either a spacecraft or an	
	earth base (e.g., and observatory or	
	laboratory on the earth). Thus,	
	INSTRUMENT_HOST_ID can contain	
	values, which are either	
	SPACECRAFT_ID values or	
	EARTH_BASE_ID values.	
INSTRUMENT_HOST_NAME	The full name of the host on which this	String
INSTRUMENT NAME	Instrument is based	Stains
	enclosed in double quotes. See	Sung
	example labels for various names used	
	for MECA non-imaging products	
INTERCHANGE FORMAT	Set to BINARY for DAN RDRs	String
PLANET DAY	Mars Sol starting from Sol 0 at Landing	Integer
PRODUCT_CREATION_TIME	Defines the UTC system format time	String
	when a product was created.	
PRODUCT_ID	Represents a permanent, unique	String(40
	identifier assigned to a data product by)
	its producer. See also:	
	source_product_1d.	
	Note: In the PDS, the value assigned to	
	product id must be unique within its	
	data set.	
	Additional note: The product_id can	
	describe the lowest-level data object	
	that has a PDS label.	
PRODUCT TYPE	Either EDR or RDR	String

Keyword Name	Definition	Туре
MSL:REQUEST ID	Specifies the Request ID value	
	associated with the Data Product	
	generation command. Unsigned integer.	
ROVER MOTION COUNTER	Specifies a set of integers which	
	describe a (potentially) unique location	
	(position/orientation) for a rover. Each	
	time something happens that moves, or	
	could potentially move, the rover, a	
	new motion	
	counter value is created. This includes	
	intentional motion due to drive	
	commands, as well as potential motion	
	due to other articulating devices, such	
	as arms or antennae. This motion	
	counter (or part of it) is used as a	
	reference to define instances of	
	coordinate systems which can move	
	such as SITE or ROVER frames. The	
	motion counter is defined in a mission-	
	specific manner. Although the original	
	intent was to have incrementing indices	
	(e.g. MER), the motion counter could	
	also contain any integer values which	
	conform to the above definition, such as	
	time or spacecraft clock values.	
	For MSL, the motion counter consists	
	of eight values. In order, they are Site,	
	Drive, Pose, Arm, Chimra, Drill, RSM	
	and HGA. The Site value increments	
	whenever a new major Site frame is	
	declared. The Drive value increments	
	any time intentional driving is done.	
	Each of those resets all later indices to	
	0 when they increment.	
ROVER_MOTION_COUNTER_NAME	Specifies an array that provides the	
	formal names identifying each integer	
	in	
	ROVER_MOTION_COUNTER.	
SEQUENCE_ID	Specifies an identification of the	
_	spacecraft sequence associated with the	
	given product. This element replaces	
	the older seq_id, which should no	
	longer be used.	
SEQUENCE_VERSION_ID	Specifies the version identifier for a	
	particular observation sequence used	
	during planning or data processing.	
SPACECRAFT CLOCK START	Starting SCLK, smallest, value of all	string(30
	the records contained in the EDR.)
START TIME	SPACECRAFT CLOCK START CO	string
_	UNT converted and represented in UTC	0
STOP TIME	SPACECRAFT CLOCK STOP	string
	converted and represented in UTC	8

Keyword Name	Definition	Туре
TARGET_NAME	Identifies a target. The target may be a	string(30
	planet, satellite, ring, region, feature,)
	asteroid or comet. See	
	TARGET_TYPE. This is based on	
	mission phase.	
^TABLE	The name of the data file	string
COLUMNS	The number of columns in the data file	Integer
ROW_BYTES	The number of bytes per row in the data	Integer
	file	_
ROWS	The number of rows in the data file	Integer
^STRUCTURE	A pointer to the Format file the contains	String
	information about each column in the	
	data file	